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(54) **RECONSTRUCTION OF IMAGE IN A BAYER PATTERN**

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(75) Inventors: **Xiongfei Cai, Beijing (CN);
Feng-Hsiung Hsu, Cupertino, CA
(US)**

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Correspondence Address:
**MICROSOFT CORPORATION
ONE MICROSOFT WAY
REDMOND, WA 98052 (US)**

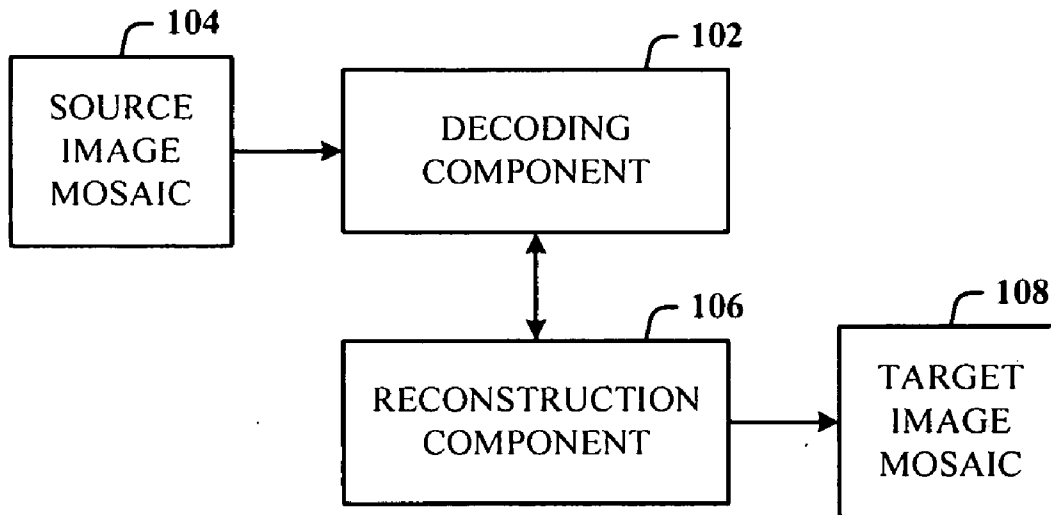
(57) **ABSTRACT**

Architecture for decoding (demosaicing) a source image and performing reconstruction directly from the Bayer pattern to reduce memory size and improve communication bandwidth. The architecture can be easily implemented in hardware such as in field programmable gate arrays (FPGAs) and application-specific integrated circuits (ASICs).

(73) Assignee: **MICROSOFT CORPORATION,
Redmond, WA (US)**

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↖ **100**



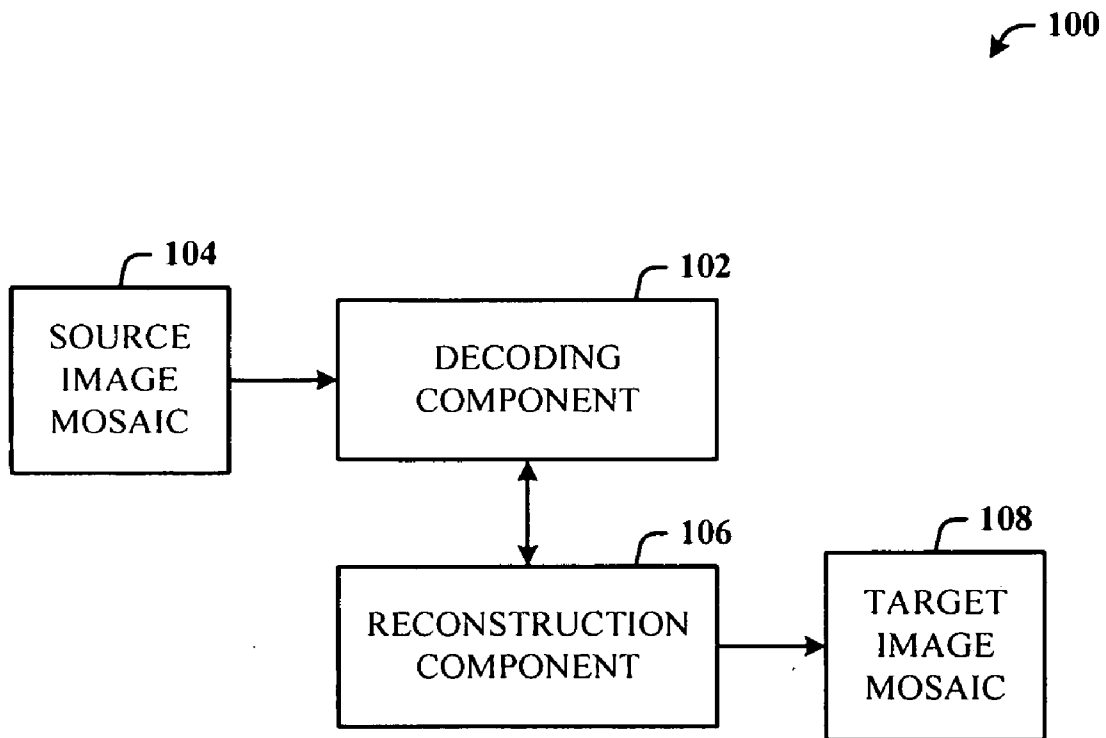


FIG. 1

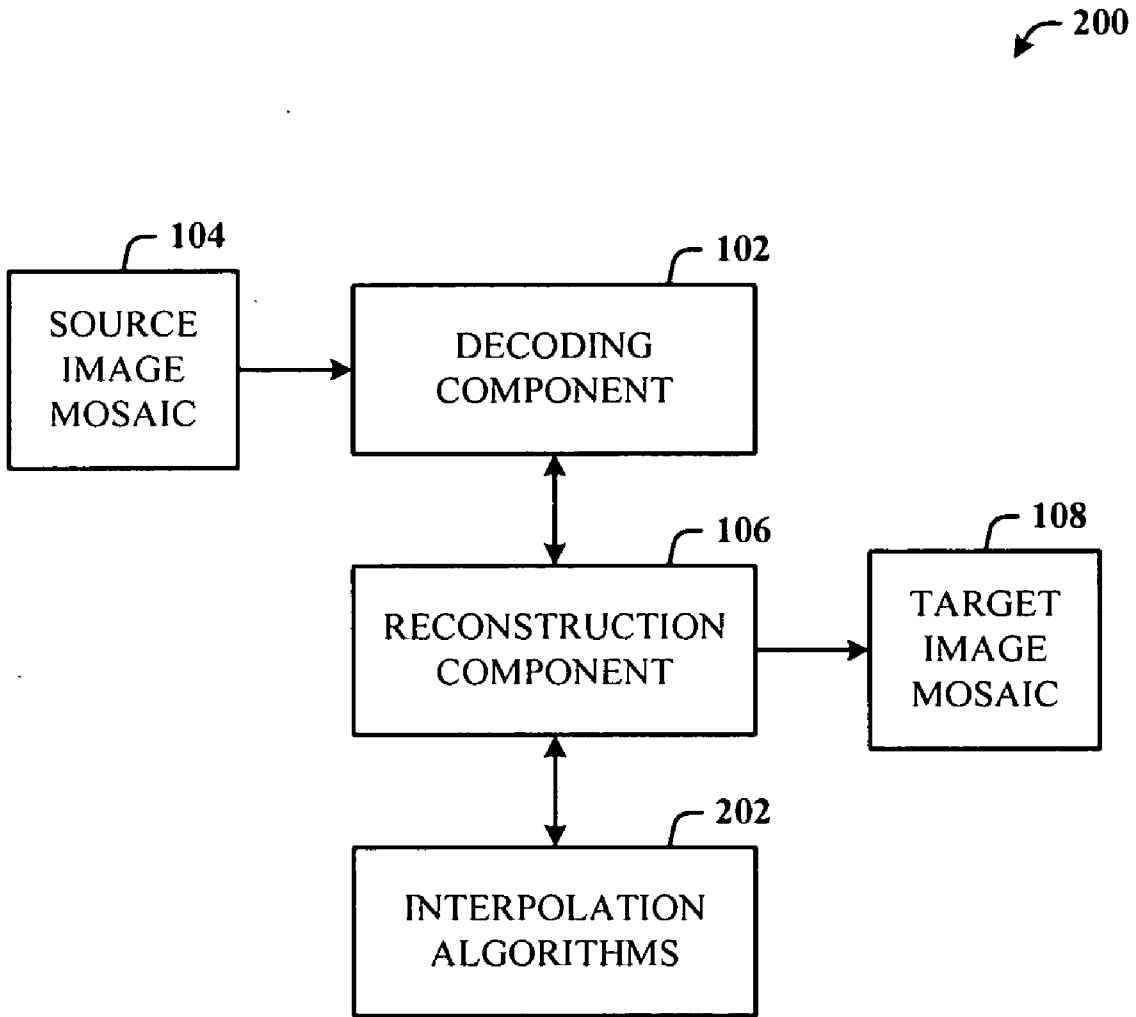


FIG. 2

300

302

$$R(X_t, Y_t) = R(x, y) = \begin{bmatrix} 1 - \frac{\Delta x}{2} - \frac{\Delta y}{2} + \frac{\Delta x \Delta y}{4} \\ \frac{\Delta x}{2} - \frac{\Delta x \Delta y}{4} \\ \frac{\Delta y}{2} - \frac{\Delta x \Delta y}{4} \\ \frac{\Delta x \Delta y}{4} \end{bmatrix} \cdot \begin{bmatrix} R(X, Y) \\ R(X + 2, Y) \\ R(X, Y + 2) \\ R(X + 2, Y + 2) \end{bmatrix}$$

304

$$R(X_t, Y_t) = R(x, y) = \begin{bmatrix} \frac{1}{2} - \frac{\Delta x}{2} - \frac{\Delta y}{4} + \frac{\Delta x \Delta y}{4} \\ \frac{1}{2} + \frac{\Delta x}{2} - \frac{\Delta y}{4} - \frac{\Delta x \Delta y}{4} \\ \frac{\Delta y}{4} - \frac{\Delta x \Delta y}{4} \\ \frac{\Delta y}{4} + \frac{\Delta x \Delta y}{4} \end{bmatrix} \cdot \begin{bmatrix} R(X - 1, Y) \\ R(X + 1, Y) \\ R(X - 1, Y + 2) \\ R(X + 1, Y + 2) \end{bmatrix}$$

306

$$R(X_t, Y_t) = R(x, y) = \begin{bmatrix} \frac{1}{2} - \frac{\Delta x}{4} - \frac{\Delta y}{2} + \frac{\Delta x \Delta y}{4} \\ \frac{\Delta x}{4} - \frac{\Delta x \Delta y}{4} \\ \frac{1}{2} - \frac{\Delta x}{4} + \frac{\Delta y}{2} - \frac{\Delta x \Delta y}{4} \\ \frac{\Delta x}{4} + \frac{\Delta x \Delta y}{4} \end{bmatrix} \cdot \begin{bmatrix} R(X, Y - 1) \\ R(X + 2, Y - 1) \\ R(X, Y + 1) \\ R(X + 2, Y + 1) \end{bmatrix}$$

308

$$R(X_t, Y_t) = R(x, y) = \begin{bmatrix} \frac{1}{4} - \frac{\Delta x}{4} - \frac{\Delta y}{4} + \frac{\Delta x \Delta y}{4} \\ \frac{1}{4} + \frac{\Delta x}{4} - \frac{\Delta y}{4} - \frac{\Delta x \Delta y}{4} \\ \frac{1}{4} - \frac{\Delta x}{4} + \frac{\Delta y}{4} - \frac{\Delta x \Delta y}{4} \\ \frac{1}{4} + \frac{\Delta x}{4} + \frac{\Delta y}{4} + \frac{\Delta x \Delta y}{4} \end{bmatrix} \cdot \begin{bmatrix} R(X - 1, Y - 1) \\ R(X + 1, Y - 1) \\ R(X - 1, Y + 1) \\ R(X + 1, Y + 1) \end{bmatrix}$$

FIG. 3

400

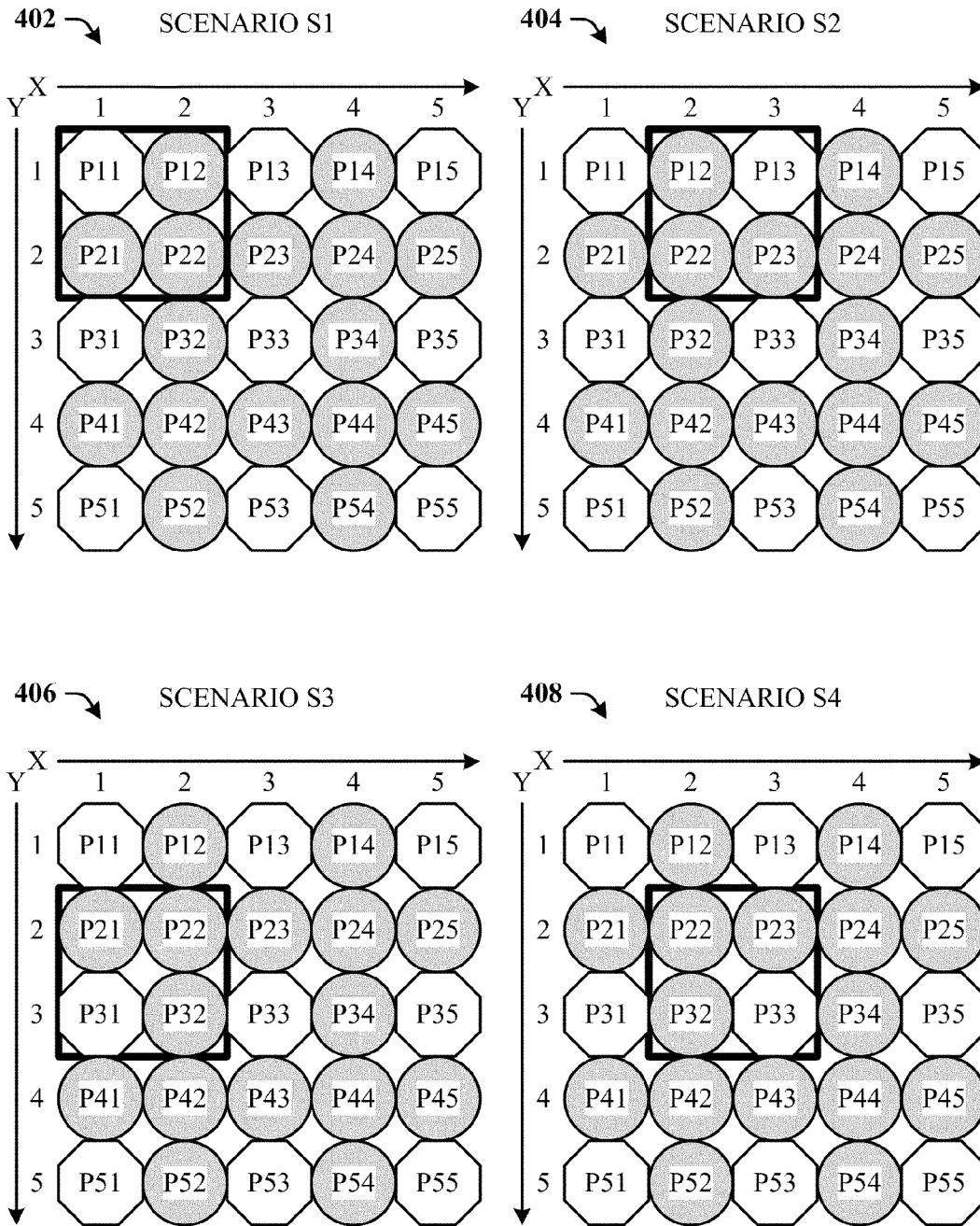


FIG. 4

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