IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Applicant:	§ Confirmation No:
	§
Noy Cohen	§
	ş

Serial No.:

Title:DUALAPERTUREZOOMCAMERAWITHVIDEOSUPPORTANDSWITCHING/NON-SWITCHINGDYNAMICCONTROL

Filed.	Concurrently	§ 8	
r neu.	concurrently	ş	Attorney Docket: Coreph-0159 US NP

Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

PRELIMINARY AMENDMENT

Sir/Madam

Before substantive examination, Applicant respectfully requests that claims 1-21 be amended to remove multiple dependencies existing in claims 10-12, 20 and 21 of international patent application PCT/IB2016/053803 of which this is a 371 national phase application.

IN THE CLAIMS:

Please amend the claims as follows:

1. (Original) A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

2. (Original) The camera of claim 1, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

3. (Original) The camera of claim 1, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

4. (Original) The camera of claim 1, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

5. (Original) The camera of claim 1, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

6. (Original) The camera of claim 1, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

7. (Original) The camera of claim 1, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

8. (Original) The camera of claim 1, wherein the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

9. (Original) The camera of claim 8, wherein the user inputs include a zoom factor, a camera mode and a region of interest.

10. (Currently amended) The camera of any of the claims 1–9, wherein the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1.

11. (Currently amended) The camera of any of the claims 1-9, wherein, if the noswitching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

12. (Currently amended) The camera of any of the claims 1-9, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

13. (Original) A method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV) and a Wide sensor, a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

14. (Original) The method of claim 13, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

15. (Original) The method of claim 13, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

16. (Original) The method of claim 13, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

17. (Original) The method of claim 13, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

18. (Original) The method of claim 13, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

19. (Original) The method of claim 13, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third threshold distance.

20. (Currently amended) The method of any of the claims 13–19, further comprising the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

21. (Currently amended) The method of any of the claims 13–19, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

REMARKS

This preliminary amendment amends claims 10-12 and 20, 21 of international application PCT/IB2016/053803 by removing multiple dependencies from those claims. No new matter is introduced.

It is respectfully submitted that claims 1-21 are in condition for allowance. Prompt notice of allowance is respectfully and earnestly solicited.

Respectfully submitted,

/ Menachem Nathan / Menachem Nathan Agent for Applicant Registration No. 65392

Date: January 8, 2017

DECLARATION FOR	UTILITY OR	Attorney Docket Number	COREPH-0159 US NP
DESIGN		First Named Invento	Nov Cohen
		Co	DMPLETE IF KNOWN
(or ofn L	53)	Application Number	
Declaration Submitted	Declaration Submitted After Initial	Filing Date	2017-01-08
With Initial OR	Filing (surcharge (37 CFR 1.16(f))	Art Unit	
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DUAL APERTURE ZOOM CAN NON-SWITCHING DYNAMIC C	IERA WITH VIE CONTROL	DEO SUPPORT AN	ID SWITCHING /
	(Títle of t	he Invention)	
As a below named inventor, I hereby decla	re that:		
This declaration is directed to:			
The attached application,			
OR			
United States Application Number o	r PCT International a	pplication number	
filed on			
The above-identified application was made	or authorized to be n	nade by me.	
I believe I am the original inventor or an orig	inal joint inventor of	a claimed invention in the	application.
I hereby acknowledge that any willful false a by fine or imprisonment of not more than fiv	statement made in thi e (5) years, or both.	s declaration is punishab	e under 18 U.S.C. 1001
Direct all The address			Correspondence
correspondence to: Associated w Customer Nu	ith 92 mber:	2342 0F	address below
Name			
Address			
City	State		Zip
Country	Telephone	Email	

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DECLARATION — Utility or Design Patent Application

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LEGAL NAME OF SOLE OR	FIRST INVENTOR:			
(E.g., Given Name (first and mid	Idle if any) and Family Name or Si	urname	2)	
Noy Cohen				
Inventor's Signature			Date (Optional)	
/Noy Cohen/				
Residence: City	State	Coun	try	
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Mailing Address				
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City	State	Zip		Country
Tel-Aviv		6912	529	1
Add	itional inventors are being named on the	2	Supplemental sheet(s) PTO/AI/	V10 attached hereto

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- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspection or an issued patent.
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Name of Additional Joint Inventor, if an	y:	A petition has been filed	for this unsigned inventor
Given Name (first and middle (if any))	Family Name or Surname	
Oded		Gigushinski	
Inventor's /Oded Gigushinski/ Signature			Date
	1		1

Herzlia			II.				
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23 Ahi Dakar St.							
Mailing Address							
Herzlia				4670223	IL.		
City	State			Zip	Cour	ntry	
Name of Additional Joint Invent	or, if any:		A petiti	on has been filed fo	r this unsigned	l inventor	
Given Name (first and mic	dle (if any))			Family Nan	ne or Surname	,	
Nadav		Ge	eva				
Inventoria /Naday Geva/							
Signature					Date		
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Tel-Aviv				6264203			
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Name of Additional Joint Invent	or, if any:		A petiti	on has been filed fo	r this unsigned	t inventor	
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Inventoria (Gal Shahtay/							
Signature					Date		
- Tel-Aviv							
Residence: City	State	State				Citizenship	
4 Shmuel Shnitzer St.	•			•		•	
Mailing Address							
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Prior Foreign Application Number(s)	Country	Foreign Filing Date (MM/DD/YYYY)	Priority Not Claimed	Certified Cop YES	y Attached? NO

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DECLARATION		ADDITIONA Supplemental	AL INVENTOR(S) Sheet	Page 2 of 2		
Name of Additional Joint Inventor, if any	y:	A petition has been filed for this unsigned inventor				
Given Name (first and middle (if any))		Family Name of	or Surname			
Ester		Ashkenazi				
Inventor's /Ester Ashkenazi / Signature				Date		
Modi'in Residence: City	State	IL Ci	ountry	IL Citizenship		
52/2 Emeq Dotan St.						
Mailing Address						
Modi'in			7170202	IL		
City	State		Zip	Country		
Name of Additional Joint Inventor, if any	y:	A petitio	n has been filed for this u	nsigned inventor		
Given Name (first and middle (if any)))		Family Name or S	urname		
Ruthy		Katz				
Inventor's ^{/Ruthy} Katz/ Signature				Date		
Tel Aviv				IL		
Residence: City	State		Country	Citizenship		
6/20 Hachmey Kiruan St.			• •	•		
Mailing Address						
Tel Aviv			6423706	IL		
City	State		Zip	Country		
Name of Additional Joint Inventor, if any	y:	A petitio	n has been filed for this u	nsigned inventor		
Given Name (first and middle (if anv))		Family Name or Surname				
Ephraim		Goldenberg				
Inventor's /Ephraim Goldenberg/ Signature				Date		
Ashdod				IL		
Residence: City	State		Country	Citizenship		
32 Tel Chai Str.						
Mailing Address	1					
Ashdod			7751025			
City	State		Zip	Country		
(and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.11 and 1.14. This collection is estimated to take 21 minutes to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual						

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Electronic Patent Application Fee Transmittal					
Application Number:					
Filing Date:					
Title of Invention:	DU/ NOI	AL APERTURE ZOO N-SWITCHING DYN	M CAMERA WITI IAMIC CONTROL	H VIDEO SUPPORT	AND SWITCHING /
First Named Inventor/Applicant Name:	Noy Cohen				
Filer:	Menachem Nathan				
Attorney Docket Number:	COREPH-0159 US NP				
Filed as Small Entity					
Filing Fees for U.S. National Stage under 35 USC 371					
Description		Fee Code	Quantity	Amount	Sub-Total in USD(\$)
Basic Filing:					
BASIC NATIONAL STAGE FEE		2631	1	140	140
Natl Stage Search Fee - U.S. was the ISA		2641	1	60	60
NATL STAGE EXAM FEE - ALL OTHER CASES		2633	1	360	360
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CLAIMS IN EXCESS OF 20		2615	1	40	40
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Petition:				APPL	-1002 / Page 16 of 435

Description	Fee Code	Quantity	Amount	Sub-Total in USD(\$)
Patent-Appeals-and-Interference:				
Post-Allowance-and-Post-Issuance:				
Extension-of-Time:				
Miscellaneous:				
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Confirmation Number:	5811			
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First Named Inventor/Applicant Name:	Noy Cohen			
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<u>New International Application Filed with the USPTO as a Receiving Office</u> If a new international application is being filed and the international application includes the necessary components for an international filing date (see PCT Article 11 and MPEP 1810), a Notification of the International Application Number and of the International Filing Date (Form PCT/RO/105) will be issued in due course, subject to prescriptions concerning national security, and the date shown on this Acknowledgement Receipt will establish the international filing date of the application.								

DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

CROSS REFERENCE TO RELATED APPLICATIONS

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This application is a 371 application from international patent application PCT/IB2016/053803 filed June 26, 2016, and is related to and claims priority from US Provisional Patent Application No. 62/204,667 filed August 13, 2015 which is expressly incorporated herein by reference in its entirety.

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FIELD

Embodiments disclosed herein relate in general to digital cameras and in particular to zoom digital cameras with video capabilities.

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BACKGROUND

Digital camera modules are currently being incorporated into a variety of host devices. Such host devices include cellular telephones, personal data assistants (PDAs), computers, and so forth. Consumer demand for digital camera modules in host devices continues to grow.

Host device manufacturers prefer digital camera modules to be small, so that they can be incorporated into the host device without increasing its overall size. Further, there is an increasing demand for such cameras to have higher-performance characteristics. One such characteristic possessed by many higher-performance cameras (e.g., standalone digital still cameras) is the ability to vary the focal length of the camera to increase and decrease the magnification of the image. This ability, typically accomplished with a zoom lens, is known as optical zooming. "Zoom" is commonly understood as a capability to provide different magnifications of the same scene and/or object by changing the focal length of an optical system, with a higher level of zoom associated with greater magnification and a lower level of zoom associated with lower magnification. Optical zooming is typically accomplished by mechanically moving lens elements relative to each other. Such zoom lenses are typically more expensive, larger and less reliable than fixed focal length lenses. An alternative approach for approximating the zoom effect is achieved with what is known as digital zooming. With digital zooming, instead of varying the focal length of the lens, a processor in the camera crops the image and interpolates between the pixels of the captured image to create a magnified but lower-resolution image.

Attempts to use multi-aperture imaging systems to approximate the effect of a zoom 5 lens are known. A multi-aperture imaging system (implemented for example in a digital camera) includes a plurality of optical sub-systems (also referred to as "cameras"). Each camera includes one or more lenses and/or other optical elements which define an aperture such that received electro-magnetic radiation is imaged by the optical sub-system and a resulting image is directed towards a two-dimensional (2D) pixelated image sensor region. 10 The image sensor (or simply "sensor") region is configured to receive the image and to generate a set of image data based on the image. The digital camera may be aligned to receive electromagnetic radiation associated with scenery having a given set of one or more objects. The set of image data may be represented as digital image data, as well known in the art. Hereinafter in this description, "image" "image data" and "digital image data" may be used 15 interchangeably. Also, "object" and "scene" may be used interchangeably. As used herein, the term "object" is an entity in the real world imaged to a point or pixel in the image.

Multi-aperture imaging systems and associated methods are described for example in US Patent Publications No. 2008/0030592, 2010/0277619 and 2011/0064327. In US 2008/0030592, two sensors are operated simultaneously to capture an image imaged through

- 20 an associated lens. A sensor and its associated lens form a lens/sensor combination. The two lenses have different focal lengths. Thus, even though each lens/sensor combination is aligned to look in the same direction, each combination captures an image of the same subject but with two different fields of view (FOV). One sensor is commonly called "Wide" and the other "Tele". Each sensor provides a separate image, referred to respectively as "Wide" (or
- 25 "W") and "Tele" (or "T") images. A W-image reflects a wider FOV and has lower resolution than the T-image. The images are then stitched (fused) together to form a composite ("fused") image. In the composite image, the central portion is formed by the relatively higherresolution image taken by the lens/sensor combination with the longer focal length, and the peripheral portion is formed by a peripheral portion of the relatively lower-resolution image
- 30 taken by the lens/sensor combination with the shorter focal length. The user selects a desired amount of zoom and the composite image is used to interpolate values from the chosen amount of zoom to provide a respective zoom image. The solution offered by US 2008/0030592 requires, in video mode, very large processing resources in addition to high frame rate requirements and high power consumption (since both cameras are fully

operational).

US 2010/0277619 teaches a camera with two lens/sensor combinations, the two lenses having different focal lengths, so that the image from one of the combinations has a FOV approximately 2-3 times greater than the image from the other combination. As a user of the camera requests a given amount of zoom, the zoomed image is provided from the lens/sensor combination having a FOV that is next larger than the requested FOV. Thus, if the requested FOV is less than the smaller FOV combination, the zoomed image is created from the image captured by that combination, using cropping and interpolation if necessary. Similarly, if the requested FOV is greater than the smaller FOV combination, using cropping and interpolation if necessary. The solution offered by US 2010/0277619 leads to parallax artifacts when moving to the Tele camera in video mode.

In both US 2008/0030592 and US 2010/0277619, different focal length systems cause matching Tele and Wide FOVs to be exposed at different times using CMOS sensors. This degrades the overall image quality. Different optical F numbers ("F#") cause image intensity differences. Working with such a dual sensor system requires double bandwidth support, i.e. additional wires from the sensors to the following HW component. Neither US 2008/0030592 nor US 2010/0277619 deal with registration errors.

US 2011/0064327 discloses multi-aperture imaging systems and methods for image data fusion that include providing first and second sets of image data corresponding to an imaged first and second scene respectively. The scenes overlap at least partially in an overlap region, defining a first collection of overlap image data as part of the first set of image data, and a second collection of overlap image data is represented as a plurality of image data cameras such that each of the cameras is based on at least one characteristic of the second collection, and each camera spans the overlap region. A fused set of image data is produced by an image processor, by modifying the first collection of overlap image data cameras. The systems and methods disclosed in this application deal solely with fused still images.

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None of the known art references provide a thin (e.g. fitting in a cell-phone) dualaperture zoom digital camera with fixed focal length lenses, the camera configured to operate in both still mode and video mode to provide still and video images, wherein the camera configuration does not use any fusion to provide a continuous, smooth zoom in video mode.

Therefore there is a need for, and it would be advantageous to have thin digital

cameras with optical zoom operating in both video and still mode that do not suffer from commonly encountered problems and disadvantages, some of which are listed above.

SUMMARY

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Embodiments disclosed herein teach the use of dual-aperture (also referred to as duallens or two-sensor) optical zoom digital cameras. The cameras include two cameras, a Wide camera and a Tele camera, each camera including a fixed focal length lens, an image sensor and an image signal processor (ISP). The Tele camera is the higher zoom camera and the Wide camera is the lower zoom camera. In some embodiments, the thickness/effective focal length (EFL) ratio of the Tele lens is smaller than about 1. The image sensor may include two separate 2D pixelated sensors or a single pixelated sensor divided into at least two areas. The digital camera can be operated in both still and video modes. In video mode, optical zoom is achieved "without fusion", by, in some embodiments, switching between the W and T images to shorten computational time requirements, thus enabling high video rate. To avoid discontinuities in video mode, the switching includes applying additional processing blocks, which include in some embodiments image scaling and shifting. In some embodiments, when

switching.

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As used herein, the term "video" refers to any camera output that captures motion by a series of pictures (images), as opposed to "still mode" that friezes motion. Examples of "video" in cellphones and smartphones include "video mode" or "preview mode".

a no-switching criterion is fulfilled, optical zoom is achieved in video mode without

In order to reach optical zoom capabilities, a different magnification image of the same scene is captured (grabbed) by each camera, resulting in FOV overlap between the two cameras. Processing is applied on the two images to fuse and output one fused image in still mode. The fused image is processed according to a user zoom factor request. As part of the fusion procedure, up-sampling may be applied on one or both of the grabbed images to scale it to the image grabbed by the Tele camera or to a scale defined by the user. The fusion or up-sampling may be applied to only some of the pixels of a sensor. Down-sampling can be performed as well if the output resolution is smaller than the sensor resolution.

The cameras and associated methods disclosed herein address and correct many of the problems and disadvantages of known dual-aperture optical zoom digital cameras. They provide an overall zoom solution that refers to all aspects: optics, algorithmic processing and system hardware (HW).

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In a dual-aperture camera image plane, as seen by each camera (and respective image sensor), a given object will be shifted and have different perspective (shape). This is referred to as point-of-view (POV). The system output image can have the shape and position of either camera image or the shape or position of a combination thereof. If the output image retains

the Wide image shape then it has the Wide perspective POV. If it retains the Wide camera 5 position then it has the Wide position POV. The same applies for Tele images position and perspective. As used in this description, the perspective POV may be of the Wide or Tele cameras, while the position POV may shift continuously between the Wide and Tele cameras. In fused images, it is possible to register Tele image pixels to a matching pixel set within the 10 Wide image pixels, in which case the output image will retain the Wide POV ("Wide fusion"). Alternatively, it is possible to register Wide image pixels to a matching pixel set within the Tele image pixels, in which case the output image will retain the Tele POV ("Tele

fusion"). It is also possible to perform the registration after either camera image is shifted, in

which case the output image will retain the respective Wide or Tele perspective POV.

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In an exemplary embodiment, there is provided a zoom digital camera comprising a Wide imaging section that includes a fixed focal length Wide lens with a Wide FOV and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene, a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to 20 provide Tele image data of the object or scene, and a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a noswitching criterion determined by inputs from both Wide and Tele image data, and, if the noswitching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF 25 value.

In an exemplary embodiment there is provided a method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of providing in the digital camera a Wide imaging section having a Wide lens with a Wide FOV and a Wide sensor, a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections, and configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF value and a higher ZF value.

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In some exemplary embodiments, the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

In some exemplary embodiments, the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

In some exemplary embodiments, the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

In some exemplary embodiments, the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

In some exemplary embodiments, the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

In some exemplary embodiments, the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

In some exemplary embodiments, the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

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In some exemplary embodiments, the user inputs include a zoom factor, a camera mode and a region of interest.

In some exemplary embodiments, the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1. For a definition of TTL and EFL see e.g. co-assigned US published patent application No. 20150244942.

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In some exemplary embodiments, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

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In some exemplary embodiments, the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

BRIEF DESCRIPTION OF THE DRAWINGS

Non-limiting examples of embodiments disclosed herein are described below with reference to figures attached hereto that are listed following this paragraph. Identical
structures, elements or parts that appear in more than one figure are generally labeled with a same numeral in all the figures in which they appear. The drawings and descriptions are meant to illuminate and clarify embodiments disclosed herein, and should not be considered limiting in any way.

FIG. 1A shows schematically a block diagram illustrating an exemplary dual-aperturezoom imaging system disclosed herein;

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A:

FIG. 2 shows an example of a Wide sensor, a Tele sensor and their respective FOVs;

FIG. 3A shows an embodiment of an exemplary method disclosed herein for acquiring

15 a zoom image in video/preview mode;

FIG. 3B shows exemplary feature points in an object;

FIG. 3C shows schematically a known rectification process;

FIG. 4 shows a graph illustrating an effective resolution zoom factor.

20 DETAILED DESCRIPTION

Definitions:

Sharpness score: the gradients (dx, dy) of the image are compared (through subtraction) to the gradients of its low pass filtered version. A higher difference indicates a sharper original image. The result of this comparison is normalized with respect to the average variations (for example, sum of absolute gradients) of the original image, to obtain an absolute sharpness score.

Edge score: for each image, the edges are found (for example, using Canny edge detection) and the average intensity of gradients along them is calculated, for example, by calculating the magnitude of gradients (dx, dy) for each edge pixel, summing the results and dividing by the total number of edge pixels. The result is the edge score.

Effective resolution score: this score is calculated only in a region of interest (ROI) and provides a good indication of the effective resolution level in the image. As used herein, "ROI" is a user-defined sub-region of the image that may be exemplarily 4% or less of the

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image area. The effective resolution score can be derived from a combination of the sharpness scores and edge scores for each image, for example by normalizing both to be between [0, 1] and by taking their average.

FIG. 1A shows schematically a block diagram illustrating an exemplary embodiment of a dual-aperture zoom imaging system (also referred to simply as "dual-camera" or "dual-5 aperture camera") disclosed herein and numbered 100. Dual-aperture camera 100 comprises a Wide imaging section ("Wide camera") that includes a Wide lens block 102, a Wide image sensor 104 and a Wide image processor 106. Dual-aperture camera 100 further comprises a Tele imaging section ("Tele camera") that includes a Tele lens block 108, a Tele image sensor 10 **110** and a Tele image processor **112**. The image sensors may be physically separate or may be part of a single larger image sensor. The Wide sensor pixel size can be equal to or different from the Tele sensor pixel size. Dual-aperture camera 100 further comprises a camera fusion processing core (also referred to as "controller") 114 that includes a sensor control module 116, a user control module 118, a video processing module 126 and a capture processing 15 module 128, all operationally coupled to sensor control block 110. User control module 118 comprises an operational mode function 120, a ROI function 122 and a zoom factor (ZF)

function 124.

Sensor control module 116 is connected to the two (Wide and Tele) cameras and to the user control module **118** and used to choose, according to the zoom factor, which of the 20 sensors is operational and to control the exposure mechanism and the sensor readout. Mode choice function 120 is used for choosing capture/video modes. ROI function 122 is used to choose a region of interest. The ROI is the region on which both cameras are focused on. Zoom factor function 124 is used to choose a zoom factor. Video processing module 126 is connected to mode choice function 120 and used for video processing. It is configurable to 25 evaluate a no-switching criterion determined by inputs from both Wide and Tele image data and to make a decision regarding video output. Specifically, upon evaluation of a noswitching criterion, if the no-switching criterion is fulfilled, module 126 is configurable to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value. If the no-switching criterion is not fulfilled, module 126 is configurable to combine in still mode, at a predefined range of 30 ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view. Still processing module 128 is connected

to the mode choice function **120** and used for high image quality still mode images. The video processing module is applied when the user desires to shoot in video mode. The capture

processing module is applied when the user wishes to shoot still pictures.

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A. Exemplary dimensions: Wide lens TTL = 4.2mm and EFL = 3.5mm; Tele lens TTL = 6mm and EFL = 7 mm; both Wide and Tele sensors 1/3 inch; external dimensions of Wide and Tele cameras: width (w) and length (1) = 8.5 mm and height (h) = 6.8 mm; distance

"d" between camera centers = 10mm.

Following is a detailed description and examples of different methods of use of dualaperture camera 100.

10 Still mode operation/function

In still camera mode, the obtained image is fused from information obtained by both cameras at all zoom levels, see FIG. 2, which shows a Wide sensor 202 and a Tele sensor 204 and their respective FOVs. Exemplarily, as shown, the Tele sensor FOV is half the Wide 15 sensor FOV. The still camera mode processing includes two stages: the first stage includes setting HW settings and configuration, where a first objective is to control the sensors in such a way that matching FOVs in both images (Tele and Wide) are scanned at the same time, a second objective is to control the relative exposures according to the lens properties, and a third objective is to minimize the required bandwidth from both sensors for the ISPs. The second stage includes image processing that fuses the Wide and the Tele images to achieve optical zoom, improves SNR and provides wide dynamic range.

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FIG. 3A shows image line numbers vs. time for an image section captured by CMOS sensors. A fused image is obtained by line (row) scans of each image. To prevent matching FOVs in both sensors to be scanned at different times, a particular configuration is applied by the camera controller on both image sensors while keeping the same frame rate. The difference in FOV between the sensors determines the relationship between the rolling shutter time and the vertical blanking time for each sensor.

Video mode operation/function

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Smooth transition

When a dual-aperture camera switches the camera output between cameras or points of view, a user will normally see a "jump" (discontinuous) image change. However, a change in the zoom factor for the same camera and POV is viewed as a continuous change. A

"smooth transition" (ST) is a transition between cameras or POVs that minimizes the jump effect. This may include matching the position, scale, brightness and color of the output image before and after the transition. However, an entire image position matching between the camera outputs is in many cases impossible, because parallax causes the position shift to be dependent on the object distance. Therefore, in a smooth transition as disclosed herein, the

5 be dependent on the object distance. Therefore, in a smooth transition as disclosed herein, the position matching is achieved only in the ROI region while scale brightness and color are matched for the entire output image area.

Zoom-in and Zoom-out in video mode

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- In video mode, sensor oversampling is used to enable continuous and smooth zoom experience. Processing is applied to eliminate the changes in the image during crossover from one camera to the other. Zoom from 1 to Z_{switch} is performed using the Wide sensor only. From Z_{switch} and on, it is performed mainly by the Tele sensor. To prevent "jumps" (roughness in the image), switching to the Tele image is done using a zoom factor which is a bit higher
 (Z_{switch} +ΔZoom) than Z_{switch}. ΔZoom is determined according to the system's properties and is different for cases where zoom-in is applied and cases where zoom-out is applied (ΔZoom_{in}≠ ΔZoom_{out}). This is done to prevent residual jumps artifacts to be visible at a certain zoom factor. The switching between sensors, for an increasing zoom and for decreasing zoom, is done on a different zoom factor.
- 20 The zoom video mode operation includes two stages: (1) sensor control and configuration and (2) image processing. In the range from 1 to Z_{switch}, only the Wide sensor is operational, hence, power can be supplied only to this sensor. Similar conditions hold for a Wide AF mechanism. From Z_{switch}+ΔZoom to Z_{max} only the Tele sensor is operational, hence, power is supplied only to this sensor. Similarly, only the Tele sensor is operational and power is supplied only to it for a Tele AF mechanism. Another option is that the Tele sensor is operational and the Wide sensor is working in low frame rate. From Z_{switch}+ΔZoom, both sensors are operational.

<u>Zoom-in</u>: at low ZF up to slightly above ZF_T (the zoom factor that enables switching between Wide and Tele outputs) the output image is the digitally zoomed, unchanged Wide camera output. ZF_T is defined as follows:

$$ZF_T = Tan (FOV_{Wide})/Tan (FOV_{Tele})$$

where Tan refers to "tangent", while FOV_{Wide} and FOV_{Tele} refer respectively to the Wide and

Tele lens fields of view (in degrees). As used herein, the FOV is measured from the center axis to the corner of the sensor (i.e. half the angle of the normal definition). Switching cannot take place below ZF_T and it can above it.

- In some embodiments for the up-transfer ZF, as disclosed in co-invented and coowned US patent 9,185,291, the output is a transformed Tele camera output, where the transformation is performed by a global registration (GR) algorithm to achieve smooth transition. As used herein "global registration" refers to an action for which the inputs are the Wide and Tele images. The Wide image is cropped to display the same FOV as the Tele image. The Tele image is passed through a low pass filter (LPF) and resized to make its appearance as close as possible to the Wide image (lower resolution and same pixel count). The outputs of GR are corresponding feature point pairs in the images along with their disparities, and parameters for differences between the images, i.e. shift and scale. As used herein, "feature point" refers to a point such as points **10a-d** in FIG. 3B and refers to a point
- point should be reproducible and invariant to changes in image scale, noise and illumination. Such points usually lie on corners or other high-contrast regions of the object.

(pixel) of interest on an object in an image. For purposes set forth in this description, a feature

Stages of Global Registration

In some exemplary embodiments, global registration may be performed as follows:

- 20 1. Find interest points (features) in each image separately by filtering it with, exemplarily, a Difference of Gaussians filter, and finding local extrema on the resulting image.
- Find feature correspondences (features in both images that describe the same point in space) in a "matching" process. These are also referred to as "feature pairs", "correspondence
 pairs" or "matching pairs". This is done by comparing each feature point from one (Tele or Wide) image (referred to hereinafter as "image 1") to all feature points in that region from the other (respectively Wide or Tele) image (referred to hereinafter as "image 2"). The features are compared only within their group of minima/maxima, using patch normalized cross-correlation. As used herein, "patch" refers to a group of neighboring pixels around an origin pixel.

3. The normalized cross correlation of two image patches t(x, y) and f(x, y) is $\frac{1}{n} \sum_{x,y} \frac{(f(x,y)-\bar{f})(t(x,y)-\bar{t})}{\sigma_f \sigma_t}$ where n is the number of pixels in both patches, \bar{f} is the average of fand σ_f is the standard deviation of f. A match for a feature point from image 1 is only confirmed if its correlation score is much higher (for example, x1.2) than the next-best matching feature from image 2.

4. Find the disparity between each pair of corresponding features (also referred to as "matching pair") by subtracting their x and y coordinate values.

⁵ 5. Filter bad matching points:

a. Following the matching process, matches that include feature points from image 2 that were matched to more than one feature from image 1 are discarded.

b. Matching pairs whose disparity is inconsistent with the other matching pairs are discarded. For example, if there is one corresponding pair which whose disparity is lower or
 ¹⁰ higher than the others by 20 pixels.

6. The localization accuracy for matched points from image 2 is refined by calculating a correlation of neighboring pixel patches from image 2 with the target patch (the patch around the current pixel (of the current matching pair) from image 1, modeling the results as a parabola and finding its maximum.

15 7. Rotation and fine scale differences are calculated between the two images according to the matching points (for example, by subtracting the center of mass from each set of points, i.e. the part of the matching points belonging to either the Wide or the Tele image, and solving a least squares problem).

8. After compensating for these differences, since the images were rectified, the disparity
²⁰ in the Y axis should be close to 0. Matching points that do not fit this criterion are discarded. A known rectification process is illustrated in FIG. 3C.

9. Finally, the remaining matching points are considered true and the disparities for them are calculated. A weighted average of the disparity is taken as the shift between both images. The maximum difference between disparity values is taken as the disparity range.

25 10. At various stages during GR, if there are not enough feature/matching points remaining, the GR is stopped and returns a failure flag.

In addition, it is possible to find range calibration to the rectification process by finding the shiftI = shift for objects at infinity and defining shiftD=shiftI and disparity D = disparity-shiftI. We then calculate *object distance* = $\frac{focalLength \cdot baseline}{disparityD \cdot pixelSize}$, where "baseline" is the distance between cameras.

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Returning now to the Zoom-in process, in some embodiments, for higher ZF than the up-transfer ZF the output is the transformed Tele camera output, digitally zoomed. However, in other embodiments for the up-transfer ZF there will be no switching from the Wide to the

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Tele camera output, i.e. the output will be from the Wide camera, digitally zoomed. This "no switching" process is described next.

No Switching

Switching from the Wide camera output to the transformed Tele camera output will be performed unless some special condition (criterion), determined based on inputs obtained from the two camera images, occurs. In other words, switching will not be performed only if at least one of the following no-switching criteria is fulfilled:

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if the shift calculated by GR is greater than a first threshold, for example 50 pixels.

2. if the disparity range calculated by GR is greater than a second threshold, for example 20 pixels, because in this case there is no global shift correction that will suppress movement/jump for all objects distances (smooth transition is impossible for all objects).

3. if the effective resolution score of the Tele image is lower than that of the Wide image. In this case, there is no point in performing the transition because no value (i.e. resolution) is gained. Smooth transition is possible but undesirable.

4. if the GR fails, i.e. if the number of matching pairs found is less than a third threshold, for example 20 matching pairs.

5. if, for example, that are imaged onto the overlap area are calculated to be closer than a first threshold distance, for example 30 cm, because this can result in a large image shift to obtain ST.

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6. if some objects (for example two objects) that are imaged in the overlap area are calculated to be closer than a second threshold distance, for example 50 cm, while other objects (for example two objects) are calculated to be farther than a third threshold distance for example 10 m. The reason is that the shift between an object position in the Wide and Tele cameras is object distance dependent, where the closer the objects the larger the shift, so an image containing significantly close and far objects cannot be matched by simple transformation (shift scale) to be similar and thus provide ST between cameras.

Zoom-out: at high ZF down to slightly below ZFT, the output image is the digitally zoomed transformed Tele camera output. For the down-transfer ZF, the output is a shifted Wide camera output, where the Wide shift correction is performed by the GR algorithm to 30 achieve smooth transition, i.e. with no jump in the ROI region. For lower (than the downtransfer) ZF, the output is basically the down-transfer ZF output digitally zoomed but with gradually smaller Wide shift correction, until for ZF=1 the output is the unchanged Wide camera output.

Note that if a no-switching criterion is not fulfilled, then the camera will output without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, the video output images being provided with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor, and wherein at the higher ZF value the output resolution is determined by the Tele sensor.

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FIG. 3A shows an embodiment of a method disclosed herein for acquiring a zoom image in video/preview mode for 3 different zoom factor (ZF) ranges: (a) ZF range = 1 : Z_{switch} ; (b) ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$: and (c) Zoom factor range = Z_{switch} + 10 $\Delta Zoom_{in}$: Z_{max} . The description is with reference to a graph of effective resolution vs. zoom factor (FIG. 4). In step 302, sensor control module 116 chooses (directs) the sensor (Wide, Tele or both) to be operational. Specifically, if the ZF range = $1:Z_{switch}$, module **116** directs the Wide sensor to be operational and the Tele sensor to be non-operational. If the ZF range is Z_{switch} : $Z_{\text{switch}} + \Delta Z_{\text{oom}_{\text{in}}}$, module **116** directs both sensors to be operational and the zoom 15 image is generated from the Wide sensor. If the ZF range is $Z_{switch} + \Delta Z_{oom_{in}} : Z_{max}$, module **116** directs the Wide sensor to be non-operational and the Tele sensor to be operational. After the sensor choice in step **302**, all following actions are performed in video processing core 126. Optionally, in step 304, color balance is calculated if two images are provided by the two sensors. Optionally yet, in step **306**, the calculated color balance is applied in one of the 20 images (depending on the zoom factor). Further optionally, in step 308, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient can be used to set an AF position in step **310**. In step **312**, an output of any of steps **302-308** is applied on one of the images (depending on the zoom factor) for image signal processing that may include denoising, demosaicing, sharpening, scaling, etc. In 25 step **314**, the processed image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function 124) and the output video resolution (for example 1080p). To avoid a transition point to be executed at the same ZF, Δ Zoom can change while zooming in and while zooming out. This will result in hysteresis in the sensor switching point.

In more detail, for ZF range 1: Z_{switch} , for ZF < Z_{switch} , the Wide image data is 30 transferred to the ISP in step **312** and resampled in step **314**. For ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$, both sensors are operational and the zoom image is generated from the Wide sensor. The color balance is calculated for both images according to a given ROI. In addition, for a given ROI, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient is used to set an AF position. The

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transformation coefficient includes the translation between matching points in the two images. This translation can be measured in a number of pixels. Different translations will result in a different number of pixel movements between matching points in the images. This movement can be translated into depth and the depth can be translated into an AF position. This enables to set the AF position by only analyzing two images (Wide and Tele). The result is fast

5 to set the focusing.

Both color balance ratios and transformation coefficient are used in the ISP step. In parallel, the Wide image is processed to provide a processed image, followed by resampling. For ZF range = $Z_{switch} + \Delta Zoom_{in}$: Z_{max} and for Zoom factor > $Z_{switch} + \Delta Zoom_{in}$, the color balance calculated previously is now applied on the Tele image. The Tele image data is transferred to the ISP in step **312** and resampled in step **314**. To eliminate crossover artifacts and to enable smooth transition to the Tele image, the processed Tele image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function **124**) and the output video resolution (for example 1080p).

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FIG. 4 shows the effective resolution as a function of the zoom factor for a zoom-in case and for a zoom-out case $\Delta Zoom_{up}$ is set when one zooms in, and $\Delta Zoom_{down}$ is set when one zooms out. Setting $\Delta Zoom_{up}$ to be different from $\Delta Zoom_{down}$ will result in transition between the sensors to be performed at different zoom factor ("hysteresis") when zoom-in is used and when zoom-out is used. This hysteresis phenomenon in the video mode results in smooth continuous zoom experience.

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In conclusion, dual aperture optical zoom digital cameras and associate methods disclosed herein reduce the amount of processing resources, lower frame rate requirements, reduce power consumption, remove parallax artifacts and provide continuous focus (or provide loss of focus) when changing from Wide to Tele in video mode. They provide a dramatic reduction of the disparity range and avoid false registration in capture mode. They reduce image intensity differences and enable work with a single sensor bandwidth instead of two, as in known cameras.

All patent applications mentioned in this specification are herein incorporated in their entirety by reference into the specification, to the same extent as if each individual patent application was specifically and individually indicated to be incorporated herein by reference. In addition, citation or identification of any reference in this application shall not be construed as an admission that such reference is available as prior art to the present disclosure.

While this disclosure has been described in terms of certain embodiments and generally associated methods, alterations and permutations of the embodiments and methods

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will be apparent to those skilled in the art. The disclosure is to be understood as not limited by the specific embodiments described herein, but only by the scope of the appended claims.
WHAT IS CLAIMED IS:

1. A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

2. The camera of claim 1, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

3. The camera of claim 1, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

4. The camera of claim 1, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

5. The camera of claim 1, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

6. The camera of claim 1, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

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7. The camera of claim 1, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

8. The camera of claim 1, wherein the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

9. The camera of claim 8, wherein the user inputs include a zoom factor, a camera mode and a region of interest.

10. The camera of any of the claims 1-9, wherein the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1.

11. The camera of any of the claims 1-9, wherein, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

12. The camera of any of the claims 1-9, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

13. A method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV) and a Wide sensor, a Tele imaging section having a Tele lens with

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a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

14. The method of claim 13, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

15. The method of claim 13, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

16. The method of claim 13, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

17. The method of claim 13, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

18. The method of claim 13, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

19. The method of claim 13, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third threshold distance.

20. The method of any of the claims 13-19, further comprising the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some

of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

21. The method of any of the claims 13-19, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

ABSTRACT

A dual-aperture zoom digital camera operable in both still and video modes. The camera includes Wide and Tele imaging sections with respective lens/sensor combinations and image signal processors and a camera controller operatively coupled to the Wide and Tele imaging sections. The Wide and Tele imaging sections provide respective image data. The controller is configured to output, in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value, a zoom video output image that includes only Wide image data or only Tele image data, depending on whether a no-switching criterion is fulfilled or not.

<u>100</u>



FIG. 1A



FIG. 1B



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FIG. 2



FIG. 3A







FIG. 3C



FIG. 4

Application Data Sheet 37 CFR 1.76		Attorney Docket Number	COREPH-0159 US NP		
		Application Number			
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL				
The application data sheet is part of the provisional or nonprovisional application for which it is being submitted. The following form contains the bibliographic data arranged in a format specified by the United States Patent and Trademark Office as outlined in 37 CFR 1.76.					

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Application Data Sheet 37 CFR 1.76		Attorney Docket	Number COREPH-0	159 US NP	
		Application Num	ber		
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Application Da	to Shoot		Attorney	Docket Number	COREPH	1-0159 US NP		
Application Data Sheet S7 CI K 1.70		Applicatio	on Number					
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Application Data Sheet 37 CFR 1.76		Attorney Docket Number	COREPH-0159 US NP	
		Application Number		
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL			

Application Information:

Title of the Invention	DUAL APERTURE ZOOM CAMERA W DYNAMIC CONTROL	/ITH VIDEO SUPPORT AND SWITCHING 7 NON-SWITCHING
Attorney Docket Number	COREPH-0159 US NP	Small Entity Status Claimed 🛛 🔀
Application Type	Nonprovisional	•
Subject Matter	Utility	-
Total Number of Drawing	Sheets (if any) 5	Suggested Figure for Publication (if any) 3A
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For the purposes of a filing date under 37 CFR 1.53(b), the description and any drawings of the present application are replaced by this reference to the previously filed application, subject to conditions and requirements of 37 CFR 1.57(a).

Application number of the previously filed application	Filing date (YYYY-MM-DD)	Intellectual Property Authority or Country

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Application Data Sheet 37 CFR 1.76		Attorney Docket Number	COREPH-0159 US NP	
		Application Number		
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL			

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Prior Application Status	Pending	•		Remove
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Statement under 37 CFR 1.55 or 1.78 for AIA (First Inventor to File) Transition Applications

	This application (1) claims priority to or the benefit of an application filed before March 16, 2013 and (2) also
	contains, or contained at any time, a claim to a claimed invention that has an effective filing date on or after March
\square	16, 2013.
	NOTE: By providing this statement under 37 CFR 1.55 or 1.78, this application, with a filing date on or after March
	16, 2013, will be examined under the first inventor to file provisions of the AIA.

Application Da	ta Shoot 37 CED 1 76	Attorney Docket Number	COREPH-0159 US NP
Application Da		Application Number	
Title of Invention	DUAL APERTURE ZOOM CA DYNAMIC CONTROL	MERA WITH VIDEO SUPPORT	FAND SWITCHING / NON-SWITCHING

Authorization or Opt-Out of Authorization to Permit Access:

When this Application Data Sheet is properly signed and filed with the application, applicant has provided written authority to permit a participating foreign intellectual property (IP) office access to the instant application-as-filed (see paragraph A in subsection 1 below) and the European Patent Office (EPO) access to any search results from the instant application (see paragraph B in subsection 1 below).

Should applicant choose not to provide an authorization identified in subsection 1 below, applicant <u>must opt-out</u> of the authorization by checking the corresponding box A or B or both in subsection 2 below.

<u>NOTE</u>: This section of the Application Data Sheet is <u>**ONLY</u>** reviewed and processed with the <u>**INITIAL**</u> filing of an application. After the initial filing of an application, an Application Data Sheet cannot be used to provide or rescind authorization for access by a foreign IP office(s). Instead, Form PTO/SB/39 or PTO/SB/69 must be used as appropriate.</u>

1. Authorization to Permit Access by a Foreign Intellectual Property Office(s)

A. <u>Priority Document Exchange (PDX)</u> - Unless box A in subsection 2 (opt-out of authorization) is checked, the undersigned hereby <u>grants the USPTO authority</u> to provide the European Patent Office (EPO), the Japan Patent Office (JPO), the Korean Intellectual Property Office (KIPO), the State Intellectual Property Office of the People's Republic of China (SIPO), the World Intellectual Property Organization (WIPO), and any other foreign intellectual property office participating with the USPTO in a bilateral or multilateral priority document exchange agreement in which a foreign application claiming priority to the instant patent application is filed, access to: (1) the instant patent application-as-filed and its related bibliographic data, (2) any foreign or domestic application to which priority or benefit is claimed by the instant application and its related bibliographic data, and (3) the date of filing of this Authorization. See 37 CFR 1.14(h) (1).

B. <u>Search Results from U.S. Application to EPO</u> - Unless box B in subsection 2 (opt-out of authorization) is checked, the undersigned hereby grants the USPTO authority to provide the EPO access to the bibliographic data and search results from the instant patent application when a European patent application claiming priority to the instant patent application is filed. See 37 CFR 1.14(h)(2).

The applicant is reminded that the EPO's Rule 141(1) EPC (European Patent Convention) requires applicants to submit a copy of search results from the instant application without delay in a European patent application that claims priority to the instant application.

2. Opt-Out of Authorizations to Permit Access by a Foreign Intellectual Property Office(s)

A. Applicant **DOES NOT** authorize the USPTO to permit a participating foreign IP office access to the instant application-as-filed. If this box is checked, the USPTO will not be providing a participating foreign IP office with any documents and information identified in subsection 1A above.

B. Applicant **DOES NOT** authorize the USPTO to transmit to the EPO any search results from the instant patent application. If this box is checked, the USPTO will not be providing the EPO with search results from the instant application.

NOTE: Once the application has published or is otherwise publicly available, the USPTO may provide access to the application in accordance with 37 CFR 1.14.

Application Da	ta Shoot 37 CEP 1 76	Attorney Docket Number	COREPH-0159 US NP
Application Da		Application Number	
Title of Invention	DUAL APERTURE ZOOM CA DYNAMIC CONTROL	MERA WITH VIDEO SUPPORT	FAND SWITCHING / NON-SWITCHING

Applicant Information:

Applicant 1				Remove						
f the applicant is the inventor The information to be provide 1.43; or the name and addres who otherwise shows sufficie applicant under 37 CFR 1.46 proprietary interest) together dentified in this section.	f (or the re od in this s ss of the a nt propriet (assignee with one c	maining joint inventor or invent ection is the name and address ssignee, person to whom the ir ary interest in the matter who i person to whom the inventor or more joint inventors, then the	ors under 37 CFR 1.45 s of the legal representativentor is under an oblig s the applicant under 37 is obligated to assign, c s joint inventor or inventa), this section should not be completed. ative who is the applicant under 37 CFR gation to assign the invention, or person 7 CFR 1.46. If the applicant is an or person who otherwise shows sufficient ors who are also the applicant should be Clear						
Assignee Legal Representative under 35 U.S.C. 117 Joint Inventor										
Person to whom the inver	tor is oblig	jated to assign.	Person who sh	ows sufficient proprietary interest						
f applicant is the legal rep	resentativ	ve, indicate the authority to	l file the patent applica	tion, the inventor is:						
				•						
Name of the Deceased or	Legally I	ncapacitated Inventor:								
If the Applicant is an Org	anization	check here.								
Organization Name	Corephoto	nics Ltd.								
Mailing Address Inform	ation Fo	r Applicant:								
Address 1	25 Ha	barzel St.								
Address 2	Rama	t Hachayal								
Citv	Tel-A	<i>i</i> v	State/Province							
,			Postal Code	6971035						
Country ⁱ	Phone Number Fax Number									
Country IL Phone Number			Email Address							

Assignee Information including Non-Applicant Assignee Information:

Providing assignment information in this section does not substitute for compliance with any requirement of part 3 of Title 37 of CFR to have an assignment recorded by the Office.

PTO/AIA/14 (11-15) Approved for use through 04/30/2017. OMB 0651-0032 U.S. Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it contains a valid OMB control number.

A	- D - 1	- 01		Attorney Doc	ket Number	COREP	H-0159 US NF)		
	Application Data Sheet 37 CFR 1.76 Application Nu				lumber					
Title of Invention DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL										
Assignee	1									
Complete this section if assignee information, including non-applicant assignee information, is desired to be included on the patent application publication. An assignee-applicant identified in the "Applicant Information" section will appear on the patent application publication as an applicant. For an assignee-applicant, complete this section only if identification as an assignee is also desired on the patent application publication.										
Remove										
If the Assigne	e or N	on-Applic	cant Assignee is ar	n Organization	check here.					
Prefix		Giv	en Name	Middle Nam	ne	Family Na	ıme	Suffix		
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Signature							[Remove		
NOTE: This Application Data Sheet must be signed in accordance with 37 CFR 1.33(b). However, if this Application Data Sheet is submitted with the INITIAL filing of the application and either box A or B is not checked in subsection 2 of the "Authorization or Opt-Out of Authorization to Permit Access" section, then this form must also be signed in accordance with 37 CFR 1.14(c). This Application Data Sheet must be signed by a patent practitioner if one or more of the applicants is a juristic entity (e.g., corporation or association). If the applicant is two or more joint inventors, this form must be signed by a patent practitioner, all joint inventors who are the applicant, or one or more joint inventor-applicants who have been given power of attorney (e.g., see USPTO Form PTO/AIA/81) on behalf of all joint inventor-applicants. See 37 CFR 1.4(d) for the manner of making signatures and certifications.										
Signature	/Menac	hem Nath	an/			Date (YYYY-MM-D	D) 2017-01-08		
First Name	MENA	CHEM	Last Name	NATHAN		Registr	ation Numbe	r 65392		
Additional Signature may be generated within this form by selecting the Add button. Add										

Application Da	ta Shoot 37 CED 1 76	Attorney Docket Number	COREPH-0159 US NP
Application Da		Application Number	
Title of Invention	DUAL APERTURE ZOOM CA DYNAMIC CONTROL	MERA WITH VIDEO SUPPORT	AND SWITCHING / NON-SWITCHING

This collection of information is required by 37 CFR 1.76. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.14. This collection is estimated to take 23 minutes to complete, including gathering, preparing, and submitting the completed application data sheet form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. **SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450**.

Privacy Act Statement

The Privacy Act of 1974 (P.L. 93-579) requires that you be given certain information in connection with your submission of the attached form related to a patent application or patent. Accordingly, pursuant to the requirements of the Act, please be advised that: (1) the general authority for the collection of this information is 35 U.S.C. 2(b)(2); (2) furnishing of the information solicited is voluntary; and (3) the principal purpose for which the information is used by the U.S. Patent and Trademark Office is to process and/or examine your submission related to a patent application or patent. If you do not furnish the requested information, the U.S. Patent and Trademark Office may not be able to process and/or examine your submission, which may result in termination of proceedings or abandonment of the application or expiration of the patent.

The information provided by you in this form will be subject to the following routine uses:

- 1 The information on this form will be treated confidentially to the extent allowed under the Freedom of Information Act (5 U.S.C. 552) and the Privacy Act (5 U.S.C. 552a). Records from this system of records may be disclosed to the Department of Justice to determine whether the Freedom of Information Act requires disclosure of these records.
- 2. A record from this system of records may be disclosed, as a routine use, in the course of presenting evidence to a court, magistrate, or administrative tribunal, including disclosures to opposing counsel in the course of settlement negotiations.
- 3 A record in this system of records may be disclosed, as a routine use, to a Member of Congress submitting a request involving an individual, to whom the record pertains, when the individual has requested assistance from the Member with respect to the subject matter of the record.
- 4. A record in this system of records may be disclosed, as a routine use, to a contractor of the Agency having need for the information in order to perform a contract. Recipients of information shall be required to comply with the requirements of the Privacy Act of 1974, as amended, pursuant to 5 U.S.C. 552a(m).
- 5. A record related to an International Application filed under the Patent Cooperation Treaty in this system of records may be disclosed, as a routine use, to the International Bureau of the World Intellectual Property Organization, pursuant to the Patent CooperationTreaty.
- 6. A record in this system of records may be disclosed, as a routine use, to another federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspections or an issued patent.
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

POWER OF ATTORNEY TO PROSECUTE APPLICATIONS BEFORE THE USPTO

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		Corephotonics Ltd				*****
signee ivan	ie and Address	25 Habarzel St. Ramat Hachayal				
	*****	IELAVIV, 6971035 ISRAEL	*****		******	
	is form, toget application i	her with a statement u n which this form is u	nder 37 CFR sed. The sta	3.73(c) (Form F tement under 3	PTO/AIA/96 or equiv 7 CFR 3.73(c) may b	alent) is required to be completed by one of
copy of th ed in each		ed in this form, and m	ust identify ti	ne application in	n which this Power	of Attorney is to be filed.
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If you need assistance in completing the form, call 1-800-PTO-9199 and select option 2. APPL-1002 / Page 57 of 435

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The information provided by you in this form will be subject to the following routine uses:

- The information on this form will be treated confidentially to the extent allowed under the Freedom of Information Act (5 U.S.C. 552) and the Privacy Act (5 U.S.C 552a). Records from this system of records may be disclosed to the Department of Justice to determine whether disclosure of these records is required by the Freedom of Information Act.
- 2. A record from this system of records may be disclosed, as a routine use, in the course of presenting evidence to a court, magistrate, or administrative tribunal, including disclosures to opposing counsel in the course of settlement negotiations.
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- A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

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STATEM	ENT UNDER 37 CFR 3.73(c)							
Applicant/Patent Owner: Corephotonics Ltd.								
Application No./Patent No.: 15324720	Filed/Issue Date: 2017-01-08							
Titled: DUAL APERTURE ZOOM CAMERA V	WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL							
Corephotonics Ltd.	, a COMPANY							
(Name of Assignee)	(Type of Assignee, e.g., corporation, partnership, university, government agency, etc.)							
states that, for the patent application/patent identified above, it is (choose one of options 1, 2, 3 or 4 below):								
1. 🔽 The assignee of the entire right, title, and int	terest.							
2. An assignee of less than the entire right, title	e, and interest (check applicable box):							
The extent (by percentage) of its ownersh holding the balance of the interest <u>must be s</u>	The extent (by percentage) of its ownership interest is%. Additional Statement(s) by the owners holding the balance of the interest <u>must be submitted</u> to account for 100% of the ownership interest.							
There are unspecified percentages of ow right, title and interest are:	There are unspecified percentages of ownership. The other parties, including inventors, who together own the entire right, title and interest are:							
Additional Statement(s) by the owner(s) holding the balance of the interest <u>must be submitted</u> to account for the entire right, title, and interest.								
3. The assignee of an undivided interest in the entirety (a complete assignment from one of the joint inventors was made). The other parties, including inventors, who together own the entire right, title, and interest are:								
Additional Statement(s) by the owner(s) h right, title, and interest.	olding the balance of the interest must be submitted to account for the entire							
4. The recipient, via a court proceeding or the I complete transfer of ownership interest was made).	ike (<i>e.g.</i> , bankruptcy, probate), of an undivided interest in the entirety (a The certified document(s) showing the transfer is attached.							
The interest identified in option 1, 2 or 3 above (not	option 4) is evidenced by either (choose <u>one</u> of options A or B below):							
A. An assignment from the inventor(s) of the pa the United States Patent and Trademark Off thereof is attached.	atent application/patent identified above. The assignment was recorded in fice at Reel, Frame, or for which a copy							
B. \Box A chain of title from the inventor(s), of the particular title from the inventor(s).	atent application/patent identified above, to the current assignee as follows:							
1. From:	To:							
The document was recorded in th	e United States Patent and Trademark Office at							
Reel, Frame	, or for which a copy thereof is attached.							
2. From:	То:							
The document was recorded in th	e United States Patent and Trademark Office at							
Reel, Frame	, or for which a copy thereof is attached.							
	[Page 1 of 2]							

[Page 1 01 2] This collection of information is required by 37 CFR 3.73(b). The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.11 and 1.14. This collection is estimated to take 12 minutes to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. **SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450**.

		STATEME	NT UNDER 37 CFR 3.73(c)				
3. From:			То:				
	The docume	nt was recorded in the U	United States Patent and Tradema	rk Office at			
	Reel	, Frame	, or for which a copy thereo	of is attached.			
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6. From:			To:				
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As reasig	equired by 37 CFR gnee was, or conci	3.73(c)(1)(i), the docun urrently is being, submit	nentary evidence of the chain of tit ted for recordation pursuant to 37	le from the original owner to the CFR 3.11.			
[NOT Divis	FE: A separate cop ion in accordance	by (i.e., a true copy of th with 37 CFR Part 3, to	e original assignment document(s) record the assignment in the recor) must be submitted to Assignment ds of the USPTO. See MPEP 302.08]			
The undersig	gned (whose title is	s supplied below) is auth	norized to act on behalf of the assig	gnee.			
Gal Shab	otay			01-08-2017			
Signature				Date			
/Gal Sh	abtay/			VP-R&D			
Printed or Ty	ped Name			Title or Registration Number			

[Page 2 of 2]

Privacy Act Statement

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The information provided by you in this form will be subject to the following routine uses:

- 1. The information on this form will be treated confidentially to the extent allowed under the Freedom of Information Act (5 U.S.C. 552) and the Privacy Act (5 U.S.C 552a). Records from this system of records may be disclosed to the Department of Justice to determine whether disclosure of these records is required by the Freedom of Information Act.
- 2. A record from this system of records may be disclosed, as a routine use, in the course of presenting evidence to a court, magistrate, or administrative tribunal, including disclosures to opposing counsel in the course of settlement negotiations.
- 3. A record in this system of records may be disclosed, as a routine use, to a Member of Congress submitting a request involving an individual, to whom the record pertains, when the individual has requested assistance from the Member with respect to the subject matter of the record.
- 4. A record in this system of records may be disclosed, as a routine use, to a contractor of the Agency having need for the information in order to perform a contract. Recipients of information shall be required to comply with the requirements of the Privacy Act of 1974, as amended, pursuant to 5 U.S.C. 552a(m).
- 5. A record related to an International Application filed under the Patent Cooperation Treaty in this system of records may be disclosed, as a routine use, to the International Bureau of the World Intellectual Property Organization, pursuant to the Patent Cooperation Treaty.
- 6. A record in this system of records may be disclosed, as a routine use, to another federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
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- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

	Application Number		15324720		
	Filing Date		2017-01-08		
INFORMATION DISCLOSURE	First Named Inventor Noy C		Sohen		
(Not for submission under 37 CER 1 99)	Art Unit				
	Examiner Name				
	Attorney Docket Number		COREPH-0159 US NP		

U.S.PATENTS Remove										
Examiner Initial*	Cite No	Patent Number	Kind Code ¹	Issue Date	Name of Patentee or Applicant of cited Document	Pages, Releva Figures	Columns,Lines where nt Passages or Relevant s Appear			
	1	8401276	B1	2013-03-19	Choe et al.					
	2	6104432	A	2000-08-15	Nakamura et al.					
	3	5710670	A	1998-01-20	Ohno					
	4	9185291	B1	2015-11-10	Shabtay et al.					
If you wis	h to add	additional U.S. Paten	t citatio	n information pl	ease click the Add button.		Add			
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Examiner Initial*	Cite No	Publication Number	Kind Code ¹	Publication Date	Name of Patentee or Applicant Pages of cited Document Figure		Columns,Lines where nt Passages or Relevant s Appear			
	1	20030017930	A1	2003-09-25	Bittner					
	2	20090102950	A1	2009-04-23	Ahiska					

INFORMATION DISCLOSURE Application Number 15324720 Filing Date 2017-01-08 First Named Inventor Noy Cohen Art Unit Examiner Name Attorney Docket Number COREPH-0159 US NP

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	3		20080030592	A1	2008-02-07 Border et al.								
	4		20100277619	A1	2010-11-04 Lawrence Scarff								
	5		20110064327	A1	2011-03	2011-03-17 Joseph C. Dagher et a		et al.					
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INFORMATION DISCLOSURE	Application Number		15324720
	Filing Date		2017-01-08
	First Named Inventor	Noy C	Cohen
STATEMENT BY APPLICANT (Not for submission under 37 CER 1 99)	Art Unit		
	Examiner Name		
	Attorney Docket Number		COREPH-0159 US NP

¹ See Kind Codes of USPTO Patent Documents at <u>www.USPTO.GOV</u> or MPEP 901.04. ² Enter office that issued the document, by the two-letter code (WIPO Standard ST.3). ³ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document. ⁴ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST.16 if possible. ⁵ Applicant is to place a check mark here if English language translation is attached.

INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number		15324720		
	Filing Date		2017-01-08		
	First Named Inventor	Noy C	Joy Cohen		
	Art Unit				
	Examiner Name				
	Attorney Docket Number		COREPH-0159 US NP		

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Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

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A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature	/Menachem Nathan/	Date (YYYY-MM-DD)	2017-01-08
Name/Print	MENACHEM NATHAN	Registration Number	65392

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PTO/AIA/15 (03-13)

Approved for use through 01/31/2014. OMB 0651-0032

U.S. Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE

	Attorney Docket	No.	COREPH-0159 US NP				
PATENT APPLICATION	ON First Named Inv		Noy Cohen				
TRANSMITTAL	Title		DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NO				
(Only for new nonprovisional applications under 37 CFR 1.53(b))	Express Mail Lab	oel No.					
APPLICATION ELEMENTS See MPEP chapter 600 concerning utility patent application contents.	ADDRESS	TO:	Commissioner for Patents O: P.O. Box 1450 Alexandria, VA 22313-1450				
1. Fee Transmittal Form	ACCOMPANYING APPLICATION PAPERS						
2. Applicant asserts small entity status.	10. Assignm (cover sl	10. Assignment Papers (cover sheet & document(s))					
3. Applicant certifies micro entity status. See 37 CFR 1.29.	Name of Assignee						
A. Specification [Total Pages] Both the claims and abstract must start on a new page. (See MPEP § 608.01(a) for information on the preferred arrangement)	11. 37 CFR 3 (when th	11. 37 CFR 3.73(c) Statement (when there is an assignee) Power of Attorney 12. English Translation Document					
5. Drawing(s) (35 U.S.C. 113) [Total Sheets]	(if applic	able)	losure Stat	ement			
(including substitute statements under 37 CFR 1.64 and assignments serving as an oath or declaration under 37 CFR 1.63(e))	(PTO/SB,	(PTO/SB/08 or PTO-1449)					
a Newly executed (original or copy)	14. Prelimir	14. Preliminary Amendment					
b. A copy from a prior application (37 CFR 1.63(d))	15. Return	15. Return Receipt Postcard					
See 37 CFR 1.76 (PTO/AIA/14 or equivalent)	16. Certifie	16. Certified Copy of Priority Document(s)					
 CD-ROM or CD-R in duplicate, large table, or Computer Program (Appendix) 	(if foreig	(if foreign priority is claimed)					
Landscape Table on CD	Under 39	Under 35 U.S.C. 122(b)(2)(B)(i). Applicant must attach form PTO/SB/35					
9. Nucleotide and/or Amino Acid Sequence Submission	or equivalent. 18 J Other: Remarks - This is an IDS. Citation or identification of any						
a. Computer Readable Form (CRF)		reference in this IDS shall not be construed as an admission					
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i CD-ROM or CD-R (2 copies); or							
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 *Note: (1) Benefit claims under 37 CFR 1.78 and foreign priority claims under 1.55 must be included in an Application Data Sheet (ADS). (2) For applications filed under 35 U.S.C. 111, the application must contain an ADS specifying the applicant if the applicant is an assignee, person to whom the inventor is under an obligation to assign, or person who otherwise shows sufficient proprietary interest in the matter. See 37 CFR 1.46(b). 							
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(Print/Type) MENACHEM NATHAN		Registra (Attorn	ation No. ey/Agent)	65,392			

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(57) Abstract: A dual-aperture zoom digital camera operable in both still and video modes. The camera includes Wide and Tele imaging sections with respective lens/sensor combinations and image signal processors and a camera controller operative!y coupled to the Wide and Tele imaging sections. The Wide and Tele imaging sections provide respective image data. The controller is configured to combine in still mode at least some of the Wide and Tele image data to provide a fused output image from a particular point of view, and to provide without fusion continuous zoom video mode output images, each output image having a given output resolution, wherein the video mode output images are provided with a smooth transition when switching between a lower zoom factor (ZF) value and a higher ZF value or vice versa, and wherein at the lower ZF the output resolution is determined by the Wide sensor while at the higher ZF value the output resolution is determined by the Tele sensor.

DUAL APERTURE ZOOM DIGITAL CAMERA

CROSS REFERENCE TO RELATED APPLICATIONS

5 This application is related to and claims priority from US Provisional Patent Application No. 61/834,486 having the same title and filed June 13, 2013, which is incorporated herein by reference in its entirety.

FIELD

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Embodiments disclosed herein relate in general to digital cameras and in particular to thin zoom digital cameras with both still image and video capabilities

BACKGROUND

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Digital camera modules are currently being incorporated into a variety of host devices. Such host devices include cellular telephones, personal data assistants (PDAs), computers, and so forth. Consumer demand for digital camera modules in host devices continues to grow.

- Host device manufacturers prefer digital camera modules to be small, so that they can be incorporated into the host device without increasing its overall size. Further, there is an increasing demand for such cameras to have higher-performance characteristics. One such characteristic possessed by many higher-performance cameras (e.g., standalone digital still cameras) is the ability to vary the focal length of the camera to increase and decrease the magnification of the image. This ability, typically accomplished with a zoom lens, is known
- as optical zooming. "Zoom" is commonly understood as a capability to provide different magnifications of the same scene and/or object by changing the focal length of an optical system, with a higher level of zoom associated with greater magnification and a lower level of zoom associated with lower magnification. Optical zooming is typically accomplished by mechanically moving lens elements relative to each other. Such zoom lenses are typically
 more expensive, larger and less reliable than fixed focal length lenses. An alternative approach for approximating the zoom effect is achieved with what is known as digital zooming. With digital zooming, instead of varying the focal length of the lens, a processor in the camera crops the image and interpolates between the pixels of the captured image to create a magnified but lower-resolution image.

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Attempts to use multi-aperture imaging systems to approximate the effect of a zoom lens are known. A multi-aperture imaging system (implemented for example in a digital camera) includes a plurality of optical sub-systems (also referred to as "sub-cameras"). Each sub-camera includes one or more lenses and/or other optical elements which define an aperture such that received electro-magnetic radiation is imaged by the optical sub-system and a resulting image is directed towards a two-dimensional (2D) pixelated image sensor region.

The image sensor (or simply "sensor") region is configured to receive the image and to generate a set of image data based on the image. The digital camera may be aligned to receive electromagnetic radiation associated with scenery having a given set of one or more objects. 10 The set of image data may be represented as digital image data, as well known in the art. Hereinafter in this description, "image" "image data" and "digital image data" may be used interchangeably. Also, "object" and "scene" may be used interchangeably.

Multi-aperture imaging systems and associated methods are described for example in US Patent Publications No. 2008/0030592, 2010/0277619 and 2011/0064327. In US 2008/0030592, two sensors are operated simultaneously to capture an image imaged through 15 an associated lens. A sensor and its associated lens form a lens/sensor combination. The two lenses have different focal lengths. Thus, even though each lens/sensor combination is aligned to look in the same direction, each captures an image of the same subject but with two different fields of view (FOVs). One sensor is commonly called "Wide" and the other "Tele".

- Each sensor provides a separate image, referred to respectively as "Wide" (or "W") and 20 "Tele" (or "T") images. A W-image reflects a wider FOV and has lower resolution than the Timage. The images are then stitched (fused) together to form a composite ("fused") image. In the composite image, the central portion is formed by the relatively higher-resolution image taken by the lens/sensor combination with the longer focal length, and the peripheral portion
- is formed by a peripheral portion of the relatively lower-resolution image taken by the 25 lens/sensor combination with the shorter focal length. The user selects a desired amount of zoom and the composite image is used to interpolate values from the chosen amount of zoom to provide a respective zoom image. The solution offered by US 2008/0030592 requires, in video mode, very large processing resources in addition to high frame rate requirements and 30 high power consumption (since both cameras are fully operational).

US 2010/0277619 teaches a camera with two lens/sensor combinations, the two lenses having different focal lengths, so that the image from one of the combinations has a FOV approximately 2-3 times greater than the image from the other combination. As a user of the camera requests a given amount of zoom, the zoomed image is provided from the lens/sensor 5

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combination having a FOV that is next larger than the requested FOV. Thus, if the requested FOV is less than the smaller FOV combination, the zoomed image is created from the image captured by that combination, using cropping and interpolation if necessary. Similarly, if the requested FOV is greater than the smaller FOV combination, the zoomed image is created from the image captured by the other combination, using cropping and interpolation if necessary. The solution offered by US 2010/0277619 leads to parallax artifacts when moving to the Tele camera in video mode.

In both US 2008/0030592 and US 2010/0277619, different focal length systems cause Tele and Wide matching FOVs to be exposed at different times using CMOS sensors. This 10 degrades the overall image quality. Different optical F numbers ("F#") cause image intensity differences. Working with such a dual sensor system requires double bandwidth support, i.e. additional wires from the sensors to the following HW component. Neither US 2008/0030592 nor US 2010/0277619 deal with registration errors. Neither US 2008/000592 nor US 2010/0277619 refer to partial fusion, i.e. fusion of less than all the pixels of both Wide and Tele images in still mode.

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US 2011/0064327 discloses multi-aperture imaging systems and methods for image data fusion that include providing first and second sets of image data corresponding to an imaged first and second scene respectively. The scenes overlap at least partially in an overlap region, defining a first collection of overlap image data as part of the first set of image data, and a second collection of overlap image data as part of the second set of image data. The second collection of overlap image data is represented as a plurality of image data subcameras such that each of the sub-cameras is based on at least one characteristic of the second collection, and each sub-camera spans the overlap region. A fused set of image data is produced by an image processor, by modifying the first collection of overlap image data based on at least a selected one of, but less than all of, the image data sub-cameras. The systems and methods disclosed in this application deal solely with fused still images.

None of the known art references provide a thin (e.g. fitting in a cell-phone) dualaperture zoom digital camera with fixed focal length lenses, the camera configured to operate in both still mode and video mode to provide still and video images, wherein the camera configuration uses partial or full fusion to provide a fused image in still mode and does not use any fusion to provide a continuous, smooth zoom in video mode.

Therefore there is a need for, and it would be advantageous to have thin digital cameras with optical zoom operating in both video and still mode that do not suffer from commonly encountered problems and disadvantages, some of which are listed above.

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SUMMARY

Embodiments disclosed herein teach the use of dual-aperture (also referred to as duallens or two-sensor) optical zoom digital cameras. The cameras include two sub-cameras, a 5 Wide sub-camera and a Tele sub-camera, each sub-camera including a fixed focal length lens, an image sensor and an image signal processor (ISP). The Tele sub-camera is the higher zoom sub-camera and the Wide sub-camera is the lower zoom sub-camera. In some embodiments, the lenses are thin lenses with short optical paths of less than about 9mm. In some 10 embodiments, the thickness/effective focal length (EFL) ratio of the Tele lens is smaller than about 1. The image sensor may include two separate 2D pixelated sensors or a single pixelated sensor divided into at least two areas. The digital camera can be operated in both still and video modes. In still mode, zoom is achieved "with fusion" (full or partial), by fusing W and T images, with the resulting fused image including always information from both W and T images. Partial fusion may be achieved by not using fusion in image areas where the 15 Tele image is not focused. This advantageously reduces computational requirements (e.g. time).

In video mode, optical zoom is achieved "without fusion", by switching between the W and T images to shorten computational time requirements, thus enabling high video rate. To avoid discontinuities in video mode, the switching includes applying additional processing blocks, which include image scaling and shifting.

In order to reach optical zoom capabilities, a different magnification image of the same scene is captured (grabbed) by each camera sub-camera, resulting in FOV overlap between the two sub-cameras. Processing is applied on the two images to fuse and output one fused image in still mode. The fused image is processed according to a user zoom factor request. As part of the fusion procedure, up-sampling may be applied on one or both of the grabbed images to scale it to the image grabbed by the Tele sub-camera or to a scale defined by the user. The fusion or up-sampling may be applied to only some of the pixels of a sensor. Down-sampling can be performed as well if the output resolution is smaller than the sensor

30 resolution.

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The cameras and associated methods disclosed herein address and correct many of the problems and disadvantages of known dual-aperture optical zoom digital cameras. They provide an overall zoom solution that refers to all aspects: optics, algorithmic processing and system hardware (HW). The proposed solution distinguishes between video and still mode in

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the processing flow and specifies the optical requirements and HW requirements. In addition, it provides an innovative optical design that enables a low TTL/EFL ratio using a specific lens curvature order.

Due to the large focal length, objects that are in front or behind the plane of focus appear very blurry, and a nice foreground-to-background contrast is achieved. However, it is 5 difficult to create such a blur using a compact camera with a relatively short focal length and small aperture size, such as a cell-phone camera. In some embodiments, a dual-aperture zoom system disclosed herein can be used to capture a shallow DOF photo (shallow compared with a DOF of a Wide camera alone), by taking advantage of the longer focal length of the Tele 10 lens. The reduced DOF effect provided by the longer Tele focal length can be further enhanced in the final image by fusing data from an image captured simultaneously with the Wide lens. Depending on the distance to the object, with the Tele lens focused on a subject of the photo, the Wide lens can be focused to a closer distance than the subject so that objects behind the subject appear very blurry. Once the two images are captured, information from the out-of-focus blurred background in the Wide image is fused with the original Tele image 15 background information, providing a blurrier background and even shallower DOF.

In an embodiment there is provided a zoom digital camera comprising a Wide imaging section that includes a fixed focal length Wide lens with a Wide FOV, a Wide sensor and a Wide image signal processor (ISP), the Wide imaging section operative to provide Wide image data of an object or scene; a Tele imaging section that includes a fixed focal length

- 20 image data of an object or scene; a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV, a Tele sensor and a Tele ISP, the Tele imaging section operative to provide Tele image data of the object or scene; and a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to combine in still mode at least some of the Wide and Tele image data
- to provide a fused output image of the object or scene from a particular point of view (POV), and to provide without fusion continuous zoom video mode output images of the object or scene, a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to combine in still mode at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of
- 30 view and to provide without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, wherein the video output images are provided with a smooth transition when switching between a lower zoom factor (ZF) value and a higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor, and wherein at the higher ZF value the output

correction matrix.

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resolution is determined by the Tele sensor.

In an embodiment, the camera controller configuration to provide video output images with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa includes a configuration that uses at high ZF secondary information from the Wide camera and uses at low ZF secondary information from the Tele camera. As used herein,

"secondary information" refers to white balance gain, exposure time, analog gain and color

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In a dual-aperture camera image plane, as seen by each sub-camera (and respective image sensor), a given object will be shifted and have different perspective (shape). This is referred to as point-of-view (POV). The system output image can have the shape and position of either sub-camera image or the shape or position of a combination thereof. If the output image retains the Wide image shape then it has the Wide perspective POV. If it retains the Wide camera position then it has the Wide position POV. The same applies for Tele images

position and perspective. As used in this description, the perspective POV may be of the Wide

- 15 or Tele sub-cameras, while the position POV may shift continuously between the Wide and Tele sub-cameras. In fused images, it is possible to register Tele image pixels to a matching pixel set within the Wide image pixels, in which case the output image will retain the Wide POV ("Wide fusion"). Alternatively, it is possible to register Wide image pixels to a matching pixel set within the Tele image pixels, in which case the output image will retain the Tele
- 20 POV ("Tele fusion"). It is also possible to perform the registration after either sub-camera image is shifted, in which case the output image will retain the respective Wide or Tele perspective POV.

In an embodiment there is provided a method for obtaining zoom images of an object or scene in both still and video modes using a digital camera, the method comprising the steps of providing in the digital camera a Wide imaging section having a Wide lens with a Wide FOV, a Wide sensor and a Wide image signal processor (ISP), a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV, a Tele sensor and a Tele ISP, and a camera controller operatively coupled to the Wide and Tele imaging sections; and configuring the camera controller to combine in still mode at least some of the Wide and Tele

30 image data to provide a fused output image of the object or scene from a particular point of view, and to provide without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, wherein the video mode output images are provided with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa, and wherein at the lower ZF value the output resolution is determined by the Wide sensor while at the higher ZF value the output resolution is determined by the Tele sensor.

BRIEF DESCRIPTION OF THE DRAWINGS

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Non-limiting examples of embodiments disclosed herein are described below with reference to figures attached hereto that are listed following this paragraph. The drawings and descriptions are meant to illuminate and clarify embodiments disclosed herein, and should not be considered limiting in any way.

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FIG. 1A shows schematically a block diagram illustrating a dual-aperture zoom imaging system disclosed herein;

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A:

FIG. 2 shows an example of Wide sensor, Tele sensor and their respective FOVs;

FIG. 3 shows a schematically embodiment of CMOS sensor image grabbing vs. time;

FIG. 4 shows schematically a sensor time configuration which enables sharing one sensor interface using dual sensor zoom system;

FIG. 5 shows an embodiment of a method disclosed herein for acquiring a zoom image in capture mode;

20 FIG. 6 shows an embodiment of a method disclosed herein for acquiring a zoom image in video/preview mode;

FIG. 7 shows a graph illustrating an effective resolution zoom factor;

FIG. 8 shows one embodiment of a lens block in a thin camera disclosed herein;

FIG. 9 shows another embodiment of a lens block in a thin camera disclosed herein.

FIG. 1A shows schematically a block diagram illustrating an embodiment of a dual-

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DETAILED DESCRIPTION

aperture zoom imaging system (also referred to simply as "digital camera" or "camera")
disclosed herein and numbered 100. Camera 100 comprises a Wide imaging section ("sub-camera") that includes a Wide lens block 102, a Wide image sensor 104 and a Wide image processor 106. Camera 100 further comprises a Tele imaging section ("sub-camera") that includes a Tele lens block 108, a Tele image sensor 110 and a Tele image processor 112. The

image sensors may be physically separate or may be part of a single larger image sensor. The

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Wide sensor pixel size can be equal to or different from the Tele sensor pixel size. Camera **100** further comprises a camera fusion processing core (also referred to as "controller") **114** that includes a sensor control module **116**, a user control module **118**, a video processing module **126** and a capture processing module **128**, all operationally coupled to sensor control block **110**. User control module **118** comprises an operational mode function **120**, a region of

interest (ROI) function **122** and a zoom factor (ZF) function **124**.

Sensor control module **116** is connected to the two sub-cameras and to the user control module **118** and used to choose, according to the zoom factor, which of the sensors is operational and to control the exposure mechanism and the sensor readout. Mode choice function **120** is used for choosing capture/video modes. ROI function **122** is used to choose a region of interest. As used herein, "ROI" is a user defined as a sub-region of the image that may be exemplarily 4% or less of the image area. The ROI is the region on which both sub-cameras are focused on. Zoom factor function **124** is used to choose a zoom factor. Video processing module **126** is connected to mode choice function **120** and used for video processing. Still processing module **128** is connected to the mode choice function **120** and used for high image quality still mode images. The video processing module is applied when the user desires to shoot in video mode. The capture processing module is applied when the user wishes to shoot still pictures.

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system
of FIG. 1A. Exemplary dimensions: Wide lens TTL = 4.2mm and EFL = 3.5mm; Tele lens TTL = 6mm and EFL = 7 mm; both Wide and Tele sensors 1/3 inch. External dimensions of Wide and Tele cameras: width (w) and length (l) = 8.5 mm and height (h) = 6.8 mm. Distance "d" between camera centers = 10mm.

Following is a detailed description and examples of different methods of use of camera **100**.

Design for continuous and smooth zoom in video mode

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In an embodiment, in order to reach high quality continuous and smooth optical zooming in video camera mode while reaching real optical zoom using fixed focal length subcameras, the system is designed according to the following rules (Equations 1-3):

$$Tan (FOV_{wide})/Tan (FOV_{Tele}) = PL_{wide}/PL_{video}$$
(1)

35 where Tan refers to "tangent", while FOV_{Wide} and FOV_{Tele} refer respectively to the Wide and

Tele lens fields of view (in degrees). As used herein, the FOV is measured from the center axis to the corner of the sensor (i.e. half the angle of the normal definition). PL_{wide} and PL_{video} refer respectively to the "in-line" (i.e. in a line) number of Wide sensor pixels and in-line number of output video format pixels. The ratio PL_{wide}/PL_{video} is called an "oversampling

- ratio". For example, in order to get full and continuous optical zoom experience with a 12Mp 5 sensor (sensor dimensions 4000x3000) and a required 1080p (dimension 1920x1080) video format, the FOV ratio should be 4000/1920=2.083. Moreover, if the Wide lens FOV is given as $FOV_{Wide} = 37.5^{\circ}$, the required Tele lens FOV is 20.2° The zoom switching point is set according to the ratio between sensor pixels in-line and the number of pixels in-line in the
- video format and defined as: 10

$$Z_{switch} = PL_{Wide} / PL_{video}$$
(2)

Maximum optical zoom is reached according to the following formula:

$$Z_{max} = Tan (FOV_{Wide})/Tan (FOV_{Tele}) * PL_{Tele}/ PL_{video}$$
(3)

For example: for the configuration defined above and assuming PL_{Tele}=4000 and PL_{video}= 1920, Z_{max}=4.35.

In an embodiment, the sensor control module has a setting that depends on the Wide and Tele FOVs and on a sensor oversampling ratio, the setting used in the configuration of 20 each sensor. For example, when using a 4000x3000 sensor and when outputting a 1920x1080 image, the oversampling ratio is 4000/1920=2.0833.

In an embodiment, the Wide and Tele FOVs and the oversampling ratio satisfy the condition

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0.8*PL_{Wide}/ PL_{video} < Tan (FOV_{Wide})/Tan (FOV_{Tele}) <1.2*PL_{Wide}/ PL_{video}. (4)

Still mode operation/function

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In still camera mode, the obtained image is fused from information obtained by both sub-cameras at all zoom levels, see FIG. 2, which shows a Wide sensor 202 and a Tele sensor 204 and their respective FOVs. Exemplarily, as shown, the Tele sensor FOV is half the Wide sensor FOV. The still camera mode processing includes two stages: (1) setting HW settings and configuration, where a first objective is to control the sensors in such a way that matching

FOVs in both images (Tele and Wide) are scanned at the same time. A second objective is to 35 control the relative exposures according to the lens properties. A third objective is to

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minimize the required bandwidth from both sensors for the ISPs; and (2) image processing that fuses the Wide and the Tele images to achieve optical zoom, improves SNR and provides wide dynamic range.

FIG. 3 shows image line numbers vs. time for an image section captured by CMOS
sensors. A fused image is obtained by line (row) scans of each image. To prevent matching
FOVs in both sensors to be scanned at different times, a particular configuration is applied by
the camera controller on both image sensors while keeping the same frame rate. The
difference in FOV between the sensors determines the relationship between the rolling shutter
time and the vertical blanking time for each sensor. In the particular configuration, the
scanning is synchronized such that the same points of the object in each view are obtained

Specifically with reference to FIG. 3 and according to an embodiment of a method disclosed herein, the configuration to synchronize the scanning includes: setting the Tele sensor vertical blanking time VB_{Tele} to equal the Wide sensor vertical blanking time VB_{wide} plus half the Wide sensor rolling shutter time RST_{Wide} ; setting the Tele and Wide sensor exposure times ET_{Tele} and ET_{Wide} to be equal or different; setting the Tele sensor rolling shutter time RST_{Tele} to be 0.5*RST_{Wide}; and setting the frame rates of the two sensors to be equal. This procedure results in identical image pixels in the Tele and Wide sensor images being exposed at the same time

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In another embodiment, the camera controller synchronizes the Wide and Tele sensors so that for both sensors the rolling shutter starts at the same time.

The exposure times applied to the two sensors could be different, for example in order to reach same image intensity using different F# and different pixel size for the Tele and Wide systems. In this case, the relative exposure time may be configured according to the formula below:

$$ET_{Tele} = ET_{Wide} \cdot (F\#_{Tele}/F\#_{Wide})^2 \cdot (Pixel \ size_{Wide}/Pixel \ size_{Tele})^2$$
(5)

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Other exposure time ratios may be applied to achieve wide dynamic range and improved SNR. Fusing two images with different intensities will result in wide dynamic range image.

In more detail with reference to FIG. 3, in the first stage, after the user chooses a required zoom factor ZF, the sensor control module configures each sensor as follows:

1) Cropping index Wide sensor:

 $Y_{Wide start} = 1/2 \cdot PC_{Wide}(1-1/ZF)$

 $Y_{\text{Wide end}} = 1/2 \cdot PC_{\text{Wide}}(1+1/ZF)$

where PC is the number of pixels in a column, and Y is the row number

2) Cropping index Tele sensor:

If ZF> Tan (FOV_{Wide})/Tan (FOV_{Tele}), then

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 $Y_{\text{Tele star }t} = \frac{1}{2} \cdot PC_{\text{Tele}}(1 - (1/ZF) \cdot Tan (FOV_{\text{Tele}})/Tan (FOV_{\text{Wide}}))$ $Y_{\text{Tele end}} = \frac{1}{2} \cdot PC_{\text{Tele}}(1 + (1/ZF) \cdot Tan (FOV_{\text{Tele}})/Tan (FOV_{\text{Wide}}))$

If ZF < Tan (FOV_{Wide})/Tan (FOV_{Tele}), then

Y Tele start= 0 Y Tele end= PC_{Tele}

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This will result in an exposure start time of the Tele sensor with a delay of (in numbers of lines, relative to the Wide sensor start time):

$$(1-ZF/((Tan (FOV_{wide})/Tan (FOV_{Tele}))) \cdot 1/(2 \cdot FPS)$$
(6)

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where FPS is the sensor's frame per second configuration. In cases where ZF> Tan (FOV_{wide})/Tan (FOV_{Tele}), no delay will be introduced between Tele and Wide exposure starting point. For example, for a case where Tan (FOV_{wide})/Tan (FOV_{Tele})=2 and ZF=1, the Tele image first pixel is exposed $1/4 \cdot (1/FPS)$ second after the Wide image first pixel was exposed.

After applying the cropping according to the required zoom factor, the sensor rolling shutter time and the vertical blank should be configured in order to satisfy the equation to keep the same frame rate:

25 $VB_{Wide} + RST_{Wide} = VB_{Tele} + RST_{Tele}$ (7)

FIG. 3 exemplifies Eq. (7), One way to satisfy Eq. (7) is to increase the RST_{Wide} . Controlling the RST_{Wide} may be done by changing the horizontal blanking (HB) of the Wide sensor. This will cause a delay between the data coming out from each row of the Wide sensor.

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Generally, working with a dual-sensor system requires multiplying the bandwidth to the following block, for example the ISP. For example, using 12Mp working at 30fps, 10bit per pixel requires working at 3.6Gbit/sec. In this example, supporting this bandwidth requires 4 lanes from each sensor to the respective following ISP in the processing chain. Therefore,

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working with two sensors requires double bandwidth (7.2Gbit/sec) and 8 lanes connected to the respective following blocks. The bandwidth can be reduced by configuring and synchronizing the two sensors. Consequently, the number of lanes can be half that of a conventional configuration (3.6Gbit/sec).

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FIG. 4 shows schematically a sensor time configuration that enables sharing one sensor interface using a dual-sensor zoom system, while fulfilling the conditions in the description of FIG. 3 above. For simplicity, assuming the Tele sensor image is magnified by a factor of 2 compared with the Wide sensor image, the Wide sensor horizontal blanking time HB_{wide} is set to twice the Wide sensor line readout time. This causes a delay between output 10 Wide lines. This delay time matches exactly the time needed to output two lines from the Tele sensor. After outputting two lines from the Tele sensor, the Tele sensor horizontal blanking time HB_{Tele} is set to be one Wide line readout time, so, while the Wide sensor outputs a row from the sensor, no data is being output from the Tele sensor. For this example, every 3rd line in the Tele sensor is delayed by an additional HB_{Tele.} In this delay time, one line from the Wide sensor is output from the dual-sensor system. After the sensor configuration stage, the 15 data is sent in parallel or by using multiplexing into the processing section.

FIG. 5 shows an embodiment of a method disclosed herein for acquiring a zoom image in still mode. In ISP step 502, the data of each sensor is transferred to the respective ISP component, which performs on the data various processes such as denoising, demosaicing, sharpening, scaling, etc, as known in the art. After the processing in step 502, 20 all following actions are performed in capture processing core 128: in rectification step 504, both Wide and Tele images are aligned to be on the epipolar line; in registration step 506, mapping between the Wide and the Tele aligned images is performed to produce a registration map; in resampling step 508, the Tele image is resampled according to the registration map, resulting in a re-sampled Tele image; in decision step 510, the re-sampled Tele image and the 25 Wide image are processed to detect errors in the registration and to provide a decision output. In more detail, in step 510, the re-sampled Tele image data is compared with the Wide image data and if the comparison detects significant dissimilarities, an error is indicated. In this case, the Wide pixel values are chosen to be used in the output image. Then, in fusion step 512, the 30 decision output, re-sampled Tele image and the Wide image are fused into a single zoom

image. To reduce processing time and power, steps 506, 508, 510, 512 could be bypassed by not fusing the images in non-focused areas. In this case, all steps specified above should be

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applied on focused areas only. Since the Tele optical system will introduce shallower depth of

field than the Wide optical system, defocused areas will suffer from lower contrast in the Tele system.

Zoom-in and Zoom-out in still camera mode

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We define the following: TFOV = tan (camera FOV/2). "Low ZF" refers to all ZF that comply with ZF < Wide TFOV/Tele TFOV. "High ZF" refers to all ZF that comply with ZF > Wide TFOV/Tele TFOV. "ZFT" refers to a ZF that complies with ZF = Wide TFOV/Tele TFOV. In one embodiment, zoom-in and zoom-out in still mode is performed as follows:

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Zoom-in: at low ZF up to slightly above ZFT, the output image is a digitally zoomed, Wide fusion output. For the up-transfer ZF, the Tele image is shifted and corrected by global registration (GR) to achieve smooth transition. Then, the output is transformed to a Tele fusion output. For higher (than the up-transfer) ZF, the output is the Tele fusion output digitally zoomed.

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Zoom-out: at high ZF down to slightly below ZFT, the output image is a digitally zoomed, Tele fusion output. For the down-transfer ZF, the Wide image is shifted and corrected by GR to achieve smooth transition. Then, the output is transformed to a Wide fusion output. For lower (than the down-transfer) ZF, the output is basically the down-transfer ZF output digitally zoomed but with gradually smaller Wide shift correction, until for ZF=1 the output is the unchanged Wide camera output.

In another embodiment, zoom-in and zoom-out in still mode is performed as follows:

Zoom-in: at low ZF up to slightly above ZFT, the output image is a digitally zoomed, Wide fusion output. For the up-transfer ZF and above, the output image is the Tele fusion output.

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Zoom-out: at high ZF down to slightly below ZFT, the output image is a digitally zoomed, Tele fusion output. For the down-transfer ZF and below, the output image is the Wide fusion output.

Video mode operation/function

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Smooth transition

When a dual-aperture camera switches the camera output between sub-cameras or points of view, a user will normally see a "jump" (discontinuous) image change. However, a

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change in the zoom factor for the same camera and POV is viewed as a continuous change. A "smooth transition" is a transition between cameras or POVs that minimizes the jump effect. This may include matching the position, scale, brightness and color of the output image before and after the transition. However, an entire image position matching between the sub-

5 camera outputs is in many cases impossible, because parallax causes the position shift to be dependent on the object distance. Therefore, in a smooth transition as disclosed herein, the position matching is achieved only in the ROI region while scale brightness and color are matched for the entire output image area.

10 Zoom-in and Zoom-out in video mode

In video mode, sensor oversampling is used to enable continuous and smooth zoom experience. Processing is applied to eliminate the changes in the image during crossover from one sub-camera to the other. Zoom from 1 to Z_{switch} is performed using the Wide sensor only.
15 From Z_{switch} and on, it is performed mainly by the Tele sensor. To prevent "jumps" (roughness in the image), switching to the Tele image is done using a zoom factor which is a bit higher (Z_{switch} +ΔZoom) than Z_{switch}. ΔZoom is determined according to the system's properties and is different for cases where zoom-in is applied and cases where zoom-out is applied (ΔZoom_{in}≠ ΔZoom_{out}). This is done to prevent residual jumps artifacts to be visible at a certain zoom factor. The switching between sensors, for an increasing zoom and for decreasing zoom, is done on a different zoom factor.

The zoom video mode operation includes two stages: (1) sensor control and configuration, and (2) image processing. In the range from 1 to Z_{switch}, only the Wide sensor is operational, hence, power can be supplied only to this sensor. Similar conditions hold for a
25 Wide AF mechanism. From Z_{switch}+ΔZoom to Z_{max} only the Tele sensor is operational, hence, power is supplied only to this sensor. Similarly, only the Tele sensor is operational and power is supplied only to it for a Tele AF mechanism. Another option is that the Tele sensor is operational and the Wide sensor is working in low frame rate. From Z_{switch} to Z_{switch}+ΔZoom, both sensors are operational.

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<u>Zoom-in</u>: at low ZF up to slightly above ZFT, the output image is the digitally zoomed, unchanged Wide camera output. For the up-transfer ZF, the output is a transformed Tele sub-camera output, where the transformation is performed by a global registration (GR) algorithm to achieve smooth transition. For higher (than the up-transfer), the output is the transfer ZF output digitally zoomed.

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Zoom-out: at high ZF down to slightly below ZFT, the output image is the digitally zoomed transformed Tele camera output. For the down-transfer ZF, the output is a shifted Wide camera output, where the Wide shift correction is performed by the GR algorithm to achieve smooth transition, i.e. with no jump in the ROI region. For lower (than the down-transfer) ZF, the output is basically the down-transfer ZF output digitally zoomed but with gradually smaller Wide shift correction, until for ZF=1 the output is the unchanged Wide camera output.

FIG. 6 shows an embodiment of a method disclosed herein for acquiring a zoom image in video/preview mode for 3 different zoom factor (ZF) ranges: (a) ZF range = 1 :
Z_{switch}; (b) ZF range = Z_{switch} : Z_{switch} + ΔZoom_{in}: and (c) Zoom factor range = Z_{switch} + ΔZoom_{in} : Z_{max}. The description is with reference to a graph of effective resolution vs. zoom value (FIG. 7). In step **602**, sensor control module **116** chooses (directs) the sensor (Wide, Tele or both) to be operational. Specifically, if the ZF range = 1:Z_{switch}, module **116** directs the Wide sensor to be operational and the Tele sensor to be non-operational. If the ZF range is
Z_{switch} : Z_{switch} + ΔZoom_{in}, module **116** directs both sensors to be operational and the zoom

- image is generated from the Wide sensor. If the ZF range is $Z_{switch} + \Delta Zoom_{in} : Z_{max}$, module **116** directs the Wide sensor to be non-operational and the Tele sensor to be operational. After the sensor choice in step **602**, all following actions are performed in video processing core **126**. Optionally, in step **604**, color balance is calculated if two images are provided by the
- two sensors. Optionally yet, in step 606, the calculated color balance is applied in one of the images (depending on the zoom factor). Further optionally, in step 608, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient can be used to set an AF position in step 610. In step 612, an output of any of steps 602-608 is applied on one of the images (depending on the zoom factor) for image signal processing that may include denoising, demosaicing, sharpening, scaling, etc. In step 614, the processed image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function 124) and the output video resolution (for example 1080p). To avoid a transition point to be executed at the same ZF, ΔZoom can change while

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In more detail, for ZF range 1 : Z_{switch} , for ZF < Z_{switch} , the Wide image data is transferred to the ISP in step **612** and resampled in step **614**. For ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$, both sensors are operational and the zoom image is generated from the Wide sensor. The color balance is calculated for both images according to a given ROI. In addition, for a given ROI, registration is performed between the Wide and Tele images to output a

zooming in and while zooming out. This will result in hysteresis in the sensor switching point.

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transformation coefficient. The transformation coefficient is used to set an AF position. The transformation coefficient includes the translation between matching points in the two images. This translation can be measured in a number of pixels. Different translations will result in a different number of pixel movements between matching points in the images. This movement

5 can be translated into depth and the depth can be translated into an AF position. This enables to set the AF position by only analyzing two images (Wide & Tele). The result is fast focusing.

Both color balance ratios and transformation coefficient are used in the ISP step. In parallel, the Wide image is processed to provide a processed image, followed by resampling. 10 For ZF range = $Z_{switch} + \Delta Zoom_{in} : Z_{max}$ and for Zoom factor > $Z_{switch} + \Delta Zoom_{in}$, the color balance calculated previously is now applied on the Tele image. The Tele image data is transferred to the ISP in step **612** and resampled in step **614**. To eliminate crossover artifacts and to enable smooth transition to the Tele image, the processed Tele image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function **124**) and the output video resolution (for example 1080p).

FIG. 7 shows the effective resolution as a function of the zoom factor for a zoom-in case and for a a zoom-out case $\Delta Zoom_{up}$ is set when we zoom in, and $\Delta Zoom_{down}$ is set when we zoom out. Setting $\Delta Zoom_{up}$ to be different from $\Delta Zoom_{down}$ will result in transition between the sensors to be performed at different zoom factor ("hysteresis") when zoom-in is used and when zoom-out is used. This hysteresis phenomenon in the video mode results in smooth continuous zoom experience.

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Optical Design

Additional optical design considerations were taken into account to enable reaching optical zoom resolution using small total track length (TTL). These considerations refer to the Tele lens. In an embodiment, the camera is "thin" (see also FIG. 1B) in the sense that is has an optical path of less than 9mm and a thickness/focal length (FP) ratio smaller than about 0.85. Exemplarily, as shown in FIG. 8, such a thin camera has a lens block that includes
(along an optical axis starting from an object) five lenses: a first lens element 802 with positive power and two lenses 804 and 806 and with negative power, a fourth lens 808 with positive power and a fifth lens 810 with negative power. In the embodiment of FIG. 8, the EFL is 7 mm, the TTL is 4.7 mm, f = 6.12 and FOV = 20⁰. Thus the Tele lens TTL/EFL ratio is smaller than 0.9. In other embodiments, the Tele lens TTL/EFL ratio may be smaller than 1.

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In another embodiment of a lens block in a thin camera, shown in FIG. 9, the camera has a lens block that includes (along an optical axis starting from an object) a first lens element **902** with positive power a second lens element **904** with negative power, a third lens element with positive power **906** and a fourth lens element with negative power **908**, and a fifth filed lens element **910** with positive or negative power. In this embodiment, f = 7.14, F# = 3.5, TTL = 5.8mm and FOV = 22.7⁰.

In conclusion, dual aperture optical zoom digital cameras and associate methods disclosed herein reduce the amount of processing resources, lower frame rate requirements, reduce power consumption, remove parallax artifacts and provide continuous focus (or provide loss of focus) when changing from Wide to Tele in video mode. They provide a dramatic reduction of the disparity range and avoid false registration in capture mode. They reduce image intensity differences and enable work with a single sensor bandwidth instead of two, as in known cameras.

All patent applications mentioned in this specification are herein incorporated in their entirety by reference into the specification, to the same extent as if each individual patent application was specifically and individually indicated to be incorporated herein by reference. In addition, citation or identification of any reference in this application shall not be construed as an admission that such reference is available as prior art to the present disclosure.

While this disclosure has been described in terms of certain embodiments and generally associated methods, alterations and permutations of the embodiments and methods will be apparent to those skilled in the art. The disclosure is to be understood as not limited by the specific embodiments described herein, but only by the scope of the appended claims.

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WHAT IS CLAIMED IS:

1. A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV), a Wide sensor and a Wide image signal processor (ISP), the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV, a Tele sensor and a Tele ISP, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to combine in still mode at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view and to provide without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution;

wherein the video output images are provided with a smooth transition when switching between a lower zoom factor (ZF) value and a higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor, and wherein at the higher ZF value the output resolution is determined by the Tele sensor.

2. The camera of claim 1, wherein the controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

3. The camera of claim 2, wherein the user inputs include a zoom factor, a camera mode and a region of interest (ROI).

4. The camera of claim 2, wherein the sensor control module has a setting that depends on the Wide and Tele fields of view and on a sensor oversampling ratio, the setting used in the configuration of each sensor.

5. The camera of claim 4, wherein the Wide and Tele FOVs and the sensor oversampling ratio satisfy the condition $0.8*PL_{wide}/PL_{video} < Tan (FOV_{wide})/Tan (FOV_{Tele}) < 1.2*PL_{Wide}/PL_{video}$, wherein PL_{wide} is an in-line number of Wide sensor pixels and wherein PL_{video} is an in-line number of output video format pixels.

6. The camera of claim 1, wherein the Tele lens includes a ratio of total length (TTL)/effective focal length (EFL) smaller than 1.

7. The camera of claim 5 wherein each lens includes five lens elements.

8. The camera of claim 6, wherein the five elements have, in order from the object side, positive-negative-negative-negative-positive-negative powers.

9. The camera of claim 6, wherein the five elements have, in order from the object side, positive-negative-positive-negative and positive or negative powers.

10. The camera of claim 1, wherein the camera controller configuration to provide video output images with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa includes a configuration that uses information either from the Wide sensor or from the Tele sensor.

11. The camera of claim 1, wherein the camera controller configuration to provide video output images with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa includes a configuration that uses at high ZF secondary information from the Wide camera and uses at low ZF secondary information from the Tele camera.

12. A method for obtaining zoom images of an object or scene in both still and video modes using a digital camera, the method comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV), a Wide sensor and a Wide image signal processor (ISP), a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV, a Tele sensor and a Tele ISP, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view, and to provide without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, wherein the video mode output images are provided with a smooth transition when switching between a lower zoom factor (ZF) value and a higher ZF value or vice versa, and wherein at the lower ZF value the output resolution is determined by the Wide sensor while at the higher ZF value the output resolution is determined by the Tele sensor.

13. The method of claim 12, wherein the step of configuring the camera controller to provide without fusion continuous zoom video mode output images of the object or scene includes configuring each sensor with a setting that depends on the Wide and Tele FOVs and on a sensor oversampling ratio.

14. The method of claim 13, wherein the Wide and Tele FOVs and the oversampling ratio satisfy the condition $0.8*PL_{wide}/PL_{video} < Tan (FOV_{wide})/Tan (FOV_{Tele}) < 1.2*PL_{wide}/PL_{video}$, wherein PL_{wide} is an inline number of Wide sensor pixels and PL_{video} is an in-line number of output video format pixels.

15. The method of claim 12, wherein the step of configuring the camera controller to provide without fusion continuous zoom video mode output images of the object or scene includes performing a registration between the Wide and Tele images to output a transformation coefficient and using the transformation coefficient to set an autofocus position.

16. The method of claim 12, wherein the smooth transition is obtained when zooming-in by switching between a lower ZF factor and a higher ZF factor at a first ZF value, and is obtained when zooming-out by switching between a higher ZF factor and a lower ZF factor at a second ZF value different from the first ZF value.

17. The method of claim 12, wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

18. The method of claim 12, wherein each lens has a different F number and wherein the step of configuring the camera controller to combine in still mode at least some of the Wide

and Tele image data to provide a fused output image includes configuring the camera controller to set an exposure time based on a ratio of the different F numbers.

19. The method of claim 12, wherein the step of wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to set two images with different intensities to provide a wide dynamic range image.

20. The method of claim 12, wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the two sensors to obtain the fused image using a single sensor bandwidth.

21. The method of claim 12, wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to synchronize the Wide and Tele sensors to force an overlap area in the object image to be exposed at the same time, wherein the synchronizing includes:

i. setting a Tele sensor vertical blanking time VB_{Tele} to equal a Wide sensor vertical blanking time VB_{Wide} plus half a Wide sensor rolling shutter time RST_{Wide} ,

ii. setting respective Tele and Wide sensor exposure times ET_{Tele} and ET_{Wide} to be equal,

iii. setting a Tele sensor rolling shutter time RST_{tele} to be RST_{Wide}/2, and

iv. setting frame rates of the two sensors to be equal.

22. The method of claim 12, wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to synchronize the Wide and Tele sensors to force the two sensors to start exposure at the same time.

<u>100</u>



FIG. 1A







FIG. 2







FIG. 4



FIG. 5







FIG. 7







FIG. 9

PATENT COOPERATION TREATY

From the INTERNATIONAL SEARCHING AUTHORITY

To: GAL SHABTAY NATHAN & ASSOCIATES PATENT AGENTS LTD. B O BOX 10170	РСТ
TEL-AVIV, 611010 ISRAEL	NOTIFICATION OF TRANSMITTAL OF THE INTERNATIONAL SEARCH REPORT AND THE WRITTEN OPINION OF THE INTERNATIONAL SEARCHING AUTHORITY, OR THE DECLARATION
	(PCT Rule 44.1)
	Date of mailing (day/month/year)
Applicant's or agent's file reference	
COREPH-0159	FOR FURTHER ACTION See paragraphs 1 and 4 below
International application No.	International filing date
PCT/IB2016/053803	(day/month/year) 26 June 2016
Applicant COREPHOTONICS LTD.	
 The applicant is hereby notified that the international s Authority have been established and are transmitted he Filing of amendments and statement under Article 1 The applicant is entitled, if he so wishes, to amend the When? The time limit for filing such amendments is n search report. How? Directly to the International Bureau of WIPO p 1211 Geneva 20, Switzerland, Facsimile No. For more detailed instructions, see PCT Applicant's The applicant is hereby notified that no international Article 17(2)(a) to that effect and the written opinion o With regard to any protest against payment of (an) ad the protest together with the decision thereon ha request to forward the texts of both the protest; the no decision has been made yet on the protest; the Reminders The applicant may submit comments on an informal basis of to the International Bureau. These comments will be ma International Bureau. If the applicant wishes to avoid or p application, or of the priority claim, must reach the International Bureau. If the applicant wishes to avoid or p application, or of the priority claim, must reach the International publication (Rules 90<i>bis</i>.1 and 90<i>bis</i>.3). Within 19 months from the priority date, but only in respect of time imit of 30 months (or later); otherwise, the applicant ma out by a different International Searching Authority that of supplementary international search is described in the PCT A 	earch report and the written opinion of the International Searching rewith. 9: claims of the international application (see Rule 46): ormally two months from the date of transmittal of the international referably through ePCT or on paper to, 34 chemin des Colombettes : +41 22 338 82 70 Guide, International Phase, paragraphs 9.004 – 9.011. search report will be established and that the declaration under f the International Searching Authority are transmitted herewith. Iditional fee(s) under Rule 40.2, the applicant is notified that: us been transmitted to the International Bureau together with any d the decision thereon to the designated Offices. e applicant will be notified as soon as a decision is made. on the written opinion of the International Searching Authority ade available to the public after international publication. The s to all designated Offices unless an international preliminary ty date, the international application will be published by the postpone publication, a notice of withdrawal of the international mal Bureau before the completion of the technical preparations for of some designated Offices. In respect of other designated Offices, the in ust, within 20 months from the priority date, perform the use designated Offices. In respect of other designated Offices, the ind is filed within 19 months. For details about the applicable time limits.html and the <i>PCT Applicant's Guide</i> , National Chapters. y request that a supplementary international search be carried offers this service (Rule 45bis.1). The procedure for requesting <i>Applicant's Guide</i> , International Phase, paragraphs 8.006-8.032.
Name and mailing address of the ISA/ Mail Stop PCT Atta: ISA/	Authorized officer
Commissioner for Patents D Boy 1450, Alexandria, VA 20010, 4450	Blaine R. Copenheaver
Facsimile No. 571-273-8300	PCT Holpdesk: 571-272-4300 Telephone No. PCT OSP: 571-272-7774
DOWNALLAND	

Form PCT/ISA/220 (July 2014)

INTERNATIONAL SEARCH REPORT

International application No.

PCT/IB2016/053803

r				
 A. CLASSIFICATION OF SUBJECT MATTER IPC(8) - H04N 5/262; G02B 15/00; G06T 5/50 (2016.01) CPC - H04N 5/262; G02B 15/00; G06T 5/50 (2016.08) According to International Patent Classification (IPC) or to both national classification and IPC 				
B. FIEL	DS SEARCHED			
Minimum d	ocumentation searched (classification system followed by	classification symbols)		
IPC - G02B CPC - G02B	15/00; G06T 5/50; H04N 5/262 15/00; G06T 5/50; H04N 5/262			
Documentat USPC - 348/	ion searched other than minimum documentation to the ex 218.1; 348/240.2; 348/240.3; 359/691 (keyword delimite	ctent that such documents are included in the	fields searched	
Electronic d	ata base consulted during the international search (name c	of data base and, where practicable search te	rms used)	
Patbase, Go Search term:	ogle Patents, Google s used: dual aperture, tele, wide, no-switching criterion			
C. DOCU	MENTS CONSIDERED TO BE RELEVANT			
Category*	Citation of document, with indication, where a	ppropriate, of the relevant passages	Relevant to claim No.	
Y	WO 2014/199338 A2 (COREPHOTONICS LTD.) 18 D document	1-21		
Y	US 2003/0179303 A1 (BITTNER) 25 September 2003 (25.09.2003) entire document			
Y	US 8,401,276 B1 (CHOE et al) 19 March 2013 (19.03.	3, 15		
А	US 2009/0102950 A1 (AHISKA) 23 April 2009 (23.04.2009) entire document		1-21	
A	US 2008/0030592 A1 (BORDER et al) 07 February 2008 (07.02.2008) entire document		1-21	
А	US 6,104,432 A (NAKAMURA et al) 15 August 2000 (15.08.2000) entire document		1-21	
А	US 5,710,670 A (OHNO) 20 January 1998 (20.01.1998) entire document		1-21	
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Furthe	er documents are listed in the continuation of Box C.	See patent family annex.		
 Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance 		"T" later document published after the inter date and not in conflict with the appli- the principle or theory underlying the	national filing date or priority ation but cited to understand invention	
"E" earlier a filing d "L" docume	application or patent but published on or after the international ate ent which may throw doubts on priority claim(s) or which is	"X" document of particular relevance; the considered novel or cannot be consid step when the document is taken alone	claimed invention cannot be ered to involve an inventive	
cited to special	establish the publication date of another citation or other reason (as specified)	"Y" document of particular relevance; the considered to involve an investiga	claimed invention cannot be	
"O" document referring to an oral disclosure, use, exhibition or other means		combined with one or more other such being obvious to a person skilled in th	documents, such combination	
"P" document published prior to the international filing date but later than the priority date claimed		"&" document member of the same patent family		
Date of the a	actual completion of the international search	Date of mailing of the international sear	ch report	
05 October 2	2016	260CT 2016		
Name and m	nailing address of the ISA/	Authorized officer		
P.O. Box 145	50, Alexandria, VA 22313-1450	Blaine R. Copenheaver		
Facsimile N	0. 571-273-8300	PCT OSP: 571-272-7774		

Form PCT/ISA/210 (second sheet) (January 2015)

PATENT COOPERATION TREATY

From the INTERNATIONAL SEARCHING AUTHO	RITY		
To: GAL SHABTAY NATHAN & ASSOCIATES PATENT AGENTS LTD. P.O. BOX 10178 TEL-AVIV, 611010 ISRAEL		WR INTERNATI	PCT ITTEN OPINION OF THE ONAL SEARCHING AUTHORITY (PCT Rule 43 <i>bis.</i> 1)
		Date of mailing (day/month/year)	260CT 2016
Applicant's or agent's file reference COREPH-0159		FOR FURTHER ACTION See paragraph 2 below	
International application No	International filing date	(day/month/sear)	Priority data (day/month/page)
PCT/IB2016/053803	26 June 2016	(auy/monanyear)	13 August 2015
International Patent Classification (IPC) or IPC(8) - H04N 5/262; G02B 15/00 CPC - H04N 5/262; G02B 15/00	r both national classifica ; G06T 5/50 (2016.0 ; G06T 5/50 (2016.0	tion and IPC)1))8)	
Applicant COREPHOTONICS LTD.			
1. This opinion contains indications relating to the following items:			
Name and mailing address of the ISA/ Mail Stop PCT, Attn: ISA/US Commissioner for Patents P.O. Box 1450, Alexandria, VA 22212, 1450	Date of completion of t 05 October 2016	his opinion	Authorized officer Blaine R. Copenheaver
Facsimile No. 571-273-8300			PCT Helpdesk: 571-272-4300 PCT OSP: 571-272-7774

Form PCT/ISA/237 (cover sheet) (January 2015)

	International	application No.
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INTERNATIONAL SEARCHING AUTHORITY	PCT/IB2016/053803
Box No. 1 Basis of this opinion	······································
1. With regard to the language, this opinion has been established on the basis of:	
the international application in the language in which it was filed.	
a translation of the international application into furnished for the purposes of international search (Rules 12.3(a) and 23.	which is the language of a translation 1(b)).
2. This opinion has been established taking into account the rectification of this Authority under Rule 91 (Rule 43 <i>bis</i> .1(a)).	an obvious mistake authorized by or notified to
3. With regard to any nucleotide and/or amino acid sequence disclosed is been established on the basis of a sequence listing:	in the international application, this opinion has
a. forming part of the international application as filed:	
in the form of an Annex C/ST.25 text file.	
on paper or in the form of an image file.	
b. furnished together with the international application under PCT is search only in the form of an Annex C/ST.25 text file.	Rule 13ter 1(a) for the purposes of international
c. furnished subsequent to the international filing date for the purpo	oses of international search only:
in the form of an Annex C/ST.25 text file (Rule 13ter.1(a))).
on paper or in the form of an image file (Rule 13 <i>ter</i> .1(b) and	nd Administrative Instructions, Section 713).
 4. In addition, in the case that more than one version or copy of a sequence statements that the information in the subsequent or additional copies is in filed or does not go beyond the application as filed, as appropriate, were 5. Additional commentation 	e listing has been filed or furnished, the required dentical to that forming part of the application as furnished.
5. Additional comments:	

Form PCT/ISA/237 (Box No. I) (January 2015)

WRITTEN OPINION OF THE INTERNATIONAL SEARCHING AUTHORITY		PCT/B2016/053803	
Box No. V Reasoned statement under Rule 43 <i>bis</i> .1(a)(i) with regard to novelty, inventive step and industrial applicabi citations and explanations supporting such statement			
1. Statement			
Novelty (N)	Claims	1-21	YES
	Claims	None	NO
Inventive step (IS)	Claims	None	YES
Claims	Claims	1-21	NO
Industrial applicability (IA)	Claims	1-21	YES
	Claims	None	NO

2. Citations and explanations:

Claims 1, 2, 4-14, and 16-21 lack an inventive step under PCT Article 33(3) as being obvious over Corephotonics Ltd. (hereinafter Corephotonics) in view of Bittner.

Regarding Claim 1, Corephotonics discloses a zoom digital camera (abstract) comprising: a) a Wide imaging section (camera 100 comprises a wide imaging section, page 7, lines 28-34; wide imaging section, page 5, lines 17-34) that includes a fixed focal length Wide lens with a Wide field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide Field of view (wide lens 17-34) and a Wide sensor (wide image sensor 104, page 7, lines 28-34; a Wide sensor, page 5, lines a contract of the boot section (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length wide lens with a Wide Field of view (wide lens wide lens wide length wide leng With a Wide FOV, page 5, lines 17-34) and a Wide sensor (Wide image sensor 104, page 7, lines 28-34; a wide sensor, page 5, lines 17-34), the Wide imaging section operative to provide Wide imaging section operative to provide Wide image data of an object or scene (fig. 1A shows arrangement of camera 100 with wide lens 102, wide sensor 104, wide ISP 106; the Wide imaging section operative to provide Wide image data of an object or scene, page 5, lines 17-34); b) a Tele imaging section (camera 100 further comprises a Tele imaging section, page 7, lines 28-34; a Tele imaging section, page 5, lines 17-34); b) a Tele imaging section (camera 100 further comprises a Tele imaging section, page 7, lines 28-34; a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV (Tele lens block 108, page 7, lines 28-34; a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV, page 5, lines 17-34) that is narrower than the Wide FOV (as shown, the Tele sensor FOV is half the Wide sensor FOV, page 9, lines 30-36; a Tele FOV that is narrower than the Wide FOV, page 5, lines 17-34) and a Tele sensor (Tele image sensor 110, page 7, lines 28-34; a Tele sensor, page 5, lines 17-34), the Tele imaging section of the object or scene (fig. 1A shows arrangement of camera 100 with Tele lens 108, Tele sensor operative to provide Tele image data of the object or scene (fig. 1A shows arrangement of camera 100 with Tele lens 108, Tele sensor 110, Tele ISP 112; the Tele imaging section operative to provide Tele image data of the object or scene, page 5, lines 17-34); and c) a camera controller (camera 100 further comprises a camera fusion processing core, also referred to as controller, 114 that includes a sensor control module 116, user control module 118, video processing module 126, and capture processing module 128, page 8, lines 1-6; a camera controller, page 5, lines 17-34) operatively coupled to the Wide and Tele imaging sections (controller 114 is operationally coupled to sensor control block 110, page 8, lines 1-6; a camera controller operatively coupled to the Wide and Tele imaging sections, page 5, lines 17-34), the camera controller configured to evaluate a criterion determined by inputs from both Wide and Tele image data (the camera controller configured to combine in still mode at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view to provide without fusion continuous zoom video mode output images of the object or scene, page 5, lines 17-34), and, if the criterion is fulfilled, to output a zoom video output image that includes Wide image data in a zoom-in operation between a lower zoom factor value and a higher ZF value (wherein the video output images are provided with a smooth Transition when switching between a lower zoom factor value and a higher zoom factor value, page 5, lines 17-34; the camera controller configuration to provide video output images with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa includes a configuration that uses a high ZF secondary information from the Wide camera and uses a low ZF secondary information from the Tele camera, page 6, lines 2-7); but lacks the explicit teaching of a no-switching criterion; zoom video output image that includes only Wide image data in a zoom-in operation. Bitther is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images: the processor 40 controls the digital zoom operation. on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]); zoom video output image (to capture the scene, the user actuates an image capture button 65 and the processor 40 causes the opto-digitally enhanced scene to be stored in non-volatile memory 45, para. 23) that includes only Wide image data in a zoom-in operation (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [before switching to normal lens 25, wide angle lens is digitally zoomed by processor 40 and the image that is output is from wide-angle lens in a zoom-in operation]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the zoom video output image that includes only Wide image data in a zoom-in operation of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16).

Regarding Claim 13, Corephotonics discloses a method (method, page 4, lines 31-34; claim 12) for obtaining zoom images of an object or scene using a digital camera (abstract), comprising the steps of: a) providing in the digital camera a Wide imaging section (camera 100 comprises a wide imaging section, page 7, lines 28-34; wide imaging section, page 5, lines 17-34) having a Wide lens with a Wide field of view (wide lens block 102, page 7, lines 28-34; wide imaging section that includes a fixed focal length Wide lens with a Wide FOV, page 5, lines 17-34) and a Wide sensor (wide image sensor 104, page 7, lines 28-34; a Wide sensor, page 5, lines 17-34), a Tele imaging section

Form PCT/ISA/237 (Box No. V) (January 2015)

International application No.

PCT/IB2016/053803

Supplemental Box

In case the space in any of the preceding boxes is not sufficient.

Continuation of:

(camera 100 further comprises a Tele imaging section, page 7, lines 28-34; a Tele imaging section, page 5, lines 17-34) having a Tele lens with a Tele FOV (Tele lens block 108, page 7, lines 28-34; a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV, page 5, lines 17-34) that is narrower than the Wide FOV (as shown, the Tele sensor FOV is half the Wide sensor FOV, page 9, lines 30-36; a Tele FOV that is narrower than the Wide FOV, page 5, lines 17-34) and a Tele sensor (Tele image sensor 110, page 7; lines 28-34; a Tele sensor, page 5, lines 17-34), and a camera controller (camera 100 further comprises a camera fusion processing core, also referred to as controller, 114 that includes a sensor control module 116, user control module 118, video processing module 126, and capture processing module 128, page 8, lines 1-6; a camera controller, page 5, lines 17-34) operatively coupled to the Wide and Tele imaging sections (controller 114 is operationally coupled to sensor control block 110, page 8, lines 1-6; a camera controller operatively coupled to the Wide and Tele imaging sections, page 5, lines 17-34); and b) configuring the camera controller to evaluate a criterion determined by inputs from both Wide and Tele image data (the camera controller configured to combine in still mode at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view to provide without fusion continuous zoom video mode output images of the object or scene, page 5, lines 17-34), and, if the criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value (wherein the video output images are provided with a smooth transition when switching between a lower zoom factor and a higher zoom factor value, page 5, lines 17-34; the camera controller configuration to provide video output images with a smooth transition when switching between a lower ZF value and a higher ZF value or vice versa includes a configuration that uses a high ZF secondary information from the Wide camera and uses a low ZF secondary information from the Tele camera, page 6, lines 2-7); but lacks the explicit teaching of a no-switching criterion. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the zoom video output image that includes only Wide image data in a zoom-in operation of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16).

Regarding Claims 2, 14, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, and further teaches a shift between the Wide and Tele images calculated by global registration (at low ZF up to slightly above ZFT, the output image is a digitally zoomed, Wide fusion output; for the up-transfer ZF, the Tele image is shifted and corrected by global registration to achieve smooth transition, page 13, lines 10-14); but lacks the teaching wherein the no-switching criterion includes a shift being greater than a first threshold. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]) includes a shift being greater than a first threshold (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [switch happens at predetermined threshold]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the no-switching criterion of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16).

Regarding Claims 4, 16, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, but lacks the teaching wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]) includes an effective resolution of a first zoom being lower than an effective resolution of a second zoom (zooming is accomplished without the degradation that could occur at high powers of digital zoom, para. 7). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the zoom video output image that includes only Wide image data in a zoom-in operation of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16).

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Regarding Claims 5, 17, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, and further teaches a criterion includes a number of corresponding features in the Wide and Tele images (the sensor control module has a setting that depends on the Wide and Tele fields of view, claim 4; claim 10, 11); but lacks the teaching wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the no-switching criterion of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16). Modified Corephotonics lacks the explicit teaching of features being smaller than a third threshold. However, it would have been obvious to one of ordinary skill in the art at the time of the invention to have the no-switching criterion include a number of corresponding features in the Wide and Tele images that are smaller than a third threshold, since, where the prior art has shown computations that use settings dependent upon information from the field of view, discovering the optimum or workable ranges involves only routine skill in the art. The motivation would have been to allow a desired amount or level of accuracy, smoothness, scale, or resolution, as was known in the optical or camera arts.

Regarding Claims 6, 18, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, and further teaches a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera (configuring the camera controller to synchronize the Wide and Tele sensors to force an overlap area in the object image to be exposed at the same time, claim 21; page 4, lines 22-30; performing a registration between the Wide and Tele images to output a transformation coefficient and using the transformation coefficient to set an autofocus position, claim 15; [to calculate autofocus position, camera needs to calculate distance of objects in Wide, Tele images]); but lacks the teaching of the no-switching criterion; closer to the camera than a first threshold distance. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the no-switching cirterion of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16). Modified Corephotonics lacks the explicit teaching of closer to the camera than a first threshold distance. However, it would have been obvious to one of ordinary skill in the art at the time of the invention to have the no-switching criterion include a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance, since, where the prior art has shown computations that use settings dependent upon information from the field of view, discovering the optimum or workable ranges involves only routine skill in the art. The motivation would have been to allow a desired amount or level of accuracy, smoothness, scale, or resolution, as was known in the optical or camera arts.

Regarding Claims 7, 19, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, and further teaches some of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther (configuring the camera controller to synchronize the Wide and Tele sensors to force an overlap area in the object image to be exposed at the same time, claim 21; page 4, lines 22-30; performing a registration between the Wide and Tele images to output a transformation coefficient and using the transformation coefficient to set an autofocus position, claim 15; [to calculate autofocus position, camera needs to calculate distance of objects in Wide, Tele images]); but lacks the teaching of the no-switching criterion; closer than a second threshold distance; farther than a third distance threshold. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming ` operation]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the no-switching cirterion of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16). Modified Corephotonics lacks the explicit teaching of closer than a second threshold distance; farther than a third distance threshold. However, it would have been obvious to one of ordinary skill in the art at the time of the invention to have the no-switching criterion include some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold, since, where the prior art has shown computations that use settings dependent upon information from the field of view, discovering the optimum or workable ranges involves only routine skill in the art. The motivation would have been to allow a desired amount or level of accuracy, smoothness, scale, or resolution, as was known in the optical or camera arts.

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Regarding Claim 9, Corephotonics discloses the camera of claim 8, wherein the user inputs include a zoom factor (user zoom factor request, page 4, lines 22-30), a camera mode and a region of interest (the user inputs include a zoom factor, a camera mode, and a region of interest, claim 3; camera mode, page 8, lines 29-31; region of interest function 122, page 8, lines 1-18).

Regarding Claim 10, Corephotonics discloses the camera of claim 1, teaches the Tele lens includes a ratio of total track length (TTL = 6mm, page 8, lines 19-23) to effective focal length (EFL = 7mm, page 8, lines 19-23) smaller than 1 (page 8, lines 19-23; claim 6; [6/7 is less than 1]).

Regarding Claim 11, Corephotonics discloses the camera of claim 1, wherein, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor (wherein the video output images are provided with a smooth transition when switching between a lower zoom factor value and a higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor and wherein at the higher ZF value to vice versa, wherein at the lower ZF value the output resolution is determined by the Tele sensor (claim 1).

Regarding Claims 12, 20, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view (wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine in still mode and Tele image data only in focused areas, claim 17).

Regarding Claim 21, modified Corephotonics discloses the method of claim 13, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas (wherein the step of configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine in still mode at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas, claim 17).

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Claims 3 and 15 lack an inventive step under PCT Article 33(3) as being obvious over Corephotonics Ltd. (hereinafter Corephotonics) in view of Bittner and Choe et al. (hereinafter Choe).

Regarding Claims 3, 15, Corephotonics discloses the camera of claim 1, the method of claim 13, respectively, and further teaches a disparity range (they provide a dramatic reduction of the disparity range, page 17, lines 7-13); global registration (global registration, page 13, lines 10-14; performing a registration between the Wide and Tele images to output a transformation coefficient, claim 15); but lacks the teaching wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold. Bittner is in the field of image capture devices which perform a combination of digital and optical zoom techniques (abstract) and teaches a no-switching criterion (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [prior to activation of switching element 50, wide-angle lens 20 undergoes a zooming operation]); and further teaches a no-switching criterion includes a value being greater than a threshold (the image capture device 10 includes two lenses/groups, of which one is a wide angle lens 20 and one is a normal lens 25, para. 17; the wide angle lens group 20 is initially placed on the optical axis A; the processor 40 controls the capture and processing of images; the processor 40 controls the digital zoom operation when the user activates the external zoom switch 60; at a predetermined point in the digital zoom process, the processor 40 causes a switching element 50 to switch the normal lens 25 into optical axis A and restarts the digital zoom, para. 18; [switching operations happens at predetermined threshold]). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the no-switching criterion of Bittner in the zoom digital camera of Corephotonics. The motivation would have been to allow some moderate digital zooming which will not unacceptably deteriorate the image quality of an image capture system using a wide angle lens and a normal lens (Bittner, para. 16). Modified Corephotonics lacks the explicit teaching of a disparity range calculated by global registration, the disparity range being greater than a second threshold. Choe is in the field of accessing multiple different images of an object taken by one or more cameras (abstract) and teaches a disparity range calculated by global registration (a first bundle adjustment can determine initial camera positions in metric space; for input to a second bundle adjustment, the technique can select two images and can generate a dense disparity map between the pair, some implementations can compute the epipolar geometry between these two images using a plane + parallax approach, and can use mutual information for a matching criteria; some implementations can select a pair of images with the lowest 2-D registration error, col. 5, lines 23-35). It would have been obvious to one of ordinary skill in the art at the time of the invention to use the disparity range of Choe in the camera of Corephotonics. The motivation would have been to allow the use of desired calculations, especially which take into account associated errors (Choe, col. 5, lines 23-35). Modified Corephotonics lacks the explicit teaching that the disparity range is greater than a second threshold. However, it would have been obvious to one of ordinary skill in the art at the time of the invention to use a disparity range greater than a second threshold for the no-switching criterion, since, since, where the prior art has shown computations that use settings dependent upon information from the field of view, discovering the optimum or workable ranges involves only routine skill in the art. The motivation would have been to allow a desired amount or level of accuracy, smoothness, scale, or resolution, as was known in the optical or camera arts.

Claims 1-21 meet the criteria set out in PCT Article 33(4), and thus have industrial applicability because the subject matter claimed can be made or used in industry.

ASSIGNMENT

For good and valuable consideration, the receipt and sufficiency of which is hereby acknowledged, the undersigned:

NOY COHEN ODED GIGUSHINSKI NADAV GEVA

GAL SHABTAY ESTER ASHKENAZI RUTHY KATZ

EPHRAIM GOLDENBERG

(hereinafter called the "assignor(s)"), hereby sell(s), assign(s) and transfer(s) to:

Corephotonics Ltd. 25 Habarzel St. Ramat Hachayal Tel-Aviv, 6971035 Israel

(hereinafter called the "assignee(s)"), its/his successors, assignees, nominees or other legal representatives, the Assignor's entire right, title and interest in and to the invention entitled:

DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

described and claimed in the following National Phase Application No. 15/324,720 identified as Attorney docket No. COREPH-0159 US NP filed 01-08-2017;

and in and to said Patent Applications, and all original and reissued Patents granted therefor, and all divisions and continuations thereof, including the right to apply and obtain Patents in all other countries, the priority rights under International Conventions, and the Letters Patent which may be granted thereon;

/Noy Cohen /

/ Oded GigushinskI /

/ Nadav Geva /____

/ Gal Shabtay /

Signed and sealed this 8 day of January, 2017

NOY COHEN

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DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

5 FIELD

Embodiments disclosed herein relate in general to digital cameras and in particular to zoom digital cameras with video capabilities

10 BACKGROUND

Digital camera modules are currently being incorporated into a variety of host devices. Such host devices include cellular telephones, personal data assistants (PDAs), computers, and so forth. Consumer demand for digital camera modules in host devices continues to grow.

15 Host device manufacturers prefer digital camera modules to be small, so that they can be incorporated into the host device without increasing its overall size. Further, there is an increasing demand for such cameras to have higher-performance characteristics. One such characteristic possessed by many higher-performance cameras (e.g., standalone digital still cameras) is the ability to vary the focal length of the camera to increase and decrease the magnification of the image. This ability, typically accomplished with a zoom lens, is known 20 as optical zooming. "Zoom" is commonly understood as a capability to provide different magnifications of the same scene and/or object by changing the focal length of an optical system, with a higher level of zoom associated with greater magnification and a lower level of zoom associated with lower magnification. Optical zooming is typically accomplished by 25 mechanically moving lens elements relative to each other. Such zoom lenses are typically more expensive, larger and less reliable than fixed focal length lenses. An alternative approach for approximating the zoom effect is achieved with what is known as digital zooming. With digital zooming, instead of varying the focal length of the lens, a processor in the camera crops the image and interpolates between the pixels of the captured image to create a magnified but lower-resolution image. 30

Attempts to use multi-aperture imaging systems to approximate the effect of a zoom lens are known. A multi-aperture imaging system (implemented for example in a digital camera) includes a plurality of optical sub-systems (also referred to as "sub-cameras"). Each sub-camera includes one or more lenses and/or other optical elements which define an aperture such that received electro-magnetic radiation is imaged by the optical sub-system and a resulting image is directed towards a two-dimensional (2D) pixelated image sensor region. The image sensor (or simply "sensor") region is configured to receive the image and to generate a set of image data based on the image. The digital camera may be aligned to receive

⁵ electromagnetic radiation associated with scenery having a given set of one or more objects. The set of image data may be represented as digital image data, as well known in the art. Hereinafter in this description, "image" "image data" and "digital image data" may be used interchangeably. Also, "object" and "scene" may be used interchangeably. As used herein, the term "object" is an entity in the real world imaged to a point or pixel in the image.

Multi-aperture imaging systems and associated methods are described for example in US Patent Publications No. 2008/0030592, 2010/0277619 and 2011/0064327. In US 2008/0030592, two sensors are operated simultaneously to capture an image imaged through an associated lens. A sensor and its associated lens form a lens/sensor combination. The two lenses have different focal lengths. Thus, even though each lens/sensor combination is aligned to look in the same direction, each captures an image of the same subject but with two different fields of view (FOVs). One sensor is commonly called "Wide" and the other "Tele". Each sensor provides a separate image, referred to respectively as "Wide" (or "W") and "Tele" (or "T") images. A W-image reflects a wider FOV and has lower resolution than the T-image. The images are then stitched (fused) together to form a composite ("fused") image. In
the composite image, the central portion is formed by the relatively higher-resolution image

taken by the lens/sensor combination with the longer focal length, and the peripheral portion is formed by a peripheral portion of the relatively lower-resolution image taken by the lens/sensor combination with the shorter focal length. The user selects a desired amount of zoom and the composite image is used to interpolate values from the chosen amount of zoom
to provide a respective zoom image. The solution offered by US 2008/0030592 requires, in video mode, very large processing resources in addition to high frame rate requirements and high power consumption (since both cameras are fully operational).

US 2010/0277619 teaches a camera with two lens/sensor combinations, the two lenses having different focal lengths, so that the image from one of the combinations has a FOV approximately 2-3 times greater than the image from the other combination. As a user of the camera requests a given amount of zoom, the zoomed image is provided from the lens/sensor combination having a FOV that is next larger than the requested FOV. Thus, if the requested FOV is less than the smaller FOV combination, the zoomed image is created from the image captured by that combination, using cropping and interpolation if necessary. Similarly, if the

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requested FOV is greater than the smaller FOV combination, the zoomed image is created from the image captured by the other combination, using cropping and interpolation if necessary. The solution offered by US 2010/0277619 leads to parallax artifacts when moving to the Tele camera in video mode.

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In both US 2008/0030592 and US 2010/0277619, different focal length systems cause Tele and Wide matching FOVs to be exposed at different times using CMOS sensors. This degrades the overall image quality. Different optical F numbers ("F#") cause image intensity differences. Working with such a dual sensor system requires double bandwidth support, i.e. additional wires from the sensors to the following HW component. Neither US 2008/0030592 nor US 2010/0277619 deal with registration errors.

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US 2011/0064327 discloses multi-aperture imaging systems and methods for image data fusion that include providing first and second sets of image data corresponding to an imaged first and second scene respectively. The scenes overlap at least partially in an overlap region, defining a first collection of overlap image data as part of the first set of image data, and a second collection of overlap image data as part of the second set of image data. The second collection of overlap image data is represented as a plurality of image data sub-cameras such that each of the sub-cameras is based on at least one characteristic of the second

collection, and each sub-camera spans the overlap region. A fused set of image data is produced by an image processor, by modifying the first collection of overlap image data
based on at least a selected one of, but less than all of, the image data sub-cameras. The systems and methods disclosed in this application deal solely with fused still images.

None of the known art references provide a thin (e.g. fitting in a cell-phone) dualaperture zoom digital camera with fixed focal length lenses, the camera configured to operate in both still mode and video mode to provide still and video images, wherein the camera configuration does not use any fusion to provide a continuous, smooth zoom in video mode.

Therefore there is a need for, and it would be advantageous to have thin digital cameras with optical zoom operating in both video and still mode that do not suffer from commonly encountered problems and disadvantages, some of which are listed above.

30 SUMMARY

Embodiments disclosed herein teach the use of dual-aperture (also referred to as duallens or two-sensor) optical zoom digital cameras. The cameras include two sub-cameras, a Wide sub-camera and a Tele sub-camera, each sub-camera including a fixed focal length lens, an image sensor and an image signal processor (ISP). The Tele sub-camera is the higher zoom sub-camera and the Wide sub-camera is the lower zoom sub-camera. In some embodiments, the thickness/effective focal length (EFL) ratio of the Tele lens is smaller than about 1. The image sensor may include two separate 2D pixelated sensors or a single pixelated sensor

divided into at least two areas. The digital camera can be operated in both still and video modes. In video mode, optical zoom is achieved "without fusion", by, in some embodiments, switching between the W and T images to shorten computational time requirements, thus enabling high video rate. To avoid discontinuities in video mode, the switching includes applying additional processing blocks, which include in some embodiments image scaling and
shifting. In some embodiments, when a no-switching criterion is fulfilled, optical zoom is achieved in video mode without switching.

As used herein, the term "video" refers to any camera output that captures motion by a series of pictures (images), as opposed to "still mode" that friezes motion. Examples of "video" in cellphones and smartphones include "video mode" or "preview mode".

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In order to reach optical zoom capabilities, a different magnification image of the same scene is captured (grabbed) by each camera sub-camera, resulting in FOV overlap between the two sub-cameras. Processing is applied on the two images to fuse and output one fused image in still mode. The fused image is processed according to a user zoom factor request. As part of the fusion procedure, up-sampling may be applied on one or both of the grabbed images to scale it to the image grabbed by the Tele sub-camera or to a scale defined by the user. The fusion or up-sampling may be applied to only some of the pixels of a sensor. Down-sampling can be performed as well if the output resolution is smaller than the sensor resolution.

The cameras and associated methods disclosed herein address and correct many of the problems and disadvantages of known dual-aperture optical zoom digital cameras. They provide an overall zoom solution that refers to all aspects: optics, algorithmic processing and system hardware (HW).

In a dual-aperture camera image plane, as seen by each sub-camera (and respective image sensor), a given object will be shifted and have different perspective (shape). This is referred to as point-of-view (POV). The system output image can have the shape and position of either sub-camera image or the shape or position of a combination thereof. If the output image retains the Wide image shape then it has the Wide perspective POV. If it retains the Wide camera position then it has the Wide position POV. The same applies for Tele images position and perspective. As used in this description, the perspective POV may be of the Wide or Tele sub-cameras, while the position POV may shift continuously between the Wide and Tele sub-cameras. In fused images, it is possible to register Tele image pixels to a matching pixel set within the Wide image pixels, in which case the output image will retain the Wide POV ("Wide fusion"). Alternatively, it is possible to register Wide image pixels to a matching

- 5 pixel set within the Tele image pixels, in which case the output image will retain the Tele POV ("Tele fusion"). It is also possible to perform the registration after either sub-camera image is shifted, in which case the output image will retain the respective Wide or Tele perspective POV.
- In an embodiment, there is provided a zoom digital camera comprising a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene, a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene, and a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.
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In an embodiment there is provided a method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of providing in the digital camera a Wide imaging section having a Wide lens with a Wide FOV and a Wide sensor, a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections, and configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF value and a higher ZF value.

30 BRIEF DESCRIPTION OF THE DRAWINGS

Non-limiting examples of embodiments disclosed herein are described below with reference to figures attached hereto that are listed following this paragraph. Identical structures, elements or parts that appear in more than one figure are generally labeled with a same numeral in all the figures in which they appear. The drawings and descriptions are meant to illuminate and clarify embodiments disclosed herein, and should not be considered limiting in any way.

FIG. 1A shows exemplary feature points in an object;

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FIG. 1B shows schematically a block diagram illustrating a dual-aperture zoom imaging system disclosed herein;

FIG. 1C is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A:

FIG. 2 shows an example of Wide sensor, Tele sensor and their respective FOVs;

FIG. 3 shows an embodiment of a method disclosed herein for acquiring a zoom image in video/preview mode;

FIG. 4 shows a graph illustrating an effective resolution zoom factor.

DETAILED DESCRIPTION

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Definitions:

Sharpness score: the gradients (dx, dy) of the image are compared (subtraction) to the gradients of its low pass filtered version. A higher difference indicates a sharper original image. The result of this comparison is normalized with respect to the average variations (for example, sum of absolute gradients) of the original image, to get an absolute sharpness score.

Edge score: for each image, the edges are found (for example, using Canny edge detection) and the average intensity of gradients along them is calculated, for example, by calculating the magnitude of gradients (dx, dy) for each edge pixel, summing the results together and dividing by the total number of edge pixels. The result is the edge score.

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<u>Resolution metric</u>: is calculated only on a region of interest (ROI) and gives a good indication of the effective resolution level in the image. As used herein, "ROI" is a user defined sub-region of the image that may be exemplarily 4% or less of the image area. The effective resolution score can be derived from a combination of the sharpness and edge scores for each image, for example by normalizing both to be between [0, 1] and by taking their average.

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FIG. 1C shows schematically a block diagram illustrating an embodiment of a dualaperture zoom imaging system (also referred to simply as "digital camera" or "camera") disclosed herein and numbered **100**. Camera **100** comprises a Wide imaging section ("subcamera") that includes a Wide lens block **102**, a Wide image sensor **104** and a Wide image processor 106. Camera 100 further comprises a Tele imaging section ("sub-camera") that includes a Tele lens block 108, a Tele image sensor 110 and a Tele image processor 112. The image sensors may be physically separate or may be part of a single larger image sensor. The Wide sensor pixel size can be equal to or different from the Tele sensor pixel size. Camera

5 100 further comprises a camera fusion processing core (also referred to as "controller") 114 that includes a sensor control module 116, a user control module 118, a video processing module 126 and a capture processing module 128, all operationally coupled to sensor control block 110. User control module 118 comprises an operational mode function 120, a ROI function 122 and a zoom factor (ZF) function 124.

Sensor control module 116 is connected to the two sub-cameras and to the user control module 118 and used to choose, according to the zoom factor, which of the sensors is operational and to control the exposure mechanism and the sensor readout. Mode choice function 120 is used for choosing capture/video modes. ROI function 122 is used to choose a region of interest. The ROI is the region on which both sub-cameras are focused on. Zoom factor function 124 is used to choose a zoom factor. Video processing module 126 is connected to mode choice function 120 and used for video processing. It is configurable to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data and to make a decision regarding video output. Specifically, upon evaluation of a no-switching criterion, if the no-switching criterion is fulfilled, module 126 is configurable to output a zoom video output image that includes only Wide image data in a zoom-in operation

between a lower zoom factor (ZF) value and a higher ZF value. If the no-switching criterion is not fulfilled, module 126 is configurable to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view. Still processing module 128 is connected
to the mode choice function 120 and used for high image quality still mode images. The video processing module is applied when the user desires to shoot in video mode. The capture processing module is applied when the user wishes to shoot still pictures.

FIG. 1D is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1C. Exemplary dimensions: Wide lens TTL = 4.2mm and EFL = 3.5mm; Tele lens
TTL = 6mm and EFL = 7 mm; both Wide and Tele sensors 1/3 inch. External dimensions of Wide and Tele cameras: width (w) and length (l) = 8.5 mm and height (h) = 6.8 mm. Distance "d" between camera centers = 10mm.

Following is a detailed description and examples of different methods of use of camera 100.

Still mode operation/function

In still camera mode, the obtained image is fused from information obtained by both sub-cameras at all zoom levels, see FIG. 2, which shows a Wide sensor **202** and a Tele sensor **204** and their respective FOVs. Exemplarily, as shown, the Tele sensor FOV is half the Wide sensor FOV. The still camera mode processing includes two stages: (1) setting HW settings and configuration, where a first objective is to control the sensors in such a way that matching FOVs in both images (Tele and Wide) are scanned at the same time. A second objective is to control the relative exposures according to the lens properties. A third objective is to minimize the required bandwidth from both sensors for the ISPs; and (2) image processing that fuses the Wide and the Tele images to achieve optical zoom, improves SNR and provides wide dynamic range.

FIG. 3 shows image line numbers vs. time for an image section captured by CMOS sensors. A fused image is obtained by line (row) scans of each image. To prevent matching
FOVs in both sensors to be scanned at different times, a particular configuration is applied by the camera controller on both image sensors while keeping the same frame rate. The difference in FOV between the sensors determines the relationship between the rolling shutter time and the vertical blanking time for each sensor.

20 Video mode operation/function

Smooth transition

When a dual-aperture camera switches the camera output between sub-cameras or points of view, a user will normally see a "jump" (discontinuous) image change. However, a
change in the zoom factor for the same camera and POV is viewed as a continuous change. A "smooth transition" (ST) is a transition between cameras or POVs that minimizes the jump effect. This may include matching the position, scale, brightness and color of the output image before and after the transition. However, an entire image position matching between the sub-camera outputs is in many cases impossible, because parallax causes the position shift

30 to be dependent on the object distance. Therefore, in a smooth transition as disclosed herein, the position matching is achieved only in the ROI region while scale brightness and color are matched for the entire output image area.

Zoom-in and Zoom-out in video mode

In video mode, sensor oversampling is used to enable continuous and smooth zoom experience. Processing is applied to eliminate the changes in the image during crossover from one sub-camera to the other. Zoom from 1 to Z_{switch} is performed using the Wide sensor only.

From Z_{switch} and on, it is performed mainly by the Tele sensor. To prevent "jumps" (roughness in the image), switching to the Tele image is done using a zoom factor which is a bit higher (Z_{switch} +ΔZoom) than Z_{switch}. ΔZoom is determined according to the system's properties and is different for cases where zoom-in is applied and cases where zoom-out is applied (ΔZoom_{in}≠ ΔZoom_{out}). This is done to prevent residual jumps artifacts to be visible at a certain zoom factor. The switching between sensors, for an increasing zoom and for decreasing zoom, is done on a different zoom factor.

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The zoom video mode operation includes two stages: (1) sensor control and configuration, and (2) image processing. In the range from 1 to Z_{switch} , only the Wide sensor is operational, hence, power can be supplied only to this sensor. Similar conditions hold for a Wide AF mechanism. From $Z_{switch}+\Delta Z$ oom to Z_{max} only the Tele sensor is operational, hence, power is supplied only to this sensor. Similarly, only the Tele sensor is operational and power

is supplied only to it for a Tele AF mechanism. Another option is that the Tele sensor is operational and the Wide sensor is working in low frame rate. From Z_{switch} to $Z_{switch}+\Delta Zoom$, both sensors are operational.

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<u>Zoom-in</u>: at low ZF up to slightly above ZF_T (the zoom factor that enables switching between Wide and Tele outputs) the output image is the digitally zoomed, unchanged Wide camera output. ZF_T is defined as follows:

$$ZF_T = Tan (FOV_{Wide})/Tan (FOV_{Tele})$$

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where Tan refers to "tangent", while FOV_{Wide} and FOV_{Tele} refer respectively to the Wide and Tele lens fields of view (in degrees). As used herein, the FOV is measured from the center axis to the corner of the sensor (i.e. half the angle of the normal definition). Switching cannot take place below ZF_T and it can above it.

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In some embodiments for the up-transfer ZF, as disclosed in co-invented and coowned US patent application 14,365711, the output is a transformed Tele sub-camera output, where the transformation is performed by a global registration (GR) algorithm to achieve smooth transition. As used herein "global registration" refers to an action for which the inputs are the Wide and Tele images. The Wide image is cropped to display the same FOV as the Tele image. The Tele image is passed through a low pass filter (LPF) and resized to make its appearance as close as possible to the Wide image (lower resolution and same pixel count). The outputs of GR are corresponding feature point pairs in the images along with their disparities, and parameters for differences between the images, i.e. shift and scale. As used

5 herein, "feature point" refers to a point such as see points 10a-d in FIG. 1A and refers to a point (pixel) of interest on an object in an image. For purposes set forth in this description, a feature point should be reproducible and invariant to changes in image scale, noise and illumination. Such points usually lie on corners or other high-contrast regions of the object.

10 Stages of GR

In some exemplary embodiments, global registration may be performed as follows:

1. Find interest points (features) in each image separately by filtering it with, exemplarily, a Difference of Gaussians filter and finding local extrema on the resulting image.

- Find feature correspondences (features in both images that describe the same point in space) in a "matching" process. These are also referred to as "feature pairs", "correspondence pairs" or "matching pairs". This is done by comparing each feature point from one (Tele or Wide) image (referred to hereinafter as "image 1") to all feature points in that region from the other (respectively Wide or Tele) image (referred to hereinafter as "image 2"). The features are compared only within their group of minima/maxima, using patch normalized cross correlation. As used herein, "patch" refers to a group of neighboring pixels around an origin

pixel.

3. The normalized cross correlation of two image patches t(x, y) and f(x, y) is $\frac{1}{n}\sum_{x,y} \frac{(f(x,y)-\bar{f})(t(x,y)-\bar{t})}{\sigma_f \sigma_t}$ where n is the number of pixels in both patches, \bar{f} is the average of f and σ_f is the standard deviation of f. A match for a feature point from image 1 is only confirmed if its correlation score is much higher (for example, x1.2) than the next-best matching feature from image 2.

4. Find the disparity between each pair of corresponding features (also referred to as "matching pair") by subtracting their x and y coordinate values.

- 5. Filter bad matching points:
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a. Following the matching process, matches that include feature points from image 2 that were matched to more than one feature from image 1 are discarded.

b. Matching pairs whose disparity is inconsistent with the other matching pairs are discarded. For example, if there is one corresponding pair which whose disparity is lower or higher than the others by 20 pixels.

6. The localization accuracy for matched points from image 2 is refined by calculating a correlation of neighboring pixel patches from image 2 with the target patch (the patch around the current pixel (of the current matching pair) from image 1, modeling the results as a

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parabola and finding its maximum.

7. Rotation and fine scale differences are calculated between the two images according to the matching points (for example, by subtracting the center of mass from each set of points, i.e. the part of the matching points belonging to either the Wide or the Tele image, and solving a least squares problem).

8. After compensating for these differences, since the images were rectified, the disparity in the Y axis should be close to 0. Matching points that do not fit this criterion are discarded.

 9. Finally, the remaining matching points are considered true and the disparities for them
 ¹⁵ are calculated. A weighted average of the disparity is taken as the shift between both images. The maximum difference between disparity values is taken as the disparity range.

10. At various stages during GR, if there are not enough feature/matching points remaining, the GR is stopped and returns a failure flag.

In addition, it is possible to find range calibration to the rectification process by finding the shift = shift for objects at infinity and defining shiftD=shift-shiftI and disparity D = disparity-shiftI. We then calculate *object distance* = $\frac{focalLength \cdot baseline}{disparityD \cdot pixelSize}$, where "baseline" is the distance between cameras.

Returning now to the Zoom-in process, in some embodiments, for higher ZF than the up-transfer ZF the output is the transformed Tele sub-camera output, digitally zoomed.
However, in other embodiments for the up-transfer ZF there will be no switching from the Wide to the Tele sub-camera output, i.e. the output will be from the Wide sub-camera, digitally zoomed. This "no switching" process is described next.

No Switching

³⁰ Switching from the Wide sub-camera output to the transformed Tele sub-camera output will be performed unless some special condition (criterion), determined based on inputs obtained from the two sub-camera images, occurs. In other words, switching will not be performed only if at least one of the following no-switching criteria is fulfilled:

1. if the shift calculated by GR is greater than a first threshold, for example 50 pixels.

2. if the disparity range calculated by GR is greater than a second threshold, for example 20 pixels, because in this case there is no global shift correction that will suppress movement/jump for all objects distances (smooth transition is impossible for all objects).

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3. if the effective resolution (a result of the resolution metric) of the Tele image is lower than that of the Wide image. In this case, there is no point in performing the transition because no value (i.e. resolution) is gained. Smooth transition is possible but undesirable.

4. if the GR fails, i.e. if the number of matching pairs found is less than a third threshold, for example 20 matching pairs.

10 5. if, for example, that are imaged onto the overlap area are calculated to be closer than a first threshold distance, for example 30 cm, because this can result in a large image shift to obtain ST.

6. if some objects (for example two objects) that are imaged in the overlap area are calculated to be closer than a second threshold distance, for example 50 cm, while other

- 15 objects (for example two objects) are calculated to be farther than a third distance threshold, for example 10 m. The reason is that the shift between an object position in the Wide and Tele sub-cameras is object distance dependent, where the closer the objects the larger the shift, so an image containing significantly close and far objects cannot be matched by simple transformation (shift scale) to be similar and thus provide ST between cameras.
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Zoom-out: at high ZF down to slightly below ZFT, the output image is the digitally zoomed transformed Tele camera output. For the down-transfer ZF, the output is a shifted Wide camera output, where the Wide shift correction is performed by the GR algorithm to achieve smooth transition, i.e. with no jump in the ROI region. For lower (than the downtransfer) ZF, the output is basically the down-transfer ZF output digitally zoomed but with gradually smaller Wide shift correction, until for ZF=1 the output is the unchanged Wide camera output.

Note that if a no-switching criterion is not fulfilled, then the camera will output without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, the video output images being provided with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor,

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and wherein at the higher ZF value the output resolution is determined by the Tele sensor. FIG. 3 shows an embodiment of a method disclosed herein for acquiring a zoom

image in video/preview mode for 3 different zoom factor (ZF) ranges: (a) ZF range = 1 :

 Z_{switch} ; (b) ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$: and (c) Zoom factor range = Z_{switch} + $\Delta Zoom_{in}$: Z_{max} . The description is with reference to a graph of effective resolution vs. zoom value (FIG. 7). In step **302**, sensor control module **116** chooses (directs) the sensor (Wide, Tele or both) to be operational. Specifically, if the ZF range = 1: Z_{switch} , module **116** directs the

- 5 Wide sensor to be operational and the Tele sensor to be non-operational. If the ZF range is Z_{switch} : $Z_{switch} + \Delta Zoom_{in}$, module **116** directs both sensors to be operational and the zoom image is generated from the Wide sensor. If the ZF range is $Z_{switch} + \Delta Zoom_{in}$: Z_{max} , module **116** directs the Wide sensor to be non-operational and the Tele sensor to be operational. After the sensor choice in step **302**, all following actions are performed in video processing core
- 10 **126**. Optionally, in step **304**, color balance is calculated if two images are provided by the two sensors. Optionally yet, in step **306**, the calculated color balance is applied in one of the images (depending on the zoom factor). Further optionally, in step **308**, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient can be used to set an AF position in step **310**. In step **312**, an output
- of any of steps 302-308 is applied on one of the images (depending on the zoom factor) for image signal processing that may include denoising, demosaicing, sharpening, scaling, etc. In step 314, the processed image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function 124) and the output video resolution (for example 1080p). To avoid a transition point to be executed at the same ZF, ΔZoom can change while zooming in and while zooming out. This will result in hysteresis in the sensor switching point.

In more detail, for ZF range 1: Z_{switch} , for ZF < Z_{switch} , the Wide image data is transferred to the ISP in step **312** and resampled in step **314**. For ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$, both sensors are operational and the zoom image is generated from the Wide sensor. The color balance is calculated for both images according to a given ROI. In addition,

- 25 for a given ROI, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient is used to set an AF position. The transformation coefficient includes the translation between matching points in the two images. This translation can be measured in a number of pixels. Different translations will result in a different number of pixel movements between matching points in the images. This movement
- 30

can be translated into depth and the depth can be translated into an AF position. This enables to set the AF position by only analyzing two images (Wide & Tele). The result is fast focusing.

Both color balance ratios and transformation coefficient are used in the ISP step. In parallel, the Wide image is processed to provide a processed image, followed by resampling.

For ZF range = $Z_{switch} + \Delta Z_{oom_{in}}$: Z_{max} and for Zoom factor > Z_{switch} , + $\Delta Z_{oom_{in}}$, the color balance calculated previously is now applied on the Tele image. The Tele image data is transferred to the ISP in step **312** and resampled in step **314**. To eliminate crossover artifacts and to enable smooth transition to the Tele image, the processed Tele image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function **124**) and the output video resolution (for example 1080p).

FIG. 4 shows the effective resolution as a function of the zoom factor for a zoom-in case and for a zoom-out case ΔZoom_{up} is set when we zoom in, and ΔZoom_{down} is set when we zoom out. Setting ΔZoom_{up} to be different from ΔZoom_{down} will result in transition
between the sensors to be performed at different zoom factor ("hysteresis") when zoom-in is used and when zoom-out is used. This hysteresis phenomenon in the video mode results in smooth continuous zoom experience.

In conclusion, dual aperture optical zoom digital cameras and associate methods disclosed herein reduce the amount of processing resources, lower frame rate requirements, reduce power consumption, remove parallax artifacts and provide continuous focus (or provide loss of focus) when changing from Wide to Tele in video mode. They provide a dramatic reduction of the disparity range and avoid false registration in capture mode. They reduce image intensity differences and enable work with a single sensor bandwidth instead of two, as in known cameras.

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All patent applications mentioned in this specification are herein incorporated in their entirety by reference into the specification, to the same extent as if each individual patent application was specifically and individually indicated to be incorporated herein by reference. In addition, citation or identification of any reference in this application shall not be construed as an admission that such reference is available as prior art to the present disclosure.

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While this disclosure has been described in terms of certain embodiments and generally associated methods, alterations and permutations of the embodiments and methods will be apparent to those skilled in the art. The disclosure is to be understood as not limited by the specific embodiments described herein, but only by the scope of the appended claims.

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WHAT IS CLAIMED IS:

1. A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

2. The camera of claim 1, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

3. The camera of claim 1, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

4. The camera of claim 1, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

5. The camera of claim 1, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

6. The camera of claim 1, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

7. The camera of claim 1, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

8. The camera of claim 1, wherein the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

9. The camera of claim 8, wherein the user inputs include a zoom factor, a camera mode and a region of interest.

10. The camera of claim 1, wherein the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1.

11. The camera of claim 1, wherein, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

12. The camera of claim 1, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

13. A method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV) and a Wide sensor, a Tele imaging section having a Tele lens with

a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

14. The method of claim 13, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

15. The method of claim 13, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

16. The method of claim 13, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

17. The method of claim 13, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

18. The method of claim 13, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

19. The method of claim 13, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

20. The method of claim 13, further comprising the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the

Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

21. The method of claim 13, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

ABSTRACT

A dual-aperture zoom digital camera operable in both still and video modes. The camera includes Wide and Tele imaging sections with respective lens/sensor combinations and image signal processors and a camera controller operatively coupled to the Wide and Tele imaging sections. The Wide and Tele imaging sections provide respective image data. The controller is configured to output, in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value, a zoom video output image that includes only Wide image data or only Tele image data, depending on whether a no-switching criterion is fulfilled or not.







FIG. 1B

<u>100</u>



FIG. 1C



FIG. 1D



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FIG. 2



FIG. 3



FIG. 4

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Application Da	ta Shoot 37 CED 1 76	Attorney Docket Number	COREPH-0159 US PR			
Application Data Sheet 37 CFR 1:78		Application Number				
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL					
The application data sheet is part of the provisional or nonprovisional application for which it is being submitted. The following form contains the bibliographic data arranged in a format specified by the United States Patent and Trademark Office as outlined in 37 CFR 1.76.						

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Application Data Sheet 37 CFR 1.76			I-0159 US PR						
				Applicati	on Nu	ımber			
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Application Da	ta Shoot 27 CED 1 76	Attorney Docket Number	COREPH-0159 US PR
Application Data Sheet S7 CFK 1.76		Application Number	
Title of Invention	DUAL APERTURE ZOOM CA DYNAMIC CONTROL	MERA WITH VIDEO SUPPORT	TAND SWITCHING / NON-SWITCHING
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Title of the Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL			
Attorney Docket Number	COREPH-0159 US PR Small Entity Status Claimed X			
Application Type	Provisional			
Subject Matter	Utility			
Total Number of Drawing	Sheets (if any)	Suggested Figure for Publication (if any)		

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Application Data Sheet 37 CFR 1.76		Attorney Docket Number	COREPH-0159 US PR
		Application Number	
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL		AND SWITCHING / NON-SWITCHING

Statement under 37 CFR 1.55 or 1.78 for AIA (First Inventor to File) Transition Applications

This application (1) claims priority to or the benefit of an application filed before March 16, 2013 and (2) also contains, or contained at any time, a claim to a claimed invention that has an effective filing date on or after March 16, 2013.

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Application Da	ta She	et 37 CFR 1.76	Application Number				
Title of Invention	DUAL / DYNAI	APERTURE ZOOM CA MIC CONTROL	ERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING				
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Application Data Sheet 37 CFR 1.76		Attorney Docket Number	COREPH-0159 US PR
		Application Number	
Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT DYNAMIC CONTROL		FAND SWITCHING / NON-SWITCHING

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- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspections or an issued patent.
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

Electronic Acknowledgement Receipt				
EFS ID:	23201965			
Application Number:	62204667			
International Application Number:				
Confirmation Number:	7706			
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL			
First Named Inventor/Applicant Name:	Noy Cohen			
Customer Number:	92342			
Filer:	Menachem Nathan			
Filer Authorized By:				
Attorney Docket Number:	COREPH-0159 US PR			
Receipt Date:	13-AUG-2015			
Filing Date:				
Time Stamp:	15:02:04			
Application Type:	Provisional			

Payment information:

Submitted with Payment	yes			
Payment Type	Credit Card			
Payment was successfully received in RAM	\$130			
RAM confirmation Number	1223			
Deposit Account				
Authorized User				
The Director of the USPTO is hereby authorized to charge indicated fees and credit any overpayment as follows:				

File Listin	g:				
Document Number	Document Description	File Name	File Size(Bytes)/ Message Digest	Multi Part /.zip	Pages (if appl.)
			2071884		
1	Provisional Cover Sheet (SB16)	CoverSheet.pdf	1cfafbc9d36fc0cf7e08589e2e1dc5466b55d 939	no	4
Warnings:					
Information:					
2			80469		2
2	Power of Attorney	POA.pdf	2c0ced0095461f0d5e9642197644b090abc e6978	no	2
Warnings:					
Information:					
3	Assignee showing of ownership per 37	Assignment.pdf	18311	no	1
	Crh 3.73		e706970493ca79b12f7ea501c2d605fe6450 fff6		
Warnings:					
Information:					
4	Assignee showing of ownership per 37	STATEMENT.pdf	117641	no	3
	CFR 3.73	- · · · - · · · · · · · · · · · · · · ·	48818859135601b45c07b8580f43c4d999b 93762		
Warnings:					
Information:					
5	Specification	filing.pdf	8212688	no	25
			49fbec35a67bb47ebc1c622192df6596e5f5 f131		
Warnings:					
Information:					
6	Application Data Sheet	ADS.pdf	1503960	no	8
			c2b53797bdb33a8b30c22f0c4708e04843d ccced		
Warnings:					
Information:					
7	Fee Worksheet (SB06)	fee-info.pdf	29893	no	2
			687be29cffe618e4a493c2a1e02aa1f0d49d 11fe		
Warnings:					
Information:			[
		Total Files Size (in bytes)	120	034846	

This Acknowledgement Receipt evidences receipt on the noted date by the USPTO of the indicated documents, characterized by the applicant, and including page counts, where applicable. It serves as evidence of receipt similar to a Post Card, as described in MPEP 503.

New Applications Under 35 U.S.C. 111

If a new application is being filed and the application includes the necessary components for a filing date (see 37 CFR 1.53(b)-(d) and MPEP 506), a Filing Receipt (37 CFR 1.54) will be issued in due course and the date shown on this Acknowledgement Receipt will establish the filing date of the application.

National Stage of an International Application under 35 U.S.C. 371

If a timely submission to enter the national stage of an international application is compliant with the conditions of 35 U.S.C. 371 and other applicable requirements a Form PCT/DO/EO/903 indicating acceptance of the application as a national stage submission under 35 U.S.C. 371 will be issued in addition to the Filing Receipt, in due course.

New International Application Filed with the USPTO as a Receiving Office

If a new international application is being filed and the international application includes the necessary components for an international filing date (see PCT Article 11 and MPEP 1810), a Notification of the International Application Number and of the International Filing Date (Form PCT/RO/105) will be issued in due course, subject to prescriptions concerning national security, and the date shown on this Acknowledgement Receipt will establish the international filing date of the application.

Doc Code: **TR.PROV** Document Description: Provisional Cover Sheet (SB16)

Th	Provision is a request for film	sional Applications are not and the source of the source o	on for Patent APPLICATION F	Cover Sheet	r 37 CFR 1.53(c)
Inventor(s)		_			
Inventor 1					Remove
Given Name	Middle Name	Family Name	City	State	Country i
Noy		Cohen	Tel-Aviv		IL
Inventor 2					Remove
Given Name	Middle Name	Family Name	City	State	Country i
Oded		Gigushinski	Herzlia		IL
Inventor 3					Remove
Given Name	Middle Name	Family Name	City	State	Country i
Nadav		Geva	Tel-Aviv		IL
Inventor 4	I				Remove
Given Name	Middle Name	Family Name	City	State	Country i
Gal		Shabtay	Tel-Aviv		IL
Inventor 5	I				Remove
Given Name	Middle Name	Family Name	City	State	Country i
Ester		Ashkenazi	Modi'in		IL
Inventor 6					Remove
Given Name	Middle Name	Family Name	City	State	Country i
Ruthy		Katz	Tel-Aviv		
All Inventors Must Be Listed – Additional Inventor Information blocks may be Add Add Add Add Add Add Add Add Add Ad					
Title of Inventior	Title of Invention DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL				
Attorney Docket Number (if applicable) COREPH-0159 US PR					
Carrespondence Address					

Correspondence Address

Doc Code: TR.PROV Document Description: Provisional Cover Sheet (SB16)

PTO/SB/16 (11-08) Approved for use through 01/31/2014 OMB 0651-0032 U.S. Patent and Trademark Office: U.S. DEPARTMENT OF COMMERCE Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it displays a valid OMB control number

Direct all correspondence to (select one):				
The address corresponding to Customer Number	⊖ Firm or Individual Name			
Customer Number	92342			

The invention was made by an agency of the United States Government or under a contract with an agency of the United States Government.

(•) No			10	N	\odot
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○ Yes, the name of the U.S. Government agency and the Government contract number are:

Doc Code: **TR.PROV** Document Description: Provisional Cover Sheet (SB16)

PTO/SB/16 (11-08) Approved for use through 01/31/2014 OMB 0651-0032 U.S. Patent and Trademark Office: U.S. DEPARTMENT OF COMMERCE

Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it displays a valid OMB control number

Entity Status

Applicant claims small entity status under 37 CFR 1.27

()Yes, applicant qualifies for small entity status under 37 CFR 1.27

O No

Warning

Petitioner/applicant is cautioned to avoid submitting personal information in documents filed in a patent application that may contribute to identity theft. Personal information such as social security numbers, bank account numbers, or credit card numbers (other than a check or credit card authorization form PTO-2038 submitted for payment purposes) is never required by the USPTO to support a petition or an application. If this type of personal information is included in documents submitted to the USPTO, petitioners/applicants should consider redacting such personal information from the documents before submitting them to USPTO. Petitioner/applicant is advised that the record of a patent application is available to the public after publication of the application (unless a non-publication request in compliance with 37 CFR 1.213(a) is made in the application) or issuance of a patent. Furthermore, the record from an abandoned application may also be available to the public if the application is referenced in a published application or an issued patent (see 37 CFR1.14). Checks and credit card authorization forms PTO-2038 submitted for payment purposes are not retained in the application file and therefore are not publicly available.

Signature

Please see 37 CFR 1.4(d) for the form of the signature.						
Signature	/Menachem Nathan/			Date (YYYY-MM-DD)	2015-05-14	
First Name	Menachem	Last Name	Nathan	Registration Number (If appropriate)	65392	
This collection of information is required by 37 CFR 1.51. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.11 and 1.14. This collection is estimated to take 8 hours to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. This form can only be used when in conjunction with EFS-Web. If this form is mailed to the USPTO, it may cause delays in handling the provisioned application.						

Privacy Act Statement

The Privacy Act of 1974 (P.L. 93-579) requires that you be given certain information in connection with your submission of the attached form related to a patent application or paten. Accordingly, pursuant to the requirements of the Act, please be advised that : (1) the general authority for the collection of this information is 35 U.S.C. 2(b)(2); (2) furnishing of the information solicited is voluntary; and (3) the principal purpose for which the information is used by the U.S. Patent and Trademark Office is to process and/or examine your submission related to a patent application or patent. If you do not furnish the requested information, the U.S. Patent and Trademark Office may not be able to process and/or examine your submission, which may result in termination of proceedings or abandonment of the application or expiration of the patent.

The information provided by you in this form will be subject to the following routine uses:

- The information on this form will be treated confidentially to the extent allowed under the Freedom of Information Act (5 U.S.C. 552) and the Privacy Act (5 U.S.C 552a). Records from this system of records may be disclosed to the Department of Justice to determine whether disclosure of these records is required by the Freedom of Information Act.
- A record from this system of records may be disclosed, as a routine use, in the course of presenting evidence to a court, magistrate, or administrative tribunal, including disclosures to opposing counsel in the course of settlement negotiations.
- 3. A record in this system of records may be disclosed, as a routine use, to a Member of Congress submitting a request involving an individual, to whom the record pertains, when the individual has requested assistance from the Member with respect to the subject matter of the record.
- 4. A record in this system of records may be disclosed, as a routine use, to a contractor of the Agency having need for the information in order to perform a contract. Recipients of information shall be required to comply with the requirements of the Privacy Act of 1974, as amended, pursuant to 5 U.S.C. 552a(m).
- 5. A record related to an International Application filed under the Patent Cooperation Treaty in this system of records may be disclosed, as a routine use, to the International Bureau of the World Intellectual Property Organization, pursuant to the Patent Cooperation Treaty.
- 6. A record in this system of records may be disclosed, as a routine use, t o a n other federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspection or an issued patent.
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.



DOCUMENT MADE AVAILABLE UNDER THE PATENT COOPERATION TREATY (PCT)

International application number:

International filing date:

Document type:

Document details:

Country/Office: Number: Filing date: PCT/IB2016/053803

26 June 2016 (26.06.2016)

Certified copy of priority document

US 62/204,667 13 August 2015 (13.08.2015)

Date of receipt at the International Bureau:

27 June 2016 (27.06.2016)

Remark: Priority document submitted or transmitted to the International Bureau in compliance with Rule 17.1(a),(b) or (b-*bis*)

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PCT REQUEST

Print Out (Original in Electronic Form)

0	For receiving Office use only			
0-1	International Application No.	PCT/IB2016/053803		
0-2	International Filing Date	26 June 2016 (26.06.2016)		
0-3	Name of receiving Office and "PCT International Application"	RO/IB		
0.4	Form BCT/BO/101 BCT Paguast			
0-4-1	Prepared Using	ePCT-Filing Version 3.3.002 MT/FOP 20151028/0.20.5.24		
0-5	Petition			
	The undersigned requests that the present international application be processed according to the Patent Cooperation Treaty			
0-6	Receiving Office (specified by the applicant)	International Bureau of the World Intellectual Property Organization (RO/IB)		
0-7	Applicant's or agent's file reference	COREPH-0159		
I	Title of Invention	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL		
П	Applicant			
II-1	This person is	Applicant only		
11-2	Applicant for	All designated States		
-4	Name	COREPHOTONICS LTD.		
11-5	Address	25 Habarzel St. Ramat Hachayal 6971035 Tel-Aviv Israel		
11-6	State of nationality	IL		
11-7	State of residence	IL		
II-10	e-mail	info@natpatent.com		
II-10(a)	E-mail authorization The receiving Office, the International Searching Authority, the International Bureau and the International Preliminary Examining Authority are authorized to use this e-mail address, if the Office or Authority so wishes, to send notifications issued in respect of this international application:	exclusively in electronic form (no paper notifications will be sent)		

PCT REQUEST

2/5 Print Out (Original in Electronic Form)

III-1	Applicant and/or inventor	
III-1-1	This person is	Inventor only
III-1-3	Inventor for	All designated States
III-1 -4	Name (LAST, First)	COHEN, Noy
III-1-5	Address	30 Shlomo Ben Yossef St. 6912529 Tel-Aviv Israel
III-2	Applicant and/or inventor	
III-2-1	This person is	Inventor only
III-2-3	Inventor for	All designated States
111-2-4	Name (LAST, First)	GEVA, Nadav
III-2-5	Address	3 Vormaiza St. 6264203 Tel-Aviv Israel
III-3	Applicant and/or inventor	
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111-3-3	Inventor for	All designated States
111-3-4	Name (LAST, First)	GIGUSHINSKI, Oded
III-3-5	Address	23 Ahi Dakar St. 4670223 Herzlia Israel
III-4	Applicant and/or inventor	
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111-4-3	Inventor for	All designated States
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III- 4 -5	Address	4 Shmuel Shnitzer St. 6958313 Tel-Aviv Israel
III-5	Applicant and/or inventor	
III-5-1	This person is	Inventor only
111-5-3	Inventor for	All designated States
111-5-4	Name (LAST, First)	ASHKENAZI, Ester
III-5-5	Address	52/2 Emeq Dotan St. 7170202 Modi'in Israel
III-6	Applicant and/or inventor	
III-6-1	This person is	Inventor only
111-6-3	Inventor for	All designated States
111-6-4	Name (LAST, First)	KATZ, Ruthy
III-6-5	Address	6/20 Hachmey Kiruan St. 6423706 Tel Aviv Israel

^ RO

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3/5

Print Out (Original in Electronic Form)

III-7	Applicant and/or inventor	
111-7-1	This person is	Inventor only
111-7-3	Inventor for	All designated States
-7-4	Name (LAST, First)	GOLDENBERG, Ephraim
111-7-5	Address	32/25 Tel-Chai Av.
		7751025 Ashdod
11/ 4	Agent or common representatives or	ISFAEL
10-1	address for correspondence	
	The person identified below is hereby/ has been appointed to act on behalf of the applicant(s) before the competent International Authorities as:	Agent ^ Address for correspondence ^
IV-1-1	Name	NATHAN & ASSOCIATES PATENT AGENTS LTD.
IV-1-2	Address	P.O. BOX 10178 611010 Tel-Aviv Israel
IV-1-3	Telephone No.	972-523512845
IV-1-5	e-mail	info@natpatent.com
IV-1-5(a)	E-mail authorization The receiving Office, the International Searching Authority, the International Bureau and the International Preliminary Examining Authority are authorized to use this e-mail address, if the Office or Authority so wishes, to send notifications issued in respect of this international application:	exclusively in electronic form (no paper notifications will be sent)
v	DESIGNATIONS	
V-1	The filing of this request constitutes under Rule 4.9(a), the designation of all Contracting States bound by the PCT on the international filing date, for the grant of every kind of protection available and, where applicable, for the grant of both regional and national patents.	
VI-1	Priority claim of earlier national application	
VI-1-1	Filing date	13 August 2015 (13.08.2015)
VI-1-2	Number	62/204,667
VI-1-3	Country or Member of WTO	US
VI-2	Priority document request	
	The International Bureau is requested to obtain from a digital library a certified copy of the earlier application(s) identified above as item(s), using, where applicable, the access code(s) indicated:	VI-1 Access code: 7706

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VI-3	Incorporation by reference :		
	where an element of the international application referred to in Article 11(1)(iii)(d) or (e) or a part of the description, claims or drawings referred to in Rule 20.5(a) is not otherwise contained in this international application but is completely contained in an earlier application whose priority is claimed on the date on which one or more elements referred to in Article 11(1)(iii) were first received by the receiving Office, that element or part is, subject to confir- mation under Rule 20.6, incorporated by reference in this international application for the purposes of Rule 20.6.		
VII-1	Chosen	United States Patent Office (USPTO) (ISA/	and Trademark US)
VIII	Declarations	Number of declarations	
VIII-1	Declaration as to the identity of the inventor	-	
VIII-2	Declaration as to the applicant's entitlement, as at the international filing date, to apply for and be granted a patent	-	
VIII-3	Declaration as to the applicant's entitlement, as at the international filing date, to claim the priority of the earlier application	-	
VIII-4	Declaration of inventorship (only for the purposes of the designation of the United States of America)	-	
VIII-5	Declaration as to non-prejudicial disclosures or exceptions to lack of novelty	-	
IX	Check list	Number of sheets	Electronic file(s) attached
IX-1	Request (including declaration sheets)	5	\checkmark
IX-2	Description	16	\checkmark
IX-3	Claims	4	1
IX-4	Abstract	1	\checkmark
IX-5	Drawings	5	✓
IX-7	TOTAL	31	
	Accompanying Items	Paper document(s) attached	Electronic file(s) attached
IX-8	Fee calculation sheet	-	\checkmark
IX-20	Figure of the drawings which should accompany the abstract	ЗА	
IX-21	Language of filing of the international application	English	
IX-22	The receiving Office is requested to make this international application available to the Priority Document Access Service (DAS) (provided that an international application number and international filing date is accorded to this purported interna- tional application.)	Yes	

PCT REQUEST

5/5

Print Out (Original in Electronic Form)

X-1	Signature of applicant, agent or common representative	/Gal Shabtay/
X-1-1	Name	COREPHOTONICS LTD.
X-1-2	Name of signatory	Gal Shabtay
X-1-3	Capacity (if such capacity is not obvious from reading the request)	VP R&D

FOR RECEIVING OFFICE USE ONLY

10-1	Date of actual receipt of the purported international application	26	June	2016	(26.06.2016)
10-2	Drawings:				
10-2-1	Received				
10-2-2	Not received				
10-3	Corrected date of actual receipt due to later but timely received papers or drawings completing the purported international application				
10-4	Date of timely receipt of the required corrections under PCT Article 11(2)				
10-5	International Searching Authority	ISA	A/US		
10-6	Transmittal of search copy delayed until search fee is paid				

FOR INTERNATIONAL BUREAU USE ONLY

11-1	Date of receipt of the record copy by	
	the International Bureau	

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property

Organization

International Bureau



(43) International Publication Date 16 February 2017 (16.02.2017)

- (51) International Patent Classification: *H04N 5/262* (2006.01) *G06T 5/50* (2006.01) *G02B 15/00* (2006.01)
- (21) International Application Number:
- (22) International Filing Date:
- 26 June 2016 (26.06.2016) (25) Filing Language: English
- (26) Publication Language: English
- (30) Priority Data: 62/204,667 13 August 2015 (13.08.2015) US
- (71) Applicant: COREPHOTONICS LTD. [IL/IL]; 25 Habarzel St., Ramat Hachayal, 6971035 Tel-Aviv (IL).
- (72) Inventors: COHEN, Noy; 30 Shlomo Ben Yossef St., 6912529 Tel-Aviv (IL). GEVA, Nadav; 3 Vormaiza St., 6264203 Tel-Aviv (IL). GIGUSHINSKI, Oded; 23 Ahi Dakar St., 4670223 Herzlia (IL). SHABTAY, Gal; 4 Shmuel Shnitzer St., 6958313 Tel-Aviv (IL).

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ASHKENAZI, Ester; 52/2 Emeq Dotan St., 7170202 Modi'in (IL). KATZ, Ruthy; 6/20 Hachmey Kiruan St., 6423706 Tel Aviv (IL). GOLDENBERG, Ephraim; 32/25 Tel-Chai Av., 7751025 Ashdod (IL).

- PCT/IB2016/053803
 (81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.
 - (84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU,

[Continued on next page]

(54) Title: DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL



(57) Abstract: A dual-aperture zoom digital camera operable in both still and video modes. The camera includes Wide and Tele imaging sections with respective lens/sensor combinations and image signal processors and a camera controller operatively coupled to the Wide and Tele imaging sections. The Wide and Tele imaging sections provide respective image data. The controller is configured to output, in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value, a zoom video output image that includes only Wide image data or only Tele image data, depending on whether a no-switching criterion is fulfilled or not.

WO 2017/025822 A1

LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, **Published**: SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG). *with international search report (Art. 21(3))*

DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

CROSS REFERENCE TO RELATED APPLICATIONS

5

This application claims priority from US Provisional Patent Application No. 62/204,667 filed on August 13, 2015 which is expressly incorporated herein by reference in its entirety.

10 FIELD

Embodiments disclosed herein relate in general to digital cameras and in particular to zoom digital cameras with video capabilities.

15 **BACKGROUND**

Digital camera modules are currently being incorporated into a variety of host devices. Such host devices include cellular telephones, personal data assistants (PDAs), computers, and so forth. Consumer demand for digital camera modules in host devices continues to grow.

20 Host device manufacturers prefer digital camera modules to be small, so that they can be incorporated into the host device without increasing its overall size. Further, there is an increasing demand for such cameras to have higher-performance characteristics. One such characteristic possessed by many higher-performance cameras (e.g., standalone digital still cameras) is the ability to vary the focal length of the camera to increase and decrease the 25 magnification of the image. This ability, typically accomplished with a zoom lens, is known as optical zooming. "Zoom" is commonly understood as a capability to provide different magnifications of the same scene and/or object by changing the focal length of an optical system, with a higher level of zoom associated with greater magnification and a lower level of zoom associated with lower magnification. Optical zooming is typically accomplished by mechanically moving lens elements relative to each other. Such zoom lenses are typically 30 more expensive, larger and less reliable than fixed focal length lenses. An alternative approach for approximating the zoom effect is achieved with what is known as digital zooming. With digital zooming, instead of varying the focal length of the lens, a processor in

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the camera crops the image and interpolates between the pixels of the captured image to create a magnified but lower-resolution image.

Attempts to use multi-aperture imaging systems to approximate the effect of a zoom lens are known. A multi-aperture imaging system (implemented for example in a digital camera) includes a plurality of optical sub-systems (also referred to as "cameras"). Each camera includes one or more lenses and/or other optical elements which define an aperture such that received electro-magnetic radiation is imaged by the optical sub-system and a resulting image is directed towards a two-dimensional (2D) pixelated image sensor region. The image sensor (or simply "sensor") region is configured to receive the image and to generate a set of image data based on the image. The digital camera may be aligned to receive electromagnetic radiation associated with scenery having a given set of one or more objects. The set of image data may be represented as digital image data, as well known in the art. Hereinafter in this description, "image" "image data" and "digital image data" may be used interchangeably. Also, "object" and "scene" may be used interchangeably. As used herein, the term "object" is an entity in the real world imaged to a point or pixel in the image.

Multi-aperture imaging systems and associated methods are described for example in US Patent Publications No. 2008/0030592, 2010/0277619 and 2011/0064327. In US 2008/0030592, two sensors are operated simultaneously to capture an image imaged through an associated lens. A sensor and its associated lens form a lens/sensor combination. The two 20 lenses have different focal lengths. Thus, even though each lens/sensor combination is aligned to look in the same direction, each combination captures an image of the same subject but with two different fields of view (FOV). One sensor is commonly called "Wide" and the other "Tele". Each sensor provides a separate image, referred to respectively as "Wide" (or "W") and "Tele" (or "T") images. A W-image reflects a wider FOV and has lower resolution than the T-image. The images are then stitched (fused) together to form a composite ("fused") 25 image. In the composite image, the central portion is formed by the relatively higherresolution image taken by the lens/sensor combination with the longer focal length, and the peripheral portion is formed by a peripheral portion of the relatively lower-resolution image taken by the lens/sensor combination with the shorter focal length. The user selects a desired amount of zoom and the composite image is used to interpolate values from the chosen amount of zoom to provide a respective zoom image. The solution offered by US 2008/0030592 requires, in video mode, very large processing resources in addition to high frame rate requirements and high power consumption (since both cameras are fully

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operational).

US 2010/0277619 teaches a camera with two lens/sensor combinations, the two lenses having different focal lengths, so that the image from one of the combinations has a FOV approximately 2-3 times greater than the image from the other combination. As a user of the camera requests a given amount of zoom, the zoomed image is provided from the lens/sensor combination having a FOV that is next larger than the requested FOV. Thus, if the requested FOV is less than the smaller FOV combination, the zoomed image is created from the image captured by that combination, using cropping and interpolation if necessary. Similarly, if the requested FOV is greater than the smaller FOV combination, the zoomed image is created from the image captured by the other combination, using cropping and interpolation if necessary. Similarly, if the requested FOV is greater than the smaller FOV combination, using cropping and interpolation if necessary. The solution offered by US 2010/0277619 leads to parallax artifacts when moving to the Tele camera in video mode.

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In both US 2008/0030592 and US 2010/0277619, different focal length systems cause matching Tele and Wide FOVs to be exposed at different times using CMOS sensors. This degrades the overall image quality. Different optical F numbers ("F#") cause image intensity differences. Working with such a dual sensor system requires double bandwidth support, i.e. additional wires from the sensors to the following HW component. Neither US 2008/0030592 nor US 2010/0277619 deal with registration errors.

US 2011/0064327 discloses multi-aperture imaging systems and methods for image data fusion that include providing first and second sets of image data corresponding to an imaged first and second scene respectively. The scenes overlap at least partially in an overlap region, defining a first collection of overlap image data as part of the first set of image data, and a second collection of overlap image data as part of the second set of image data. The second collection of overlap image data is represented as a plurality of image data cameras such that each of the cameras is based on at least one characteristic of the second collection, and each camera spans the overlap region. A fused set of image data is produced by an image processor, by modifying the first collection of overlap image data based on at least a selected one of, but less than all of, the image data cameras. The systems and methods disclosed in this application deal solely with fused still images.

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None of the known art references provide a thin (e.g. fitting in a cell-phone) dualaperture zoom digital camera with fixed focal length lenses, the camera configured to operate in both still mode and video mode to provide still and video images, wherein the camera configuration does not use any fusion to provide a continuous, smooth zoom in video mode.

Therefore there is a need for, and it would be advantageous to have thin digital cameras with optical zoom operating in both video and still mode that do not suffer from

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commonly encountered problems and disadvantages, some of which are listed above.

SUMMARY

5 Embodiments disclosed herein teach the use of dual-aperture (also referred to as duallens or two-sensor) optical zoom digital cameras. The cameras include two cameras, a Wide camera and a Tele camera, each camera including a fixed focal length lens, an image sensor and an image signal processor (ISP). The Tele camera is the higher zoom camera and the Wide camera is the lower zoom camera. In some embodiments, the thickness/effective focal length (EFL) ratio of the Tele lens is smaller than about 1. The image sensor may include two 10 separate 2D pixelated sensors or a single pixelated sensor divided into at least two areas. The digital camera can be operated in both still and video modes. In video mode, optical zoom is achieved "without fusion", by, in some embodiments, switching between the W and T images to shorten computational time requirements, thus enabling high video rate. To avoid discontinuities in video mode, the switching includes applying additional processing blocks, 15 which include in some embodiments image scaling and shifting. In some embodiments, when a no-switching criterion is fulfilled, optical zoom is achieved in video mode without switching.

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As used herein, the term "video" refers to any camera output that captures motion by a series of pictures (images), as opposed to "still mode" that friezes motion. Examples of "video" in cellphones and smartphones include "video mode" or "preview mode".

In order to reach optical zoom capabilities, a different magnification image of the same scene is captured (grabbed) by each camera, resulting in FOV overlap between the two cameras. Processing is applied on the two images to fuse and output one fused image in still mode. The fused image is processed according to a user zoom factor request. As part of the fusion procedure, up-sampling may be applied on one or both of the grabbed images to scale it to the image grabbed by the Tele camera or to a scale defined by the user. The fusion or up-sampling may be applied to only some of the pixels of a sensor. Down-sampling can be performed as well if the output resolution is smaller than the sensor resolution.

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The cameras and associated methods disclosed herein address and correct many of the problems and disadvantages of known dual-aperture optical zoom digital cameras. They provide an overall zoom solution that refers to all aspects: optics, algorithmic processing and system hardware (HW).

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In a dual-aperture camera image plane, as seen by each camera (and respective image sensor), a given object will be shifted and have different perspective (shape). This is referred to as point-of-view (POV). The system output image can have the shape and position of either camera image or the shape or position of a combination thereof. If the output image retains 5 the Wide image shape then it has the Wide perspective POV. If it retains the Wide camera position then it has the Wide position POV. The same applies for Tele images position and perspective. As used in this description, the perspective POV may be of the Wide or Tele cameras, while the position POV may shift continuously between the Wide and Tele cameras. In fused images, it is possible to register Tele image pixels to a matching pixel set within the Wide image pixels, in which case the output image will retain the Wide POV ("Wide 10 fusion"). Alternatively, it is possible to register Wide image pixels to a matching pixel set within the Tele image pixels, in which case the output image will retain the Tele POV ("Tele fusion"). It is also possible to perform the registration after either camera image is shifted, in which case the output image will retain the respective Wide or Tele perspective POV.

In an exemplary embodiment, there is provided a zoom digital camera comprising a Wide imaging section that includes a fixed focal length Wide lens with a Wide FOV and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene, a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene, and a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

In an exemplary embodiment there is provided a method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of providing in the digital camera a Wide imaging section having a Wide lens with a Wide FOV and a Wide sensor, a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections, and configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF value and a higher ZF value.

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In some exemplary embodiments, the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

In some exemplary embodiments, the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

In some exemplary embodiments, the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

In some exemplary embodiments, the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

In some exemplary embodiments, the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

In some exemplary embodiments, the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

In some exemplary embodiments, the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

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In some exemplary embodiments, the user inputs include a zoom factor, a camera mode and a region of interest.

In some exemplary embodiments, the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1. For a definition of TTL and EFL see e,g. co-assigned US published patent application No. 20150244942.

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In some exemplary embodiments, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

In some exemplary embodiments, the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

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BRIEF DESCRIPTION OF THE DRAWINGS

Non-limiting examples of embodiments disclosed herein are described below with reference to figures attached hereto that are listed following this paragraph. Identical
structures, elements or parts that appear in more than one figure are generally labeled with a same numeral in all the figures in which they appear. The drawings and descriptions are meant to illuminate and clarify embodiments disclosed herein, and should not be considered limiting in any way.

FIG. 1A shows schematically a block diagram illustrating an exemplary dual-aperturezoom imaging system disclosed herein;

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A:

FIG. 2 shows an example of a Wide sensor, a Tele sensor and their respective FOVs;

FIG. 3A shows an embodiment of an exemplary method disclosed herein for acquiring

15 a zoom image in video/preview mode;

FIG. 3B shows exemplary feature points in an object;

FIG. 3C shows schematically a known rectification process;

FIG. 4 shows a graph illustrating an effective resolution zoom factor.

20 DETAILED DESCRIPTION

Definitions:

Sharpness score: the gradients (dx, dy) of the image are compared (through subtraction) to the gradients of its low pass filtered version. A higher difference indicates a sharper original image. The result of this comparison is normalized with respect to the average variations (for example, sum of absolute gradients) of the original image, to obtain an absolute sharpness score.

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Edge score: for each image, the edges are found (for example, using Canny edge detection) and the average intensity of gradients along them is calculated, for example, by calculating the magnitude of gradients (dx, dy) for each edge pixel, summing the results and dividing by the total number of edge pixels. The result is the edge score.

Effective resolution score: this score is calculated only in a region of interest (ROI) and provides a good indication of the effective resolution level in the image. As used herein, "ROI" is a user-defined sub-region of the image that may be exemplarily 4% or less of the

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image area. The effective resolution score can be derived from a combination of the sharpness scores and edge scores for each image, for example by normalizing both to be between [0, 1] and by taking their average.

FIG. 1A shows schematically a block diagram illustrating an exemplary embodiment of a dual-aperture zoom imaging system (also referred to simply as "dual-camera" or "dual-5 aperture camera") disclosed herein and numbered 100. Dual-aperture camera 100 comprises a Wide imaging section ("Wide camera") that includes a Wide lens block 102, a Wide image sensor 104 and a Wide image processor 106. Dual-aperture camera 100 further comprises a Tele imaging section ("Tele camera") that includes a Tele lens block 108, a Tele image sensor **110** and a Tele image processor **112**. The image sensors may be physically separate or may 10 be part of a single larger image sensor. The Wide sensor pixel size can be equal to or different from the Tele sensor pixel size. Dual-aperture camera 100 further comprises a camera fusion processing core (also referred to as "controller") 114 that includes a sensor control module 116, a user control module 118, a video processing module 126 and a capture processing module 128, all operationally coupled to sensor control block 110. User control module 118 15 comprises an operational mode function 120, a ROI function 122 and a zoom factor (ZF) function 124.

Sensor control module **116** is connected to the two (Wide and Tele) cameras and to the user control module 118 and used to choose, according to the zoom factor, which of the 20 sensors is operational and to control the exposure mechanism and the sensor readout. Mode choice function 120 is used for choosing capture/video modes. ROI function 122 is used to choose a region of interest. The ROI is the region on which both cameras are focused on. Zoom factor function 124 is used to choose a zoom factor. Video processing module 126 is connected to mode choice function 120 and used for video processing. It is configurable to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data 25 and to make a decision regarding video output. Specifically, upon evaluation of a noswitching criterion, if the no-switching criterion is fulfilled, module **126** is configurable to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value. If the no-switching criterion is not fulfilled, module **126** is configurable to combine in still mode, at a predefined range of 30 ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view. Still processing module 128 is connected to the mode choice function 120 and used for high image quality still mode images. The video processing module is applied when the user desires to shoot in video mode. The capture

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processing module is applied when the user wishes to shoot still pictures.

FIG. 1B is a schematic mechanical diagram of the dual-aperture zoom imaging system of FIG. 1A. Exemplary dimensions: Wide lens TTL = 4.2mm and EFL = 3.5mm; Tele lens TTL = 6mm and EFL = 7 mm; both Wide and Tele sensors 1/3 inch; external dimensions of Wide and Tele cameras: width (w) and length (1) = 8.5 mm and height (h) = 6.8 mm; distance "d" between camera centers = 10mm.

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Following is a detailed description and examples of different methods of use of dualaperture camera 100.

Still mode operation/function 10

In still camera mode, the obtained image is fused from information obtained by both cameras at all zoom levels, see FIG. 2, which shows a Wide sensor 202 and a Tele sensor 204 and their respective FOVs. Exemplarily, as shown, the Tele sensor FOV is half the Wide sensor FOV. The still camera mode processing includes two stages: the first stage includes 15 setting HW settings and configuration, where a first objective is to control the sensors in such a way that matching FOVs in both images (Tele and Wide) are scanned at the same time, a second objective is to control the relative exposures according to the lens properties, and a third objective is to minimize the required bandwidth from both sensors for the ISPs. The second stage includes image processing that fuses the Wide and the Tele images to achieve optical zoom, improves SNR and provides wide dynamic range.

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FIG. 3A shows image line numbers vs. time for an image section captured by CMOS sensors. A fused image is obtained by line (row) scans of each image. To prevent matching FOVs in both sensors to be scanned at different times, a particular configuration is applied by the camera controller on both image sensors while keeping the same frame rate. The difference in FOV between the sensors determines the relationship between the rolling shutter time and the vertical blanking time for each sensor.

Video mode operation/function

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Smooth transition

When a dual-aperture camera switches the camera output between cameras or points of view, a user will normally see a "jump" (discontinuous) image change. However, a change in the zoom factor for the same camera and POV is viewed as a continuous change. A

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"smooth transition" (ST) is a transition between cameras or POVs that minimizes the jump effect. This may include matching the position, scale, brightness and color of the output image before and after the transition. However, an entire image position matching between the camera outputs is in many cases impossible, because parallax causes the position shift to be dependent on the object distance. Therefore, in a smooth transition as disclosed herein, the position matching is achieved only in the ROI region while scale brightness and color are matched for the entire output image area.

Zoom-in and Zoom-out in video mode

- In video mode, sensor oversampling is used to enable continuous and smooth zoom experience. Processing is applied to eliminate the changes in the image during crossover from one camera to the other. Zoom from 1 to Z_{switch} is performed using the Wide sensor only. From Z_{switch} and on, it is performed mainly by the Tele sensor. To prevent "jumps" (roughness in the image), switching to the Tele image is done using a zoom factor which is a bit higher
 (Z_{switch} +ΔZoom) than Z_{switch}. ΔZoom is determined according to the system's properties and is different for cases where zoom-in is applied and cases where zoom-out is applied (ΔZoom_{in}≠ ΔZoom_{out}). This is done to prevent residual jumps artifacts to be visible at a certain zoom factor. The switching between sensors, for an increasing zoom and for decreasing zoom, is done on a different zoom factor.
- The zoom video mode operation includes two stages: (1) sensor control and configuration and (2) image processing. In the range from 1 to Z_{switch}, only the Wide sensor is operational, hence, power can be supplied only to this sensor. Similar conditions hold for a Wide AF mechanism. From Z_{switch}+ΔZoom to Z_{max} only the Tele sensor is operational, hence, power is supplied only to this sensor. Similarly, only the Tele sensor is operational and power is supplied only to it for a Tele AF mechanism. Another option is that the Tele sensor is operational and the Wide sensor is working in low frame rate. From Z_{switch}+ΔZoom, both sensors are operational.

<u>Zoom-in</u>: at low ZF up to slightly above ZF_T (the zoom factor that enables switching between Wide and Tele outputs) the output image is the digitally zoomed, unchanged Wide camera output. ZF_T is defined as follows:

$$ZF_T = Tan (FOV_{Wide})/Tan (FOV_{Tele})$$

where Tan refers to "tangent", while FOV_{Wide} and FOV_{Tele} refer respectively to the Wide and

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Tele lens fields of view (in degrees). As used herein, the FOV is measured from the center axis to the corner of the sensor (i.e. half the angle of the normal definition). Switching cannot take place below ZF_T and it can above it.

In some embodiments for the up-transfer ZF, as disclosed in co-invented and co-5 owned US patent 9,185,291, the output is a transformed Tele camera output, where the transformation is performed by a global registration (GR) algorithm to achieve smooth transition. As used herein "global registration" refers to an action for which the inputs are the Wide and Tele images. The Wide image is cropped to display the same FOV as the Tele image. The Tele image is passed through a low pass filter (LPF) and resized to make its appearance as close as possible to the Wide image (lower resolution and same pixel count). 10 The outputs of GR are corresponding feature point pairs in the images along with their disparities, and parameters for differences between the images, i.e. shift and scale. As used herein, "feature point" refers to a point such as points 10a-d in FIG. 3B and refers to a point (pixel) of interest on an object in an image. For purposes set forth in this description, a feature point should be reproducible and invariant to changes in image scale, noise and illumination. 15 Such points usually lie on corners or other high-contrast regions of the object.

Stages of Global Registration

In some exemplary embodiments, global registration may be performed as follows:

20 1. Find interest points (features) in each image separately by filtering it with, exemplarily, a Difference of Gaussians filter, and finding local extrema on the resulting image.

Find feature correspondences (features in both images that describe the same point in space) in a "matching" process. These are also referred to as "feature pairs", "correspondence
 pairs" or "matching pairs". This is done by comparing each feature point from one (Tele or Wide) image (referred to hereinafter as "image 1") to all feature points in that region from the other (respectively Wide or Tele) image (referred to hereinafter as "image 2"). The features are compared only within their group of minima/maxima, using patch normalized cross-correlation. As used herein, "patch" refers to a group of neighboring pixels around an origin pixel.

3. The normalized cross correlation of two image patches t(x, y) and f(x, y) is $\frac{1}{n} \sum_{x,y} \frac{(f(x,y) - \bar{f})(t(x,y) - \bar{t})}{\sigma_f \sigma_t}$ where n is the number of pixels in both patches, \bar{f} is the average of fand σ_f is the standard deviation of f. A match for a feature point from image 1 is only

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confirmed if its correlation score is much higher (for example, x1.2) than the next-best matching feature from image 2.

4. Find the disparity between each pair of corresponding features (also referred to as "matching pair") by subtracting their x and y coordinate values.

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5. Filter bad matching points:

a. Following the matching process, matches that include feature points from image 2 that were matched to more than one feature from image 1 are discarded.

b. Matching pairs whose disparity is inconsistent with the other matching pairs are discarded. For example, if there is one corresponding pair which whose disparity is lower or higher than the others by 20 pixels.

6. The localization accuracy for matched points from image 2 is refined by calculating a correlation of neighboring pixel patches from image 2 with the target patch (the patch around the current pixel (of the current matching pair) from image 1, modeling the results as a parabola and finding its maximum.

¹⁵ 7. Rotation and fine scale differences are calculated between the two images according to the matching points (for example, by subtracting the center of mass from each set of points, i.e. the part of the matching points belonging to either the Wide or the Tele image, and solving a least squares problem).

8. After compensating for these differences, since the images were rectified, the disparity
 ²⁰ in the Y axis should be close to 0. Matching points that do not fit this criterion are discarded. A known rectification process is illustrated in FIG. 3C.

9. Finally, the remaining matching points are considered true and the disparities for them are calculated. A weighted average of the disparity is taken as the shift between both images. The maximum difference between disparity values is taken as the disparity range.

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10. At various stages during GR, if there are not enough feature/matching points remaining, the GR is stopped and returns a failure flag.

In addition, it is possible to find range calibration to the rectification process by finding the shiftI = shift for objects at infinity and defining shiftD=shift-shiftI and disparity D

= disparity-shiftI. We then calculate $object \, distance = \frac{focalLength \cdot baseline}{disparityD \cdot pixelSize}$, where "baseline" is the distance between cameras.

Returning now to the Zoom-in process, in some embodiments, for higher ZF than the up-transfer ZF the output is the transformed Tele camera output, digitally zoomed. However, in other embodiments for the up-transfer ZF there will be no switching from the Wide to the Tele camera output, i.e. the output will be from the Wide camera, digitally zoomed. This "no switching" process is described next.

No Switching

Switching from the Wide camera output to the transformed Tele camera output will be performed unless some special condition (criterion), determined based on inputs obtained from the two camera images, occurs. In other words, switching will not be performed only if at least one of the following no-switching criteria is fulfilled:

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if the shift calculated by GR is greater than a first threshold, for example 50 pixels.

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2. if the disparity range calculated by GR is greater than a second threshold, for example 20 pixels, because in this case there is no global shift correction that will suppress movement/jump for all objects distances (smooth transition is impossible for all objects).

3. if the effective resolution score of the Tele image is lower than that of the Wide image. In this case, there is no point in performing the transition because no value (i.e. resolution) is gained. Smooth transition is possible but undesirable.

4. if the GR fails, i.e. if the number of matching pairs found is less than a third threshold, for example 20 matching pairs.

5. if, for example, that are imaged onto the overlap area are calculated to be closer than a first threshold distance, for example 30 cm, because this can result in a large image shift to obtain ST.

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6. if some objects (for example two objects) that are imaged in the overlap area are calculated to be closer than a second threshold distance, for example 50 cm, while other objects (for example two objects) are calculated to be farther than a third threshold distance for example 10 m. The reason is that the shift between an object position in the Wide and Tele cameras is object distance dependent, where the closer the objects the larger the shift, so an image containing significantly close and far objects cannot be matched by simple transformation (shift scale) to be similar and thus provide ST between cameras.

Zoom-out: at high ZF down to slightly below ZFT, the output image is the digitally zoomed transformed Tele camera output. For the down-transfer ZF, the output is a shifted Wide camera output, where the Wide shift correction is performed by the GR algorithm to achieve smooth transition, i.e. with no jump in the ROI region. For lower (than the downtransfer) ZF, the output is basically the down-transfer ZF output digitally zoomed but with gradually smaller Wide shift correction, until for ZF=1 the output is the unchanged Wide camera output. 5

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Note that if a no-switching criterion is not fulfilled, then the camera will output without fusion continuous zoom video mode output images of the object or scene, each output image having a respective output resolution, the video output images being provided with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output resolution is determined by the Wide sensor, and wherein at the higher ZF value the output resolution is determined by the Tele sensor.

FIG. 3A shows an embodiment of a method disclosed herein for acquiring a zoom image in video/preview mode for 3 different zoom factor (ZF) ranges: (a) ZF range = 1 : Z_{switch} ; (b) ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$: and (c) Zoom factor range = Z_{switch} + $\Delta Zoom_{in}$: Z_{max} . The description is with reference to a graph of effective resolution vs. zoom 10 factor (FIG. 4). In step 302, sensor control module 116 chooses (directs) the sensor (Wide, Tele or both) to be operational. Specifically, if the ZF range = $1:Z_{switch}$, module **116** directs the Wide sensor to be operational and the Tele sensor to be non-operational. If the ZF range is Z_{switch} : $Z_{\text{switch}} + \Delta Z_{\text{oomin}}$, module **116** directs both sensors to be operational and the zoom image is generated from the Wide sensor. If the ZF range is $Z_{switch} + \Delta Zoom_{in}$: Z_{max} , module 15 **116** directs the Wide sensor to be non-operational and the Tele sensor to be operational. After the sensor choice in step **302**, all following actions are performed in video processing core 126. Optionally, in step 304, color balance is calculated if two images are provided by the two sensors. Optionally yet, in step **306**, the calculated color balance is applied in one of the 20 images (depending on the zoom factor). Further optionally, in step 308, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient can be used to set an AF position in step 310. In step 312, an output of any of steps **302-308** is applied on one of the images (depending on the zoom factor) for image signal processing that may include denoising, demosaicing, sharpening, scaling, etc. In step **314**, the processed image is resampled according to the transformation coefficient, the 25 requested ZF (obtained from zoom function 124) and the output video resolution (for example 1080p). To avoid a transition point to be executed at the same ZF, ΔZ oom can change while zooming in and while zooming out. This will result in hysteresis in the sensor switching point.

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In more detail, for ZF range 1: Z_{switch} , for ZF < Z_{switch} , the Wide image data is transferred to the ISP in step **312** and resampled in step **314**. For ZF range = Z_{switch} : Z_{switch} + $\Delta Zoom_{in}$, both sensors are operational and the zoom image is generated from the Wide sensor. The color balance is calculated for both images according to a given ROI. In addition, for a given ROI, registration is performed between the Wide and Tele images to output a transformation coefficient. The transformation coefficient is used to set an AF position. The transformation coefficient includes the translation between matching points in the two images. This translation can be measured in a number of pixels. Different translations will result in a different number of pixel movements between matching points in the images. This movement can be translated into depth and the depth can be translated into an AF position. This enables to set the AF position by only analyzing two images (Wide and Tele). The result is fast

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focusing.

Both color balance ratios and transformation coefficient are used in the ISP step. In parallel, the Wide image is processed to provide a processed image, followed by resampling. For ZF range = $Z_{switch} + \Delta Zoom_{in}$: Z_{max} and for Zoom factor > $Z_{switch} + \Delta Zoom_{in}$, the color balance calculated previously is now applied on the Tele image. The Tele image data is transferred to the ISP in step **312** and resampled in step **314**. To eliminate crossover artifacts and to enable smooth transition to the Tele image, the processed Tele image is resampled according to the transformation coefficient, the requested ZF (obtained from zoom function **124**) and the output video resolution (for example 1080p).

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FIG. 4 shows the effective resolution as a function of the zoom factor for a zoom-in case and for a zoom-out case $\Delta Zoom_{up}$ is set when one zooms in, and $\Delta Zoom_{down}$ is set when one zooms out. Setting $\Delta Zoom_{up}$ to be different from $\Delta Zoom_{down}$ will result in transition between the sensors to be performed at different zoom factor ("hysteresis") when zoom-in is used and when zoom-out is used. This hysteresis phenomenon in the video mode results in smooth continuous zoom experience.

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In conclusion, dual aperture optical zoom digital cameras and associate methods disclosed herein reduce the amount of processing resources, lower frame rate requirements, reduce power consumption, remove parallax artifacts and provide continuous focus (or provide loss of focus) when changing from Wide to Tele in video mode. They provide a dramatic reduction of the disparity range and avoid false registration in capture mode. They reduce image intensity differences and enable work with a single sensor bandwidth instead of two, as in known cameras.

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All patent applications mentioned in this specification are herein incorporated in their entirety by reference into the specification, to the same extent as if each individual patent application was specifically and individually indicated to be incorporated herein by reference. In addition, citation or identification of any reference in this application shall not be construed as an admission that such reference is available as prior art to the present disclosure.

While this disclosure has been described in terms of certain embodiments and generally associated methods, alterations and permutations of the embodiments and methods

will be apparent to those skilled in the art. The disclosure is to be understood as not limited by the specific embodiments described herein, but only by the scope of the appended claims.
WHAT IS CLAIMED IS:

1. A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

2. The camera of claim 1, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

3. The camera of claim 1, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

4. The camera of claim 1, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

5. The camera of claim 1, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

6. The camera of claim 1, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

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7. The camera of claim 1, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

8. The camera of claim 1, wherein the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

9. The camera of claim 8, wherein the user inputs include a zoom factor, a camera mode and a region of interest.

10. The camera of any of the claims 1-9, wherein the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1.

11. The camera of any of the claims 1-9, wherein, if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor.

12. The camera of any of the claims 1-9, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

13. A method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV) and a Wide sensor, a Tele imaging section having a Tele lens with

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a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value.

14. The method of claim 13, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

15. The method of claim 13, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

16. The method of claim 13, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

17. The method of claim 13, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

18. The method of claim 13, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

19. The method of claim 13, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third threshold distance.

20. The method of any of the claims 13-19, further comprising the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some

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of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

21. The method of any of the claims 13-19, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

<u>100</u>



FIG. 1A







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FIG. 2



FIG. 3A



FIG. 3B



FIG. 3C



FIG. 4

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APPLICATION NUMBER	FILING or 371(c) DATE	GRP ART UNIT	FIL FEE REC'D	ATTY.DOCKET.NO	TOT CLAIMS IND CLAIMS
15/324,720	01/08/2017		600	COREPH-0159 US NP	21 2
				CC	ONFIRMATION NO. 5811
92342				FILING REC	EIPT
Nathan & Asse P.O.Box 1017 Tel Aviv, 6110	ociates Patent / 8 101	Agents Ltd			00000098143720

Date Mailed: 03/20/2018

Receipt is acknowledged of this non-provisional patent application. The application will be taken up for examination in due course. Applicant will be notified as to the results of the examination. Any correspondence concerning the application must include the following identification information: the U.S. APPLICATION NUMBER, FILING DATE, NAME OF APPLICANT, and TITLE OF INVENTION. Fees transmitted by check or draft are subject to collection. Please verify the accuracy of the data presented on this receipt. If an error is noted on this Filing Receipt, please submit a written request for a Filing Receipt Correction. Please provide a copy of this Filing Receipt with the changes noted thereon. If you received a "Notice to File Missing Parts" for this application, please submit any corrections to this Filing Receipt with your reply to the Notice. When the USPTO processes the reply to the Notice, the USPTO will generate another Filing Receipt incorporating the requested corrections

Inventor(s)

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Applicant(s)

Corephotonics Ltd., Tel-Aviv, ISRAEL

Power of Attorney: The patent practitioners associated with Customer Number 92342

Domestic Priority data as claimed by applicant

This application is a 371 of PCT/IB2016/053803 06/26/2016 which claims benefit of 62/204,667 08/13/2015

Foreign Applications for which priority is claimed (You may be eligible to benefit from the **Patent Prosecution Highway** program at the USPTO. Please see <u>http://www.uspto.gov</u> for more information.) - None. Foreign application information must be provided in an Application Data Sheet in order to constitute a claim to foreign priority. See 37 CFR 1.55 and 1.76.

Permission to Access Application via Priority Document Exchange: Yes

Permission to Access Search Results: Yes

Applicant may provide or rescind an authorization for access using Form PTO/SB/39 or Form PTO/SB/69 as appropriate.

If Required, Foreign Filing License Granted: 03/17/2018

The country code and number of your priority application, to be used for filing abroad under the Paris Convention, is **US 15/324,720**

Projected Publication Date: 06/28/2018

Non-Publication Request: No

Early Publication Request: No ** SMALL ENTITY **

Title

DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

Preliminary Class

Statement under 37 CFR 1.55 or 1.78 for AIA (First Inventor to File) Transition Applications: No

PROTECTING YOUR INVENTION OUTSIDE THE UNITED STATES

Since the rights granted by a U.S. patent extend only throughout the territory of the United States and have no effect in a foreign country, an inventor who wishes patent protection in another country must apply for a patent in a specific country or in regional patent offices. Applicants may wish to consider the filing of an international application under the Patent Cooperation Treaty (PCT). An international (PCT) application generally has the same effect as a regular national patent application in each PCT-member country. The PCT process **simplifies** the filing of patent applications on the same invention in member countries, but **does not result** in a grant of "an international patent" and does not eliminate the need of applicants to file additional documents and fees in countries where patent protection is desired.

Almost every country has its own patent law, and a person desiring a patent in a particular country must make an application for patent in that country in accordance with its particular laws. Since the laws of many countries differ in various respects from the patent law of the United States, applicants are advised to seek guidance from specific foreign countries to ensure that patent rights are not lost prematurely.

Applicants also are advised that in the case of inventions made in the United States, the Director of the USPTO must issue a license before applicants can apply for a patent in a foreign country. The filing of a U.S. patent application serves as a request for a foreign filing license. The application's filing receipt contains further information and guidance as to the status of applicant's license for foreign filing.

Applicants may wish to consult the USPTO booklet, "General Information Concerning Patents" (specifically, the section entitled "Treaties and Foreign Patents") for more information on timeframes and deadlines for filing foreign patent applications. The guide is available either by contacting the USPTO Contact Center at 800-786-9199, or it can be viewed on the USPTO website at http://www.uspto.gov/web/offices/pac/doc/general/index.html.

For information on preventing theft of your intellectual property (patents, trademarks and copyrights), you may wish to consult the U.S. Government website, http://www.stopfakes.gov. Part of a Department of Commerce initiative, this website includes self-help "toolkits" giving innovators guidance on how to protect intellectual property in specific page 2 of 4

countries such as China, Korea and Mexico. For questions regarding patent enforcement issues, applicants may call the U.S. Government hotline at 1-866-999-HALT (1-866-999-4258).

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U.S. APPLICATION NUMBER NO.	FIRST NAMED INVENTOR		ATTY.	DOCKET NO.
15/324,720	Noy Cohen		COREPI	H-0159 US NP
92342	Γ	INTER	NATIONAL APPI	LICATION NO.
Nathan & Associates Patent Agents Ltd	_	PCT/IB2016/053803		
P.O.Box 10178	[I.A. FILI	NG DATE	PRIORITY DATE
Tel Aviv, 6110101	Γ	06/26	5/2016	08/13/2015
ISRAEL	-	37	CONFIRMA 71 ACCEPT	ATION NO. 5811 ANCE LETTER

OC00000098143721

Date Mailed: 03/20/2018

NOTICE OF ACCEPTANCE OF APPLICATION UNDER 35 U.S.C 371 AND 37 CFR 1.495

The applicant is hereby advised that the United States Patent and Trademark Office, in its capacity as a Designated / Elected Office (37 CFR 1.495), has ACCEPTED the above identified international application for national patentability examination in the United States Patent and Trademark Office.

The United States Application Number assigned to the application is shown above. A Filing Receipt will be issued for the present application in due course. THE DATE APPEARING ON THE FILING RECEIPT AS THE "FILING DATE or 371(c) DATE" IS THE DATE ON WHICH THE LAST OF THE 35 U.S.C. 371 (c)(1) and (c)(2) REQUIREMENTS HAS BEEN RECEIVED IN THE OFFICE. THIS DATE IS SHOWN BELOW. The filing date of the above identified application is the international filing date of the international application (Article 11(3) and 35 U.S.C. 363)

<u>01/08/2017</u>

DATE OF RECEIPT OF 35 U.S.C. 371(c)(1) and (c)(2) REQUIREMENTS

The following items have been received:

- Indication of Small Entity Status
- Copy of the International Application filed on 01/08/2017
- Copy of the International Search Report filed on 01/08/2017
- Preliminary Amendments filed on 01/08/2017
- Information Disclosure Statements filed on 01/08/2017
- Inventor's Oath or Declaration filed on 01/08/2017
- U.S. Basic National Fees filed on 01/08/2017
- Assignment filed on 01/08/2017
- Authorize Access to Search Results filed on 01/08/2017
- Priority Documents filed on 01/08/2017
- Power of Attorney filed on 01/08/2017
- Authorization to Permit Access filed on 01/08/2017
- Application Data Sheet (37 CFR 1.76) filed on 01/08/2017

Applicant is reminded that any communications to the United States Patent and Trademark Office must be mailed to the address given in the heading and include the U.S. application no. shown above (37 CFR 1.5)

ROSA M WEST

Telephone: (571) 272-1019

MULTIPLE DEPENDENT CLAIM					Application Number Filing Date								
FEE CALCULATION SHEET							15324720						
		Substitut (For use w	e for Form vith Form F	PTO-1360 PTO/SB/06))		Applicant(s)	Noy Co	hen				
								* May	be used for a	lditional clai	ms or amend	ments	
CLAIMS	AS F	FILED	AFTEF AMEN	R FIRST DMENT	AFTER AMEN	SECOND DMENT			*		*		*
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Total Claims	57		21		0								

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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP	5811
92342 Nathan & Asso	7590 06/19/2018 ciates Patent Agents I td		EXAM	INER
P.O.Box 10178 Tel Aviv, 6110	101		TRAN, I	NHAN T
ISRAEL			ART UNIT	PAPER NUMBER
			2664	
			NOTIFICATION DATE	DELIVERY MODE
			06/19/2018	ELECTRONIC

Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

Notice of the Office communication was sent electronically on above-indicated "Notification Date" to the following e-mail address(es):

info@natpatent.com mnathan@post.tau.ac.il talya.nathan@gmail.com

	Application No. 15/324,720	Applicant(s COHEN ET) AL.
Office Action Summary	Examiner NHAN T. TRAN	Art Unit 2664	AIA (First Inventor to File) Status Yes
The MAILING DATE of this communication app Period for Reply	bears on the cover sheet with the	corresponden	ace address
 A SHORTENED STATUTORY PERIOD FOR REPL THIS COMMUNICATION. Extensions of time may be available under the provisions of 37 CFR 1.1 after SIX (6) MONTHS from the mailing date of this communication. If NO period for reply is specified above, the maximum statutory period Failure to reply within the set or extended period for reply will, by statute Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b). 	Y IS SET TO EXPIRE <u>3</u> MONTH 36(a). In no event, however, may a reply be ti will apply and will expire SIX (6) MONTHS from a, cause the application to become ABANDON g date of this communication, even if timely file	S FROM THE mely filed n the mailing date c ED (35 U.S.C. § 13 id, may reduce any	E MAILING DATE OF of this communication. 3).
Status			
1) Responsive to communication(s) filed on $\frac{1/8/2}{1}$	<u>2017</u> .		
A declaration(s)/attidavit(s) under 37 CFR 1.	130(b) was/were filed on		
2a) This action is FINAL . $2b)$ This	action is non-final.		
3) An election was made by the applicant in resp	onse to a restriction requirement	set forth duri	ng the interview on
; the restriction requirement and election	nave been incorporated into thi	s action.	to the menuite is
4) Since this application is in condition for allowa	nce except for formal matters, pr	osecution as	to the merits is
closed in accordance with the practice under E	<i>x parte Quayle</i> , 1935 C.D. 11, 4	53 O.G. 213.	
 Disposition of Claims* 5) ☐ Claim(s) <u>1-21</u> is/are pending in the application 5a) Of the above claim(s) is/are withdrated is/are withdrated for a claim(s) is/are allowed. 7) ☐ Claim(s) <u>1.2.8-11,13,14,20 and 21</u> is/are reject 8) ☐ Claim(s) <u>3-7 and 15-19</u> is/are objected to. 9) ☐ Claim(s) are subject to restriction and/ot * If any claims have been determined allowable, you may be e participating intellectual property office for the corresponding a http://www.uspto.gov/patents/init_events/pph/index.jsp or send 11) ☐ The specification is objected to by the Examined 11) ☐ The drawing(s) filed on <u>1/8/2017</u> is/are: a) ☐ a Applicant may not request that any objection to the Replacement drawing sheet(s) including the correct 	wn from consideration. ted. ligible to benefit from the Patent Pro pplication. For more information, ple d an inquiry to <u>PPHfeedback@uspto.</u> er. accepted or b)☐ objected to by t drawing(s) be held in abeyance. Set tion is required if the drawing(s) is of	esecution Higl ase see <u>aov</u> . he Examiner. te 37 CFR 1.85 ojected to. See	1way program at a 5(a). 37 CFR 1.121(d).
Priority under 35 U.S.C. § 119 12) Acknowledgment is made of a claim for foreign Certified copies: a) All b) Some** c) None of the: 1. Certified copies of the priority documen	n priority under 35 U.S.C. § 119(a	ı)-(d) or (f).	
 2. Certified copies of the priority document 3. Copies of the certified copies of the priority application from the International Burea ** See the attached detailed Office action for a list of the certified 	its have been received in Applica brity documents have been received u (PCT Rule 17.2(a)). ed copies not received.	tion No ved in this Na	 tional Stage
Attachment(s) 1) X Notice of References Cited (PTO-892)	3) 🔲 Interview Summar Paper No(s)/Mail F	y (PTO-413) Date.	
2) X Information Disclosure Statement(s) (PTO/SB/08a and/or PTO/ Paper No(s)/Mail Date	SB/08b) 4) Other:	•	

DETAILED ACTION

The present application, filed on or after March 16, 2013, is being examined under the

first inventor to file provisions of the AIA.

Information Disclosure Statement

1. The information disclosure statement (IDS) submitted on 1/8/2017 is in

compliance with the provisions of 37 CFR 1.97. Accordingly, the information disclosure

statement is being considered by the examiner.

Claim Rejections - 35 USC § 102

2. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that

form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

(a)(1) the claimed invention was patented, described in a printed publication, or in public use, on sale or otherwise available to the public before the effective filing date of the claimed invention.

3. Claims 1, 2, 4, 8-14, 20 and 21 are rejected under 35 U.S.C. 102(a)(1) as being anticipated by Shabtay et al. (WO 2014/199338, hereinafter "Shabtay", cited in the IDS dated 1/8/2017).

Regarding claim 1, Shabtay discloses a zoom digital camera (Figs. 1 & 2) comprising:

a) a Wide imaging section (102/104/106) that includes a fixed focal length Wide

lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section

operative to provide Wide image data of an object or scene (Fig. 1A; page 4, lines 4-17; page 6, lines 23-35 and page 7, lines 28-33);

b) a Tele imaging section (108/110/112) that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene (Fig. 1A; page 4, lines 4-17; page 6, lines 23-35 and page 7, lines 28-33); and

c) a camera controller (114) operatively coupled to the Wide and Tele imaging sections (see Fig. 1A and page 8, lines 1-6), the camera controller configured to evaluate a no-switching criterion determined by inputs from both Wide and Tele image data, and, if the no-switching criterion is fulfilled, to output a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value (see page 14, lines 11-34, wherein a no-switching criterion is met when the zoom factor is within the range of 1 to Zswitch (or slightly above ZFT), the zoom video is only output from the Wide sensor using digital zoom. The Tele sensor is not operational in this mode).

Regarding claim 2, it is also seen in Shabtay that the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold (see page 13, lines 10-14 and page 14, lines 11-34. It should be noted that the first threshold is considered as ZF in the still image mode, and 1 to Zswitch in the video mode, wherein "global registration" is given its

broadest reasonable interpretation as the registration of the above thresholds that have been programmed beforehand in the camera).

Regarding claim 8, Shabtay further discloses that the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs (see Fig. 1A, user control 118; page 8, lines 5-6).

Regarding claim 9, as also seen in Shabtay, the user inputs include a zoom factor (ZF), a camera mode and a region of interest (page 8, lines 5-6).

Regarding claim 10, Shabtay also clearly discloses that the Tele lens includes a ration of total track length (TTL)/effective focal length (EFL) smaller than 1 *(see page 8, lines 20-21 in which TTL= 6mm and EFL= 7mm).*

Regarding claim 11, it is also seen in Shabtay that if the no-switching criterion is not fulfilled, the camera controller is further configured to output video output images with a smooth transition when switching between the lower ZF value and the higher ZF value or vice versa, wherein at the lower ZF value the output image is determined by the Wide sensor, and wherein at the higher ZF value the output image is determined by the Tele sensor (see Fig. 6 and page 15, lines 8-20).

Regarding claim 12, Shabtay further discloses that the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view (see page 13, lines 5-27, wherein in a still image mode, a fused output image is obtained using both Wide image data and Tele image data for a predetermined range of ZF values).

Regarding claims 13, 14 & 20, the subject matter of these claims are met by Shabtay as discussed in claims 1, 2 and 12, respectively.

Regarding claim 21, Shabtay also discloses that the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas (see claim 17 in Shabtay).

Allowable Subject Matter

4. Claims 3-7 and 15-19 are objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claims.

5. The following is a statement of reasons for the indication of allowable subject matter:

The prior art of record fails to teach or fairly suggest the limitations of each of claims 3-7 and 15-19. The Examiner has found no teaching, support and/or reason that render these claims obvious over the disclosure of Shabtay reference in view of the whole prior art of record. Shabtay and other teachings provide no disclosure for the no-switching criterion setting as clearly defined by each of claims 3-7. For claims 15-19, the same reason is applied as these claims recite similar method limitations as in the apparatus claims 3-7.

Conclusion

6. Any inquiry concerning this communication or earlier communications from the examiner should be directed to NHAN T. TRAN whose telephone number is (571)272-7371. The examiner can normally be reached on Monday - Friday 8:30AM - 5:00PM.

Examiner interviews are available via telephone, in-person, and video conferencing using a USPTO supplied web-based collaboration tool. To schedule an interview, applicant is encouraged to use the USPTO Automated Interview Request (AIR) at http://www.uspto.gov/interviewpractice.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Lin Ye can be reached on 571-272-7372. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free). If you would like assistance from a USPTO Customer Service Representative or access to the automated information system, call 800-786-9199 (IN USA OR CANADA) or 571-272-1000.

/NHAN T TRAN/ Primary Examiner, Art Unit 2664

Notice of References Cited	Application/Control No. 15/324,720	Applicant(s)/Patent Under Reexamination COHEN ET AL.			
Notice of Helefences Offeu	Examiner	Art Unit			
	NHAN T. TRAN	NHAN T. TRAN 2664 Pag			

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*	А	US-2007/0025713 A1	02-2007	Hosono; Eiji	H04N5/2259	396/72
*	В	US-2007/0182833 A1	08-2007	Toyofuku; Toshiyuki	H04N5/232	348/240.3
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*	F	US-2015/0085174 A1	03-2015	Shabtay; Gal	H04N5/23296	348/336
*	G	US-2016/0241793 A1	08-2016	Ravirala; Narayana Karthik	H04N5/23296	1/1
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	К	US-				
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NON-PATENT DOCUMENTS

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*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).) Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.

Part of Paper No. 20180610

Doc code: IDS

Doc description: Information Disclosure Statement (IDS) Filed

15/324,720 - GAU: 2664

PTO/SB/08a (01-10) Approved for use through 07/31/2012. OMB 0651-0031 U.S. Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE

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	Application Number		15324720	
	Filing Date		2017-01-08	
INFORMATION DISCLOSURE	First Named Inventor Noy C		Sohen	
(Not for submission under 37 CER 1 99)	Art Unit			
	Examiner Name			
	Attorney Docket Number		COREPH-0159 US NP	

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Examiner Initial*	Cite No	Patent Number	Kind Code1Issue DateName of Patentee or Applicant of cited DocumentPages Relev Figure		Pages, Releva Figures	Columns,Lines where Int Passages or Relevant s Appear	
	1	8401276	B1	2013-03-19	Choe et al.		
	2	6104432	A	2000-08-15	Nakamura et al.		
	3	5710670	A	1998-01-20) Ohno		
	4	9185291	B1	2015-11-10	Shabtay et al.		
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	1	20030017930	A1	2003-09-25	Bittner		
2		20090102950	A1	2009-04-23	Ahiska		

15/324,720 - GAU: 2664

INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)

Application Number		15324720
Filing Date		2017-01-08
First Named Inventor Noy C		Cohen
Art Unit		
Examiner Name		
Attorney Docket Number		COREPH-0159 US NP

	3		20080030592	A1	2008-02	2-07	Border et al.						
	4		20100277619	A1	2010-11-04		Lawrence Scarff						
	5		20110064327	A1	2011-03-17 Joseph C. Dagher et al.		Joseph C. Dagher et al.						
	6		20150244942	A1	2015-08	3-27	Shabtay et al.		Shabtay et al.				
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	1	201	4199338	wo		A2	2014-12-18	18 Corephotonics Ltd.					
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	1 International Search Report and Written Opinion issued in relation to PCT patent application PCT/IB2016/053803 dated June 26, 2016, 9 pages.												
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15/324,720 - GAU: 2664

4.	Application Number		15324720
	Filing Date		2017-01-08
INFORMATION DISCLOSURE	First Named Inventor	Noy C	Cohen
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	Examiner Name		
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15/324,720 - GAU: 2664

	, application realized		10021120	
	Filing Date		2017-01-08	
INFORMATION DISCLOSURE	First Named Inventor	Noy C	Cohen	
(Not for submission under 37 CER 1 99)	Art Unit			
	Examiner Name			
	Attorney Docket Number		COREPH-0159 US NP	

Application Number

15324720

CERTIFICATION STATEMENT

Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

That each item of information contained in the information disclosure statement was first cited in any communication from a foreign patent office in a counterpart foreign application not more than three months prior to the filing of the information disclosure statement. See 37 CFR 1.97(e)(1).

OR

That no item of information contained in the information disclosure statement was cited in a communication from a foreign patent office in a counterpart foreign application, and, to the knowledge of the person signing the certification after making reasonable inquiry, no item of information contained in the information disclosure statement was known to any individual designated in 37 CFR 1.56(c) more than three months prior to the filing of the information disclosure statement. See 37 CFR 1.97(e)(2).

See attached certification statement.

The fee set forth in 37 CFR 1.17 (p) has been submitted herewith.

 \times A certification statement is not submitted herewith.

SIGNATURE

A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature	/Menachem Nathan/	Date (YYYY-MM-DD)	2017-01-08
Name/Print	MENACHEM NATHAN	Registration Number	65392

This collection of information is required by 37 CFR 1.97 and 1.98. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.14. This collection is estimated to take 1 hour to complete, including gathering, preparing and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. **SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450.**

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EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	0	("15324720").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/10 16:31
S2	10660	H04N5/23296.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S3	6676	H04N5/2258.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S4	10722	H04N5/23216.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S5	12379	H04N5/23245.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S6	23	"2014199338"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:17
S7	6	"20030017930"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:29
S8	6	(("20030017930") or ("20090102950") or ("20080030592") or ("20100277619") or ("20110064327") or ("20150244942")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/11 11:30
S9	1	("20030179303").PN.	US-PGPUB;	OR	OFF	2018/06/11

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			USPAT; USOCR			11:32
S10	4	(("8401276") or ("6104432") or ("5710670") or ("9185291")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/11 11:34
S11	4890	(wide near1 angle or wide) same lens same (telephoto or tele) same (dual or two) same (lens or imag\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:37
S12	3503	S11 same zoom\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:37
S13	287	S12 same (switch\$3 or transition\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:38
S14	256	S13 and @ad< "20150813"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:38
S15	9	(transition\$3 or switch\$3 or shift\$3) near3 digital near2 zoom\$4 with (telephoto or tele) near3 (lens or optical or imag\$3 near2 sens\$3 or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:09
S16	74503	fixed near1 focal with wide wth (telephoto or tele) same (dual or two)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:36
S17	3561	(transition\$3 or switch\$3 or shift\$3) with wide with (tele or telephoto or zoom\$4 adj1 in)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:36
S18	502	S16 same S17	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:37

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S19	32	S18 same (digital or electronic) near2 (zoom or magnification)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:38
S20	150	fixed with wide with (tele or telephoto) with (dual or two) with (lens or optic\$3 or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 13:35
S21	18	S20 same (switch\$3 or transition\$3 or shift\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 13:35
S22	293	(shift\$3 near3 image) with wide with (tele or telephoto)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:19
S23	0	S22 same (registration or register) with global	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:20
S24	4	S22 and (registration or register) with global	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:20
S25	37579	(disparity or misalign\$4) with image	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:21
S26	274	switch\$3 near2 (camera or tele or telephoto or long near1 focal) with resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 15:42
S27	0	S26 with (digital near1 zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO;	OR	ON	2018/06/12 16:15

			DERWENT; IBM_TDB			
S28	0	S26 with ((digital or electronic) near1 zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:15
S29	49	(wide or short near2 focal) near2 (camera or lens or optic\$3) with (tele or telephoto or long near2 focal) with (switch\$3 or transition\$3 or shift\$3) with condition	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:17
S30	431	(wide or short near2 focal) near2 (camera or lens or optic\$3) with (tele or telephoto or long near2 focal) with (switch\$3 or transition\$3 or shift\$3) with (condition or zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:17
S31	7	S30 same (digital or electronic) near2 (zoom\$4 or magnification or enlargement) with resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:18
S32	145	resolution with (wide or short near1 focal) near2 imag\$3 with (tele or telephoto or long near1 focal)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:21
533	1	S32 same threshold	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:21
S34	49	(dual near2 (camera or imag\$3 near2 sens\$3) with wide with (tele or telephoto))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:23
S35	27	S34 and resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:24
S36	0	("14386823").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 16:24

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S37	1	("20150085174"). PN .	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 16:25
S38	1	("9800798"). PN .	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 17:28
S39	16	("20020152557" "20060139463" "20060187312" "20060187338" "20070025713" "20080024596" "20080030592" "20090295949" "20110249086" "20130235234" "20130250159" "20140184854" "20140232905" "5870139" "7561191" "8456515").PN. OR ("9800798").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2018/06/12 17:28
S40	5	S34 and (disparity or parallax or misalign\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:38
S41	5	effective near2 resolution with image with (digital or electronic) near2 zoom\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:44
S42	147	detect\$3 near2 (object or subject or feature) near3 (clos\$3 or short adj1 distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S43	0	S42 with (switch\$3 or chang\$3 or shift\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S44	0	S42 same (switch\$3 or chang\$3 or shift\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S45	4797	(object or subject or feature) near3 (clos\$2 or short adj1 distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:50
S46	1	S45 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 (lens or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO;	OR	ON	2018/06/12 17:50

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			DERWENT; IBM_TDB			
S47	47	S45 and (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 (lens or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:51
S48	0	S45 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 mode	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:53
S49	4978	(object or subject or feature or target) near3 clos\$2 near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:55
S50	0	S49 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 mode	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:06
S51	2278	(detect\$3 or determin\$3 or if or when) near2 (object or subject or feature or target) near3 (clos\$2 or distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:07
S52	0	S51 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 mode	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:08
S53	0	S51 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:08
S54	10	(switch\$3 or shift\$3 or chang\$3) near3 (wide or short near2 focal) near3 (zoom\$3 or close-up or closeup or long near1 focal) with (detect\$3 near3 (object or subject or target))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:17
L2	1	("20090022276").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 22:35

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L11 311	Cohen near2 Noy or Gigushinski near2	US-PGPUB;	OR	ON	2018/06/13
	Oded or GEva near1 Nadav or Shabtay	USPAT;			00:00
	near1 Gal or Ashkenazi near2 Ester or	USOCR;			
	Katz near1 Ruthy or Goldenberg near1	FPRS; EPO;			
	Ephraim).in.	JPO;			
		DERWENT;			
		IBM_TDB			

EAST Search History (Interference)

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Bibliographic Data

Application No: 15/324,72	20			
Foreign Priority claimed:	Oyes	• No		
35 USC 119 (a-d) conditions met:	Yes	No	🗆 N	fet After Allowance
Verified and Acknowledged:	/NHAN T TRAN/			
	Examiner's	Signature	Initial	8
Title:	DUAL AP	ERTURE ZOOM CA FCHING / NON-SWI	MERA W TCHING	TTH VIDEO SUPPORT DYNAMIC CONTROL

FILING or 371(c) DATE	CLASS	GROUP ART UNIT	ATTORNEY DOCKET NO.
01/08/2017	348	2664	COREPH-0159 US NP
RULE			

APPLICANTS

Corephotonics Ltd., Tel-Aviv, ISRAEL

INVENTORS

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Gal Shabtay Tel-Aviv, ISRAEL

Ester Ashkenazi Modi'in, ISRAEL

Ruthy Katz Tel Aviv, ISRAEL

Ephraim Goldenberg Ashdod, ISRAEL

CONTINUING DATA

This application is a 371 of PCT/IB2016/053803 06/26/2016

PCT/IB2016/053803 has PRO of 62204667 08/13/2015

FOREIGN APPLICATIONS

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03/17/2018

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STATE OR COUNTRY

ISRAEL

ADDRESS

Nathan & Associates Patent Agents Ltd P.O.Box 10178 Tel Aviv, 6110101 ISRAEL

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	Application/Control No.	Applicant(s)/Patent Under Reexamination
Search Notes	15324720	COHEN ET AL.
	Examiner	Art Unit
	NHAN T TRAN	2664

CPC- SEARCHED					
Symbol	Date	Examiner			
H04N5/23296; H04N5/2258; H04N5/23216; H04N5/23245	6/10/2018	NT			

CPC COMBINATION SETS - SEARCHED					
Symbol	Date	Examiner			

US CLASSIFICATION SEARCHED								
Class	Subclass	Date	Examiner					

* See search history printout included with this form or the SEARCH NOTES box below to determine the scope of the search.

SEARCH NOTES		
Search Notes	Date	Examiner
EAST search in all available databases (see search history)	6/10/2018	NT
EAST text search in all groups and subgroups (see search history)	6/11/2018	NT
Inventorship search	6/11/2018	NT

INTERFERENCE SEARCH							
US Class/ CPC Symbol	US Subclass / CPC Group	Date	Examiner				

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Index of Claims				1	15324720			COHE	COHEN ET AL.					
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APPLICATION NUMBER	FILING OR 371(C) DATE	FIRST NAMED APPLICANT	ATTY. DOCKET NO./TITLE
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP
92342 Nathan & Associates Pate P.O.Box 10178 Tel Aviv, 6110101 ISRAEL	ent Agents Ltd		

Title:DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

Publication No.US-2018-0184010-A1 Publication Date:06/28/2018

NOTICE OF PUBLICATION OF APPLICATION

The above-identified application will be electronically published as a patent application publication pursuant to 37 CFR 1.211, et seq. The patent application publication number and publication date are set forth above.

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INFORMATION DISCLOSURE	First Named Inventor Noy Co		Sohen	
STATEWENT BY APPLICANT (Not for submission under 37 CEP 1 99)	Art Unit			
	Examiner Name			
	Attorney Docket Number	ər	COREPH-0159 US NP	

				U.S.F	PATENTS	Remove
Examiner Initial*	Cite No	Patent Number	Kind Code ¹	Issue Date	Name of Patentee or Applicant of cited Document	Pages,Columns,Lines where Relevant Passages or Relevant Figures Appear
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Examiner Name		
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(Not for	submission	under 37	CFR	1.99
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Application Number		15324720
Filing Date		2017-01-08
First Named Inventor	Noy C	Cohen
Art Unit		
Examiner Name		
Attorney Docket Number		COREPH-0159 US NP

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Application Number		15324720			
Filing Date		2017-01-08			
First Named Inventor Noy C		Cohen			
Art Unit					
Examiner Name					
First Named InventorNovArt UnitExaminer NameAttorney Docket Number		COREPH-0159 US NP			

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Application Number		15324720		
Filing Date		2017-01-08		
First Named Inventor	Noy C	Cohen		
Art Unit				
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Application Number		15324720			
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First Named Inventor Noy C		Cohen			
Art Unit					
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2	103024272	CN	A	2013-04-03	Gao Xiaowen	
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Application Number		15324720				
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Art Unit						
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INFORMATION DISCLOSURE Application Number 15324720 Filing Date 2017-01-08 First Named Inventor Noy Cohen Art Unit Examiner Name Attorney Docket Number COREPH-0159 US NP

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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number		15324720
	Filing Date		2017-01-08
	First Named Inventor	Noy C	Cohen
	Art Unit		
	Examiner Name		
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16 J	Ingineered to the task: Why camera-phone une 2009, 3 pages	e cameras are different, Giles Humpston, Publisher:	Solid State Technology,				
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	Art Unit		
	Examiner Name		
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Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

That each item of information contained in the information disclosure statement was first cited in any communication from a foreign patent office in a counterpart foreign application not more than three months prior to the filing of the information disclosure statement. See 37 CFR 1.97(e)(1).

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That no item of information contained in the information disclosure statement was cited in a communication from a foreign patent office in a counterpart foreign application, and, to the knowledge of the person signing the certification after making reasonable inquiry, no item of information contained in the information disclosure statement was known to any individual designated in 37 CFR 1.56(c) more than three months prior to the filing of the information disclosure statement. See 37 CFR 1.97(e)(2).

See attached certification statement.

The fee set forth in 37 CFR 1.17 (p) has been submitted herewith.

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A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature	/Menachem Nathan/	Date (YYYY-MM-DD)	2018-09-23
Name/Print	Menachem Nathan	Registration Number	65392

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UTILITY	Attorney Docket No		REPH-0159 US NP			
PATENT APPLICATION	First Named Invent	or Noy C	ohen			
TRANSMITTAL	Title	DUAL APERTURE	ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NC			
(Only for new nonprovisional applications under 37 CFR 1.53(b))	Express Mail Label	No.				
APPLICATION ELEMENTS See MPEP chapter 600 concerning utility patent application contents.	ADDRESS TO	Cc); Ale	Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450			
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a. Newly executed (original or copy)	14. Preliminar	14. Preliminary Amendment				
b. A copy from a prior application (37 CFR 1.63(d)) 7. Application Data Sheet * See note below.	15. Return Receipt Postcard (MPEP § 503) (Should be specifically itemized)					
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Application Number:	15324720		
International Application Number:			
Confirmation Number:	5811		
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL		
First Named Inventor/Applicant Name:	Noy Cohen		
Customer Number:	92342		
Filer:	Menachem Nathan		
Filer Authorized By:			
Attorney Docket Number:	COREPH-0159 US NP		
Receipt Date:	23-SEP-2018		
Filing Date:	08-JAN-2017		
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Control method for multi-lens camera and multi-lens device

Abstract

Disclosed is an improved device provided with a multi-lens and multi-censor camera module. The device has a new mechanism for adjusting multiple lenses and angles of sensors. The new device makes each lens integrated with perspective of the sensors by using a new principle so that images composited by a multi-lens module have high quality and satisfactory properties such as high resolution, high depth of field, high color saturation, high signal-to-noise ratio, high dynamic range, high sensitivity and the like.

o Roserva Other languages: Chinese Inventor: Zhang Kerum Original Assignee: Zhang Kerun Priority date: 2011-04-01 Family: CN (1) App/Pub Number Date Status 2011-04-01 CN 201110082063 2012-10-17 CN102739949A Application

Double camera control device, method and system of mobile terminal and mobile terminal

Abstract

The invention is suitable for camera control technology and provides a double camera control device of a mobile terminal. The mobile terminal comprises a first camera, a second camera, a power supply unit and a control chip, the power supply unit respectively supplies power for the first camera and the second camera in single mode, and the control chip is respectively communicated with the first camera and the second camera in single mode. The double camera control device of the mobile terminal enables two cameras to be power supplied and communicated individually and avoids mutual interference of control of the two cameras. In use, users can select opening of singular camera and can also open two cameras simultaneously to preview and shoot at the same time, after shooting, pictures of the double camera can be combined, and accordingly shooting experience of the users is well improved.

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(54) Handheld electronic device with dual image capturing method and computer program product

(57) A handheld electrical device includes a first lens module with a first image capturing boundary, a second lens module with a second image capturing boundary, an input unit and a control unit. The first image capturing boundary is different from the second image capturing boundary. The input unit receives a user input for capturing images. When the input unit receives the user input, the control unit controls the first lens module and the second lens module to respectively capture a first image and a second image at the same time.



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Description

BACKGROUND

Technical Field

[0001] The present invention relates to an electrical device, an image capturing method and a computer program product for loading into thereof. More particularly, the present invention relates to a handheld electrical device, a dual image capturing method and a computer program product for loading into thereof.

Description of Related Art

[0002] As 3C (Computer, Communications and Consumer) technology develops, there are more and more people utilizing handheld electrical devices in their daily life. Most common handheld electrical devices are personal digital assistants (PDA), mobile phones, smart phones etc. Since mobile electrical devices are designed much smaller and easy to carry, more and more people use handheld electrical device and more functions are developed for different users.

[0003] Nowadays, most handheld electrical devices are equipped with cameras. Wherein, images captured and output by such cameras are landscape images (or called landscape images). If users want images output vertically (as portrait images), the images must be reduced or cut since the width/length ratio of the portrait image and that of the landscape image are different. However, users may not be satisfied with the portrait images after reduce or cut. In particular, when the images captured are video, distortion of the portrait images (videos) thereof may be more obviously since the image may be further trans-coded, which may disturbs users.

SUMMARY

[0004] According to one embodiment of this invention, a handheld electrical device is provided. When a user wants to utilize the handheld electrical device to capture images, the handheld electrical device controls different lens modules, image capturing boundaries of which are different, to capture images with the different image capturing boundaries at the same time. The handheld electrical device includes a first lens module with a first image capturing boundary, a second lens module with a second image capturing boundary, an input unit and a control unit. The first lens module and the second lens module are disposed on the handheld electrical device respectively. Wherein, the first image capturing boundary and the second image capturing boundary are different. The input unit is configured to receive a user input for capturing images. When the input unit receives the user input, the control unit controls the first lens module and the second lens module to respectively capture a first image and a second image at the same time.

[0005] According to another embodiment of this invention, a dual image capturing method is provided. In the dual image capturing method, when a user wants to utilize a handheld electrical device to capture images, the handheld electrical device controls different lens modules, image capturing boundaries of which are different,

to capture images with the different image capturing boundaries at the same time. The dual image capturing method is suitable for a handheld electrical device. The ¹⁰ handheld electrical device includes a first lens module

with a first image capturing boundary and a second lens module with a second image capturing boundary. Wherein, the first image capturing boundary and the second image capturing boundary are different. The dual image ¹⁵ capturing method can be implemented as a computer

program product, which includes at least one program instruction. The at least one program instruction of the computer program product is used for being loaded into the handheld electrical device. After the at least one pro-

20 gram instruction of the computer program product is loaded into the handheld electrical device, the handheld electrical device executes the steps of the dual image capturing method. The dual image capturing method includes the following steps: a user input for capturing im-

25 ages is received. When the user input is received, a first image and a second image are captured at the same time by the first lens module and the second lens module respectively.

[0006] Above all, the handheld electrical device can capture images in different image capturing boundaries at the same time without moving the handheld electrical device. Hence, when capturing images occurring in a flash, images in different image capturing boundaries can be captured to avoid missing any of the boundaries. Besides, if the images captured by the handheld electrical device are videos, the user can switch between portrait

images and landscape images without too much image distortion.
 [0007] These and other features, aspects, and advan-

40 tages of the present invention will become better understood with reference to the following description and appended claims. It is to be understood that both the foregoing general description and the following detailed description are by examples, and are intended to provide
 45 further explanation of the invention as claimed.

BRIEF DESCRIPTION OF THE DRAWINGS

[0008] The invention can be more fully understood by reading the following detailed description of the embodiments, with reference made to the accompanying drawings as follows:

Fig. 1 is a rear-view diagram of a handheld electrical device according to one embodiment of this invention;

Fig. 2 is a block diagram of the handheld electrical device in Fig. 1;

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Fig. 3 illustrates a front-view diagram of the handheld electrical device in Fig. 1 in a portrait orientation; Fig. 4 illustrates a front-view diagram of the handheld electrical device in Fig. 1 in a landscape orientation;

Fig. 5 illustrates an embodiment of the indication line displayed on the handheld electrical device 100 in Fig. 1;

Fig. 6 illustrates another embodiment of the indication line displayed on the handheld electrical device 100 in Fig. 1;

Fig. 7 illustrates an embodiment of the miniature displayed on the handheld electrical device 100 in Fig. 1;

Fig. 8 illustrates another embodiment of the miniature displayed on the handheld electrical device 100 in Fig. 1; and

Fig. 9 is a flow diagram of a dual image capturing method according to one embodiment of this invention.

DETAILED DESCRIPTION

[0009] Reference will now be made in detail to the present embodiments of the invention, examples of which are illustrated in the accompanying drawings. Wherever possible, the same reference numbers are used in the drawings and the description to refer to the same or like parts.

[0010] Fig. 1 is a rear-view diagram of a handheld electrical device according to one embodiment of this invention. Fig. 2 is a block diagram of the handheld electrical device in Fig. 1. When a user wants to utilize the handheld electrical device to capture images, the handheld electrical device controls different lens modules, image capturing boundaries of which are different, to capture images with the different image capturing boundaries at the same time.

[0011] The handheld electrical device 100 includes a control unit 110, a first lens module 120, a second lens module 130, and an input unit 140. The first lens module 120 and the second lens module 130 are disposed on the handheld electrical device 100 respectively. The first lens module 120, the second lens module 130, and the input unit 140 are electrically connected to the control unit 110. The input unit 140 may be at least one button, a keyboard, a graphical user interface (GUI) or other types of input units.

[0012] The first lens module 120 can capture scenes with a first image capturing boundary. The second lens module 130 can capture scenes with a second image capturing boundary. Wherein, the first image capturing boundary and the second image capturing boundary are different. The input unit 140 is configured to receive a user input for capturing images. When the input unit 140 receives the user input, the control unit 110 controls the first lens module 120 and the second lens module 130 to respectively capture a first image and the second image at the same time. Wherein, the first image and the second

image may include pictures, videos or other types of image. Therefore, the handheld electrical device 100 can capture images in different image capturing boundaries at the same time without moving the handheld electrical device 100. Hence, when capturing images occurring in a flash, images in different image capturing boundaries can be captured to avoid missing any of the boundaries. **[0013]** In one embodiment of this invention, the first

image captured by the first lens module 120 is a portrait
image (captured in a portrait mode), and the second image captured by the second lens module 130 is a land-scape image (captured in a landscape mode). Hence, the disposed orientation of the first lens module 120 is substantially vertical to that of the second lens module

130. Therefore, the first image (portrait image) captured by the first lens module 120 may be substantially vertical to the second image (landscape image) captured by the second lens module 130. In other words, a portrait image and a landscape image can be captured at the same time

20 without moving the handheld electrical device 100. In addition, when the user selects a video mode of a traditional handheld electrical device, the user can only take a landscape video. If the user wants to view the landscape video on a portrait screen, the user has to wait a long time for

²⁵ image trans-coding. In other words, during the trans-coding, the original coded landscape video must be decoded before encoding to a portrait video. Since the image trans-coding takes a long time, the user can't view the landscape images immediately. Besides, since the land-

30 scape images are coded twice, the landscape images may be distorted, which may lead to worse image quality. If the present invention is applied, the user can switch between portrait images and landscape images without too much image distortion.

³⁵ [0014] Besides, the handheld electrical device 100 can display image captured by different lens modules with different image capturing boundaries corresponding to the orientation (such as portrait orientation or landscape orientation) of the handheld electrical device 100. Hence,

40 the handheld electrical device 100 may further include a display unit 150 and an orientation sensing module 160. The orientation sensing module 160 is configured to sense an orientation of the handheld electrical device. Wherein, the orientation sensing module 160 may be a

45 g sensor or any other element which can sense the orientation of the handheld electrical device 100. Hence, when the handheld electrical device 100 is in a photograph mode, the handheld electrical device 100 can control the display unit 150 to display images captured by 50 different lens modules with different image capturing boundaries corresponding to the orientation of the handheld electrical device 100. Wherein, when the orientation sensing module 160 senses that the handheld electrical device 100 is in a first orientation, the control unit 110 55 controls the display unit 150 to display a scene captured by the first lens module 120 with the first image capturing boundary; when the orientation sensing module 160

senses that the handheld electrical device 100 is in a

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second orientation, the control unit 110 controls the display unit 150 to display another scene captured by the second lens module 130 with the second image capturing boundary. Wherein, the first orientation and the second orientation are different. Hence, when the handheld electrical device 100 is in the photograph mode, the handheld electrical device 100 can control its display unit 150 to display scenes captured by different lens modules with different image capturing boundaries in real time corresponding to the orientation of the handheld electrical device 100. In other words, when the handheld electrical device 100 is in the photograph mode, the user can change the orientation of the handheld electrical device 100 to control the handheld electrical device 100 to display scenes captured with different image capturing boundaries.

[0015] Fig. 3 illustrates a front-view diagram of the handheld electrical device in Fig. 1 in a portrait orientation. Fig. 4 illustrates a front-view diagram of the handheld electrical device in Fig. 1 in a landscape orientation. In one embodiment of this invention, the first orientation of the handheld electrical device 100 may be a portrait orientation, and the second orientation of the handheld electrical device 100 may be a landscape orientation. Hence, when the orientation sensing module 160 senses that the handheld electrical device 100 is in the portrait orientation, the control unit 110 controls the display unit 150 to display the portrait image captured by the first lens module 120 with the first image capturing boundary (as shown in Fig. 3). When the orientation sensing module 160 senses that the handheld electrical device 100 is in the landscape orientation, the control unit 110 controls the display unit 150 to display the landscape image captured by the second lens module 130 with the second image capturing boundary (as shown in Fig. 4). In other embodiments, the first orientation and the second orientation are not limited to the portrait orientation and the landscape orientation in this disclosure. Therefore, when the handheld electrical device 100 is in the photograph mode, the user can put the handheld electrical device 100 in the portrait or landscape orientation to display the portrait or landscape image correspondingly for user's convenience. Besides, the portrait image being displayed horizontally or the landscape image being displayed vertically on the display unit 150, which may waste the display area of the display unit 150, can be avoided. [0016] When the handheld electrical device 100 displays images captured by one of the lens modules, at least one indication line to indicate the boundary of the other lens module can be displayed on the displayed images. Hence, when the handheld electrical device 100 is in the photograph mode and the orientation sensing module 160 senses that the handheld electrical device 100 is in the first orientation, the control unit 110 controls the display unit 150 to display a scene captured by the first lens module 120 with the first image capturing boundary, and to further display one or more first indication lines on the displayed scenes. Wherein the one or more

first indication lines indicate the position that the second image capturing boundary captured by the second lens module 130 corresponds to the first image capturing boundary. In one embodiment of this invention, the first indication line may be a fixed position on the displayed first image capturing boundary. In another embodiment of this invention, the position of the first indication line can be obtained by comparing the scenes captured with the first image capturing boundary with that with the sec-

¹⁰ ond image capturing boundary. However, the corresponding position of the first indication line can be obtained utilizing other methods, which should not be limited in this disclosure.

[0017] Besides, when the handheld electrical device
100 is in the photograph mode and the orientation sensing module 160 senses that the orientation of the handheld electrical device 100 is in the second orientation, the control unit 110 controls the display unit 150 to display a scene captured by the second lens module 130 with
the second image capturing boundary, and to further display one or more second indication lines on the displayed scenes to indicate the first image capturing boundary captured by the first lens module 120. Therefore, when

the handheld electrical device 100 displays images captured by one of the lens modules, at least one indication line to indicate the boundary of the other lens module can be displayed on the displayed images, which can help users understand the boundary captured by the other lens module.

³⁰ [0018] Fig. 5 illustrates an embodiment of the indication line displayed on the handheld electrical device 100 in Fig. 1. Fig. 6 illustrates another embodiment of the indication line displayed on the handheld electrical device 100 in Fig. 1. For example, the first orientation of the handheld electrical device 100 may be a portrait orientation, and the second orientation of the handheld electrical device 100 may be a landscape orientation. Hence, when the handheld electrical device 100 is in the photograph mode and the orientation sensing module 160

40 senses that the handheld electrical device 100 is in the portrait orientation, the control unit 110 controls the display unit 150 to display the portrait image 201 captured by the first lens module 120 with the first image capturing boundary, and to further display a first indication line 201

45 a (as shown in Fig. 5) on the displayed first image 201. Wherein the first indication line 201 a indicate the position that the second image capturing boundary captured by the second lens module 130 corresponds to the first image capturing boundary. Besides, when the orientation 50 sensing module 160 senses that the handheld electrical device 100 is in the landscape orientation, the control unit 110 controls the display unit 150 to display the landscape image 202 captured by the second lens module 130 with the second image capturing boundary, and to 55 further display one second indication line 202a on the displayed scenes (as shown in Fig. 6) to indicate the first image capturing boundary captured by the first lens module 120. Therefore, when photographing portrait images,

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the corresponding landscape images can be indicated; when photographing landscape images, the corresponding portrait images can be indicated, which can assist users during photographing. In other embodiments, more indication lines can be further displayed, which should not be limited in this disclosure.

[0019] When the handheld electrical device 100 displays images captured by one of the lens modules, a miniature captured by the other lens module can be further displayed. Hence, when the handheld electrical device 100 is in the photograph mode and the orientation sensing module 160 senses that the handheld electrical device is in the first orientation, the control unit 110 controls the display unit 150 to further display a first miniature captured with the second image capturing boundary. When the handheld electrical device 100 is in the photograph mode and the orientation sensing module senses that the handheld electrical device 100 is in the second orientation, the control unit 110 controls the display unit 150 to further display a second miniature captured with the first image capturing boundary. Therefore, when the handheld electrical device 100 displays images captured by one of the lens modules, users can reach the miniature captured by the other lens module with the other image capturing boundary.

[0020] Fig. 7 illustrates an embodiment of the miniature displayed on the handheld electrical device 100 in Fig. 1. Fig. 8 illustrates another embodiment of the miniature displayed on the handheld electrical device 100 in Fig. 1. For example, the first orientation of the handheld electrical device 100 may be a portrait orientation, and the second orientation of the handheld electrical device 100 may be a landscape orientation. Hence, when the handheld electrical device 100 is in the photograph mode and the orientation sensing module 160 senses that the handheld electrical device is in the portrait orientation, the control unit 110 controls the display unit 150 to display the portrait image 301 captured by the first lens module 120 with the first image capturing boundary, and to further display a first miniature 301 a of the landscape image captured with the second image capturing boundary (as shown in Fig. 7). When the handheld electrical device 100 is in the photograph mode and the orientation sensing module 160 senses that the handheld electrical device is in the landscape orientation, the control unit 110 controls the display unit 150 to display the landscape image 302 captured by the first lens module 130 with the second image capturing boundary, and to further display a second miniature 302a of the portrait image captured with the first image capturing boundary (as shown in Fig. 8).

[0021] When the handheld electrical device 100 is in a browsing mode, the handheld electrical device 100 can display images corresponding to its orientation. Hence, when the handheld electrical device 100 is in a browsing mode and the orientation sensing module 160 senses that the handheld electrical device 100 is in the first orientation, the control unit 110 controls the display unit 150

to display the first image. When the handheld electrical device 100 is in the browsing mode and the orientation sensing module 160 senses that the handheld electrical device 100 is in the second orientation, the control unit 110 controls the display unit 150 to display the second image. Hence, when the handheld electrical device 100 is in the browsing mode, the handheld electrical device 100 can control its display unit 150 to display images captured with different image capturing boundaries cor-

¹⁰ responding to the orientation of the handheld electrical device 100. In other words, when the handheld electrical device 100 is in the browsing mode, the user can change the orientation of the handheld electrical device 100 to control the handheld electrical device 100 to display im-¹⁵ ages captured with different image capturing boundaries

for browsing, which is convenient image capturing boundaries for browsing, which is convenient to users for operation.
 [0022] In addition, the handheld electrical device 100 can set the first image capturing boundary and the second image capturing boundary according to the interest ing characteristics set by the user. Hence, the control

unit 110 can receive an interesting characteristic through the input unit 140. The control unit 110 determines the first image capturing boundary and the second image capturing boundary automatically according to the interesting characteristic. Then, the first lens module 120 can

⁵ esting characteristic. Then, the first lens module 120 can capture the first image with the interesting characteristic according to the first image capturing boundary; the second lens module 130 can capture the second image with the interesting characteristic according to the second im-

30 age capturing boundary. Wherein, the interesting characteristic may be a human facial feature, smiling feature etc.. Therefore, the interesting characteristic, which interests user, can always captured in the image.

[0023] Fig. 9 is a flow diagram of a dual image captur ing method according to one embodiment of this invention. In the dual image capturing method, when a user wants to utilize a handheld electrical device to capture images, the handheld electrical device controls different lens modules, image capturing boundaries of which are
 different, to capture images with the different image capture image capture images with the different image capture image capture image capture image capture images with the different image capture image capture image capture image capture image capture image capture images with the different image capture image capt

turing boundaries at the same time. The dual image capturing method is suitable for a handheld electrical device. The handheld electrical device includes a first lens module with a first image capturing boundary and a second

45 lens module with a second image capturing boundary. Wherein, the first image capturing boundary and the second image capturing boundary are different. The dual image capturing method can be implemented as a computer program product, which includes at least one pro-50 gram instruction. The at least one program instruction of the computer program product is used for being loaded into the handheld electrical device. After the at least one program instruction of the computer program product is loaded into the handheld electrical device, the handheld 55 electrical device executes the steps of the dual image capturing method. The computer program product can be stored in a handheld-electrical-device readable storage medium. Any suitable storage medium may be used including nonvolatile memory such as read only memory (ROM), programmable read only memory (PROM), erasable programmable read only memory (EPROM), and electrically erasable programmable read only memory (EEPROM) devices; volatile memory such as SRAM, DRAM, and DDR-RAM; optical storage devices such as CD-ROMs and DVD-ROMs; and magnetic storage devices such as hard disk drives and floppy disk drives.

[0024] The dual image capturing method 400 includes the following steps:

[0025] In step 410, a user input for capturing images is received.

[0026] In step 420, when the user input is received (step 410), a first image and a second image are captured at the same time by the first lens module and the second lens module respectively. Wherein, the first image is the one captured by the first lens module with the first image capturing boundary, and the second image is the one captured by the second lens module with the second image capturing boundary. The first image and the second image may include pictures, videos or other types of image. Therefore, the handheld electrical device can capture images with different image capturing boundaries at the same time without moving the handheld electrical device.

[0027] In one embodiment of step 420, the first image, which is captured by the first lens module with the first image capturing boundary, may be a portrait image (captured in a portrait mode), and the second image, which is captured by the second lens module with the second image capturing boundary, may be a landscape image (captured in a landscape mode). Therefore, a portrait image and a landscape image can be captured at the same time without moving the handheld electrical device. In addition, when the user selects a video mode of a traditional handheld electrical device, the user can only take a landscape video. If the user wants to view the landscape video on a portrait screen, the user has to wait a long time for image trans-coding. In other words, during the trans-coding, the original coded landscape video must be decoded before encoding to a portrait video. Since the image trans-coding takes a long time, the user can't view the landscape images immediately. Besides, since the landscape images are coded twice, the landscape images may be distorted, which may lead to worse image quality. If the present invention is applied, the user can switch between portrait images and landscape images without too much image distortion.

[0028] Besides, the handheld electrical device can display image captured by different lens modules with different image capturing boundaries corresponding to the orientation (such as portrait orientation or landscape orientation) of the handheld electrical device. Hence, in step 430, an orientation of the handheld electrical device may be sensed. Wherein, the orientation of the handheld electrical device may be sensed (step 430) utilizing a g sensor or any other element which can do orientation sensing. [0029] In step 440, when the handheld electrical device

is in a first orientation and the handheld electrical device is in a photograph mode, the handheld electrical device displays a scene captured by the first lens module with the first image capturing boundary.

5 [0030] In step 450, when the handheld electrical device is in a second orientation and the handheld electrical device is in a photograph mode, the handheld electrical device displays another scene captured by the second lens module with the second image capturing boundary.

10 Wherein, the first orientation and the second orientation are different. Hence, when the handheld electrical device is in the photograph mode, the handheld electrical device can display scenes captured by different lens modules with different image capturing boundaries in real time cor-

15 responding to the orientation of the handheld electrical device. Besides, the first orientation of the handheld electrical device may be a portrait orientation, the second orientation of the handheld electrical device may be a landscape orientation, the first image corresponding to

20 the first orientation (portrait orientation) is a portrait image, and the second image corresponding to the second orientation (landscape orientation) is a landscape image. Therefore, when the handheld electrical device is in the photograph mode, the user can put the handheld elec-

25 trical device in the portrait or landscape orientation correspondingly for user's convenience. Besides, the portrait image being displayed horizontally or the landscape image being displayed vertically on the display unit of the handheld electrical device, which may waste the display 30

area of the handheld electrical device, can be avoided. [0031] When the handheld electrical device displays images captured by one of the lens modules, at least one indication line to indicate the boundary of the other lens module can be displayed on the displayed images. 35 Hence, when the handheld electrical device is in the pho-

tograph mode and the handheld electrical device is in the first orientation, the handheld electrical device can further display one or more first indication lines on the displayed scenes on the displayed images in step 440. 40 Wherein the one or more first indication lines indicate the

position that the second image capturing boundary captured by the second lens module corresponds to the first image capturing boundary. Besides, when the handheld electrical device is in the photograph mode and the hand-

45 held electrical device is in the second orientation, the handheld electrical device further displays one or more second indication lines on the displayed images in step 450. Wherein the one or more second indication lines indicate the position that the first image capturing bound-

50 ary captured by the first lens module corresponds to the second image capturing boundary. Therefore, when the handheld electrical device displays images captured by one of the lens modules, at least one indication line to indicate the corresponding boundary of the other lens 55 module can be displayed on the displayed images, which can help users understand the boundary captured by the other lens module.

[0032] When the handheld electrical device displays

images captured by one of the lens modules, a miniature captured by the other lens module can be further displayed. Hence, when the handheld electrical device is in the photograph mode and the handheld electrical device is in the first orientation, the handheld electrical device may further display a first miniature captured with the second image capturing boundary on the images displayed in step 440. When the handheld electrical device is in the photograph mode and the handheld electrical device is in the second orientation, the handheld electrical device may further display a second miniature captured with the first image capturing boundary on the images displayed in step 450. Therefore, when the handheld electrical device displays images captured by one of the lens modules, users can reach the miniature captured by the other lens module in the other image capturing boundary.

[0033] When the handheld electrical device is in a browsing mode, the handheld electrical device can display images corresponding to its orientation. Hence, when the handheld electrical device is in the first orientation and the handheld electrical device is in the browsing mode, the handheld electrical device displays the first image captured by the first lens module. Besides, when the handheld electrical device is in the second orientation and the handheld electrical device is in the browsing mode, the handheld electrical device displays the second image captured by the second lens module. Hence, when the handheld electrical device is in the browsing mode, the handheld electrical device can display images captured with different image capturing boundaries corresponding to the orientation of the handheld electrical device.

[0034] In addition, the handheld electrical device can set the first image capturing boundary and the second image capturing boundary, which are taken as the factor to execute step 420, according to the interesting characteristics set by the user. Hence, the dual image capturing method 400 may further includes the following steps: an interesting characteristic is received. The first image capturing boundary and the second image capturing boundary are determined automatically according to the interesting characteristic, such that the image with the interesting characteristic can be captured. Wherein, the interesting characteristic may be a human facial feature, smiling feature etc.. Hence, in step 420, the first image and the second image are captured at the same time by the first lens module and the second lens module according to the first image capturing boundary and the second image capturing boundary respectively. Therefore, the interesting characteristic, which interests user, can always captured in the image.

[0035] Above all, the handheld electrical device can capture images with different image capturing boundaries at the same time without moving the handheld electrical device. Hence, when capturing images occurring in a flash, images in different image capturing boundaries can be captured to avoid missing any of the boundaries.

Besides, if the images captured by the handheld electrical device are videos, the user can switch between portrait images and landscape images without too much image distortion.

⁵ [0036] Although the present invention has been described in considerable detail with reference to certain embodiments thereof, other embodiments are possible. Therefore, the spirit and scope of the appended claims should not be limited to the description of the embodi-

10 ments contained herein. It will be apparent to those skilled in the art that various modifications and variations can be made to the structure of the present invention without departing from the scope or spirit of the invention. In view of the foregoing, it is intended that the present invention

¹⁵ cover modifications and variations of this invention provided they fall within the scope of the following claims.

Claims

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1. A handheld electrical device comprising:

a first lens module with a first image capturing boundary, disposed on the handheld electrical device ;

a second lens module with a second image capturing boundary, disposed on the handheld electrical device, wherewith the first image capturing boundary and the second image capturing boundary are different;

an input unit, configured to receive a user input for capturing images; and

a control unit, configured to control the first lens module and the second lens module to respectively capture a first image and a second image at the same time when the input unit receives the user input.

- 2. The handheld electrical device of claim 1, wherein the first image is a portrait image, the second image is a landscape image, and the disposed orientation of the first lens module is substantially vertical to that of the second lens module.
- 45 **3.** The handheld electrical device of claim 1 further comprising:

a display unit;

an orientation sensing module, configured to sense an orientation of the handheld electrical device; and

wherein when the handheld electrical device is in a photograph mode:

when the orientation sensing module senses that the handheld electrical device is in a first orientation, the control unit controls the display unit to display a scene captured

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by the first lens module with the first image capturing boundary; and

when the orientation sensing module senses that the handheld electrical device is in a second orientation, the control unit controls the display unit to display another scene captured by the second lens module with the second image capturing boundary.

4. The handheld electrical device of claim 3, wherein:

when the handheld electrical device is in the photograph mode and the orientation sensing module senses that the handheld electrical device is in the first orientation, the control unit controls the display unit to further display one or more first indication lines to indicate the second image capturing boundary; and when the handheld electrical device is in the photograph mode and the orientation sensing module senses that the handheld electrical device is in the second orientation, the control unit controls the display unit to further display one or more second indication lines to indicate the first image capturing boundary.

5. The handheld electrical device of claim 3, wherein:

when the handheld electrical device is in the photograph mode and the orientation sensing module senses that the handheld electrical device is in the first orientation, the control unit controls the display unit to further display a first miniature captured by the second lens module with the second image capturing boundary; and when the handheld electrical device is in the photograph mode and the orientation sensing module senses that the handheld electrical device is in the second orientation, the control unit controls the display unit to further display a second miniature captured by the first lens module with the first image capturing boundary.

6. The handheld electrical device of claim 1 further comprising:

when the handheld electrical device is in a browsing mode and a orientation sensing module of the handheld electrical device senses that the handheld electrical device is in a first orientation, the control unit controls a display unit of the handheld electrical device to display the first image; and

when the handheld electrical device is in the browsing mode and the orientation sensing module senses that the handheld electrical device is in a second orientation, the control unit controls the display unit to display the second image.

- 7. The handheld electrical device of claim 1, wherein the first image and the second image include pictures and/or videos.
- 8. A dual image capturing method for a handheld electrical device, wherein the handheld electrical device comprises a first lens module with a first image capturing boundary and a second lens module with a second image capturing boundary, wherewith the first image capturing boundary is different from the second image capturing boundary, the method comprises:

receiving a user input for capturing images; and capturing a first image and a second image at the same time by the first lens module and the second lens module respectively when the user input is received.

- **9.** The method of claim 8, wherein the first image is a portrait image, and the second image is a landscape image.
- **10.** The method of claim 8 further comprising:

sensing an orientation of the handheld electrical device; and

when the handheld electrical device is in a photograph mode:

> when handheld electrical device is in a first orientation, making the handheld electrical device display a scene captured by the first lens module with the first image capturing boundary; and

> when the handheld electrical device is in a second orientation, making the handheld electrical device display another scene captured by the second lens module with the second image capturing boundary.

- **11.** The method of claim 10 further comprising:
 - when the handheld electrical device is in the photograph mode and the handheld electrical device is in the first orientation, further displaying one or more first indication lines to indicate the second image capturing boundary; and when the handheld electrical device is in the photograph mode and the handheld electrical device is in the second orientation, further displaying one or more second indication lines to indicate the first image capturing boundary.
- **12.** The method of claim 10 further comprising:

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when the handheld electrical device is in the photograph mode and the handheld electrical device is in the first orientation, further displaying a first miniature captured by the second lens module with the second image capturing boundary; and

when the handheld electrical device is in the photograph mode and the handheld electrical device is in the second orientation, further displaying a second miniature captured by the first lens module with the first image capturing boundary.

13. The method of claim 8 further comprising:

when the handheld electrical device is in a browsing mode and the handheld electrical device is in a first orientation, displaying the first image; and

when the handheld electrical device is in the 20 browsing mode and the handheld electrical device is in a second orientation, displaying the second image.

- **14.** The method of claim 8, wherein the first image and ²⁵ the second image include pictures and/or videos.
- 15. A computer program product comprising at least one program instruction for being loaded into a handheld electrical device, wherein the handheld electrical device comprises a first lens module with a first image capturing boundary and a second lens module with a second image capturing boundary, wherewith the first image capturing boundary is different from the second image capturing boundary, wherein the at least one program instruction executes at least following steps after loading into the handheld electrical device:
 - receiving a user input for capturing images; and 40 capturing a first image and a second image at the same time by the first lens module and the second lens module respectively when the user input is received.

45

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55



<u>100</u>

Fig. 1





Fig. 2



Fig. 3



Fig. 4



Fig. 5



Fig. 6



Fig. 7







Fig. 9

<u>400</u>



EUROPEAN SEARCH REPORT

Application Number EP 11 16 5407

	DOCUMENTS CONSID	ERED TO BE RELEVANT		
Category	Citation of document with in of relevant pass	ndication, where appropriate, ages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (IPC)
X Y	US 2007/285550 A1 (13 December 2007 (2 * abstract; claims	SON JAE-GON [KR]) 007-12-13) 1-5; figures 1,2 *	1,7,8, 14,15 3-6, 10-13	INV. H04N5/225
Y	US 2011/045812 A1 (24 February 2011 (2 * abstract; claims * paragraphs [0007] paragraph [0165] *	KIM HO-SOO [KR] ET AL) 011-02-24) 11,21; figures 26-31 * , [0011], [0148] -	3-6, 10-13	
X Y	EP 1 763 243 A2 (L0 14 March 2007 (2007 * abstract; figures * paragraph [0037]	G ELECTRONICS INC [KR]) (-03-14) (3,11, 14 * - paragraph [0043] *	1,7,8, 14,15 3-6, 10-13	
Х	EP 1 560 421 A1 (MA CO LTD [JP] PANASON 3 August 2005 (2005	TSUSHITA ELECTRIC IND IIC CORP [JP]) 5-08-03)	1,7,8, 14,15	
Y	* abstract; figures	; 2-4 *	3-6, 10-13	TECHNICAL FIELDS SEARCHED (IPC)
Х	WO 01/31893 A1 (NOH [FI]; HAERMAE ESA 3 May 2001 (2001-05	FI]) (IA MOBILE PHONES LTD (FI]) (-03)	1,7,8, 14,15	H04N H04M G06F
Y	* abstract; figure	2 *′	3-6, 10-13	
X Y	EP 1 566 974 A1 (SA 24 August 2005 (200 * abstract; figures	NYO ELECTRIC CO [JP]) 5-08-24) 5 la-b *	1,7,8, 14,15 3-6, 10-13	
A	US 2010/238327 A1 (AL) 23 September 20 * the whole documer	GRIFFITH JOHN D [US] ET 10 (2010-09-23) 1t *	1-15	
	The present search report has	been drawn up for all claims	-	
	Place of search	Date of completion of the search	Kat	ruff. Martin
C, X : part docu A : tech O : non P : intel	ATEGORY OF CITED DOCUMENTS icularly relevant if taken alone ioularly relevant if oombined with anot ument of the same category unological background -written disclosure rmediate document	T : theory or principle E : earlier patent doc after the filing dat ber L : document cited in L : document cited for &: member of the sa document	e underlying the in ument, but publis the application or other reasons me patent family	vention shed on, or , corresponding

EP 2 523 450 A1

ANNEX TO THE EUROPEAN SEARCH REPORT ON EUROPEAN PATENT APPLICATION NO.

EP 11 16 5407

This annex lists the patent family members relating to the patent documents cited in the above-mentioned European search report. The members are as contained in the European Patent Office EDP file on The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

08-08-2011

oi	Patent document ted in search report		Publication date		Patent family member(s)		Publication date
US	8 2007285550	A1	13-12-2007	CN	101090442	Α	19-12-2007
US	5 2011045812	A1	24-02-2011	KR	20110020082	A	02-03-2011
EF	9 1763243	A2	14-03-2007	JP US	2007082223 2007057866	A A1	29-03-2007 15-03-2007
EF	P 1560421	A1	03-08-2005	AU CN WO JP JP KR US	2003301611 1708979 2004039065 3948387 2004147046 20050062633 2006044396	A1 A A1 B2 A A A1	$13-05-2004 \\ 14-12-2005 \\ 06-05-2004 \\ 25-07-2007 \\ 20-05-2004 \\ 23-06-2005 \\ 02-03-2006 \\ \end{array}$
WC	0131893	A1	03-05-2001	AU EP FI	1148001 1232633 992309	A A1 A	08-05-2001 21-08-2002 27-04-2001
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05	5 2010238327	A1	23-09-2010	WO	2010108119	A2	23-09-2010
74M P0459							

Apparatus and method for realizing multi-resolutions image acquisition with multi-focusing video camera

Abstract

A device and a method for using a multi-focusing camera to realize collection of multi-resolution images are disclosed, comprising five focusing cameras having restraining relationship with others, wherein four of them are located at the same horizontal plane and on four top points of the same square, and the four cameras have the identical focus which is set as f<s>; the rest 1 camera is located in the direction of the four cameras, axes line of the camera is perpendicular to the surfaces of four cameras and passes a central point 0 of the square, and the distance from the fifth camera to the rest four cameras is d, the focus of the camera is set as f<t>, and initial setting is performed to the parameters and locations of the five focusing cameras with the location relationship satisfying the following restraint. f<t>=f<s>+d. The invention achieves the function of lossless zooming film of the multi-focusing camera with adjustable details of scenes and images, and with flexible and controllable structure, the invention can rapidly collect the multi-resolution images in the large visual scene.

O MARINA O Other languages: Chinese Inventor: Wei We, Zhong Zhou, Zhang Shejen, Xu Zhao, Zhao Yuma Original Assignee: Beijing Aerospace University Priority date : 2008-03-03 Family: CN(1) App/Pub Number <u>936 (</u> 9,966 2008-03-03 CN 200810101241 2008-10-01 CN101276415A Application

Abstract

PROBLEM TO BE SOLVED. To provide a thin camera module that can selectively obtain images of different magnifications, and is suitable to portable equipment.

SOLUTION: The camera module comprises a plurality of lens units 21, 22 having different focal lengths, image sensor chips 25a and 25b which process imaging signals based upon light made incident through the lens units, and a selecting means of selecting the light made incident through the plurality of lens units and imaging signals based upon the light. This selecting means is operative to select light made incident through one of the plurality of lens units or an imaging signal based upon the light.

COPYRIGHT (C) 2008, JPO & INPIT

Other languages: Japanese Inventor: Yasuaki Kayamuma, Amzhao Original Assignee: Ottzen Electronics Co Ltd, Citizen Electronics Č0., 138. Priority date: 2006-05-11 Family: JP (1) App/Pub Number Oate Status Pending 2006-05-11 JP2006132321A 2007-11-22 JP2007306282A Application

Digital camera

Abstract

PROBLEM TO BE SOLVED. To provide a digital camera provided with a plurality of photographing optical systems and imaging elements for realizing high magnification zooming without interruption and upsizing.

SOLUTION: The digital camera has two kinds of modes comprising: a high image quality mode for processing an image obtained by composing high quality image information with a small field angle and possible for optical zooming obtained by a combination of a first OCD 30 with a small size and high pixel density, a first imaging lens 12 with a short focal length, a second OCD 32 with a large size and low pixel density, and a second imaging lens 14 with a long focal length and slightly lower quality image information with a large field angle by an image interpolation means, and a high magnification mode for processing an image obtained by composing high quality image information with a minimum field angle obtained by a combination of the first CCD 30 and the second imaging lens 14, and the second CCD 32 and the first imaging lens 12 and low quality image information with a large field angle by the image interpolation means 38. Each mode can be selected by selecting an optical path from each lens to each CCD to change the combination of the lenses and the CCDs. COPYRIGHT: (C)2004,JPO

UP230832989284 αποτοσια Ο ποτροτική Σίνουν

Other languages: Japanese

Inventor: Milsoforni Misawa, Michilako Nakazawa, 元史三河, 通 隆 中沢

Original Assignce: Foji Photo Film Co Ltd. 富士国国フイル之株 式会社

Priority date : 2002-03-29

Øate	App/Pub Number	Shahas
2002-03-29	JP2802096977A	Pending
2003-10-17	JP2003298920A	Application

External links: Espacepet, Global Doosier, Discuss

Camera system

Abstract

<P>PROBLEM TO BE SOLVED: To provide a camera system which makes a display image legible when a control of PTZ or the like is performed while an image of a Tele camera is seen by a display device, and which makes a display image legible in a recorded image in a camera system with a Tele/Wide camera. <P>SOLUTION: A camera system has a Tele camera means which enables a high-powered zoom by which a narrow range is photographed with a subject centered, a Wide camera means which enables a wide angle shot by which a wide range is photographed including an adjacent area of a subject. The camera system is provided with a means for performing a PTZ (pan, till and zoom) control to a Tele camera, a means for communicating between the Tele camera and a Wide camera, a means for cutting an image complying with the PTZ control of the Tele camera from a Wide image, a means for magnifying the image cut from the Wide image to a Tele image, and a means for switching the Tele image with the Wide image to be transmitted. An image while the Tele camera is moving is substituted for an image by the Wide camera. <P>COPYRIGHT: (C)2006.JPO&NCIPI

Other languages: Japanese Inventor: Keisuke Kagiwada, 🖄 🕅 🕅 Original Assignee: Canon inc. キャノン体式会社 Priority date: 2005-02-28 Family: JP (1) App/Pub Namber 267678 Oate 2005-02-28 JP2005053348A Withdrawn 2006-09-07 JP2006238325A Application Info: Oted by (6). Legal events: Similar documents: Priority and Related Applications External links: Espacement, Global Dospier, Discuss

Imaging apparatus

Abstract

PROBLEM TO BE SOLVED. To provide high image quality with high resolution for an entire wide variable power region. SOLUTION: An imaging apparatus includes first and second imaging optical systems LN1 and LN2 with single focus, which look the same direction. A focal length of the second imaging optical system LN2 is longer than that of the first imaging optical system LN1. Zooming is performed from a wide angle end to an intermediate focal length state with an electronic zoom by segmentation of an image obtained in the first imaging optical system LN1, and zooming is performed from the intermediate focal length state to a telescopic end with an electronic zoom by segmentation of an image obtained in the first imaging optical system. Thus, zooming from the wide angle end to the telescopic end is performed as a whole. Both the first and second imaging optical systems LN1 and LN2 consist of four or more lenses of first lenses of positive power and second lenses of negative power in order from an object side, the lenses nearest to the image side are negative lenses, composite focal lengths of the first lenses and the second lenses are positive and they satisfy a conditional expression :1.0<fFw/fFm<1.5.

Images (23)





Inventor: Keriji Komo, 新始 金彩, Keiji Meteozaka, 新二 松振, Keiko Yamada, 武子 山田

Original Assignee: Konica Minolta Advanced Layers Inc. コニカ ミノルタフドバンストレイヤー株式会社

Priority date : 2011-11-16

Family: JP(1)		
Dette	App/Pub Number	Status
2011-11-16	JP2011250322A	Active
2013-05-30	JP2013106289A	Application
2015-07-01	JP574139582	Grant

Imaging apparatus, imaging method, and range finding method

Abstract

<P>PROBLEM TO BE SOLVED: To provide an imaging apparatus which realizes high precision range finding by utilizing a plurality of imaging systems having different photographic viewing angles and an imaging method and a range finding method, and to provide an imaging apparatus which realizes compensation of parallax caused among the plurality of imaging systems, with simple configuration, and an imaging method. <P>SOLUTION: Imaging signals from imaging systems 10A, 10B, and 10C are corrected so that photographed images by the respective imaging systems 10A, 10B, and 10C photographed at mutually different photographic viewing angles can be images photographed in the mutually same photographing conditions with respect to viewing angles, and correlation operations among photographic imaging signals, and a distance to an object is calculated on the basis of the respective corrected imaging signals, and a distance to an object is calculated on the basis of correlation values. Parallax correction is performed on the basis of information of the calculated distance. <P>COPYRIGHT: (C)2005,JPO&NCIPI

Images (18)



JP200609022652 Provide the Connect I27 ① The Rest As 文 Entres Other languages: Japanese Inventor: Yoshihiro Ito, Kenichi Sato, Hideo Yoshida, 高広 伊喜 住服 第一、分大 吉田 Original Assignee: Fuji Photo Film Co Ltd, Fujinon Corp. フジノ ン株式会社、富士写賞フィルム株式会社

Priority date: 2009-09-24

Family: JP (1)		
Data	App/Pub Number	Status
2003-09-24	JP2003331404A	Pending
2005-04-14	JP2005099265A	Application

Photographing method using a mobile terminal having a dual camera and this

Abstract

translated from Korean

The present invention relates to, and more particularly a portable terminal and a recording method using the same, recognizing the face of the photographer to take a picture and having a dual camera on the mobile terminal having a photographing function.

The present invention dual-in camera, a mobile terminal having a second camera portion, wherein the first the photographer of the image input via the camera part is a first camera unit, of the subject image is photographed person's image is input to be input recognizing the photographed to the subject to be imaged is characterized in that a control unit for controlling the second camera unit. Because the recorded picture by recognizing the image of the photographer by using a dual-camera provided in the mobile terminal can acquire the right image to prevent camera shake, there is an advantage that the photographer can take an image of an object at the moment of intended.





Portable terminal having dual camera and photographing method using the same

Abstract

PURPOSE: A portable terminal with a dual camera and a photographing method using the same are provided to exactly and stably photograph at the time when a photographer intends regardless of the shake due to hand. CONSTITUTION: A first camera part(150) collects a first image. A second camera part(160) collects a second image. A controller(110) recognizes the first image inputted through the first camera part. The controller checks whether the recognized first image belongs to a preset reference image or not. According to the confirmation result, the controller controls the camera operation of the second camera part.

Images (4)



Other languages: Korean Inventor: friendship, Lee Byung-sun Original Assignee: Samsung Electronics Co., Ltd. Priority date : 2008-07-17 Family: KR (1) Data App/Pub Number Status 2008-07-17 KR20080069570A 2010-01-27 Application KR20100008936A 2014-12-29 KR10147717881 Grant

EUROPEAN PATENT OFFICE

Patent Abstracts of Japan

PUBLICATION NUMBER	:	08271976
PUBLICATION DATE	:	18-10-96

- APPLICATION DATE: 29-03-95APPLICATION NUMBER: 07094242
- APPLICANT : CANON INC;
- INVENTOR : TAMAMURA HIDEO;
- INT.CL. : G03B 19/06 G03B 17/20 G03B 17/48 H04N 5/335
- TITLE : CAMERA



ABSTRACT : PURPOSE: To enhance operability and quick photographing property by improving a finder function, in a camera provided with both video and still camera functions.

CONSTITUTION: The camera is constituted of a video camera part consisting of each of a video photographing camera unit 20, an operation unit 30 for changing a zoom ratio, driven by motor and a video deck part 40 recording video on a magnetic tape and a still camera part for exposing a sliver salt photographic film, to record a still picture. The video taken by the video camera part is displayed as a picture on an LCD in a camera main body 1 and a half mirror is disposed in mid-way of an optical path, so that when the picture is optically led to a part of a visual field in an optical finder, the picture of the video is placed in the still picture as a window. Further, a light shielding plate can be overlapped with or retreated from the rear surface of the half mirror, in accordance with the operation of a photographer.

COPYRIGHT: (C)1996,JPO

EUROPEAN PATENT OFFICE

Patent Abstracts of Japan

PUBLICATIO PUBLICATIO	N N N E	NUMBER DATE	:	04211230 03-08-92
				10 10 00
APPLICATIO	NN	NUMBER	:	19-10-90 02282755
APPLICANT	:	FUJI PHOTO FILM	СС	O LTD;
INVENTOR	:	UEDA SATOSHI;		
INT.CL.	:	G03B 5/00 G01P	9/0	00
TITLE	:	COMPENSATOR F SHAKE BY HAND	=OF	R CAMERA



ABSTRACT : PURPOSE: To realize the downsizing and cost reduction of a device by arranging a mirror to compensate camera shake caused by hand in front of a photographing lens, making possible design of the photographing lens without taking the mirror into consideration, and simplifying a mirror support mechanism.

> CONSTITUTION: A compensator 10 to compensate camera shake caused by hand is arranged in front of a photographing lens 11, and generally, introduces a subject image to the photographing lens 11 by folding down the image by 90 degrees by means of a mirror 12. The mirror 12 is tillably supported in all directions, and when a camera is put in tilting motion due to camera shake and the like, the mirror 12 is put in tilting motion by a half of the camera shake angle in the opposite direction to the camera shake direction, and thereby, image oscillation caused by camera shake and the like can be compensated.

COPYRIGHT: (C)1992, JPO& Japio

Camera module

Abstract

The present invention relates to a camera module. According to an embodiment of the present invention, the camera module includes a reflector reflecting the optical image of an object; a lens; an actuator adjusting the focus of the optical image of the object; and an image sensor changing the optical image of the object to an electrical signal. [Reference numerals] (AA) Optical image

Images (5)



Other languages: Korean Inventor: Kim, Young-Ho Original Assignee: LG knoctek Co., Etd. Priority date : 2012-07-26 Family: KR(1) Date App/Pub Number Status 2012-07-26 KR20120081773A 2014-02-06 KR20140014787A Application

Digital camera

Abstract

<P>PROBLEM TO BE SOLVED: To provide a digital camera of a bent optical system for realizing pan/tilt photographing. <P>SOLUTION: A mirror 210 for bending incident light onto an imaging element is supported turnably around the X revolving axis and the Z revolving axis. A second actuator 321 is driven in response to a pan operation by a user to revolve the mirror 210 around the Z revolving axis. A first actuator 311 is driven in response to a tilt operation by the user to revolve the mirror 210 around the X revolving axis. Thus, the pan/tilt at moving picture photographing is achieved by the revolving of the mirror 210 in response to the user operation. That is, since the pan/tilt photographing can be executed in a state that a camera main body is at a standatill, a camera shake and an image shake caused by movement of the camera main body can be prevented. <P>COPYRIGHT: (C)2007,JPO&INPIT

Images (12)



JP2007/228006A P Application Developed PDF Q Find Proc Am I Similar

Other languages: Japanese

Inventor: Kazunosi Kita Johigo

Original Assignee: Casio Comput Co Ltd, Casio Computer Co., Ltd.

Priority date : 2006-02-23

Family: JP(1)								
Date	App/Pub Number	Status						
2006-02-21	JP2006043435A	Expired - Fee Related						
2007-09-06	JP2007228006A	Application						
2011-02-02	JP462288292	Grant						

Optical axis correcting mechanism

Abstract

PURPOSE: To prevent the generation of eroneous detection on the respective positions by correcting hand shake in the vertical direction by so-called an ABS system and in the horizontal direction by socalled a gimbal system.

CONSTITUTION: When hand shake in the vertical direction is generated, angle data detected by a hand shake amount arithmetic circuit 38V is compared with the position data of a correcting convex lens 5 obtained by a position sensor 18 in a position control circuit 39V for the correcting lens, the amount of angle to be corrected is detected, the correction data are outputted to a lens driving means 7, the correcting convex lens 5 is moved in the vertical direction and the optical axis is corrected. When hand shake in the horizontal direction is generated, the angle data are compared with the position data of a lens barrel 14 obtained by an angle position sensor 34, the amount of angle to be corrected is detected, the correction data are outputted to a barrel driving means 22, the lens barrel 14 is rotated in the horizontal direction and the optical axis is corrected. (COPYRIGHT (C) 1995, JPO

o antenn Zhan

Other languages: Japanese

Inventor: Hiroshi Kawamura, Elji Oshima, Kazuhiro Tanaka, Elji Oshima, Yoshikawa, Wada and Tanaka

Original Assignee: Sony Corp. Sony Corporation

Priority date : 1994-05-20

Family: JP (1)		
Bate	App/Pub Number	Statue
1994-05-20	JP12984994A	Expired - Fee Related
1995-12-08	JPH07318864A	Application
2002-12-09	JP335578782	Grant

Electronic Patent Application Fee Transmittal						
Application Number:	153	15324720				
Filing Date:	08-	Jan-2017				
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL					
First Named Inventor/Applicant Name:	Noy Cohen					
Filer:	Menachem Nathan					
Attorney Docket Number:	со	REPH-0159 US NP				
Filed as Small Entity						
Filing Fees for U.S. National Stage under 35 USC 371						
Description		Fee Code	Quantity	Amount	Sub-Total in USD(\$)	
Basic Filing:						
Pages:						
Claims:						
Miscellaneous-Filing:						
Petition:						
Patent-Appeals-and-Interference:						
Post-Allowance-and-Post-Issuance:						
Extension-of-Time:						

Description	Fee Code	Quantity	Amount	Sub-Total in USD(\$)			
Extension - 1 month with \$0 paid	2251	1	100	100			
Miscellaneous:							
	Tot	al in USD	(\$)	100			

Electronic Acknowledgement Receipt	
EFS ID:	33969934
Application Number:	15324720
International Application Number:	
Confirmation Number:	5811
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL
First Named Inventor/Applicant Name:	Noy Cohen
Customer Number:	92342
Filer:	Menachem Nathan
Filer Authorized By:	
Attorney Docket Number:	COREPH-0159 US NP
Receipt Date:	10-OCT-2018
Filing Date:	08-JAN-2017
Time Stamp:	14:58:43
Application Type:	U.S. National Stage under 35 USC 371

Payment information:

Submitted with Payment	yes
Payment Type	CARD
Payment was successfully received in RAM	\$100
RAM confirmation Number	101118INTEFSW15031700
Deposit Account	
Authorized User	

The Director of the USPTO is hereby authorized to charge indicated fees and credit any overpayment as follows:
File	Listin	g:
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Document Number	Document Description	File Name	File Size(Bytes)/ Message Digest	Multi Part /.zip	Pages (if appl.)			
1	Amendment/Req. Reconsideration-After Non-Final Reject	OA_Response.pdf	158030 df8e8524004aa939042369a115d6f1b05d5f e822	no	10			
Warnings:								
Information:								
2	Fee Worksheet (SB06)	fee-info.pdf	30674 1fe18670172edfd97f97b43119a816c24460 58df	no	2			
Warnings:								
Information:								
		Total Files Size (in bytes)	18	38704				
This Acknowledgement Receipt evidences receipt on the noted date by the USPTO of the indicated documents, characterized by the applicant, and including page counts, where applicable. It serves as evidence of receipt similar to a Post Card, as described in MPEP 503. New Applications Under 35 U.S.C. 111 If a new application is being filed and the application includes the necessary components for a filing date (see 37 CFR 1.53(b)-(d) and MPEP 506), a Filing Receipt (37 CFR 1.54) will be issued in due course and the date shown on this Acknowledgement Receipt will establish the filing date of the application. National Stage of an International Application under 35 U.S.C. 371 If a timely submission to enter the national stage of an international application is compliant with the conditions of 35 U.S.C. 371 and other applicable requirements a Form PCT/DO/EO/903 indicating acceptance of the application as a national stage submission under 35 U.S.C. 371 will be issued in addition to the Filing Receipt, in due course. New International Application is being filed and the international application includes the necessary components for an international Application is being filed and the international application includes the necessary components for an international filing date (see PCT Article 11 and MPEP 1810), a Notification of the International Application Number and of the International Filing Date (Form PCT/RO/105) will be issued in due course, subject to prescriptions concerning national security, and the date shown on this Acknowledgement Receipt will establish the international filing date of the application.								

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Applicant:	§ Confirmation No: 5811
Noy Cohen	8 §
Serial No.: 15/324,720	§ §
E:1.d. 01/09/2017	§ S. Group Art Hait: 2664
rileu. 01/08/2017	§ Group Art Onit. 2004 §
For: DUAL APERTURE ZOOM	
CAMERA WITH VIDEO SUPPORT	
AND SWITCHING / NON-	
SWITCHING DYNAMIC CONTROL	
	§ Attorney Docket: Coreph-0159 US NP
	§
Examiner: Tran, Nhan T.	

Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

RESPONSE

Sir:

This is in response to the United States Patent and Trademark Office Action having a Notification Date of 06/19/2018, which response is being made with a one month extension for which the appropriate fee is paid herewith.

Amendment to the Specification is provided on page 2.

A listing and amendmens of Claims begins on page 3.

Remarks/Arguments begin on page 7.

IN THE DESCRIPTION:

Please amend the paragraph on page 12, lines 24-28 as follows:

Returning now to the Zoom-in process, in some embodiments, for higher ZF than the up-transfer ZF_{\star} the output is the transformed Tele camera output, digitally zoomed. However, in other embodiments, for <u>higher ZF than the</u> up-transfer ZF_{*} there will be no switching from the Wide to the Tele camera output, i.e. the output will be from the Wide camera, digitally zoomed. This "no switching" process is described next.

IN THE CLAIMS:

Please amend the claims as follows:

1. (Currently amended) A zoom digital camera comprising:

a) a Wide imaging section that includes a fixed focal length Wide lens with a Wide field of view (FOV) and a Wide sensor, the Wide imaging section operative to provide Wide image data of an object or scene;

b) a Tele imaging section that includes a fixed focal length Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, the Tele imaging section operative to provide Tele image data of the object or scene; and

c) a camera controller operatively coupled to the Wide and Tele imaging sections, the camera controller and configured to evaluate if a no-switching criterion is fulfilled or not fulfilled, determined by inputs from both Wide and Tele image data, and, wherein if the no-switching criterion is fulfilled in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value at a zoom factor (ZF) higher than an up-transfer ZF, the camera controller is further configured to output a zoom video output image that includes only Wide image data, and wherein if the no-switching criterion is not fulfilled, the camera controller is further configured to output a zoom video output image that includes only transformed, digitally zoomed Tele image data.

2. (Original) The camera of claim 1, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

3. (Original) The camera of claim 1, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

4. (Original) The camera of claim 1, wherein the no-switching criterion includes an

3

effective resolution of the Tele image being lower than an effective resolution of the Wide image.

5. (Original) The camera of claim 1, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

6. (Original) The camera of claim 1, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

7. (Original) The camera of claim 1, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third distance threshold.

8. (Original) The camera of claim 1, wherein the camera controller includes a user control module for receiving user inputs and a sensor control module for configuring each sensor to acquire the Wide and Tele image data based on the user inputs.

9. (Original) The camera of claim 8, wherein the user inputs include a zoom factor, a camera mode and a region of interest.

10. (Previously presented) The camera of claim 1, wherein the Tele lens includes a ratio of total track length (TTL)/effective focal length (EFL) smaller than 1.

11. (Cancelled)

12. (Previously presented) The camera of claim 1, wherein the camera controller is further configured to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a

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particular point of view.

13. (Currently amended A method for obtaining zoom images of an object or scene using a digital camera, comprising the steps of:

a) providing in the digital camera a Wide imaging section having a Wide lens with a Wide field of view (FOV) and a Wide sensor, a Tele imaging section having a Tele lens with a Tele FOV that is narrower than the Wide FOV and a Tele sensor, and a camera controller operatively coupled to the Wide and Tele imaging sections; and

b) configuring the camera controller to evaluate <u>if a no-switching criterion determined by</u> inputs from both Wide and Tele image data <u>is fulfilled or not fulfilled</u>, and, if the noswitching criterion is fulfilled, <u>configuring the camera controller</u> to output <u>at a zoom factor</u> (ZF) higher than an up-transfer ZF a zoom video output image that includes only Wide image data in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value, <u>or</u> if the no-switching criterion is not fulfilled, configuring the camera controller to output a zoom video output image that includes only transformed, digitally zoomed Tele image data.

14. (Original) The method of claim 13, wherein the no-switching criterion includes a shift between the Wide and Tele images calculated by global registration, the shift being greater than a first threshold.

15. (Original) The method of claim 13, wherein the no-switching criterion includes a disparity range calculated by global registration, the disparity range being greater than a second threshold.

16. (Original) The method of claim 13, wherein the no-switching criterion includes an effective resolution of the Tele image being lower than an effective resolution of the Wide image.

17. (Original) The method of claim 13, wherein the no-switching criterion includes a number of corresponding features in the Wide and Tele images being smaller than a third threshold.

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18. (Original) The method of claim 13, wherein the no-switching criterion includes a majority of objects imaged in an overlap area of the Wide and Tele images being calculated to be closer to the camera than a first threshold distance.

19. (Original) The method of claim 13, wherein the no-switching criterion includes some objects imaged in an overlap area of the Wide and Tele images being calculated to be closer than a second threshold distance while other objects imaged in the overlap area of the Wide and Tele images being calculated to be farther than a third threshold distance.

20. (Previously presented) The method of claim 13, further comprising the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image of the object or scene from a particular point of view.

21. (Previously presented) The method of claim 13, wherein the step of configuring the camera controller to combine in still mode, at a predefined range of ZF values, at least some of the Wide and Tele image data to provide a fused output image includes configuring the camera controller to combine Wide and Tele image data only in focused areas.

REMARKS

The present response is intended to be fully responsive to all points of objection and/or rejection raised by the Examiner and is believed to place the application in condition for allowance.

Applicant asserts that the instant invention is new, non-obvious and useful. Prompt consideration and allowance of the claims is respectfully requested.

Status of Claims

Claims 1-21 are pending in the application. Claims 1, 2, 8-11, 13, 14, 20 and 21 were rejected in the Office Action dated 06/19/2018. The rejection is respectfully traversed. Claims 3-7 and 15-19 were objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claim. The conditional allowance of claims 3-7 and 15-19 is gratefully acknowledged.

Claim 11 is cancelled herewith without prejudice, with most of its limitations being moved to claims 1 and 13. With the cancellation of claim 11, its rejection is moot.

Description and Claim amendments

Applicant hereby amends the language in the paragraph on page 12, lines 24-28 to add the inadvertently left out words "<u>higher ZF than the</u>" before "up-transfer ZF". These words should have clearly been present in view of the immediately previous sentence and in view of the qualifier "However" at the start of this sentence. No new matter is introduced.

Claims 1 and 13 are amended to recite the added limitation that if the no-switching criterion is fulfilled, the camera controller is configured to output at a zoom factor (ZF) higher than an up-transfer ZF a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF value and a higher ZF value, and if the no-switching criterion is not fulfilled, the camera controller is configured to output a zoom video output image that includes only transformed, digitally zoomed Tele image data. Support for

the amendments may be found in p. 12, lines 24-28, in original claim 11, and in the broader description of the "zoom in" video operation at ZFs equal to or higher than the up-transfer ZF.

Claim rejections - 35 U.S.C. § 102

Claims 1, 2, 4, 8-14, 20 and 21 were rejected under 35 U.S.C. § 102(a)(1) as being anticipated by Shabtay et al. (WO 2014/199338, hereinafter Shabtay). The rejection is respectfully traversed. With the cancellation of claim 11, its rejection is moot. However, while traversing the rejection, Applicant hereby amends claim 1 to recite in (c):

c) a camera controller operatively coupled to the Wide and Tele imaging sections and configured to evaluate if a no-switching criterion is fulfilled or not fulfilled, wherein if the no-switching criterion is fulfilled in a zoom-in operation between a lower zoom factor (ZF) value and a higher ZF value at a zoom factor (ZF) higher than an up-transfer ZF, the camera controller is further configured to output a zoom video output image that includes only Wide image data, and wherein if the no-switching criterion is not fulfilled, the camera controller is further configured to output a zoom video output image that includes only transformed, digitally zoomed Tele image data.

and amends claim 13 to recite in (b):

b) configuring the camera controller to evaluate <u>if a no-switching criterion is fulfilled or</u> not fulfilled, and, if the no-switching criterion is fulfilled, <u>configuring the camera controller</u> to output <u>at a zoom factor (ZF) higher than an up-transfer ZF</u> a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF-value and a higher ZF value, or if the no-switching criterion is not fulfilled, configuring the camera controller to output a zoom video output image that includes only transformed, digitally zoomed Tele image data.

Support for the amendment may be found in p. 12, lines 24-28 as well as being clearly supported by the broader description of the "zoom in" video operation at ZFs equal to or higher than the up-transfer ZF.

Applicant respectfully submits that Shabtay does not teach in any way a camera controller configured to output, at a ZF higher than an up-transfer ZF, a zoom video output image that includes only Wide image data in a zoom-in operation between a lower ZF value

and a higher ZF value. Shabtay teaches that at <u>any</u> ZF higher that the up-transfer ZF a camera outputs a <u>Tele image</u>. as indicated for example in Shabtay page 13, lines 10-14:

Zoom-in: at low ZF up to slightly above ZFT, the output image is a digitally zoomed, Wide fusion output. For the up-transfer ZF, the Tele image is shifted and corrected by global registration (GR) to achieve smooth transition. Then, the output is transformed to a Tele fusion output. For higher (than the up-transfer) ZF, the output is the Tele fusion output digitally zoomed.

Applicant therefore submits that Shabtay cannot and does not anticipate claims 1, 13 and all claims depending therefrom, and cannot even render these claims unpatentable.

Claim objections

Claims 3-7 and 15-19 were objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claim. Applicant submits that with the amendment of claims 1 and 13 from which these claims depend directly or indirectly, these claims are allowable in their present form.

Conclusion

In view of the foregoing remarks, Applicant asserts that the pending claims are allowable. Their favorable reconsideration and allowance is respectfully requested.

Should the Examiner have any question or comment as to the form, content or entry of this Amendment, the Examiner is requested to contact the undersigned at the telephone number below. Similarly, if there are any further issues yet to be resolved to advance the prosecution of this application to issue, the Examiner is requested to telephone the undersigned counsel.

Respectfully submitted, /Menachem Nathan/ Menachem Nathan Agent for Applicant Registration No. 65392

Tel: 516-442-9736

Date: October 10, 2018

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P	ATENT APPL	ICATION F Substitute f	EE DETI or Form P	ERMINATION TO-875	N RECORD	Applicatior 15	n or Docket Number /324,720	Filing Date 01/08/2017	To be Mailed
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то	(37 CFR 1.16(o), (p), (TAL CLAIMS	or (q))	IN/A		N/A		N/A		
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This of proce	collection of informates) an application. (tion is required b Confidentiality is	y 37 CFR 1. governed by	16. The information 35 U.S.C. 122 and	n is required to obt d 37 CFR 1.14. Th	ain or retain a is collection is	a benefit by the public s estimated to take 12	which is to file (and minutes to complete	by the USPTO to e, including gathering,

process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 GFH 1.14. This collection is estimated to take 12 minutes to complete, including gathering preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450.

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NOTICE OF ALLOWANCE AND FEE(S) DUE

92342 7590 11/16/2018 Nathan & Associates Patent Agents Ltd P.O.Box 10178 Tel Aviv, 6110101 ISRAEL

EXAMINER TRAN, NHAN T ART UNIT PAPER NUMBER

2664

DATE MAILED: 11/16/2018

APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP	5811

TITLE OF INVENTION: DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL

APPLN. TYPE	ENTITY STATUS	ISSUE FEE DUE	PUBLICATION FEE DUE	PREV. PAID ISSUE FEE	TOTAL FEE(S) DUE	DATE DUE
nonprovisional	SMALL	\$500	\$0.00	\$0.00	\$500	02/19/2019

THE APPLICATION IDENTIFIED ABOVE HAS BEEN EXAMINED AND IS ALLOWED FOR ISSUANCE AS A PATENT. <u>PROSECUTION ON THE MERITS IS CLOSED</u>. THIS NOTICE OF ALLOWANCE IS NOT A GRANT OF PATENT RIGHTS. THIS APPLICATION IS SUBJECT TO WITHDRAWAL FROM ISSUE AT THE INITIATIVE OF THE OFFICE OR UPON PETITION BY THE APPLICANT. SEE 37 CFR 1.313 AND MPEP 1308.

THE ISSUE FEE AND PUBLICATION FEE (IF REQUIRED) MUST BE PAID WITHIN <u>THREE MONTHS</u> FROM THE MAILING DATE OF THIS NOTICE OR THIS APPLICATION SHALL BE REGARDED AS ABANDONED. <u>THIS STATUTORY PERIOD</u> <u>CANNOT BE EXTENDED</u>. SEE 35 U.S.C. 151. THE ISSUE FEE DUE INDICATED ABOVE DOES NOT REFLECT A CREDIT FOR ANY PREVIOUSLY PAID ISSUE FEE IN THIS APPLICATION. IF AN ISSUE FEE HAS PREVIOUSLY BEEN PAID IN THIS APPLICATION (AS SHOWN ABOVE), THE RETURN OF PART B OF THIS FORM WILL BE CONSIDERED A REQUEST TO REAPPLY THE PREVIOUSLY PAID ISSUE FEE TOWARD THE ISSUE FEE NOW DUE.

HOW TO REPLY TO THIS NOTICE:

I. Review the ENTITY STATUS shown above. If the ENTITY STATUS is shown as SMALL or MICRO, verify whether entitlement to that entity status still applies.

If the ENTITY STATUS is the same as shown above, pay the TOTAL FEE(S) DUE shown above.

If the ENTITY STATUS is changed from that shown above, on PART B - FEE(S) TRANSMITTAL, complete section number 5 titled "Change in Entity Status (from status indicated above)".

For purposes of this notice, small entity fees are 1/2 the amount of undiscounted fees, and micro entity fees are 1/2 the amount of small entity fees.

II. PART B - FEE(S) TRANSMITTAL, or its equivalent, must be completed and returned to the United States Patent and Trademark Office (USPTO) with your ISSUE FEE and PUBLICATION FEE (if required). If you are charging the fee(s) to your deposit account, section "4b" of Part B - Fee(s) Transmittal should be completed and an extra copy of the form should be submitted. If an equivalent of Part B is filed, a request to reapply a previously paid issue fee must be clearly made, and delays in processing may occur due to the difficulty in recognizing the paper as an equivalent of Part B.

III. All communications regarding this application must give the application number. Please direct all communications prior to issuance to Mail Stop ISSUE FEE unless advised to the contrary.

IMPORTANT REMINDER: Maintenance fees are due in utility patents issuing on applications filed on or after Dec. 12, 1980. It is patentee's responsibility to ensure timely payment of maintenance fees when due. More information is available at www.uspto.gov/PatentMaintenanceFees.

	Alexandria, Virgir	nia 22313-1450						
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Tel Aviv, 611010	Tel Aviv, 6110101				USPTO via EFS-W	eb or b	y facsimile to (571) 273	3-2885, on the date below.
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APPLICATION NO.	FILING DATE		FIRST NAMED INVEN	TOR		ATTO	RNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017	•	Noy Cohen			COR	EPH-0159 US NP	5811
TITLE OF INVENTION: I	DUAL APERTURE ZO	OOM CAMERA WITH V	IDEO SUPPORT ANI	D SW	/ITCHING / NON-	SWITC	CHING DYNAMIC CO	NTROL
APPLN. TYPE	ENTITY STATUS	ISSUE FEE DUE	PUBLICATION FEE I	DUE	PREV. PAID ISSUI	E FEE	TOTAL FEE(S) DUE	DATE DUE
nonprovisional	SMALL	\$500	\$0.00		\$0.00		\$500	02/19/2019
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 1. Change of correspondence address or indication of "Fee Address" (37 CFR 1.363). Change of correspondence address (or Change of Correspondence Address form PTO/SB/122) attached. Tee Address" indication (or "Fee Address" Indication form PTO/SB/47; Rev 03-09 or more recent) attached. Use of a Customer 			 For printing on The names of or agents OR, alter The name of a registered attorney registered attorney registered patent listed, no name wi 	Por printing on the patent front page, not (1) The names of up to 3 registered patent attorneys (2) The name of a single firm (having as a member a gistered attorney or agent) and the names of up to (2) The name of a single firm (having as a member a gistered attorney or agent) and the names of up to (3) The name will be printed.				
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(A) NAME OF ASSIG	NEE		(B) RESIDENCE: (C	CITY	and STATE OR C	OUNT	RY)	
Please check the appropria	te assignee category or	categories (will not be pr	inted on the patent) : [┛ In	dividual 🖵 Corpo	ration c	or other private group er	ntity 🖵 Government
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The Director is here	by authorized to charge	e the required fee(s), any	deficiency, or credit a	ny ov	erpayment to Depo	sit Acc	ount No	
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5. Change in Entity Statu	s (from status indicate	d above)						
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Applicant asserting	Applicant asserting small entity status. See 37 CFR 1.27 NOTE: If the application was previously under micro entity status, checking this box will be taken to be a notification of loss of entitlement to micro entity status.					g this box will be taken		
Applicant changing	Applicant changing to regular undiscounted fee status. NOTE: Checking this box will be taken to be a notification of loss of entitlement to small or micro entity status, as applicable.							
NOTE: This form must be	signed in accordance v	vith 37 CFR 1.31 and 1.33	3. See 37 CFR 1.4 for	signa	ture requirements a	and cer	tifications.	
Authorized Signature					Date			
Typed or printed name					Registration N	0		

PART B - FEE(S) TRANSMITTAL

Mail Stop ISSUE FEE Commissioner for Patents

P.O. Box 1450

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PTOL-85 Part B (08-18) Approved for use through 01/31/2020

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(Typed or printed name)	
(Signature)	
(Date)	

TRAN, NHAN T	2664	348-240990		
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CFR 1.363).		(1) The names of up to or agents OR alternativ	3 registered patent attorneys	1
Change of correspondence address (or Cha	nge of Correspondence	(2) The name of a single	e firm (having as a member a	
Address form PTO/SB/122) attached.		registered attorney or a	gent) and the names of up to	2
□ "Fee Address" indication (or "Fee Address"	'Indication form PTO/	listed, no name will be	printed.	3
Number is required.	se of a Customer			5

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5. Change in Entity Status (from status indicated above)	
Applicant certifying micro entity status. See 37 CFR 1.29	<u>NOTE:</u> Absent a valid certification of Micro Entity Status (see forms PTO/SB/15A and 15B), issue fee payment in the micro entity amount will not be accepted at the risk of application abandonment.
Applicant asserting small entity status. See 37 CFR 1.27	<u>NOTE:</u> If the application was previously under micro entity status, checking this box will be taken to be a potification of loss of entitlement to micro entity status

Complete and send this form, together with applicable fee(s), by mail or fax, or via EFS-Web.

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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.	
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP	5811	
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P.O.Box 10178			ART UNIT	PAPER NUMBER	
1 el Aviv, 61 10101			2664		
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			DATE MAILED: 11/16/201	8	

Determination of Patent Term Adjustment under 35 U.S.C. 154 (b)

(Applications filed on or after May 29, 2000)

The Office has discontinued providing a Patent Term Adjustment (PTA) calculation with the Notice of Allowance.

Section 1(h)(2) of the AIA Technical Corrections Act amended 35 U.S.C. 154(b)(3)(B)(i) to eliminate the requirement that the Office provide a patent term adjustment determination with the notice of allowance. See Revisions to Patent Term Adjustment, 78 Fed. Reg. 19416, 19417 (Apr. 1, 2013). Therefore, the Office is no longer providing an initial patent term adjustment determination with the notice of allowance. The Office will continue to provide a patent term adjustment determination Letter that is mailed to applicant approximately three weeks prior to the issue date of the patent, and will include the patent term adjustment on the patent. Any request for reconsideration of the patent term adjustment determination (or reinstatement of patent term adjustment) should follow the process outlined in 37 CFR 1.705.

Any questions regarding the Patent Term Extension or Adjustment determination should be directed to the Office of Patent Legal Administration at (571)-272-7702. Questions relating to issue and publication fee payments should be directed to the Customer Service Center of the Office of Patent Publication at 1-(888)-786-0101 or (571)-272-4200.

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The information collected by PTOL-85 Part B is required by 37 CFR 1.311. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.14. This collection is estimated to take 30 minutes to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, Virginia 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, Virginia 22313-1450. Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it displays a valid OMB control number.

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The Privacy Act of 1974 (P.L. 93-579) requires that you be given certain information in connection with your submission of the attached form related to a patent application or patent. Accordingly, pursuant to the requirements of the Act, please be advised that: (1) the general authority for the collection of this information is 35 U.S.C. 2(b) (2); (2) furnishing of the information solicited is voluntary; and (3) the principal purpose for which the information is used by the U.S. Patent and Trademark Office is to process and/or examine your submission related to a patent application or patent. If you do not furnish the requested information, the U.S. Patent and Trademark Office may not be able to process and/or examine your submission, which may result in termination of proceedings or abandonment of the application or expiration of the patent.

The information provided by you in this form will be subject to the following routine uses:

- 1. The information on this form will be treated confidentially to the extent allowed under the Freedom of Information Act (5 U.S.C. 552) and the Privacy Act (5 U.S.C 552a). Records from this system of records may be disclosed to the Department of Justice to determine whether disclosure of these records is required by the Freedom of Information Act.
- 2. A record from this system of records may be disclosed, as a routine use, in the course of presenting evidence to a court, magistrate, or administrative tribunal, including disclosures to opposing counsel in the course of settlement negotiations.
- 3. A record in this system of records may be disclosed, as a routine use, to a Member of Congress submitting a request involving an individual, to whom the record pertains, when the individual has requested assistance from the Member with respect to the subject matter of the record.
- 4. A record in this system of records may be disclosed, as a routine use, to a contractor of the Agency having need for the information in order to perform a contract. Recipients of information shall be required to comply with the requirements of the Privacy Act of 1974, as amended, pursuant to 5 U.S.C. 552a(m).
- 5. A record related to an International Application filed under the Patent Cooperation Treaty in this system of records may be disclosed, as a routine use, to the International Bureau of the World Intellectual Property Organization, pursuant to the Patent Cooperation Treaty.
- 6. A record in this system of records may be disclosed, as a routine use, to another federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspection or an application of 435
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

	Application No.	Applicant(s)	
	15/324,720	Cohen et al.	
Notice of Allowability	Examiner	Art Unit	AIA Status
	NHAN T TRAN	2664	Yes

The MAILING DATE of this communicate All claims being allowable, PROSECUTION ON THE ME herewith (or previously mailed), a Notice of Allowance (P NOTICE OF ALLOWABILITY IS NOT A GRANT OF PA of the Office or upon petition by the applicant. See 37 CF	tion appears on the RITS IS (OR REM/ TOL-85) or other ap TENT RIGHTS. Th TR 1.313 and MPEF	AINS) CLOSED in this application. If not included ppropriate communication will be mailed in due course. THIS is application is subject to withdrawal from issue at the initiative 1308.
1. This communication is responsive to <u>amendment f</u> A declaration(s)/affidavit(s) under 37 CFR 1.13	iled on 10/10/2018. 80(b) was/were filed	I on
2. An election was made by the applicant in response restriction requirement and election have been included	e to a restriction req orporated into this a	uirement set forth during the interview on; the action.
3. In the allowed claim(s) is/are <u>1-10</u> , <u>12-21</u> (renumber from the Patent Prosecution Highway program a more information, please see http://www.uspto.g PPHfeedback@uspto.gov.	<u>ed as 1-20)</u> . As a r it a participating inte ov/patents/init_eve	result of the allowed claim(s), you may be eligible to benefit ellectual property office for the corresponding application. For ents/pph/index.jsp or send an inquiry to
4. Acknowledgment is made of a claim for foreign priv	ority under 35 U.S.(C. § 119(a)-(d) or (f).
Certified copies:		
a) 🗌 All b) 🗋 Some *c) 🗔 None of th	ie:	
 Certified copies of the priority docum Certified copies of the priority docum Copies of the certified copies of the priority docum 	ents have been rec ents have been rec priority documents h	ceived. ceived in Application No have been received in this national stage application from the
International Bureau (PCT Rule 17.2	(a)).	
* Certified copies not received:		
Applicant has THREE MONTHS FROM THE "MAILIN noted below. Failure to timely comply will result in AB/ THIS THREE-MONTH PERIOD IS NOT EXTENDABI	IG DATE" of this co ANDONMENT of th L E.	mmunication to file areply complying with the requirements is application.
5. CORRECTED DRAWINGS (as "replacement shee	ets") must be submi	tted.
including changes required by the attached E Paper No./Mail Date	xaminer's Amendm	ent / Comment or in the Office action of
Identifying indicia such as the application number (see sheet. Replacement sheet(s) should be labeled as such	37 CFR 1.84(c)) sho in the header accor	uld be written on the drawings in the front (not the back) of each rding to 37 CFR 1.121(d).
6. DEPOSIT OF and/or INFORMATION about the de attached Examiner's comment regarding REQUIRI	POSIT OF BIOLOGIC	AL MATERIAL must be submitted. Note the DEPOSIT OF BIOLOGICAL MATERIAL.
Attachment(s) 1. Notice of References Cited (PTO-892)		5. 🗌 Examiner's Amendment/Comment
2. Information Disclosure Statements (PTO/SB/08),		6. 🗹 Examiner's Statement of Reasons for Allowance
3. Examiner's Comment Regarding Requirement for I	Deposit	7. 🗌 Other
4. Interview Summary (PTO-413), Paper No./Mail Date		
/NHAN T TRAN/		
Primary Examiner, Art Unit 2664		
U.S. Patent and Trademark Office		
PTOL-37 (Rev. 08-13)	Notice of Allowab	ility Part of Paper No./Mail Date 20181113

DETAILED ACTION

Notice of Pre-AIA or AIA Status

1. The present application, filed on or after March 16, 2013, is being examined under the first inventor to file provisions of the AIA.

Response to Arguments

2. Applicant's amendment and arguments, filed on 10/10/2018, with respect to claims 1-10 and 12-21 have been fully considered and are persuasive. The rejection indicated in the previous Office Action has been overcome and withdrawn.

Information Disclosure Statement

3. The information disclosure statement (IDS) submitted on 9/23/2018 is in compliance with the provisions of 37 CFR 1.97. Accordingly, the information disclosure statement is being considered by the examiner.

Specification

4. The amendment to the specification filed on 10/10/2018 is accepted and entered.

Allowable Subject Matter

5. Claims 1-10 and 12-21 are allowed.

6. The reasons for allowance of the claims are clear from the written record of prosecution. Attention is specifically drawn to the amendments and arguments dated 10/10/2018. As such, the reasons for allowance have been fully addressed and complied

according to MPEP 1302.14(I). As such, the reasons for allowance have been fully addressed and complied according to MPEP 1302.14(I).

Conclusion

7. Any inquiry concerning this communication or earlier communications from the examiner should be directed to NHAN T TRAN whose telephone number is (571)272-7371. The examiner can normally be reached on Monday - Friday, 9:00am - 5:00pm.

Examiner interviews are available via telephone, in-person, and video conferencing using a USPTO supplied web-based collaboration tool. To schedule an interview, applicant is encouraged to use the USPTO Automated Interview Request (AIR) at

http://www.uspto.gov/interviewpractice.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Lin Ye can be reached on 571-372-7372. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free). If you would like assistance from a USPTO Customer Service Representative or access to the automated information system, call 800-786-9199 (IN USA OR CANADA) or 571-272-1000. /NHAN T TRAN/ Primary Examiner, Art Unit 2664

	Application/Control No.	Applicant(s)/Patent Under Reexamination
Issue Classification	15/324,720	Cohen et al.
	Examiner	Art Unit
	NHAN T TRAN	2664

CPC					
Symbol			Туре	Version	
H04N	5	23296	F	2013-01-01	
H04N	5	/ 2258	1	2013-01-01	
H04N	5	/ 23216	1	2013-01-01	
H04N	5	23245	I	2013-01-01	

CPC Combination Sets				
Symbol	Туре	Set	Ranking	Version

NONE		Total Claims	s Allowed:
(Assistant Examiner)	(Date)	20)
/NHAN T TRAN/ Primary Examiner, Art Unit 2664	13 November 2018	O.G. Print Claim(s)	O.G. Print Figure
(Primary Examiner)	(Date)	1	1A & 3A
U.S. Patent and Trademark Office		Pari	t of Paper No.: 20181113

	Application/Control No.	Applicant(s)/Patent Under Reexamination
Issue Classification	15/324,720	Cohen et al.
	Examiner	Art Unit
	NHAN T TRAN	2664

INTERNATIONAL CLASSIFICATION			
CLAIMED			
H04N	5	232	
H04N	5	225	

US ORIGINAL CLAS	SIFICATION		
	CLASS	SUBCLASS	
CROSS REFERENCES(S)			
CLASS	CLASS SUBCLASS (ONE SUBCLASS PER BLOCK)		

NONE		Total Claim	s Allowed:
(Assistant Examiner)	(Date)	20)
/NHAN T TRAN/ Primary Examiner, Art Unit 2664	13 November 2018	O.G. Print Claim(s)	O.G. Print Figure
(Primary Examiner)	(Date)	1	1A & 3A
U.S. Patent and Trademark Office		Par	t of Paper No.: 20181113

	Application/Control No.	Applicant(s)/Patent Under Reexamination
Issue Classification	15/324,720	Cohen et al.
	Examiner	Art Unit
	NHAN T TRAN	2664

	Claims re	enumbe	ered in th	ne same	e order a	is prese	ented by	applica	ant [] CPA		T.D.	🗌 R.1	1.47	
CLAIN	IS														
Final	Original	Final	Original	Final	Original	Final	Original	Final	Original	Final	Original	Final	Original	Final	Original
1	1	10	10	18	19										
2	2	-	11	19	20										
3	3	11	12	20	21										
4	4	12	13												
5	5	13	14												
6	6	14	15												
7	7	15	16												
8	8	16	17												
9	9	17	18												

NONE	Total Claims Allowed:		
(Assistant Examiner)	(Date)	20)
/NHAN T TRAN/ Primary Examiner, Art Unit 2664	13 November 2018	O.G. Print Claim(s)	O.G. Print Figure
(Primary Examiner)	(Date)	1	1A & 3A
U.S. Patent and Trademark Office		Pari	t of Paper No.: 20181113



Application/Control No.	Applicant(s)/Patent Under Reexamination		
15/324,720	Cohen et al.		
Examiner	Art Unit		
NHAN T TRAN	2664		

CPC - Searched*				
Symbol	Date	Examiner		
H04N5/23296; H04N5/2258; H04N5/23216; H04N5/23245	6/10/2018	NT		

CPC Combination Sets - Searched*				
Symbol	Date	Examiner		

US Classification - Searched*					
Class	Subclass	Date	Examiner		

* See search history printout included with this form or the SEARCH NOTES box below to determine the scope of the search.

Search Notes		
Search Notes	Date	Examiner
EAST search in all available databases (see search history)	6/10/2018	NT
EAST text search in all groups and subgroups (see search history)	6/11/2018	NT
Inventorship search	6/11/2018	NT
Updated EAST text search (see search history)	11/13/2018	NT

Interference Search						
US Class/CPC Symbol	US Subclass/CPC Group	Date	Examiner			
ALL	Interference text search in USPAT and USPGPUB	11/13/2018	NT			

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2403	(detect\$3 or determin\$3 or if or when) near2 (object or subject or feature or target) near3 (clos\$2 or distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:01
L2	5028	(wide near1 angle or wide) same lens same (telephoto or tele) same (dual or two) same (lens or imag\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:01
L3	3594	L2 same zoom\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:01
L4	297	L3 same (switch\$3 or transition\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:01
L5	257	L4 and @ad<"20150813"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:01
L7	5015	(object or subject or feature) near3 (clos\$2 or short adj1 distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:21
L8	48	L7 and (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 (lens or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/11/13 14:21
S1	0	("15324720").PN.	US-PGPUB;	OR	OFF	2018/06/10

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			USPAT; USOCR			16:31
S2	10660	H04N5/23296.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM TDB	OR	ON	2018/06/10 16:36
S3	6676	H04N5/2258.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S4	10722	H04N5/23216.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S5	12379	H04N5/23245.cpc.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/10 16:36
S6	23	"2014199338"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:17
S7	6	"20030017930"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:29
S8	6	(("20030017930") or ("20090102950") or ("20080030592") or ("20100277619") or ("20110064327") or ("20150244942")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/11 11:30
S9	1	("20030179303").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/11 11:32
S10	4	(("8401276") or ("6104432") or ("5710670") or ("9185291")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/11 11:34
S11	4890	(wide near1 angle or wide) same lens same (telephoto or tele) same (dual or two) same (lens or imag\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT;	OR	ON	2018/06/11 11:37 PPL-1002 / Page 314 of 43

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		<u> </u>	IBM_TDB			
S12	3503	S11 same zoom\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:37
S13	287	S12 same (switch\$3 or transition\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:38
S14	256	S13 and @ad< "20150813"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 11:38
S15	9	(transition\$3 or switch\$3 or shift\$3) near3 digital near2 zoom\$4 with (telephoto or tele) near3 (lens or optical or imag\$3 near2 sens\$3 or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:09
S16	74503	fixed near1 focal with wide wth (telephoto or tele) same (dual or two)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:36
S17	3561	(transition\$3 or switch\$3 or shift\$3) with wide with (tele or telephoto or zoom\$4 adj1 in)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:36
S18	502	S16 same S17	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:37
S19	32	S18 same (digital or electronic) near2 (zoom or magnification)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 12:38
S20	150	fixed with wide with (tele or telephoto) with (dual or two) with (lens or optic\$3 or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO;	OR	ON	2018/06/11 13:35

			JPO; DERWENT; IBM_TDB			
S21	18	S20 same (switch\$3 or transition\$3 or shift\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 13:35
S22	293	(shift\$3 near3 image) with wide with (tele or telephoto)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:19
S23	0	S22 same (registration or register) with global	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:20
S24	4	S22 and (registration or register) with global	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:20
S25	37579	(disparity or misalign\$4) with image	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/11 14:21
S26	274	switch\$3 near2 (camera or tele or telephoto or long near1 focal) with resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 15:42
S27	0	S26 with (digital near1 zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:15
S28	0	S26 with ((digital or electronic) near1 zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:15
S29	49	(wide or short near2 focal) near2 (camera or lens or optic\$3) with (tele or	US-PGPUB; USPAT;	OR	ON	2018/06/12 16:17

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		telephoto or long near2 focal) with (switch\$3 or transition\$3 or shift\$3) with condition	USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB			
S30	431	(wide or short near2 focal) near2 (camera or lens or optic\$3) with (tele or telephoto or long near2 focal) with (switch\$3 or transition\$3 or shift\$3) with (condition or zoom\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:17
S31	7	S30 same (digital or electronic) near2 (zoom\$4 or magnification or enlargement) with resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:18
S32	145	resolution with (wide or short near1 focal) near2 imag\$3 with (tele or telephoto or long near1 focal)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:21
S33	1	S32 same threshold	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:21
S34	49	(dual near2 (camera or imag\$3 near2 sens\$3) with wide with (tele or telephoto))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:23
S35	27	S34 and resolution	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 16:24
S36	0	("14386823").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 16:24
S37	1	("20150085174").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 16:25
S38	1	("9800798").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 17:28
S39	16	("20020152557" "20060139463" "20060187312" "20060187338" "20070025713" "20080024596" "20080030592" "20090295949"	US-PGPUB; USPAT; USOCR	OR	ON	2018/06/12 17:28
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		"20110249086" "20130235234" "20130250159" "20140184854" "20140232905" "5870139" "7561191" "8456515").PN. OR ("9800798").URPN.				
S40	5	S34 and (disparity or parallax or misalign\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:38
S41	5	effective near2 resolution with image with (digital or electronic) near2 zoom\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:44
S42	147	detect\$3 near2 (object or subject or feature) near3 (clos\$3 or short adj1 distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S43	0	S42 with (switch\$3 or chang\$3 or shift\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S44	0	S42 same (switch\$3 or chang\$3 or shift\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:49
S45	4797	(object or subject or feature) near3 (clos\$2 or short adj1 distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:50
S46	1	S45 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 (lens or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:50
S47	47	S45 and (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 (lens or camera)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:51
S48	0	S45 same (switch\$3 or chang\$3 or	US-PGPUB;	OR	ON	2018/06/12 PPL-1002 / Page

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		shift\$3 or driv\$3) near2 wide near2 mode	USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB			17:53
S49	4978	(object or subject or feature or target) near3 clos\$2 near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 17:55
S50	0	S49 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 mode	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:06
S51	2278	(detect\$3 or determin\$3 or if or when) near2 (object or subject or feature or target) near3 (clos\$2 or distance) near2 camera	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:07
S52	0	S51 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide near2 mode	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:08
S53	0	S51 same (switch\$3 or chang\$3 or shift\$3 or driv\$3) near2 wide	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:08
S54	10	(switch\$3 or shift\$3 or chang\$3) near3 (wide or short near2 focal) near3 (zoom\$3 or close-up or closeup or long near1 focal) with (detect\$3 near3 (object or subject or target))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/12 18:17
S55	1	("20090022276").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2018/06/12 22:35
S56	311	(Cohen near2 Noy or Gigushinski near2 Oded or GEva near1 Nadav or Shabtay near1 Gal or Ashkenazi near2 Ester or Katz near1 Ruthy or Goldenberg near1 Ephraim).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2018/06/13 00:00

EAST Search History (Interference)

Ref	Hits	Search Query	DBs	Default	Plurals	Time
#				Operator		Stamp
L9	1	(zoom\$4 and digital\$2 and fixed and focal and length and wide and (telephoto or tele) and	US- PGPUB;	OR	ON	2018/11/13 14:39
		factor and low\$3 and high\$3 and switch\$3 and (criteria or criterion)).clm.	USPAT			

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Doc code: IDS

Doc description: Information Disclosure Statement (IDS) Filed

PTO/SB/08a (01-10)

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	15	2007228006	JP	A	2007-09-06	lchigo			
	16	H07318864	JP	A	1995-12-08	Kawamura et al.			
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	1	Statistical Modeling and I Greienhagen et al., Publi	Statistical Modeling and Performance Characterization of a Real-Time Dual Camera Surveillance System, Greienhagen et al., Publisher: IEEE, 2000, 8 pages						
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Application Number		15324720		
Filing Date		2017-01-08		
First Named Inventor	Noy Cohen			
Art Unit				
Examiner Name				
Attorney Docket Number		COREPH-0159 US NP		

5	Defocus Video Matting, McGuire et al., Publisher: ACM SIGGRAPH, 07/31/2005, 11 pages	
6	Compact multi-aperture imaging with high angular resolution, Santacana et al., Publisher: Optical Society of America, 2015, 10 pages	
7	Multi-Aperture Photography, Green et al., Publisher: Mitsubishi Electric Research Laboratories, Inc., July 2007, 10 pages	
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9	Super-resolution imaging using a camera array, Santacana et al., Publisher: Optical Society of America, 2014, 6 pages	
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13	Superimposed multi-resolution imaging, Carles et al., Publisher: Optical Society of America, 2017, 13 pages	
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Application Number		15324720	
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Examiner Name			
Attorney Docket Number		COREPH-0159 US NP	
First Named Inventor Art Unit Examiner Name Attorney Docket Numbe	Noy C	COREPH-0159 US NP	

Engi 16 June	neered to the task: Why camera-phone cameras 2009, 3 pages	s are different, Giles Humpston, Publisher:	Solid State Technology,				
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¹ See Kind Codes of USP Standard ST.3). ³ For Jap ⁴ Kind of document by the English language translati	FO Patent Documents at <u>www.USPTO.GOV</u> or MPEP panese patent documents, the indication of the year of appropriate symbols as indicated on the document ur on is attached.	⁹ 901.04. ² Enter office that issued the documer f the reign of the Emperor must precede the seri nder WIPO Standard ST.16 if possible. ⁵ Applic	nt, by the two-letter code (WIPO al number of the patent document. ant is to place a check mark here if				

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	Filing Date		2017-01-08	
INFORMATION DISCLOSURE	First Named Inventor	Noy C	Cohen	
(Not for submission under 37 CFR 1.99)	Art Unit			
	Examiner Name			
	Attorney Docket Numb	er	COREPH-0159 US NP	

Application Number

15324720

CERTIFICATION STATEMENT

Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

That each item of information contained in the information disclosure statement was first cited in any communication from a foreign patent office in a counterpart foreign application not more than three months prior to the filing of the information disclosure statement. See 37 CFR 1.97(e)(1).

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See attached certification statement.

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Signature	/Menachem Nathan/	Date (YYYY-MM-DD)	2018-09-23
Name/Print	Menachem Nathan	Registration Number	65392

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- 6. A record in this system of records may be disclosed, as a routine use, to another federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (i.e., GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspections or an issued patent.
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number		15324720	
	Filing Date		2017-01-08	
	First Named Inventor Noy C		Cohen	
	Art Unit			
	Examiner Name			
	Attorney Docket Number		COREPH-0159 US NP	

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	1	9185291	B1	2015-11-10	Shabtay et al.			
	2	7773121	B1	2010-08-10	Huntsberger et al.			
	3	9927600	B2	2018-03-27	Goldenberg et al.			
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	1	20120062780	A1	2012-03-15	Taijiro MORIHISA			
	2	20150162048	A1	2015-06-11	Hirata et al.			
	3	20180241922	A1	2018-08-23	Baldwin et al.			

INFORMATION DISCLOSURE STATEMENT BY APPLICANT **3**)

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Application Number		15324720			
Filing Date		2017-01-08			
First Named Inventor	Noy C	Cohen			
Art Unit					
Examiner Name					
Attorney Docket Number		COREPH-0159 US NP			

	4	20180295292	A1	2018-10-11	Lee et al.	
	5	20110234881	A1	2011-09-29	Wakabayashi et al.	
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	10	20020075258	A1	2002-06-20	Park et al.	
	11	20100283842	A1	2010-11-11	Guissin et al.	
	12	20160070088	A1	2016-03-10	Mutsumi KOGUCHI	
	13	20180120674	A1	2018-05-03	Avivi et al.	
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INFORMATION DISCLOSURE Application Number 15324720 Filing Date 2017-01-08 First Named Inventor Noy Cohen Art Unit Examiner Name Attorney Docket Number COREPH-0159 US NP

Examiner Initial*	Cite No	Foreign Document Number ³	Country Code²i	Kind Code⁴	Publication Date	Name of Patentee or Applicant of cited Document	Pages,Columns,Lines where Relevant Passages or Relevant Figures Appear	T⁵		
	1	1536633	EP	A1	2005-06-01	Sony Corp				
	2	2008076485	ĴΡ	A	2008-04-03	Mitani et al.				
	3	2004133054	JP	A	2004-04-30	Futami et al.				
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INFORMATION DISCLOSURE	First Named Inventor	Noy C	Cohen
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Signature	/Menachem Nathan/	Date (YYYY-MM-DD)	2018-11-25
Name/Print	MENACHEM NATHAN	Registration Number	65392

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PATENT APPLICATION TRANSMITTAL First Named Inventor Noy Cohen (Only for new nonprovisional applications under 37 CFR 1.53(b)) First Named Inventor Noy Cohen (Only for new nonprovisional applications under 37 CFR 1.53(b)) Express Mail Label No. Express Mail Label No. Application ELEMENTS See MPEP chapter 600 concerning utility patent application contents. ADDRESS TO: P.O. Box 1450 Alexandria, VA 22313-14 1. Fee Transmittal Form (PTO/SB/17 or equivalent) Applicant asserts small entity status. See 37 CFR 1.27 Applicant certifies micro entity status. See 37 CFR 1.27 See 37 CFR 1.29. Applicant must attach form PTO/SB/15A or B or equivalent. In. Assignment Papers (cover sheet & document(s)) Name of Assignee 4. Specification [Total Pages In. In. In. In. In. In. In. In. Power of	D SWITCHING / NO ts 50 RS
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Name (Print/Type)MENACHEM NATHANRegistration No. (Attorney/Agent)65,392	

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- 4. A record in this system of records may be disclosed, as a routine use, to a contractor of the Agency having need for the information in order to perform a contract. Recipients of information shall be required to comply with the requirements of the Privacy Act of 1974, as amended, pursuant to 5 U.S.C. 552a(m).
- 5. A record related to an International Application filed under the Patent Cooperation Treaty in this system of records may be disclosed, as a routine use, to the International Bureau of the World Intellectual Property Organization, pursuant to the Patent Cooperation Treaty.
- 6. A record in this system of records may be disclosed, as a routine use, to another federal agency for purposes of National Security review (35 U.S.C. 181) and for review pursuant to the Atomic Energy Act (42 U.S.C. 218(c)).
- 7. A record from this system of records may be disclosed, as a routine use, to the Administrator, General Services, or his/her designee, during an inspection of records conducted by GSA as part of that agency's responsibility to recommend improvements in records management practices and programs, under authority of 44 U.S.C. 2904 and 2906. Such disclosure shall be made in accordance with the GSA regulations governing inspection of records for this purpose, and any other relevant (*i.e.*, GSA or Commerce) directive. Such disclosure shall not be used to make determinations about individuals.
- 8. A record from this system of records may be disclosed, as a routine use, to the public after either publication of the application pursuant to 35 U.S.C. 122(b) or issuance of a patent pursuant to 35 U.S.C. 151. Further, a record may be disclosed, subject to the limitations of 37 CFR 1.14, as a routine use, to the public if the record was filed in an application which became abandoned or in which the proceedings were terminated and which application is referenced by either a published application, an application open to public inspection or an issued patent.
- 9. A record from this system of records may be disclosed, as a routine use, to a Federal, State, or local law enforcement agency, if the USPTO becomes aware of a violation or potential violation of law or regulation.

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(54) Photographing apparatus and method, supervising system, program and recording medium

(57) The motion of a moving subject is captured at a short time interval up to a wide area by tracking and photographing the moving subject. A wide angle area is photographed by a first camera, an area narrower than the wide angle area is photographed by a second camera, the presence or absence of the motion in an image is detected by a motion detecting section by comparing the first image with the second image in terms of the difference of luminance levels. The correlation of the positions of the first image and the second image is recorded by a memory, and the photographing direction of the second camera is controlled by a controller by using the correlation information when the presence of the motion is detected by the motion detecting section.



FIG. 1

Description

BACKGROUND OF THE INVENTION

5 1. Field of the Invention

[0001] The present invention relates to a photographing apparatus and method, a supervising system, a program and a recording medium which supervise a state of a wide range through a panoramic image obtained by photographing by sequentially altering a photographing direction.

10 [0002] This application claims priority of Japanese Patent Application No. 2003-398152, filed on November 27, 2003 and Japanese Patent Application No. 2004-266014, filed on September 13, 2004, the entireties of which are incorporated by reference herein.

2. Description of Related Art

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[0003] An electronic still camera which has been, heretofore, widely used, converts a light passed through a lens by photographing a subject into an image signal through a solid state imaging element, such as a CCD (Charge Coupled Device) and the like, records the image signal in a recording medium and can reproduce the recorded image signal. Most of electronic still cameras each has a monitor which can display the photographed still image, and can selectively display the photographed still image.

- 20 display the specific one of the still images recorded so far. In this electronic still camera, the image signal supplied to the monitor corresponds to the subject on each screen. Therefore, the simultaneously displayed images become a narrow range, and the electronic still camera cannot simultaneously supervise the state of a wide range.
 [0004] Therefore, a supervisory camera which can supervise the states of a wide range by obtaining the whole
- panoramic image formed of a plurality of unit images by photographing a subject while sequentially shifting the pho tographing direction of the camera prevails. Particularly, in recent years, a technique for contracting and synthesizing a plurality of image signals to an image signal of one frame has been proposed (for example, refer to Patent Document No. 1 of Japanese Patent Application Laid-Open Publication No. 10-108163). Also, a centralized supervisory recording system which can realize a supervision by gathering supervisory images from a plurality of supervisory video cameras installed and recording the images in a recording medium, such as a video tape and the like has been proposed (for
- 30 example, refer to Patent Document No. 2 of Japanese Patent Application Laid-Open Publication No. 2000-243062).
 [0005] When a photographing range as shown in FIG. 1 is, for example, photographed at a predetermined photographing angle of view by a conventional supervisory camera, it is necessary to photograph a subject by sequentially shifting the photographing direction in a horizontal or vertical direction. If the size of the photographing range can be expressed by (s × t) times as large as the size of a frame (hereinafter referred to as a "unit image") obtained by
- photographing the size of the photographing range at the above-mentioned photographing angle of view, it is necessary to set at least (s × t) ways of the photographing directions.
 [0006] Actually, the photographing direction of the supervisory camera is first matched to the coordinates (1, 1) disposed at an upper left side, and the photographing is executed. Then, the photographing direction of this supervisory camera is sequentially altered to the coordinates (2, 1), (3, 1), (4, 1),..., (s, 1) in the horizontal direction and the photographing
- tographing is executed. After the photographing of a first row is finished, the photographing direction is regulated to the coordinates (1, 2) of a second row, and the photographing is executed. Thereafter, the photographing is executed while sequentially shifting the photographing direction in the horizontal direction. Such an operation is repeated, the photographing is executed to the coordinates (s, t). Thereafter, the unit images of the (s \times t) pieces are laminated, and the whole image expressing the entire photographing range can be synthesized.
- ⁴⁵ [0007] However, the supervisory camera as the conventional art needs to photograph all of the (s × t) pieces of the unit images constructing the whole image of one sheet to generate the whole image. Particularly, there is a problem that even small state change occurring in a short time in the photographing range cannot be captured without exception.
 [0008] FIG. 2 shows the state that, as time is elapsed from time t1 to time t4, a moving subject (bird) having a fast moving speed gradually goes away from a building. When the unit images of the (s × t) pieces for constructing the
- ⁵⁰ whole image at the time t1 shown in FIG. 2 are photographed, since the moving subject including the unit images for constituting the building, clouds or the like in which the moving subject does not exist need to be sequentially photographed, a long time is required.

[0009] As a result, when the whole image is photographed at next timing, the time might already reach the time t4. Thus, the states of the moving subject at the times t2 and t3 cannot be captured as the image data, and hence there is a problem that a practical effect of supervising via the supervisory camera cannot be planned.

[0010] Further, if this moving subject is deviated from the photographing range, there also is a problem that photographing of the subject by capturing the subject at any time cannot be continued.

SUMMARY OF THE INVENTION

[0011] Accordingly, the present invention has been made in view of the above-mentioned problems and has an object of providing photographing apparatus and method, supervising system, a program and a recording medium which can

- ⁵ capture the motion of a moving subject at a short time interval up to a wide area by tracking and photographing the moving subject in the photographing apparatus and method, the supervising system, the program and the recording medium which photograph the respective unit images constructing the whole image expressing the entire photographing range to supervise the state of a wide photographing range.
- [0012] In order to solve the above-mentioned problems, a wide angle area is photographed by a first camera, an area narrower than the wide angle area in a direction corresponding to the designated photographing direction is photographed by a second camera, the presence or absence of the motion in the image is detected by a motion detecting section by comparing a first image generated by the first camera with the previous image photographed previously from the first image in terms of the difference of a luminance level, correlation information showing the correlation of the positions of the first image and a second image obtained by the second camera is previously recorded
- ¹⁵ by a memory, and the photographing direction of the second camera at the motion detected position by using the correlation information when the presence of the motion is detected by the motion detecting section is controlled by a controller.

[0013] That is, the photographing apparatus according to the present invention comprises: a first camera for photographing a wide angle area; a second camera for photographing an area narrower than the wide angle area in a

- 20 direction corresponding to the designated photographing direction; a motion detecting section for detecting the presence or absence of a motion in the image by comparing a first image generated by the first camera with the previous image photographed previously from the first image in terms of the difference of a luminance level; a memory for previously recording correlation information showing the correlation of the positions of the first image and a second image obtained by the second camera, and a controller for controlling the photographing direction of the second camera
- at the motion detected position by using the correlation information when the presence of the motion is detected by the motion detecting section.
 [0014] The photographing apparatus according to the present invention comprises: a first camera for photographing

a wide angle area; a second camera for photographing an area narrower than the wide angle area in a direction corresponding to the designated photographing direction; a motion detecting section for detecting the presence or absence of a motion at each unit image by comparing a first unit image constructing a first wide angle image generated

30 absence of a motion at each unit image by comparing a first unit image constructing a first wide angle image generated by the first camera with the unit image in the same photographing direction photographed previously from the first unit image in terms of the difference of a luminance level; a recording section previously recording correlation information showing correlation of the respective image positions between the first unit image and the second unit image obtained by the second camera; and a controller for controlling the photographing direction of the second camera at the motion

detected position by using the correlation information when the presence of the motion is detected by the motion detection section.

[0015] The photographing method according to the invention comprises: a step of photographing a first image of a wide angle area by a first camera; a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image

- 40 by comparing the first image with the previous image photographed previously from the first image in terms of a luminance level; controlling the photographing direction of the second camera at the motion detected position when the presence of the motion is detected by the motion detecting section by using the correlation information showing the correlation of the positions of the images of the first image and the second image obtained by the second camera. [0016] The photographing method according to the present invention comprises: a step of photographing a first wide
- 45 angle image of a wide angle area by a first camera; a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image at each unit image by comparing a first unit image constructing the first wide angle image with a unit image in the same photographing direction previously photographed from the unit image in terms of the difference of a luminance level; controlling the photographing direction of the second camera at the motion detected position
- ⁵⁰ when the presence of the motion is detected by the motion detecting section by using the correlation information showing the correlation of the positions of the images of the first unit image and a second unit image obtained by the second camera.

[0017] A supervising system according to the invention comprises: a first camera for photographing a wide angle area; a second camera for photographing an area narrower than the wide angle area in a direction corresponding to

55 the designated photographing direction; a motion detecting section for detecting the presence or absence of a motion at each unit image by comparing a first unit image constructing a first wide angle image generated by the first camera with the unit image in the same photographing direction photographed previously from the first unit image in terms of the difference of a luminance level; a recording section previously recording correlation information showing correlation

of the respective image positions between the first unit image and a second unit image obtained by the second camera; and a controller for controlling the photographing direction of the second camera at the motion detected position by using the correlation information when the presence of the motion is detected by the motion detecting section. **[0018]** A program according to the present invention causes a computer to execute: a step of photographing a first

- 5 image of a wide angle area by a first camera; a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image by comparing the first image with the previous image photographed previously from the first image in terms of a luminance level; controlling the photographing direction of the second camera at the motion detected position when the presence of the motion is detected by the motion detecting section by using the correlation information
- 10 showing the correlation of the positions of the images of the first image and the second image obtained by the second camera.

BRIEF DESCRIPTION OF THE DRAWINGS

15 **[0019]**

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- FIG. 1 is a view for explaining an example of a unit image constructing a whole panoramic image;
- FIG. 2 is a view for explaining the problems of a conventional art;
- FIG. 3 is a view showing a supervising system applied by the present invention;
- ²⁰ FIG. 4 is a block diagram of cameras and a supervising unit;
 - FIG. 5 is a view for explaining a detailed structure of a whole image forming section;
 - FIG. 6 is a view for explaining the case that a photographing range shown by a rectangular frame is photographed by a camera unit at a photographing angle of view u;
 - FIG. 7 is a view showing the structural example of a display screen on a display;
- 25 FIG. 8 is a view showing a normal photographing mode and a tracking and photographing mode in a time series manner;
 - FIG. 9 is a view for explaining the normal photographing mode and the tracking and photographing mode in further detail;
 - FIG. 10 is a flowchart for explaining the sequence of obtaining a tracking photographing position by a tracking position calculating section;
 - FIG. 11 is a view for explaining setting of a supervising frame when a parking place is supervised;
 - FIG. 12 is a flowchart for explaining a photographing sequence by an entire photographing camera;
 - FIG. 13 is a flowchart for explaining an operating sequence of a difference sensing section;
 - FIG. 14 is a view for explaining the case that relative positions in a supervising area defined by points A to D of an image position E are identified;
 - FIG. 15 is a flowchart showing the photographing operation sequence of the tracking photographing section to which a tracking image position E' is notified;
 - FIG. 16 is a view for explaining an application example of a supervising system to which the present invention is applied;
- FIG. 17 is a view showing another structure of a supervising system to which the present invention is applied; FIG. 18 is a view showing still another structure of the supervising system to which the present invention is applied; FIG. 19 is a view showing a structure of a supervising system in which a fixed camera is used for the entire photographing camera;
- FIG. 20A is a front view showing a disposition example of the fixed camera and the tracking photographing camera
 in the above-mentioned supervising system, and FIG. 20B is a side view thereof;
 - FIG. 21 is a view showing an image of all directions of 360° acquired in real time by the fixed camera in the abovementioned supervising system;
 - FIG. 22 is a view showing a panoramic image formed by laminating images obtained by the tracking photographing camera in the above-mentioned supervising system;
- ⁵⁰ FIG. 23 is a view showing an image space in the above-mentioned supervising system;
 - FIG. 24 is a view showing four points A, B, C and D on the image of all directions of 360° initially set in the supervising unit in the above-mentioned supervising system;
 - FIG. 25 is a view showing four points A', B', C' and D' of the panoramic image initially set in the supervising unit in the above-mentioned supervising system;
- ⁵⁵ FIG. 26 is a flowchart showing the operation of the supervising unit in the above-mentioned supervising system; and FIG. 27 is a sectional view of a visual angle in a vertical direction of the entire photographing camera and the tracking photographing camera in the above-mentioned supervising system.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

[0020] Now, preferred embodiment the present invention will be described in greater detail by referring to the accompanying drawings. The supervising system 1 to which the present invention is applied comprises: as shown, for

- 5 example, in FIG. 3, an entire photographing camera 2 for generating an image signal by photographing a subject and a tracking and photographing camera 5, a network 8 connected to these cameras 2, 5, and a supervising unit 15 for controlling the entire photographing camera 2 and the tracking and photographing camera 5 through the connected network 8 or acquiring the image signals from the cameras 2 and 5.
- [0021] The entire photographing camera 2 includes a pan tilter section 3 and a camera section 4 integrally constructed. The pan tilter section 3 is constructed as a rotating pedestal for freely altering the photographing direction at two axes of, for example, a pan and a tilt. The camera section 4 is arranged on the rotating pedestal constructing the pan tilter section 3 to photograph a subject while regulating the photographing direction in a horizontal or vertical direction under the control of the supervising unit 15. This camera section 4 sequentially alters the photographing angle of view in response to the control by the supervising unit 15, thereby enlarging or contracting a photographing magnification to photograph the subject.
- [0022] This entire photographing camera 2 sequentially matches the photographing direction to the respective unit images constructing the panoramic image expressing the entire photographing range to execute the photographing, as shown in FIG. 3. Such unit images are transmitted as an image signal to the supervising unit 15 side through the network 8, and can thereby synthesize the whole image expressing the photographing range entirety by laminating the unit images.

[0023] The tracking and photographing camera 5 includes a pan tilter section 6, and a camera section 7 integrally constructed. Since the structures of the pan tilter section 6 and the camera section 7 are the same as the pan tilter section 3 and the camera section 4 in the entire photographing camera 2, the detailed description thereof will be omitted. [0024] The supervising unit 15 is constructed of a personal computer (PC) and the like, and records the image signal

- 25 transmitted from the entire photographing camera 2 through the network 8 in recording media, and displays the respective images based on the image signal recorded in the recording media for a user. The supervising unit 15 also judges the presence or absence of a motion by identifying a luminance component for the image signal transmitted from the entire photographing camera 2, and controls to switch a photographing mode in the entire photographing camera 2 in response to the judged result. Further, this supervising unit 15 serves as a so-called central control unit
- 30 for controlling the network 8 entirety, and transmits an image and a voice in response to a request from another terminal unit (not shown).

[0025] The network 8 is a communication network which can transmit and receive information interactively, for example, like an internet network connected to the supervising unit 15 through a telephone channel, an ISDN (Integrated Services Digital Network)/B (broadband)-ISDN and the like connected to TA/modem. Incidentally, when this supervising

- 35 system 1 is used in a predetermined narrow area, this network 8 may be constructed of a LAN (Local Area Network), or may be connected through an IEEE1394 interface and the like. Further, this network 8 may transmit even a moving image in addition to a still image. In such a case, a moving image, such as, for example, an MPEG (Moving Picture Experts Group) data is transmitted continuously from certain one channel based on an internet protocol (IP), and still image data is transmitted from another channel at regular time intervals. Note that, a network server (not shown) may
- be further connected to this network 8. This network server (not shown) manages, for example, internet information, receives request by a terminal unit, and transmits a predetermined information stored in itself.
 [0026] Subsequently, the constructions of the entire photographing camera 2, the tracking and photographing camera 5, and the supervising unit 15 in the supervising system 1 to which the present invention is applied will be described in detail.
- ⁴⁵ **[0027]** FIG. 4 is a structural view of the entire photographing camera 2, the tracking and photographing camera 5 and the supervising unit 15. In FIG. 4, the pan tilter section 3 constructing the entire photographing camera 2 includes a tilt section for controlling the rotating pedestal for altering the photographing direction and the pan section. The information regarding the position and the angle of the camera section 4 is transmitted by the connected azimuth sensor 25 to the pan tilter section 3. The camera section 4 constructing the entire photographing camera 2 includes a lens
- control section 23 for mainly altering the angle of view of the lens section 22, and an imaging section 24 arranged at a position perpendicular to the optical axis of the lens section 22.
 [0028] Similarly, the pan tilter section 6 constructing the tracking and photographing camera 5 includes a tilt section for controlling the rotating pedestal for altering the photographing direction and a pan section. The information regarding the position and the angle of the camera section 52 is transmitted by the connected azimuth sensor 55 to this pan tilter
- 55 section 6. The camera section 7 constructing the entire photographing camera 2 includes a lens control section 53 for mainly altering the angle of view of the lens section 52, and an imaging section 54 arranged at the position perpendicular to the optical axis of the lens section 52.

[0029] The supervising unit 15 includes a whole image forming section 31 for forming the whole panorama-like image

(panoramic image) based on the image signal transmitted from the entire photographing camera 2 through the network 8, a difference sensing section 32 for detecting the motion of the whole image formed in the whole image forming section 31, a tracking and photographing control section 33 connected to the tracking and photographing camera 5 through the network 8 for controlling the tracking and photographing camera 5, a tracking position calculating section

- 5 34 for obtaining a tracking image position in response to the image position judged that the motion exists in the difference sensing section 32, a panorama setting database (DB) 35 connected to at least the whole image forming section 31 and the tracking position calculating section 34 for recording a correlation information showing a correlation at respective image positions among unit images obtained from the entire photographing camera 2 and the tracking and photographing camera 5, a correlation information forming section 36 for forming the above-mentioned correlation infor-
- 10 mation, a tracking and photographing conditions setting section 38 for setting conditions for tracking and photographing (hereinafter, referred to as "tracking and photographing conditions"), and a tracking and photographing conditions DB 39 for recording the tracking and photographing conditions set in the above-mentioned tracking and photographing conditions setting section 38.
- [0030] The pan tilter section 3 rotates a stepping motor constructed as a drive source of the rotating pedestal based on a drive signal from the whole image forming section 31. Since the rotating pedestal itself can be turned in a horizontal direction or a vertical direction in this manner, the photographing direction of the camera section 4 placed on the rotating pedestal can be turned in the horizontal direction or the vertical direction.

[0031] The lens control section 23 executes an automatic diaphragm control operation and an automatic focusing control operation for the lens section 22 based on the drive signal from the whole image forming section 31. This lens
 control section 23 alters the photographing angle of view to the subject based on such a drive signal. Thus, the camera section 4 sequentially regulates a photographing magnification to thereby photographing the subject.

[0032] The imaging section 24 includes a solid state imaging element, such as, a CCD (Charge Coupled Device) and the like, focuses a subject image incident through the lens section 22 on an imaging surface, and generates an image signal by a photoelectric conversion. The imaging section 24 transmits the generated image signal to the whole image forming section 31.

[0033] The pan tilter section 6 rotates a stepping motor constructed as a drive source of the rotating pedestal based on the drive signal from the tracking and photographing control section 33. Thus, the photographing direction of the camera section 7 placed on the rotating pedestal can be turned in the horizontal direction or the vertical direction. [0034] The lens control section 53 executes an automatic diaphragm control operation and an automatic focusing

- control operation for the lens section 52 based on the drive signal from the tracking and photographing control section 33. This lens control section 53 alters the photographing angle of view to the subject based on such a drive signal. Thus, the camera section 4 sequentially regulates a photographing magnification to thereby photographing the subject.
 [0035] The imaging section 54 includes, for example, a solid state imaging element, such as, a CCD (Charge Coupled Device) and the like, focuses a subject image incident through the lens section 52 on an imaging surface, and generates
- an image signal by a photoelectric conversion. The imaging section 54 transmits the generated image signal to the tracking and photographing control section 33.

[0036] The whole image forming section 31 executes predetermined control through the network 8 so that the photographing direction can be gradually altered at the imaging time by the entire photographing camera 2 to realize photographing of a wide range. This whole image forming section 31 creates the whole panorama-like image of one

40 sheet by laminating the unit images photographed by the entire photographing camera 2. The whole image forming section 31 records the formed whole image, and reads the image in response to the request of the difference sensing section 32.

[0037] The difference sensing section 32 detects the motion of the whole image formed in the whole image forming section 31. The difference sensing section 32 notifies the detected result of the motion to the tracking position calculating section 34 and the tracking and photographing control section 33. Incidentally, the difference sensing section 32 may

section 34 and the tracking and photographing control section 33. Incidentally, the difference sensing section 32 may inquire this motion detecting conditions to the tracking and photographing conditions DB 39.
 [0038] The tracking and photographing control section 33 controls the photographing direction, the photographing

angle of view and the like of the tracking and photographing camera 5 through the network 8 based on the motion detected result and the like notified from the difference sensing section 32. The tracking and photographing control section 33 acquires the unit image photographed by the tracking and photographing camera 5 through the network 8.
 [0039] The panorama setting section 36 includes a keyboard, a mouse and the like for a user to input desired infor-

mation to form the above-mentioned correlation information.

[0040] The tracking and photographing conditions setting section 38 includes a keyboard, a mouse and the like for setting the conditions of the motion detection to be stored in the tracking and photographing conditions DB 39.

- ⁵⁵ [0041] Next, the detailed structure of the whole image forming section 31 will be described.
 - **[0042]** The whole image forming section 31 includes, as shown in FIG. 5, an A/D conversion section 61 connected to the entire photographing camera 2 through the network 8, an encoder 63 connected to this A/D conversion section 61, a recording media 66 for storing the image outputted from the encoder 63, a decoder 67 for expanding the image
read from the recording media 66, a monitor image processing section 68 connected to the A/D conversion section 61 and the decoder 67 for forming the image to be displayed for a user, a memory 69 for temporarily storing the image supplied from the connected monitor image processing section 68, a D/A conversion section 74 for converting the signal inputted from the connected monitor image processing section 68 into an analog signal, and a control section 70 for controlling respective constituting elements.

- ⁵ 70 for controlling respective constituting elements. [0043] Incidentally, a monitor 75 including a liquid crystal display screen and the like and displaying predetermined information for a user is connected to the D/A conversion section 74. An operating section 76 for designating a desired image area and an image position by a user from the image displayed on the monitor 75 is connected to the control section 70.
- 10 **[0044]** The A/D conversion section 61 digitizes the image signal transmitted from the entire photographing camera 2, and transmits the digitized image signal to the encoder 63, the difference sensing section 32, and the monitor image processing section 68.

[0045] The encoder 63 performs compression and coding based on the standards, such as, JPEG (Joint Photographic Experts Group) and the like. Incidentally, this encoder 63 may add position information or meta data to the

¹⁵ image signal to be compressed and coded. The encoder 63 outputs the compressed and coded image signal to the recording media 66. Incidentally, when the supplied image signal is not subjected to compressing and coding, the process in the encoder 63 is omitted.

[0046] The recording media 66 is applied, for example, as a hard disc, a detachable disc-like recording medium and the like, the image signal outputted from the encoder 63 is sequentially recorded in association with position information

- or meta data. The image signal recorded in the recording media 66 is read based on the control by the control section 70 and is transmitted to the decoder 67. Incidentally, the image signal recorded in a memory card can be transferred to the other PC by controlling to record the image signal recorded in the recording media 66 into a memory card (not shown). The recording media 66 can be replaced with a network server (not shown) by controlling to record the image signal recorded network server (not shown).
- [0047] The decoder 67 expands the image signal of the JPEG format read from the recording media 66, and transmits the image signal to the monitor image processing section 68.
 [0048] The monitor image processing section 68 executes picture processing to the monitor 75 based on the image signal transmitted from the A/D conversion section 61 or the decoder 67 under the control of the control section 70. The monitor image processing section 68 executes the control of a contrast, a luminance in the monitor 75 based on
- 30 the control by the control section 70. This monitor image processing section 68 executes thinning process of pixels for displaying a plurality of images on a liquid crystal display screen in the monitor 75 simultaneously by cooperating with the memory 69.

[0049] The control section 70 transmits a drive signal for driving the pan tilter section 3 and the lens control section 23, and a control signal for controlling the respective units in the supervising unit 15 when the image area and the image position are designated by a user through the operating section 76. This control section 70 receives a request from other terminal unit through the network 8, selects optimum still image, moving image or various information recorded in the recording media 66, and controls to transmit the image or the information to the terminal unit.

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[0050] The monitor 75 includes, for example, a liquid crystal display element, a back light and the like (not shown), and is an interface for visually recognizing the image photographed by the user. The liquid crystal display element is irradiated with an illumination light by the above-mentioned back light from the back surface of the liquid crystal display

element, and the visibility of the monitor 75 can be entirety improved. **[0051]** The operating section 76 includes a keyboard, a mouse and the like for a user to designate a desired image area and an image position from the image displayed on the monitor 75. Incidentally, the operating section 76 may take the structures of the panorama setting section 36 and/or the tracking and photographing conditions setting section

- 38, as a result, the section 36 and/or section 37 may be, as a matter of course, omitted.
 [0052] Then, the operation until the whole image is formed by this whole image forming section 31 will be described.
 [0053] FIG. 6 shows the case that a photographing range shown by a rectangular frame is photographed by a photographing angle of view u by the entire photographing camera 2. To photograph all the photographing range by the photographing angle of view u, it is necessary to sequentially shift the photographing direction in a horizontal direction
- ⁵⁰ or a vertical direction. If the size of the photographing range is expressed by $(i \times j)$ times as large as the sizes of the frame (hereinafter referred to as a "unit image") obtained by photographing the size of the photographing range at an arbitrary photographing angle of view u, it is necessary to set the photographing directions of at least the $(i \times j)$ ways. The whole image expressing the entire photographing range can be synthesized by laminating the $(i \times j)$ pieces of the unit images photographed at this photographing angle of view u.
- ⁵⁵ **[0054]** Here, when the coordinates (M, N) of the respective unit images of the photographing range are sequentially indicated from a left end in the horizontal direction by 1, 2,..., M,..., i, and from an upper end in the vertical direction by 1, 2,..., N,..., j, the control section 70 transmits a predetermined drive signal to the pan tilter section 3. Thereby, the photographing direction of the camera section 4 is first matched to the coordinates (1, 1) disposed at an upper left

side, and the camera section 4 executes imaging. The image signal based on the unit images generated by imaging this coordinates (1, 1) is A/D converted by the A/D conversion section 61, and then stored in the memory 69 through the monitor image processing section 68. The image signal is compression coded based on the JPEG standards in the encoder 62, meta data and the like are simultaneously added, and sequentially recorded in the recording media 66.

- 5 [0055] Similarly, the control section 70 transmits the drive signal to the pan tilter section 3, thereby shifts the photographing direction of the camera section 4 to a right side by one image frame, and executes photographing by matching to the coordinates (2, 1). The image signal generated by photographing this coordinates (2, 1) is similarly recorded in the recording media 66. The camera section 4 sequentially alters the photographing direction to the coordinates (3, 1), (4, 1),.., (i, 1) in the horizontal direction based on the control by the control section 70, and executes photographing.
- **[0056]** After the camera section 4 finishes the photographing of a first row, the camera section 4 executes photographing by regulating the photographing direction to the coordinates (1, 2) of a second row, thereafter executes photographing while sequentially shifting the photographing direction in the horizontal direction based on the control by the control section 70. When such an operation is repeated and the photographing is finished to the coordinates (i, j), the memory 69 and the recording media 66 become the state that the image signals based on the $(i \times j)$ pieces of the
- ¹⁵ unit images photographed at the respective coordinates are recorded. Incidentally, after the photographing to the coordinates (i, j) is finished, the control section 70 transmits the drive signal to the pan tilter section 3, and thereby executes the photographing at next timing by matching the photographing direction of the camera section 4 to the coordinates (1, 1) disposed again at the upper left side.
- [0057] It should be noted that the sequence of photographing the unit images is not limited to the above-mentioned example. For example, after the photographing of the first row is finished, the photographing direction is regulated to the coordinates (i, 2) of a second row based on the control by the control section 70, the photographing is executed, and, thereafter, the photographing direction may be shifted toward the coordinates (1, 2).

[0058] The image signals based on the respective unit images recorded in the memory 69 are sequentially read by the monitor image processing section 68, and reduced to be matched to the size of the display screen in the monitor 75. This reduced respective unit images are displayed on the monitor 75 through the D/A conversion section 74. All the unit images of the (i × j) pieces recorded in the memory 69 are displayed on the monitor 75, and thereby one

- panorama-like image is synthesized. The above-mentioned photographing operation is executed at a predetermined interval, and thereby the whole image showing the latest state of the photographing range can be acquired.
 [0059] Further, when the unit images recorded in the recording media 66 before are to be displayed on the monitor
 75 is designated by the control section 70, the image signals based on the unit images from the recording media 66
- are sequentially read, enlarged by the decoder 67, and transmitted to the monitor image processing section 68. The image signal is reduced to be matched to the size of the display screen as described above in the monitor image processing section 68, synthesized to the whole panorama-like image, and displayed.
 [0060] FIG. 7 shows an example of displaying the whole image synthesized by laminating the photographed unit
- images of the (i \times j) pieces on the entire image display section 170 of the monitor 75. Incidentally, this supervising unit 15 may display a boundary between the respective unit images for constructing the whole image on the entire image display section 170, or may display only a seamless entire image. The supervising unit 15 may cause to display the whole image of one sheet photographed at the photographing angle of view, the entire photographing range of which can be captured instead of the whole panorama-like image on this entire image display section 170.
- 40 [0061] Incidentally, an enlarged image display section 171 for displaying the enlarged image obtained by enlarging the unit image is further provided in the display screen 45. This enlarged image display section 171 may enlarge and display one unit image designated by the user of the unit images constructing the whole image displayed on the whole image display section 170. Or, moving images may be sequentially displayed with respect to the photographing direction of such a unit image. Thus, the user can confirm the state of the photographing direction of the designated unit image 45 in real time.
 - **[0062]** On the display screen 45, a WIDE button 172 for displaying the unit image displayed on the enlarged image display section 171 by reducing the photographing magnification, and a ZOOM button 173 for enlarging the photographing magnification and displaying the image are displayed. On this display screen 45, a photographing direction control section 175 for regulating the photographing direction of the camera section 4 in horizontal direction and vertical
- ⁵⁰ direction, and a set button 176 or the like for recording the image signal based on the unit image on a desired address in case of setting various modes or a server, is displayed.
 [0063] The user can designate a desired image area, an image position to the entire image display section 170 and the enlarged image display section 171 through the operating section 176. It should be noted that an aiming line or a pointer for executing the above-mentioned designating operation may further be displayed by cooperating with the
- ⁵⁵ motion of a mouse or the like in the operating section 176 on the respective display sections 170, 171. [0064] In the supervising system 1 to which the present invention is applied, in addition to the normal photographing mode for synthesizing the whole image displaying the whole photographing range by laminating the unit images of (i × j) pieces photographed by the entire photographing camera 2 as described above, a tracking and photographing

mode for capturing the desired moving subject and continuously photographing the moving subject at any time by the tracking and photographing camera 5 is incorporated. In this tracking and photographing mode, the whole image is generated at a short time interval. Thus, the motion of the moving subject such as a bird displayed on the entire image display section 170 in FIG. 7 is captured as an image signal without leakage.

- ⁵ **[0065]** FIG. 8 shows a normal photographing mode and a tracking and photographing mode in time series. Since the photographing direction is sequentially matched to all the unit images for constructing the whole image and photographing is executed in the normal photographing mode, it takes a long time until one whole image is synthesized. As a result, the number of the whole images which can be generated at a unit time (hereinafter referred to as a "refresh rate") is reduced.
- 10 [0066] On the other hand, in the tracking and photographing mode, since it is sufficient to photograph only one or more unit images including the tracking image position by capturing the moving subject, the photographing can be finished in a short time as compared with the normal photographing mode, and the refresh rate can be raised.
 [0067] In the supervising system 1 to which the present invention is applied, when the photographing operation of
- the subject is started, photographing by the normal photographing mode is first executed. In this case, the difference sensing section 32 judges, as shown in FIG. 8, the presence or absence of the motion between the photographed unit image and the unit images in the same photographing direction constructing the previous whole image. As a result, if the unit image judged that there is the motion is exist by the difference sensing section 32, the fact is notified to the tracking position calculating section 34 and the tracking photographing control section 33 as the suggestion of the presence of the moving subject, and the tracking and photographing mode is initiated.
- 20 [0068] Incidentally, in this tracking and photographing mode, the tracking image position in the unit image al judged that there is a motion by the difference sensing section 32, a unit image b1 is generated by tracking photographing by the tracking and photographing camera 5. In such a case, since there is the case that an installing environment, a photographing direction and the like are different from each other between the entire photographing camera 2 and the tracking and photographing camera 5, and, therefore, the photographing directions between the cameras 2 and 5 are
- 25 matched by referring to the correlation information recorded in the panorama setting DB 35 in the tracking position calculating section 34. In fact, this tracking position calculating section 34 matches the photographing directions between the cameras 2 and 5 through the calculated tracking image positions. Thus, the tracking and photographing camera 5 is scanned by the pan tilting in the photographing direction designated from the tracking position calculating section 34 through the tracking photographing control section 33. Thereby, the acquired unit image 1b can be matched
- to the unit image al. The detailed procedure for matching the photographing directions of the cameras 2 and 5 through the tracking image positions will be described later.
 [0069] Incidentally, the difference sensing section 32 may use not only the whole image photographed at the previous timing as the previous whole image to be compared with newly photographed unit image with respect to a luminance
- level, but also the whole image stored in advance. In such a case, the use of any whole image is previously set under
 any conditions by the tracking and photographing condition setting section 39, and this may be recorded in the tracking and photographing condition DB.

[0070] When the tracking and photographing mode is started, photographing is executed by two cameras in parallel with the normal photographing mode. For example, as shown in FIG. 9, as time is elapsed from time t1 to t4, in the case that the moving subject (bird) having a fast moving speed is gradually separated from a building, since it is

necessary to sequentially photograph including the unit images for constructing the building, clouds and the like where the moving subject does not exist, it requires a long time, in the normal photographing mode, when the unit images of (s × t) pieces constructing the whole image is photographed at the time t1.
 [0071] As a result, in this normal photographing mode, there might be the case that the time already reaches t4 when

[0071] As a result, in this normal photographing mode, there might be the case that the time already reaches t4 when the whole image is photographed at next timing, and, therefore, the state of the moving subject at times t2, t3 cannot be captured as image data.

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[0072] On the contrary, in the tracking and photographing mode, since only the unit images including the moving subject may be sequentially photographed, the state of the moving subject at the times t2, t3 are sequentially imaged, and can be stored. Even when this moving subject is deviated from the photographing range, this subject can be captured at any time by the tracking and photographing camera 5, and can be continuously photographed. As a result,

⁵⁰ in the tracking and photographing mode, as shown in FIG. 9, the unit images photographed only in the area in the frame at the times t1 to t4 can be obtained, and the slight state change occurring for a short time can be captured without exception.

[0073] Then, the procedure for obtaining the tracking image position by the tracking position calculating section 34 will be further described in detail.

⁵⁵ **[0074]** First, in step S11 shown in FIG. 10, the unit image is photographed by the entire photographing camera 2 and the tracking and photographing camera 5 while the photographing direction is turning at 340° in a tilt direction. The unit images photographed by the respective cameras 2 and 5 are transmitted to the whole image forming section 31, and are recorded in the recording media 66. It is noted that the turning angle is not limited to 340°, but may be any

angle.

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[0075] Then, the operation is transferred to step S 12, the unit images photographed by turning the cameras 2 and 5 at 340° in step S11 are laminated to form the whole image. The formed respective whole images are displayed on the monitor 75.

⁵ **[0076]** Then, the operation is transferred to step S13, a user specifies a desired area to be supervised from the whole image displayed on the monitor 75 in step S12. In such a case, the user designates the area desired to be supervised by the operating section 76 from the whole image displayed on the monitor 75.

[0077] FIG. 11A shows the part of the whole image from the unit image photographed by the entire photographing camera 2 when a parking lot is supervised. FIG. 11B shows the part of whole image photographed by the tracking and

- 10 photographing camera 5 installed at a different position. In step S12, the user sets the area desired to be supervised for the whole image shown in FIG. 11A, for example, in a frame for connecting points A to D (hereinafter referred to as a supervising "frame"). This supervising frame becomes the above-mentioned photographing range. Similarly, in this step S12, the user sets points A' to D' so that the objects to be photographed correspond to the above-mentioned A to D for the whole image shown in FIG. 11B. These sets are called supervising frame sets.
- ¹⁵ **[0078]** Incidentally, the supervising frame set of the points A to D and the points A' to D' may be set manually via the operating section 76. Alternatively, it may be automatically performed based on, for example, luminance information and the like.

[0079] Then, the operation is transferred to step S13, the points A to D set at the supervising frame in step S12 and the points A' to D' are finely regulated to show the same image position. In such a case, the names, the coordinates,

- 20 setting names and the like of the respective set points are finely regulated to coincide between the points A to D and A' to D'. This fine regulations may be corresponded between the points A to D and the points A' to D'. Thus, not only the set points A to D and the points A' to D', but also between the image positions in the supervising frame, can be corresponded to each other. Since the image positions are corresponded to each other, a relative movement in the other image position can be identified in response to the movement of one image position.
- [0080] Then, the operation is transferred to step S14, and all the supervising frame sets are stored in the panorama setting DB35. That is, in this step S14, the correspondence between the set points A to D and the set points A' to D' is stored in the panorama setting DB 35 as the above-mentioned correlation information.
 [0081] Incidentally, the entire photographing camera 2 and the tracking and photographing camera 5 are superposed

on each other, and are arranged on substantially the same position, and, therefore, processes in the above-mentioned steps S11 to S14 can be processed.

[0082] According to the present invention, the processes to the above-mentioned steps S11 to S14 are executed before the actual supervising. In the actual photographing, the operation is executed based on the procedure shown in FIG. 12.

[0083] First, in step S21, the whole image forming section 31 reads the supervising frame set recorded in the panorama setting DB35, and identifies the photographing range.

- **[0084]** Then, the operation is transferred to step S22. This whole image forming section 31 generates a drive signal for controlling the pan tilter section 3 based on the identified photographing range. This drive signal is transmitted to the pan tilter section 3, and thereby sequentially shifting the photographing range in the horizontal direction or the vertical direction in the identified photographing range to perform photographing.
- 40 **[0085]** Then, the operation is transferred to step S23, whether the photographing of all the unit images in the photographing range (supervising frame) is finished or not is judged. As a result, all the unit images are not yet finished to be photographed is judged, the photographing is continued, while if the finish is judged, the operation is transferred to step S24.

[0086] If the operation is transferred to step S24, the unit images are laminated to form the whole image. Then, the generated whole image is reformed, and may be displayed on the monitor 75.

[0087] Then, the operation is transferred to step S25, and the whole image forming section 31 notifies the effect of generating new whole image to the difference sensing section 32.

[0088] FIG. 13 shows the operating sequence of the difference sensing section 32 which receives such a notification.

[0089] First, in step S31, the difference sensing section 32 accesses to the tracking and photographing condition
 DB39, and thereby acquiring the tracking and photographing condition recorded in the tracking and photographing condition DB39.

[0090] Then, the operation is transferred to step S32, the difference sensing section 32 detects the motion based on the acquired tracking and photographing condition. The motion detection in this step S32 is executed by obtaining a differential value of the luminance levels between the newly generated whole image and the previously acquired

⁵⁵ whole image. In such a case, whether the differential value of the obtained luminance levels exceeds a preset threshold value or not is judged (Step S33). Here, when the differential value of the luminance levels exceeds a threshold value, the detection of the motion is judged, and the operation is transferred to step S34. On the other hand, when the differential value of the luminance levels is the threshold value or less, it is judged that the motion is not detected, and the

process is finished. In such a case, the difference sensing section 32 acquires the above-mentioned threshold value from the tracking and photographing condition DB39 as the above-mentioned tracking and photographing condition. The accuracy of the motion detection is controlled according to how this threshold value is set. Therefore, this threshold value can be freely set through the tracking and photographing conditions setting section 38, and thereby the level

- and the accuracy of the motion detection may be freely regulated.
 [0091] Then, the operation is transferred to step S34, the difference sensing section 32 accesses to the tracking position calculating section 34, and informs the image position E of the motion detection, that is, the coordinates (Ex, Ey) of the image area exceeding the threshold value by the differential value of the luminance level, to the tracking position calculating section 34. Then, the operation is transferred to step S35, and the difference sensing section 32.
- 10 acquires the tracking image position calculated by the tracking position calculating section 34. Further, this difference sensing section 32 notifies the acquired tracking image position in step S36 to the tracking photographing control section 33.

[0092] Here, a method for calculating the tracking image position in step S35 will be explained in the above-mentioned steps S11 to S 14 with reference to the case that the supervising frame of the parking lot is set as an example.

- ¹⁵ [0093] First, the tracking position calculating section 34 reads the supervising frame set at the points A to D and the points A' to D' recorded in the panorama setting DB35. The coordinates of a point A read here is (Ax, Ay), the coordinates of a point B is (Bx, By), the coordinates of a point C is (Cx, Cy), and the coordinates of a point D is (Dx, Dy).
 [0094] The tracking position calculating section 34 identifies a relative position in the supervising area defined by
- the points A to D of the image position E notified from the difference sensing section 32 in the above-mentioned step S34. In such a case, the relative position of the image position E may be expressed by a ratio (x1: x2) of a longitudinal direction and a ratio (y1:y2) of a lateral direction, as shown in FIG. 14A. In such a case, the ratio of the longitudinal direction and the ratio of the lateral direction can be expressed by formula 1 and formula 2 as below:

$$x1: x2 = Ex \times (Ax + Bx)/2: Ex \times (Dx + Cx)/2$$
 (formula 1)

$$y1: y2 = Ey \times (Ay + Cy)/2: Ey \times (By + Dy)/2$$
 (formula 2)

30 **[0095]** Thus, the relative position of the motion detected image position E can be obtained in the whole image photographed by the entire photographing camera 2.

[0096] Then, this tracking position calculating section 34 calculates what coordinates of the whole image corresponds to this image position E in the tracking and photographing camera 5. Here, as shown in FIG. 14B, the coordinates of the acquired point A' is (A'x, A'y), the coordinates of the acquired point B' is (B'x, B'y), the coordinates of the point C'

is (C'x, C'y), and the coordinates of the point D' is (D'x, D'y). In the whole image of the tracking and photographing camera 5, the tracking image position corresponding to the above-mentioned image position E will be hereinafter the tracking image position E', and the coordinates will be (E'x, E'y).

[0097] In such a case, in the case of A'x \ge B'x and D'x \ge C'x, E'x can be expressed by the following formula 3:

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$$E'x = ((C'x + (D'x-C'x) \times y1/(y1+y2)) - ((B'x + (A'x-B'x) \times y2/(y1+y2) \times y2))$$

$$x1/(x1+x2)) + B'x + (A'x-B'x) \times y2/(y1+y2)$$
 (formula 3)

45 [0098] In the case of D'y \geq B'y and A'y \geq C'y, E'y can be expressed by the following formula 4:

$$E'y = ((B'y + (D'y-B'y) \times x1/(x1+x2)) - ((C'y + (A'y-C'y) \times x2/(x1+x2) \times y1/(y1+y2) + C'y + (A'y-C'y) \times x2/(x1+x2))$$
 (formula 4)

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[0099] That is, the coordinates (E'x, E'y) of this obtained tracking image position E' corresponds to the coordinates (Ex,Ey) of the coordinates position E. Even if the entire photographing camera 2 and the tracking and photographing camera 5 are installed at different positions or are installed at different distance from a parking lot from each other, the coordinate position E' in the tracking and photographing camera 5 can be uniquely obtained from the coordinate position E motion detected from the entire image in the entire photographing camera 2.

[0100] The tracking position calculating section 34 can transmit the coordinates (E'x, E'y) of the obtained tracking image position E' as the tracking image position to the difference sensing section 32. The difference sensing section

32 transmits the coordinates (E'x, E'y) of the tracking image position E' to the tracking photographing control section 33. The tracking photographing control section 33 is set to include the coordinates (E'x, E'y) in the photographing direction of the tracking and photographing camera 5, and can match the photographing direction to the motion detected image position.

⁵ **[0101]** FIG. 15 shows the photographing operation sequence of the tracking photographing control section 33 to which such a tracking image position E' is notified.

[0102] First, in step S41, the tracking photographing control section 33 acquiring the tracking image position from the difference sensing section resets the photographing direction of the tracking and photographing camera 5 to include the coordinates (E'x, E'y). Then, the operation is transferred to step S42, a drive signal is transmitted to the tracking and photographing camera 5, and the photographing is started in the photographing direction.

[0103] The tracking and photographing camera 5 checks whether the signal for stopping the photographing is transmitted from the tracking and photographing control section 33 or not one by one. If the signal is transmitted, the photographing operation is stopped.

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- [0104] Such a supervising system 1 sets the supervising frame in no admittance area by the entire photographing camera 2 as shown, for example, in FIG. 16A as an application of particularly in supervising a parking lot. If a difference occurs at an illumination level from the previous entire image due to entrance of a person into this area, the photographing direction is matched to include the tracking image position by the tracking and photographing camera 5 as shown in FIG. 16B, and the tracking photographing is executed.
- [0105] Such a supervising system 1 can be installed in a projection room of a multiplex movie theater so called a cinema complex. The entire image of the so called an empty state before audience sit is obtained, and the supervising frame is set to include the respective seats. Thus, a difference of the luminance level of the audience sitting on the seats occurs. As a result that the obtained difference value exceeds the threshold value, the photographing direction is matched to include the tracking image position, and the tracking photographing can be executed. Thus, when a person sits the reserved seat by comparing the selling information of tickets and reservation information of the seats, this can be traced.
 - **[0106]** In the above-mentioned embodiment, the case that the one entire photographing camera 2 for photographing the subject to generate the image signal and the one tracking and photographing camera 5 are provided has been explained as an example. However, the present invention is not limited to such a case. For example, one or more entire photographing cameras 2 and one or more tracking and photographing cameras 5 may be provided. FIG. 17 shows a
- 30 supervising system 100 having three entire photographing cameras 2, and one tracking and photographing camera 5. In this supervising system 100, the same subject may be photographed from the different photographing directions by a plurality of entire photographing cameras 2, or the different subjects may be photographed. When the motion detection is performed by the entire photographing camera 2, the camera is transferred to the tracking and photographing mode, and the photographing by the tracking and photographing camera 5 is executed. The number and the ratio of the entire
- ³⁵ photographing camera 2 and the tracking and photographing camera 5 may be, of course, arbitrarily determined. [0107] In the supervising system 1 to which the present invention is applied, the cameras 2 and 5 may not specify the roles as the entire photographing and the tracking photographing, but the entire photographing or the tracking photographing may be executed in response to the circumstances. In the supervisory camera 101 shown in FIG. 18, two cameras 2 and 5 are respectively arranged. Under the normal photographing mode, two cameras 2 and 5 respectively.
- tively photograph the whole image. When any of the cameras 2 and 5 detects a motion, operation shifts to the tracking and photographing mode, and any one of the cameras 2 and 5 executes the tracking photographing.
 [0108] In the supervising system 1 to which the present invention is applied, the comparison of the luminance levels of the above-mentioned unit images may be executed at respective primary colors of R, G and B. The comparison of the luminance levels is executed among the unit images in the same coordinates (M, N) as described above, in other
- ⁴⁵ words, among the unit images in the same photographing direction. Thus, the change of the luminance levels in the respective primary color components of the comparison entire image to the reference entire image, in other words, the differential values of the luminance levels in the respective primary color components can be detected in the respective photographing directions.
- [0109] Further, the present invention is executed not only as the above-mentioned supervising system 1, but also, for example, the functions of the supervising unit 15 may be all carried at the camera side. In addition, the present invention may also be applied to a program for executing the above-mentioned process in a computer or a recording medium for recording such a program.

[0110] The present invention can also be applied to a supervising system 200 in which a fixed camera 2A for photographing an area of a wide range of 360 degrees as shown in FIG. 19 is used for the entire photographing camera

⁵⁵ 2 in the above-mentioned supervising system 1. This supervising system 200 includes the entire photographing camera 2A for generating an image signal by photographing a subject, a tracking and photographing camera 5, a network 8 connected to these cameras 2A, 5, and a supervising unit 15 for acquiring the image signal by controlling the entire photographing camera 2 and the tracking and photographing camera 5 via the connected network 8.

[0111] In this supervising system 200, the fixed camera 2A which can photograph in all directions of 360° in real time is used as the entire photographing camera 2, and this fixed camera 2A and tracking and photographing camera 5 which can perform pan/tilt/zoom are coaxially disposed as shown in FIGS. 20A and 20B.

[0112] FIG. 20A is a front view showing disposing examples of the fixed camera 2A and the tracking and photographing camera 5 in a front view and FIG. 20B is a side view thereof.

- [0113] The image of all directions of 360° acquired in real time by the fixed camera 2A in this supervising system 200 is shown, for example, in FIG. 21, a pan direction angle of view of 360°, a tilt direction angle of view of 55° (an elevation angle: 38°, and a depression angle: 17°), and the number of pixels is about 1280 × 240 of image quality.
 [0114] The panoramic image formed by laminating the images obtained by the tracking and photographing camera
- 5 has, for example, as shown in FIG. 22, a pan direction angle of view of 340°, a tilt direction angle of view of 51° (an elevation angle: 25.5°, and a depression angle: 25.5°), and the number of pixels is about 6400 × 960 of image quality.
 [0115] In this supervising system 200, its image space is, as shown in FIG. 23, obtained by laminating image (VGA 10 × 2 sheets).
 - **[0116]** One image obtained by the tracking and photographing camera 5 is zoom regulated in advance so that a tilt direction becomes 25.5° and pan direction becomes 34°.
 - **[0117]** The supervising unit 15 of this supervising system 200 is executed by next initializing (1) and initializing (2) at the shipment.
- Initializing (1): A wide angle image space of a panoramic image in this supervising system 200 has a pan direction = 340°, a tilt direction = 51° of total angle of view. An image information is 6400 equally divided in a pan direction, and 960 equally divided in a tilt direction. This image information is stored in a panorama setting database of the supervising unit 15.

Initializing (2): Four points of A, B, C and D are set on the image of 360° entire direction shown in FIG. 24 acquired in real time by the fixed camera 2A, and four points of A', B', C' and D' are set on the panoramic image shown in FIG. 25 formed by laminating the image obtained by the tracking and photographing camera 5. The above-mentioned four points are regarded as being the same position. This is also stored in the panorama setting database

[0118] In this supervising system 200, the tracking and photographing camera 5 is controlled based on the designating information on the image of the 360° entire direction acquired in real time by the fixed camera 2A according to the sequence shown in the flowchart of FIG. 26 by the supervising unit 15 initialized in this manner.

[0119] That is, the supervising unit 15 of this supervising system 200 acquires the coordinates on the 360° of the point E (X, Y) designated by the user with mouse paint (step S52), when the user designates an arbitrary point on the image of the 360° entire direction (step S51), positioning points A, B, C and D of the 360° entire direction image is

- 35 acquired from the panorama setting database (step S53), positioning points A', B', C' and D' of the 340° panoramic image of the tracking and photographing camera 5 is acquired from the panorama setting database (step S54), the position information of the 340° panoramic image corresponding to the position E(X, Y) on the 360° entire direction image is acquired (step S55), a request for moving to the position of E(X', Y') is transmitted to the tracking and photographing camera 5 (step S56), and the image of moving destination is displayed (step S57).
- ⁴⁰ **[0120]** That is, in this supervising system 200, when an arbitrary point E is clicked on the image of the 360° entire direction shown in FIG. 24, the coordinates E(X, Y) on the image of FIG. 24 is led, and the relative position (approximation) is calculated from the respective points of A, B, C and D stored in advance in the panorama setting database for the coordinates E (X, Y).
- [0121] A', B', C' and D' of FIG. 25 stored in advance in the panorama setting database is regarded as being corresponded to the points of A, B, C and D, the E' (X', Y') of FIG. 25 corresponding to E (X, Y) of FIG. 24 is can be obtained from the relative positions of the A', B', C' and D' and the calculated A, B, C and D. The calculated E', (X', Y') is expressed as position information on the image information stored in the database.
 [0122] Pan tilt control is performed so that the center of the image of the tracking and photographing camera 5.

[0122] Pan tilt control is performed so that the center of the image of the tracking and photographing camera 5 becomes E' based on the position information of this E' (X', Y').

⁵⁰ **[0123]** Here, the calculation of the relative position (approximation) of the E arbitrarily designated on the image of the 360° entire direction acquired in real time by the fixed camera 2A in this supervising system 200 will be performed as follows:

X1 : X2 = Ex - (Ax+Bx)/2 : (Dx+Cx)/2 - Ex

Y1: Y2 = Ey - (Ay+Cy)/2: (By+Dy)/2 - Ey

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of the supervising unit 15.

[0124] The calculation of the position (approximation) of E' on the 340° panoramic image obtained by the tracking and photographing camera 5 is performed as follows:

[0125] The ratio X1:X2 of the relative position obtained in the previous calculation is 5:2, the ratio Y1:Y2 is 3:4, and the case where $A'x \ge B'x$ and $D'x \ge C'x$,

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 $E'x = ((C'x+(D'x-C'x)^{*3/7})-(B'x+(A'x B'x)^{*4/7}))^{*5/7}+B'x+(A'x B'x)^{*4/7})$

[0126] The case where $D'y \ge B'y$ and $A'y \ge C'y$,

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E'y = ((B'y+(D'y-B'y)*5/7)-(C'y+(A'y-C'y)*2/7))*3/7+C'y+(A'y-C'y)*2/7)

[0127] Here, the visual field angle sectional view of a vertical direction of the entire photographing camera 2A and the tracking and photographing camera 5 in this supervising system 200 is shown in FIG. 27.

[0128] FIG. 27 shows a graphical expression of capturing a subject in a substantially equal direction (vertical direction) by both the entire photographing camera 2A, that is, a wide angle camera (Panorama Camera) and the tracking and photographing camera 5 in this supervising system 200. **[0129]** First,

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X: a horizontal direction distance of a photographing subject and a camera

Y: a vertical direction distance (height) which can be photographed in the entire tilt angle of view at a distance X Δ Y: distance between centers of imaging parts of two cameras.

25 [0130] As a premise, the following two premises exist.

Premise 1: the tracking and photographing camera 5 and 360° camera exist on substantially the same vertical line at the centers of the imaging parts of the cameras.

Premise 2: the tilt direction angle of view of the tracking and photographing camera 5 and the entire photographing
 camera 2A is regulated to the same angle of view in a range of about 55° to 65°.

- [0131] In addition, the positional relation of two visual angles as shown in FIG. 27.
- **[0132]** If the two angles of view are 55°,

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 $\Delta Y = 100 \text{ mm}$ of camera positional relation,

When an article of the position of X = 10 m is photographed,

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Y = 2*X*Tan (55/2)° = 10.41 m

is obtained. As a result,

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$$\Delta Y/Y = 0.0096 = 0.96\%$$

is obtained,

Y: a difference of the position in the vertical direction between two cameras is very short with respect to the entire distance of the vertical direction. When two images are displayed by a monitor, it is not a level to feel the difference.

[0133] That is, the difference is mere about 5 dots when it is calculated in terms of VGA: 640×480 .

[0134] Due to the coaxial layout, the angle of view of the horizontal direction is shared with the same angle of view in both cameras.

[0135] In this supervising system 200, the cameras 2A and 5 are coaxially disposed. Thus, the position calculating algorithm of the subject according to the relative positional relation of the cameras 2 and 5 is not required, but the point of the image of the 360° entire direction obtained by the photographing camera 2A is designated, and can be photographed by the tracking and photographing camera 5 of the image at the point as a center.

Claims

1. A photographing apparatus comprising:

5 a first camera for photographing a wide angle area;

a second camera for photographing an area narrower than the wide angle area in a direction corresponding to the designated photographing direction;

a motion detecting section for detecting the presence or absence of a motion in the image by comparing a first image generated by the first camera with the previous image photographed previously from the first image in terms of the difference of luminance levels;

- a memory for previously recording correlation information showing the correlation of the positions of the first image and a second image obtained by the second camera; and a controller for controlling the photographing direction of the second camera at the motion detected position
- by using the correlation information when the presence of the motion is detected by the motion detecting section.
 - 2. The photographing apparatus according to claim 1, wherein the correlation information is an information obtained based on a plurality of predetermined positions of the first image and the second image.
- The photographing apparatus according to claim 1, wherein the presence or absence of the motion is detected by the motion detecting section by comparing the difference of the luminance levels with a predetermined threshold value.
- 4. The photographing apparatus according to claim 1, wherein the first camera and the second camera are arranged 25 at the substantially same positions.
 - 5. The photographing apparatus according to claim 1, further comprising:
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recording means for recording the photographed first image on a recording medium.

- 6. The photographing apparatus according to claim 1, wherein the first camera is a wide angle fixed camera, and the first image is the image of the entire photographing range of the first camera.
- 7. The photographing apparatus according to claim 1, wherein the first camera is a camera for photographing by sequentially matching the photographing direction to the respective unit images constructing the first image, and the first image is the image formed by connecting the respective unit images.
 - 8. A photographing apparatus comprising:
- 40 a first camera for photographing a wide angle area;
 - a second camera for photographing an area narrower than the wide angle area in a direction corresponding to the designated photographing direction;

a motion detecting section for detecting the presence or absence of a motion at each unit image by comparing a first unit image constructing a first wide angle image generated by the first camera with the unit image in the same photographing direction photographed previously from the first unit image in terms of the difference of luminance levels:

a recording section previously recording correlation information showing correlation of the respective image positions between the first unit image and the second unit image obtained by the second camera; and

- a controller for controlling the photographing direction of the second camera at the motion detected position
 by using the correlation information when the presence of the motion is detected by the motion detecting section.
 - 9. The photographing apparatus according to claim 8, wherein the first camera is a camera for photographing by sequentially matching the photographing direction to a direction of each first unit image, and the first wide angle image is an image formed by connecting the first unit images.
 - **10.** A photographing method comprising:

a step of photographing a first image of a wide angle area by a first camera;

- a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image by comparing the first image with the previous image photographed previously from the first image in terms of a luminance level; controlling the photographing direction of the second camera at the motion detected position when the presence of the motion is detected by the motion detecting section by using the correlation information showing the correlation of the positions of the images of the first image and the second image obtained by the second camera.
- 10 **11.** A photographing method comprising:
 - a step of photographing a first wide angle image of a wide angle area by a first camera;
 - a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image at each unit image by comparing a first unit image constructing the first wide angle image with a unit image in the same photographing direction previously photographed from the unit image in terms of the difference of a luminance level; controlling the photographing direction of the second camera at the motion detected position when the presence of the motion is detected by the motion detecting section by using the correlation information showing the correlation of the positions of the images of the first unit image and a second unit image obtained by the second camera.
 - 12. A supervising system comprising:
- a first camera for photographing a wide angle area;
 a second camera for photographing an area narrower than the wide angle area in a direction corresponding to the designated photographing direction;
 a motion detecting section for detecting the presence or absence of a motion at each unit image by comparing a first unit image constructing a first wide angle image generated by the first camera with the unit image in the same photographing direction photographed previously from the first unit image in terms of the difference of a luminance level;
 a recording section previously recording correlation information showing correlation of the respective image positions between the first unit image and a second unit image obtained by the second camera; and a controller for controlling the photographing direction of the second camera at the motion detected position by using the correlation information when the presence of the motion is detected by the motion detecting section.
 - **13.** A program for causing a computer to execute:
 - a step of photographing a first image of a wide angle area by a first camera;
- a step of photographing a second image of an area narrower than the wide angle area by a second camera; and a motion detecting step of detecting the presence or absence of the motion in the image by comparing the first image with the previous image photographed previously from the first image in terms of luminance levels; controlling the photographing direction of the second camera at the motion detected position when the presence of the motion is detected by the motion detecting section by using the correlation information showing
 the correlation of the positions of the images of the first image and the second image obtained by the second camera.

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FIG. 3











EP 1 536 633 A1



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FIG. 10









FIG. 11B

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FIG. 14B



FIG. 15















FIG.20A FIG.20B



X-350

FIG.21

FIG.22

Y-360





FIG. 23









European Patent

Office

EUROPEAN SEARCH REPORT

Application Number EP 04 02 8026

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	Place of search	Date of com	pletion of the search			Examiner
The Hague		8 Mar	8 March 2005			ierlaurent, P
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EP 04 02 8026

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08-03-2005

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FORM								

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EUROPEAN PATENT OFFICE

Patent Abstracts of Japan

PUBLICATION I	NUMBER DATE	:	2008076485 03-04-08	
APPLICATION I	DATE NUMBER	:	19-09-06 2006252495	
APPLICANT :	KONICA MINOLTA	40	PTO INC;	
INVENTOR :	MITANI YOSHIJI;			4)
INT.CL. :	G02B 7/04 (2006) (2006.01)	.01)), G02B 7/08	02
TITLE :	LENS BARREL AN APPARATUS	1D	MAGING	
				(a)



ABSTRACT : PROBLEM TO BE SOLVED: To provide a lens barrel that is small and rigid and can easily be incorporated and to provide a small imaging apparatus.

SOLUTION: The box-shaped lens barrel includes: an imaging optical system having two lens groups held in lens frames; and two drive shafts for supporting the respective lens frames so that they are movable relative to each other in the direction of an optical axis. In the lens barrel, openings are made in opposite walls of the lens barrel, which are orthogonal to a plane including the two drive shafts so as to be displaced from each other in the direction of the optical axis.

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EUROPEAN PATENT OFFICE

Patent Abstracts of Japan

PUBLICATION NUMBER	:	2004133054
PUBLICATION DATE	:	30-04-04

- APPLICATION DATE:08-10-02APPLICATION NUMBER:2002295258
- APPLICANT : OLYMPUS CORP;
- INVENTOR : FUTAMI AKIRA;
- INT.CL. : G02B 7/02 G02B 7/04 G02B 7/08 G03B 9/14 G03B 9/26 H04N 5/225
- TITLE : LENS BARREL



ABSTRACT : PROBLEM TO BE SOLVED: To provide a lens barrel made reliable, and made small in size and thin in thickness.

SOLUTION: The lens barrel 10 has a 1st group frame 31 and a fixed frame 32, and incorporates a prism to refract subject luminous flux from an incident optical axis to an optical axis being in a perpendicular direction in the 1st group frame. A lens group capable of moving forward and backward, a shutter unit and a CCD or the like are arranged in the frame 32, and a solenoid for driving a shutter is arranged on the left side of the frame 31 and a step motor for driving a lens group is arranged on the left side wall part 32k of the frame 32. PRs 58 and 59 for detecting the position of a lens group are positioned on a front side wall part 32j and mounted on an FPC for connection 86, and the motor terminals 53d and 54d of the step motor are inserted through the insertion holes 32m and 32n of the wall part 32k to the outside and connected to the FPC 86. By arranging the solenoid and the step motor on the left side of the frame member, the lens barrel is thinned.

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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP	5811
-	12/10/2018		EXAM	INER
, Nathan & Assoc	iates Patent Agents L	td	TRAN, M	NHAN T
P.O.Box 10178 Tel Aviv 611010)1		ART UNIT	PAPER NUMBER
ISRAEL			2664	
			NOTIFICATION DATE	DELIVERY MODE
			12/10/2018	ELECTRONIC

NOTICE OF NON-COMPLIANT INFORMATION DISCLOSURE STATEMENT

An Information Disclosure Statement (IDS) filed 11.25.1% in the above-identified application fails to meet the requirements of 37 CFR 1.97(d) for the reason(s) specified below. Accordingly, the IDS will be placed in the file, but the information referred to therein has not been considered.

The IDS is not compliant with 37 CFR 1.97(d) because:

- The IDS lacks a statement as specified in 37 CFR 1.97(e).
- □ The IDS lacks the fee set forth in 37 CFR 1.17(p).
- □ The IDS was filed after the issue fee was paid. Applicant may wish to consider filing a petition to withdraw the application from issue under 37 CFR 1.313(c) to have the IDS considered. See MPEP 1308.

571-272-4200 or 1-888-786-0101 Application Assistance Unit Office of Data Management

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	OF COMMERCE mark Office ATENTS 0			
APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017	Noy Cohen	COREPH-0159 US NP	5811
92342 Nathan & Asso	7590 12/13/201	8	EXAM	IINER
P.O.Box 10178	Gales I alent Agents Li	u	TRAN, N	NHAN T
Tel Aviv, 6110	101		ART UNIT	PAPER NUMBER
ISKAEL			2664	
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			12/13/2018	ELECTRONIC

Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

Notice of the Office communication was sent electronically on above-indicated "Notification Date" to the following e-mail address(es):

amirr@natpatent.com dorong@natpatent.com info@natpatent.com



APPLICATION NO./	FILING DATE	FIRST NAMED INVENTOR/	ATTORNEY DOCKET NO.
CONTROL NO.		PATENT IN REEXAMINATION	
15/324,720	01/08/2017	Cohen et al.	COREPH-0159 US NP

	EX	AMINER
Nathan & Associates Patent Agents Ltd P.O. Box 10178	NHA	AN T TRAN
Tel Aviv, 6110101	ART UNIT	PAPER
	2664	20181208

DATE MAILED:

Please find below and/or attached an Office communication concerning this application or proceeding.

Commissioner for Patents

The IDS filed on 9/23/2018 contains invalid reference number 98896655 at item 89. This reference could not be identified and has been crossed out from consideration by the Examiner.

See attached document.

/NHAN T TRAN/ Primary Examiner, Art Unit 2664 Doc code: IDS

Doc description: Information Disclosure Statement (IDS) Filed

PTO/SB/08a (01-10)

Approved for use through 07/31/2012. OMB 0651-0031 U.S. Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it contains a valid OMB control number.

	Application Number		15324720	
	Filing Date		2017-01-08	
INFORMATION DISCLOSURE	First Named Inventor Noy Co		Cohen	
SIAIEWIENI BY APPLICANI (Not for submission under 37 CER 1 99)	Art Unit			
	Examiner Name			
	Attorney Docket Number		COREPH-0159 US NP	

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Application Number		15324720			
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First Named Inventor	Noy C	Cohen			
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Application Number		15324720		
Filing Date		2017-01-08		
First Named Inventor	Noy Cohen			
Art Unit				
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Attorney Docket Number		COREPH-0159 US NP		

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92342	7590 11/16/2	2018		Cer	rtificate	e of Mailing or Transı	mission
Nathan & Assoc	ciates Patent Ager	ts Ltd	I her State	reby certify that th es Postal Service v	us Fee(: vith suf	s) Transmittal is being ficient postage for firs	deposited with the United t class mail in an envelope
P.O.Box 10178	. 1		addr the l	essed to the Mail	Stop IS	SUE FEE address abo	ve, or being transmitted to
Tel Aviv, 611010	1					$\frac{1}{2}$	(Typed or printed name)
ISKALL							(Signature)
							(Date)
APPLICATION NO.	FILING DATE		FIRST NAMED INVENTOR		ATTO	RNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	01/08/2017		Noy Cohen		COF	EPH-0159 US NP	5811
TITLE OF INVENTION: I	DUAL APERTURE ZO	OM CAMERA WITH V	IDEO SUPPORT AND SW	/ITCHING / NON-	-SWITC	CHING DYNAMIC CO	ONTROL
APPLN. TYPE	ENTITY STATUS	ISSUE FEE DUE	PUBLICATION FEE DUE	PREV. PAID ISSU	E FEE	TOTAL FEE(S) DUE	DATE DUE
nonprovisional	SMALL	\$500	\$0.00	\$0.00		\$500	02/19/2019
			•	1			
EXAMI	NER	ART UNIT	CLASS-SUBCLASS				
TRAN, NI	HAN T	2664	348-240990				
 I. Change of correspondence address or indication of "Fee Address" (37 CFR 1.363). Change of correspondence address (or Change of Correspondence Address form PTO/SB/122) attached. "Fee Address" indication (or "Fee Address" Indication form PTO/SB/47; Rev 03-09 or more recent) attached. Use of a Customer 		 2. For printing on the patent front page, list The names of up to 3 registered patent attorneys or agents OR, alternatively, The name of a single firm (having as a member a registered attorney or agent) and the names of up to 2 registered patent attorneys or agents. If no name is listed, no name will be printed. 1 Nathan & Associat 2 Menachem Nathan 3 			& Associates em Nathan		
3. ASSIGNEE NAME AN	D RESIDENCE DATA	TO BE PRINTED ON	THE PATENT (print or tyr)			
PLEASE NOTE: Unles recorded, or filed for re	ss an assignee is identifie ecordation, as set forth in	d below, no assignee dat 37 CFR 3.11 and 37 CF	a will appear on the patent. FR 3.81(a). Completion of	If an assignee is id this form is NOT a	dentifie 1 substit	d below, the document tute for filing an assign	must have been previously ment.
(A) NAME OF ASSIG	NEE		(B) RESIDENCE: (CITY	and STATE OR C	COUNT	'RY)	
Corephotonic	cs Ltd.		Tel Aviv, Israe				
Please check the appropria	ate assignee category or o	ategories (will not be pr	rinted on the patent) : 🖵 In	idividual 🖵 Corpo	oration o	or other private group e	entity 🖵 Government
4a. Fees submitted:	Suc Fee Public	cation Fee (if required)	Advance Order - #	of Copies			
Selectronic Payment	via EES-Web	nclosed check	Non-electronic payment by	credit card (Attack	h form l	PTO-2038)	
The Director is here	by authorized to charge	the required fee(s) any	deficiency, or credit any ox	verpayment to Dep		Pount No	
	eby authorized to charge	the required ree(s), any	denciency, or create any ov	erpayment to Dep	USIL AC	.ount 100	
5. Change in Entity State		- h)					
Applicant certifying	micro entity status findicated	37 CFR 1 29	<u>NOTE:</u> Absent a valid ce	rtification of Micro	• Entity	Status (see forms PTC	/SB/15A and 15B), issue
Applicant county ing increase of the field of the fi		fee payment in the micro <u>NOTE:</u> If the application	entity amount will was previously un	not be der mic	accepted at the risk of ro entity status, checki	application abandonment. ng this box will be taken	
		to be a notification of loss of entitlement to micro entity status. <u>NOTE:</u> Checking this box will be taken to be a notification of loss of entitlement to small or micro				lement to small or micro	
NOTE: This form must be	signed in accordance w	th 37 CFR 1.31 and 1.3	3. See 37 CFR 1.4 for sign	ature requirements	and cer	tifications.	
Authorized Signature	/ Menachem N	lathan /		Date 2019/	/01/0	3	
				Registration N	No. <u>6</u> 5	392	

PART B - FEE(S) TRANSMITTAL

Complete and send this form, together with applicable fee(s), by mail or fax, or via EFS-Web.

By mail, send to: Mail Stop ISSUE FEE Commissioner for Patents P.O. Box 1450 Alexandria, Virginia 22313-1450 By fax, send to: (571)-273-2885

Electronic Patent Application Fee Transmittal					
Application Number:	153	324720			
Filing Date:	08-	Jan-2017			
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL			AND SWITCHING /	
First Named Inventor/Applicant Name:	Noy Cohen				
Filer:	Menachem Nathan				
Attorney Docket Number:	со	REPH-0159 US NP			
Filed as Small Entity					
Filing Fees for U.S. National Stage under 35 USC 371					
Description		Fee Code	Quantity	Amount	Sub-Total in USD(\$)
Basic Filing:					
Pages:					
Claims:					
Miscellaneous-Filing:					
Petition:					
Patent-Appeals-and-Interference:					
Post-Allowance-and-Post-Issuance:					
UTILITY APPL ISSUE FEE		2501	1	500	500

Description	Fee Code	Quantity	Amount	Sub-Total in USD(\$)
Extension-of-Time:				
Miscellaneous:				
	Tot	al in USD) (\$)	500

Electronic Acknowledgement Receipt					
EFS ID:	34771079				
Application Number:	15324720				
International Application Number:					
Confirmation Number:	5811				
Title of Invention:	DUAL APERTURE ZOOM CAMERA WITH VIDEO SUPPORT AND SWITCHING / NON-SWITCHING DYNAMIC CONTROL				
First Named Inventor/Applicant Name:	Noy Cohen				
Customer Number:	92342				
Filer:	Menachem Nathan				
Filer Authorized By:					
Attorney Docket Number:	COREPH-0159 US NP				
Receipt Date:	05-JAN-2019				
Filing Date:	08-JAN-2017				
Time Stamp:	04:06:46				
Application Type:	U.S. National Stage under 35 USC 371				

Payment information:

Submitted with Payment	yes
Payment Type	CARD
Payment was successfully received in RAM	\$500
RAM confirmation Number	010719INTEFSW04080600
Deposit Account	
Authorized User	

The Director of the USPTO is hereby authorized to charge indicated fees and credit any overpayment as follows:

File	Listing:
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Document Number	Document Description	File Name	File Size(Bytes)/ Message Digest	Multi Part /.zip	Pages (if appl.)
1	lssue Fee Payment (PTO-85B)	lssue_fee.pdf	271252 cab5f3acb94f3fc88fc31c6246e8fdb7d5645 586	no	1
Warnings:					
Information:					
			30199		
2	Fee Worksheet (SB06)	fee-info.pdf	9675d0f004c90404e4707d3b8428163912f 6a86d	no	2
Warnings:					
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Total Files Size (in bytes):301451					
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IN THE DESCRIPTION:

Change(s) applied to document, Please amend the paragraph on page 12, lines 24-28 as follows: /J.M.C./ 12/6/2018 Paturning now to the Zoom in process, in some embed

Returning now to the Zoom-in process, in some embodiments, for higher ZF than the up-transfer ZF_{\star} the output is the transformed Tele camera output, digitally zoomed. However, in other embodiments, for <u>higher ZF than the</u> up-transfer ZF_{\star} there will be no switching from the Wide to the Tele camera output, i.e. the output will be from the Wide camera, digitally zoomed. This "no switching" process is described next.
15/324,720 - GAU: 2664

INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)

Application Number		15324720		
Filing Date		2017-01-08		
First Named Inventor Noy C		Cohen		
Art Unit				
Examiner Name				
Attorney Docket Number		COREPH-0159 US NP		

		73	20040061788	A1	2004-04-01	John Bateman	
		74	20150215516	A1	2015-07-30	Benjamin P. Dolgin	
		75	20140313316	A1	2014-10-23	Olsson et al.	
		76	20110229054	A1	2011-09-22	Weston et al.	
Cł	ange(s) a	77 pplied	20020063711	A1	0 <i>5/</i> 2002 2 016-08-14	Park et al.	
to c /R 12/	document .5./ /7/2018	78	20090128644	A1	2009-05-21	Camp et al.	
		79	20130321668	A1	2013-12-05	Ajith Kamath	
		80	20130202273	A1	2013-08-08	Ouedraogo et al.	
		81	20120069235	A1	2012-03-22	Francisco Imai	
		82	20130002928	A1	2013-01-03	Francisco Imai	
		83	20120105579	A1	2012-05-03	Jeon et al.	

Doc code: IDS

Doc description: Information Disclosure Statement (IDS) Filed

15/324,720 - GAU: 2664

PTO/SB/08a (01-10)

Approved for use through 07/31/2012. OMB 0651-0031 U.S. Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE Under the Paperwork Reduction Act of 1995, no persons are required to respond to a collection of information unless it contains a valid OMB control number.

INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number		15324720	
	Filing Date		2017-01-08	
	First Named Inventor Noy Cohen		ohen	
	Art Unit			
	Examiner Name			
	Attorney Docket Number		COREPH-0159 US NP	

	U.S.PATENTS Remove								
Examiner Initial*	Cite No	Patent Number	Kind Code ¹	Issue Date	Name of Patentee or Applicant of cited Document	Pages,Columns,Lines where Relevant Passages or Relevant Figures Appear			
	1	9286680	B1	2016-03-15	Jiang et al.				
	2	9736391	B2	2017-08-15	Du et al.				
	3	9894287	B2	2018-02-13	Qian et al.				
	4	6750903	B1	2004-06-15	Miyatake et al.				
	5	5032917	A	1991-07-16	Felix Aschwanden				
	6	5287093	A	1994-02-15	Amano et al.				
	7	5287093	A	02/1 <i>994</i> 1995-82-28	Amano et al. John T. Hall-				
hange(s) a	8 pplied	5444478	A	1995-08-22	Lelong et al.				

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12/7/2018 EFS Web 2.1.17

UNITED STATES PATENT AND TRADEMARK OFFICE



APPLICATION NO.	ISSUE DATE	PATENT NO.	ATTORNEY DOCKET NO.	CONFIRMATION NO.
15/324,720	03/12/2019	10230898	COREPH-0159 US NP	5811

92342 7590 02/20/2019 Nathan & Associates Patent Agents Ltd P.O.Box 10178 Tel Aviv, 6110101 ISRAEL

ISSUE NOTIFICATION

The projected patent number and issue date are specified above.

Determination of Patent Term Adjustment under 35 U.S.C. 154 (b)

(application filed on or after May 29, 2000)

The Patent Term Adjustment is 0 day(s). Any patent to issue from the above-identified application will include an indication of the adjustment on the front page.

If a Continued Prosecution Application (CPA) was filed in the above-identified application, the filing date that determines Patent Term Adjustment is the filing date of the most recent CPA.

Applicant will be able to obtain more detailed information by accessing the Patent Application Information Retrieval (PAIR) WEB site (http://pair.uspto.gov).

Any questions regarding the Patent Term Extension or Adjustment determination should be directed to the Office of Patent Legal Administration at (571)-272-7702. Questions relating to issue and publication fee payments should be directed to the Application Assistance Unit (AAU) of the Office of Data Management (ODM) at (571)-272-4200.

APPLICANT(s) (Please see PAIR WEB site http://pair.uspto.gov for additional applicants):

Nov Cohen, Tel-Aviv, ISRAEL; Corephotonics Ltd., Tel-Aviv, ISRAEL Oded Gigushinski, Herzlia, ISRAEL; Nadav Geva, Tel-Aviv, ISRAEL; Gal Shabtay, Tel-Aviv, ISRAEL; Ester Ashkenazi, Modi'in, ISRAEL; Ruthy Katz, Tel Aviv, ISRAEL; Ephraim Goldenberg, Ashdod, ISRAEL;

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