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Typesetting: Camera-ready copy by authors Cover-Design: de'blik, Berlin SPIN: 10836055 62/3020 5 4 3 2 1 0 Printed on acid-free paper open questions and explores the future of

Part I concerns the problem of enhalm an array of microphones. For a variety computer interaction and hands-free tele roam unfettered in diverse environments speech signal and robustness against based and reverberation effects. The use of microphones sources are physically separated in ing techniques, typically developed for a were initially applied to the hands-free specific environment in which microphone are from that of conventional array application has an extremely wide bandwidth relational techniques.





and track one or more speech sources is an essential requirement of microphone array systems. For speech enhancement applications, an accurate fix on the primary talker, as well as knowledge of any interfering talkers or coherent noise sources, is necessary to effectively steer the array, enhancing a given source while simultaneously attenuating those deemed undesirable. Location data may be used as a guide for discriminating individual speakers in a multisource scenario. With this information available, it would then be possible to automatically focus upon and follow a given source on an extended basis. Of particular interest lately, is the application of the speaker location estimates for aiming a camera or series of cameras in a video-conferencing system. In this regard, the automated localization information eliminates the need for a human or number of human camera operators. Several existing commercial products apply microphone-array technology in small-room environments to steer a robotic camera and frame active talkers. Chapter 8 summarizes the various approaches which have been explored to accurately locate an individ-

shown to dramatically improve the speech paired and to increase their overall satisfated focuses on the case of a simple two-element to achieve noise and echo reduction. The is analyzed under realistic acoustic conditions for desktop conferencing and intercom approximation to achieve noise and echo reduction. The is analyzed under realistic acoustic conditions involving loudspeakers and microph cancellation methods are integrated within enhanced echo suppression. These results channel conferencing scenarios. Chapter a larrays for sound capture in automobiles. The echo cancellation specifically within the caparticularly effective approach is detailed.





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2.1	Intro	duction
		ation of Beamformers
		Array-Gain
		Beampattern
	2.2.3	Directivity
	2.2.4	Front-to-Back Ratio
		White Noise Gain
2.3	Design of Superdirective Beamforme	
	2.3.1	Delay-and-Sum Beamformer
		Design for spherical isotropic
		Design for Cylindrical Isotrop
		Design for an Optimal Front-
		Design for Measured Noise Fi
2.4	Extensions and Details	
		Alternative Form





helped us in a big way. In the early days nal processing complexity were possible. high cost DSP computations, where com widespread use of the technology. Today us to implement all but the most comple processing technology in real-time. But t from breaking through the computing be problems at hand has significantly progres of the results presented are from recent y the potential and the limitations of micr too often the same problems that were years ago are still set apart for 'future proposed solutions are similar to the ones for a long time. Generally speaking we i tions add to our understanding but lack r future for themselves.

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