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**APPLICATION NUMBER: 11/147,688** 

FILING DATE: June 08, 2005 PATENT NUMBER: 7725253 ISSUE DATE: May 25, 2010

Certified by

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for Intellectual Property and Director of the United States Patent and Trademark Office

DOCKET A L A R M



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Attorney Docket: 09970-011002

Commissioner for Patents P.O. Box 1450

Alexandria, VA 22313-1450

Presented for filing is a new continuation patent application of:

112996 U.S. PT 11/147688



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WASHINGTON, DC

Ti

Applicant: ERIC FOXLIN

Title:

June 8, 2005

TRACKING AUTO-CALIBRATION, AND MAP-BUILDING

**SYSTEM** 

The prior application is assigned of record to InterSense, Inc., a Delaware corporation, by virtue of an assignment submitted to the Patent and Trademark Office and recorded on November 13, 2003 at 014124/0825.

Enclosed are the following papers, including those required to receive a filing date under 37 CFR §1.53(b):

	<u>Pages</u>
Specification	77
Claims	14
Abstract	1
Declaration	1
Drawings	12

### **Enclosures:**

- Preliminary amendment, 6 pages.
- New disclosure information, including: Information disclosure statement, 1 page. PTO-1449, 1 page.
- Postcard.

This application is a continuation (and claims the benefit of priority under 35 USC 120) of U.S. application serial no. 10/639,242, filed August 11, 2003, which claims the benefit of U.S. Provisional Application No. 60/402,178, filed August 9, 2002. The disclosure of the prior application is considered part of (and is incorporated by reference in) the disclosure of this application.

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Express Mail Label No	EV382038175US	
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### FISH & RICHARDSON P.C.

Commissioner for Patents June 8, 2005 Page 2

Applicant claims small entity status. See 37 CFR 1.27.

Basic Filing Fee	\$150
Search Fee	\$250
Examination Fee	\$100
Total Filing fee	\$500

A check for the filing fee is enclosed. Please apply any other required fees or any credits to deposit account 06-1050, referencing attorney docket 09970-011002.

If this application is found to be incomplete, or if a telephone conference would otherwise be helpful, please call the undersigned at (617) 542-5070.

Kindly acknowledge receipt of this application by returning the enclosed postcard.

Please direct all correspondence to the following:

26161

**PTO Customer Number** 

Respectfully submitted,

Rex I. Huang\* for David L. Feigenbaum, Reg. No. 30,378

**Enclosures** RIH/txk

\* See attached document certifying that Rex Huang has limited recognition to practice before the U.S. Patent and Trademark Office under 37 CFR § 10.9(b).

21076751.doc



Attorney Docket: 09970-011002

## **APPLICATION**

## **FOR**

## UNITED STATES LETTERS PATENT

TITLE:

TRACKING AUTO-CALIBRATION, AND MAP-BUILDING

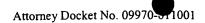
**SYSTEM** 

APPLICANT:

ERIC FOXLIN

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### TRACKING, AUTO-CALIBRATION, AND MAP-BUILDING SYSTEM

### Cross-Reference to Related Applications

[01] This application claims the benefit of U.S. Provisional Application No. 60/402,178, filed August 9, 2002, titled "Localization, Auto-Calibration, and Map-Building," the contents of which are incorporated herein by reference.

### Background

- [02] This invention relates to tracking, navigation, pose estimation, localization, autocalibration, scene modeling, structure-from-motion and/or map-building based on sensor inputs.
- [03] Tracking or navigation systems often make use of measurements from sensors to aid in determining a location ("localization") or an orientation (attitude and heading) or a pose (position and orientation) of an object such as a person, a vehicle or a robot as it navigates in an environment, such as within the bounds of a building. A variety of types of sensors are available for such systems, including sensors that measure a relative location between a sensor and a target. An example of such a sensor/target combination is an acoustic emitter (target) and a microphone array (sensor) that can determine a direction of arrival of an acoustic signal broadcast from the emitter. Different types of sensors measure different aspects of the relative pose of a sensor and a target, such as a range, direction, or relative orientation. Different sensors may have different measurement characteristics that affect the mapping between the relative pose of a sensor and a target and the measurement values provided by the sensor. These characteristics can include uncertainty or noise characteristics of the measurement values.
- [04] Systems have been developed that use Kalman Filtering techniques to incorporate information in sensor measurements to track the position or orientation of an object, typically also using information about the dynamic characteristics of the object. The implementation of such Kalman Filtering techniques is often complex, and typically



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