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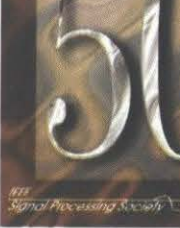
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maximally decimated multirate filterbanks. Unlike the existing precoding methods, such as the TH and trellis precodings, the new precoding

- i) may be independent of the ISI channel;
- ii) is linear and does not have to implement any modulo operation;
- iii) gives the ideal FIR equalization at the receiver for any FIR ISI channel including spectral-null channels;
- iv) expands the transmission bandwidth in a minimum amount.

The precoding is built on nonmaximally decimated multirate filterbanks. Based on multirate filterbank theory, we present a necessary and sufficient condition on an FIR ISI transfer function in terms of its zero set such that there is a linear FIR $N \times K$ precoder so that an ideal FIR equalizer exists, where the integers K and N are arbitrarily fixed. The condition is easy to check. As a consequence of the condition, for any given FIR ISI transfer function (not identically 0), there always exist such linear FIR precoders. Moreover, for almost all given FIR ISI transfer functions, there exist linear FIR precoders with size $N \times (N - 1)$, i.e., the bandwidth is expanded by $1/N$. In addition to the conditions on the ISI transfer functions, a method for the design of the linear FIR precoders and the ideal FIR equalizers is also given. Numerical examples are presented to illustrate the theory.

I. INTRODUCTION

INTERSYMBOL interference (ISI) is a common problem in telecommunication systems, such as terrestrial television broadcasting, digital data communication systems, and cellular mobile communication systems. The main reasons for the ISI are because of high-speed transmission and multipath fading. There have been considerable studies for these problems, such as [1]–[29] and [33]–[40]. These studies can be primarily split into three categories:

- i) post equalization, such as least-mean-squared (LMS) equalizer and decision feedback equalization (DFE), for example, [1]–[3], [18]–[29], and [36]–[39];
- ii) multicarrier modulation to increase transmission symbol length, for example, [4]–[6];

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and Forney [9], [10], matched spectral null precoding in partial response channels [12], and other precoding schemes, for example, [13]–[17] and [40].

The basic idea for DFE is that once an information has been detected, the ISI that it causes on future symbols can be estimated and subtracted out prior to symbol detection. The DFE usually consists of a feedforward filter and feedback filter. The feedback filter is driven by decisions of the output symbol detector, and its coefficients are adjusted to cancel the ISI from the current symbol that results from past detected symbols. The coefficient adjustment may be done via a linear equalization algorithm such as LMS algorithms. The convergence of these iterative algorithms are dependent of the channel characteristics. When a channel has a spectral null or frequency selective fading, these algorithms converge very slow and, therefore, become computationally expensive. The performance of the existing linear equalizers significantly degrades over frequency selective fading channels. Although DFE has better performance than the existing linear equalizers when the frequency fading is in the middle of a passband, it does not offer much improvement in other fading channels. For more details, see, for example, [3] and [35]. In addition to equalization techniques, there are many research results on blind equalization, for example, [18]–[29] and [36]–[39] on blind equalization where channel characteristics are assumed unknown. In addition to equalization techniques, there are approximately three categories of results:

- i) high-order statistics techniques;
- ii) second-order cyclostationary statistics techniques with oversampling;
- iii) antenna array (smart antenna) multireceiver techniques

where there is a considerable amount of overlaps between categories i) and iii).

A block diagram for TH precoding is shown in Fig. 1. The basic idea is to equalize the signal before transmission. With TH precoding there are two drawbacks: i) The transmitter needs to know the channel characteristics, and ii) the precoding is not reliable when the ISI channel $H(z)$ has spectral nulls or frequency selective fading characteristics, which is because the pre-equalizer mod $[1/H(z), M]$ oscillates in a discrete way when $H(z)$ is close to zero. The trellis precoding, proposed by Eyuboglu and Forney [9] whitens the noise at the equalizer output. This scheme combines precoding and

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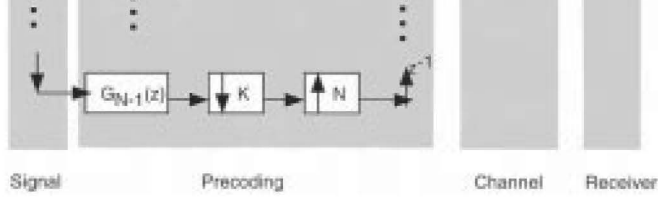


Fig. 2. Nonmaximally decimated multirate filterbank in a communication channel with ISI.

shaping. There are also similar drawbacks about this approach.

- i) The transmitter also needs to know the ISI channel characteristics.
- ii) The trellis shaping depends on the ISI channel.
- iii) The trellis precoding technique may not be suitable for spectral-null channels either.

In the matched spectral null precoding scheme [12] in partial response channels, certain error control codes are chosen to match the spectral nulls of partial response channels in order to lose less signal information through the channel. This approach is mainly for magnetic recording systems.

We now propose a multirate filterbank as a precoder before transmission (shown in Fig. 2), where $\downarrow K$ indicates downsampling by K , and $\uparrow N$ indicates upsampling by N , i.e., inserting $N - 1$ zeros between two adjacent samples, and $H(z)$ is the ISI transfer function. Later, we will see a multirate filterbank decoder for the receiver to eliminate the ISI. If input signal $x[n]$ in Fig. 2 can be completely recovered from the received signal $\hat{x}[n]$ through an FIR linear system, we call that the system in Fig. 2 has perfect reconstruction (PR) or an FIR ideal linear equalizer. In what follows, we use “precoder” and “multirate filterbank” interchangeably.

With the precoder proposed in Fig. 2, there are three questions to be answered:

- i) What is the condition on $H(z)$ such that there exists a multirate filterbank with N channels and decimation by K in Fig. 2 so that $x[n]$ can be recovered from $\hat{x}[n]$ through an FIR linear system?
- ii) If the condition on $H(z)$ in the first question is satisfied, how does one design a multirate filterbank in Fig. 2 to eliminate the ISI?
- iii) If both of these two problems are solved, how does the receiver recover the input signal $x[n]$ from the received $\hat{x}[n]$?

equivalent to the fractionally spaced equalizer studied in, for example, [36]–[39], where the receiver needs to sample the signal N times faster than the baud sampling. When $K = 1$, the precoding concept has appeared in [39] by Tsatsanis and Giannakis, where the precoder $G_l(z) = c_l, l = 0, 1, \dots, N - 1$ for N constants c_l was used. As we can see, the case of $K = 1$ is a very special case in our precoding scheme. Moreover, our new precoding scheme in Fig. 2 provides a set of potential precoders $G_l(z), l = 0, 1, \dots, N - 1$ rather than only constants c_l , which allows one to search the optimum precoder with respect to an individual channel.

When $K \geq N$ and there are N interference channels instead of a single channel $H(z)$ in Fig. 2, a detailed analysis is given by Nguyen [31]. When $K > N$, as mentioned in [31], PR is impossible, but partial alias cancellation filters were proposed in [31]. The applications discussed in [31] are in wide-band radio communications, where only part of the signal frequencies is of interest to the user. In this paper, we are interested in applications in the ISI channels with multiple channels in Fig. 2 and, therefore, the case of $K < N$ also implies that unlike the existing precoding techniques, the new precoding expands the transmission bandwidth, while what we lose for the new precoding method, and fortunately, we will show that the bandwidth expansion can be achieved as far as possible in theory.

An intuitive way to reduce the ISI generated from a lowpass filter $H(z)$ is to smoothly interpolate $x[n]$ with a large number of interpolations between samples of $x[n]$. The interpolated one has the lowpass property. However, several drawbacks about this approach may occur. One is that it usually requires a large amount of increasing of data rate (number of interpolations between samples). The other is that a good frequency band structure for a nonlowpass filter, as bandpass, filter $H(z)$ is required for PR. In this paper, we want to solve the above three problems systematically. Given two integers $0 < K < N$, we present a necessary and sufficient condition (see Theorem 1) on an FIR filter $H(z)$ such that there exists an FIR nonmaximally decimated multirate filterbank with N channels and decimation by K in Fig. 2 so that $x[n]$ can be recovered from $\hat{x}[n]$ in Fig. 2 with an FIR synthesis bank. The condition we found is basically very simple. In fact, it can be proved that for any given FIR filter $H(z)$ not identically 0, there always exists an FIR nonmaximally decimated multirate filterbank in Fig. 2 for recovering

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