PROVISIONAL APPLICATION COVER SHEET

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Attorney Docket No.: ADAPP085A+

First Named Inventor: WILSON, Andrew



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Kay Harlow

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Sir: This is a request for filing a PROVISIONAL APPLICATION under 37 CFR 1.53(c). INVENTOR(S)/APPLICANT(S)

LAST NAME	FIRST NAME	MIDDLE INITIAL	RESIDENCE (CITY AND EITHER STATE OR FOREIGN COUNTRY)
WILSON	Andrew		San Jose, CA
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	CORRESPOND	ENCE ADDRESS	
Albert S. Penilla, Esq. MARTINE PENILLA & KIM, LLP 710 Lakeway Drive, Suite 170 Sunnyvale, California 94086			
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YPED NAME Albert S. Penilla		REGISTRATION NO. <u>39,487</u>	
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eSCSI

SCSI over Ethernet eSCSI

Inventor

Andrew Wilson

1 Introduction

This document will show how adding an appropriate light weight protocol to Gigabit Ethernet can turn it into a high quality disk subsystem interconnect.

1.1 Scope and Requirements

Because Ethernet is has price and performance points which cover everything from homes and small offices to the largest computer rooms, an Ethernet based storage subsystem could also find applicability in the same wide range of settings. However, there are some differences in the requirements, which might preclude an eSCSI designed for one end of the scale from working at the other. For the desktop and small server market, the basic requirement is to connect local storage class devices to computer systems, especially when the devices are housed outside of the main computer case. For the large server system market, the requirements of storage subsystem sharing and interprocess communication over campus area networks are added. The specific requirements are detailed in the next two subsections.

1.1.1 Desktop and small system requirements

- 1. Low latency, on the order of a couple hundred microseconds or less
- 2. Maximum distances of a few hundred meters
- 3. For disk storage, needs to support bandwidths up to those of small RAID boxes
- 4. For desktop connectivity, needs to support bandwidths of tapes, printers, scanners, etc.
- 5. CPU utilization on the order of current storage systems
- 6. Data must be delivered completely and without corruption.
- 7. Use off-the-shelf Ethernet components
- 8. Needs to configure automatically, i.e. can function satisfactorily with little or no system administrator intervention
- 9. Low cost, especially for desktop connectivity
- 10. The ability to jointly operate with other protocols is highly desirable.

1.1.2 Large System Requirements

- 1. Low latency, on the order of a couple hundred microseconds or less
- 2. Maximum distances of a few kilometers

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- 3. Needs to support bandwidth of leading edge RAID boxes for at least the next 5-10 years
- 4. Needs to support interprocess communication paradigms
- 5. CPU utilization on the order of current storage systems
- 6. Data must be delivered completely and without corruption.
- 7. Able to use off-the-shelf Ethernet switches and IP routers
- 8. Needs easy management by system administrator
- 9. Needs to be cost competitive with other storage network technologies
- 10. The ability to jointly operate with other protocols is highly desirable.

1.1.3 Requirements discussion

As you can see, there are both similarities and differences between the two sets of requirements. Fortunately, Ethernet offers a range of compatible technologies that can cover the requirements of both small and large systems.

Requirement 1 of each list is easily met using today's Ethernet switches and switching routers. Typical values for latency are 3-20 microseconds for commercially available Gigabit Ethernet switches. Even with several switches and a couple hundred meters of cable, the round trip delay will be less than 100 microseconds in the absence of congestion.

Requirement 2 for small systems can be met with just CD/CSMA Ethernet, which can span 500 meters with fiber optics, or 200 meters diameter with copper. With full duplex, multi-mode optical fiber cables can handle several kilometers between switches, so cross country distances are theoretically possible. Thus switched (or router) based networks can handle the requirements of both small and large systems.

The bandwidth requirements imposed by future disk drives (#3) are difficult to predict, since they depend on advances in recording density and mechanical speed of the disk drives, as well as the access patterns of future applications. Figure 1 shows projected access times and sequential access rates for disk drives, assuming historical annual improvement rates continue. For applications which access data sequentially, or in very large random reads, the projections show that a single drive will be able to nearly saturate a gigabit interconnect. On the other hand, transaction processing applications will still be limited by disk access time to about 350 IOPS per drive, or one to five megabytes a second depending on request size. Even at five megabytes a second, over 20 drives could be supported by a single gigabit link. Thus, gigabit links should be adequate for small server installations, while large systems will need a mixture of 1 and 10 gigabit links.

For the types of traffic discussed in the requirement 4 of the small system section, 100 BaseT will often be adequate, and should be supported along with Gigabit. Large systems will have to support interprocess communication traffic, which consists of fairly short, time sensitive packets. Thus, Gigabit speeds are fine, but low latency and overhead protocols are required to support the IPC.

For large systems with external RAID boxes, the new 10 Gigabit Ethernet will be required. Interprocess communication doesn't require large bandwidths, but does require very low latencies (the lower the better) and efficient transport of short packets. This argues for a light weight transport protocol, but also argues for QOS and priority features such as found in IP version 6.

In order to equal the low CPU utilization of current host adapters (requirement #5 on both lists), the transport protocol will have to run onboard the *e*SCSI host adapter, ideally with special purpose hardware. To keep the hardware from becoming too complicated and expensive, a protocol with much less complexity than TCP/IP must be used. Such a protocol will be proposed later in this document.

Advocates of other storage interconnect proposals often cite the requirement for error free and complete data transfer (#6) as a reason not to use Ethernet. It is true that the basic Ethernet protocol is that of an unreliable Datagram, but addition of any of a number of transport layer protocols can produce a reliable data conduit quite suitable for storage applications. Actually, all other storage interconnects rely on similar mechanisms to mask the occasional data corruption that occurs with any physical interconnect medium, so the differences between Gigabit Ethernet (especially full-duplex Gigabit Ethernet) and other storage interconnects are not as large as they might at first appear.

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eSCSI

This document will describe a transport protocol which provides reliable, in-order delivery between systems. Using this protocol, SCSI commands and data can be transferred reliably between initiators and targets.

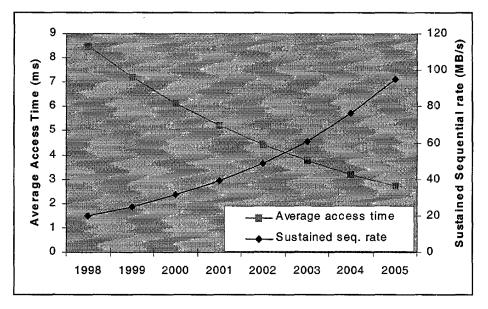


Figure 1: Projected advances in hard disk drives

In a contention and/or level 2 switched environment, requirement seven simply means that we use the basic Ethernet (original or 802.3 version) to encapsulate our eSCSI traffic. If routers are present than IP version 4 or 6 must also be used.

The requirement for small systems of automatic configuration (#8) can be readily satisfied by using switches over plain (no IP) Ethernet with the addition of an automatic discovery protocol (discussed later in this document). Larger systems will have system administrators who will want to manage certain aspects of the storage network, which can be done through use of IP and existing IP based tools. We may need proxy interfaces to eSCSI's native protocols, but this can be easily done.

For desktop systems, their low cost requirement (#9) can be easily satisfied with 100BaseT and 1000BaseT over cat5 UDP wiring. Larger systems will want to use fiber optics for longer distance Gigabit runs, and for ten Gigabit links. The use of of-the-shelf Ethernet switches and wiring will produce substantial cost savings due to the large volumes associated with the use of such equipment for networks.

Basic shared media Ethernet (either hub or cable) is completely oblivious to the data it is transporting, and propagates the data between stations (e.g. NICs) using addressing information contained in its own frame header. Thus, any number of protocols, including any we might invent, can be used to package the user's data. Routers, on the other hand, usually need to understand portions of those protocols in order to determine the appropriate path for the packets. Thus, routers only work with a few standard protocols, such as IPX and IP.

Between shared media and routers lie switches, which provide much of the bandwidth multiplication of routers but can use the addressing information contained in the Ethernet frame header to pass packets on to their correct destinations. Thus, Ethernet switches can work with private protocols just as well as plain Ethernet and hence meet requirement number ten.

When mixing several protocols on the same wire however, requirement ten is a little more complicated to achieve. The original Ethernet specification dedicated two bytes in the header to a type field, allowing 65,000 different protocols to co-exist on a single Ethernet. At this time there is still plenty of room for additional protocols. However, IEEE 802.3 changed that field to a length field, requiring other means to distinguish between protocols. Their solution is the addition of eight more bytes of information (3 bytes of 802.2 LLC plus 5 bytes of SNAP) to specify which protocol is encapsulated within a given frame. If we want to be fully compatible with 802.3, we will have to use these eight bytes as well.

In summary, as long as the scope of our eSCSI proposal is limited to desktop, computer room or campus networks, the requirements can be easily met with a combination of 100baseT, Gigabit and 10 Gigabit Ethernet and an appropriate transport protocol. We will now proceed to develop such a protocol.

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eSCSI

1.2 Topologies

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Implementations of *e*SCSI can be developed for both the desktop connectivity market and server storage market. The desktop products will use 100BaseT and some Gigabit to connect to peripherals and expansion drives through point-to-point links or switches. The Server products will use switches and routers interconnected with one and ten gigabit Ethernet to connect multiple hosts to disk and tape farms, and provide host to host communication.

1.2.1 Desktop Connectivity

The desktop topologies start with a point to point link connecting a eSCSI PIC to a eSCSI target, as depicted by the solid lines in Figure 2. Expansion to more peripherals can follow either of two paths. First of all, any eSCSI port can use Ethernet Hubs (or switches) to allow connection to additional targets. Thus, even a single port eSCSI PIC can connect to a nearly unlimited number of targets, provided that bandwidth limits are not exceeded. Secondly, Adaptec can produce a multiport eSCSI PIC allowing several (e.g. 4) targets to be connected without an external hub. The multiport eSCSI PIC could simply have a small hub built into the card, or it could actually have independent ports, providing additional bandwidth. If the independent port approach is used, then port aggregation can be used to provide higher bandwidth to high performance eSCSI targets. Finally, Figure 2 also illustrates how multiple hosts could share peripherals when a hub is employed.

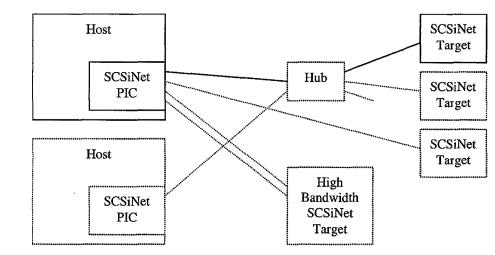


Figure 2: Possible desktop topologies for eSCSI

One problem with point-to-point links that do not involve a Hub or a switch is that an Ethernet Crossover cable is required. This is because traditional Ethernet NICS have their receive and transmit wires on the opposite ends of the connector from those of the Hubs. Since networks seldom consist of just two NICS there usually is a hub or switch in between, allowing straight through cables to work just fine.

But, a eSCSI PIC with multiple ports would normally be connected to just one target per port. Since target ports would have to be wired the same as PIC ports (to allow connection to hubs and switches), a crossover cable is required. The other option is to make eSCSI PIC ports configurable (hopefully automatically) as "hub" type ports or "NIC" type ports. How feasible this is has not yet been determined.

1.2.2 Combined with Network

While it would be simplest to have eSCSI separate from communications networks, there is a significant appeal to having a single, combined function Ethernet connector on the desktop computer. Even if several eSCSI connectors are provided, being able to use them for either external network or eSCSI, without regard to which connector is used for which purpose is a strong selling point.

For example, a single computer with PIC/NIC with two or more independent ports might dedicate one to an external network connection, and the other(s) to *e*SCSI devices. If several computers were involved, and they shared both a network connection and several desktop peripherals, then connecting them through a single small hub would be

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