Assumptions:

- 1. One-dimensional conduction in r.
- 2. Constant properties.

Analysis:

1. To determine whether the lumped capacitance method can be used, the Biot number is calculated. From Equation 5.10, with $L_c = r_o/3$,

$$Bi = \frac{h_a r_o}{3k} = \frac{10 \text{ W/m}^2 \cdot \text{K} \times 0.005 \text{ m}}{3 \times 20 \text{ W/m} \cdot \text{K}} = 8.33 \times 10^{-4}$$

Accordingly, the lumped capacitance method may be used, and the temperature is nearly uniform throughout the sphere. From Equation 5.5 it follows that

$$t_a = \frac{\rho Vc}{h_a A_s} \ln \frac{\theta_i}{\theta_a} = \frac{\rho r_o c}{3h_a} \ln \frac{T_i - T_\infty}{T_a - T_\infty}$$

where $V = (4/3)\pi r_o^3$ and $A_s = 4\pi r_o^2$. Hence

$$t_a = \frac{3000 \text{ kg/m}^3 \times 0.005 \text{ m} \times 1000 \text{ J/kg} \cdot \text{K}}{3 \times 10 \text{ W/m}^2 \cdot \text{K}} \ln \frac{400 - 20}{335 - 20} = 94 \text{ s}$$

 To determine whether the lumped capacitance method may also be used for the second step of the cooling process, the Biot number is again calculated. In this case

$$Bi = \frac{h_w r_o}{3k} = \frac{6000 \text{ W/m}^2 \cdot \text{K} \times 0.005 \text{ m}}{3 \times 20 \text{ W/m} \cdot \text{K}} = 0.50$$

and the lumped capacitance method is not appropriate. However, to an excellent approximation, the temperature of the sphere is uniform at $t=t_a$ and the Heisler charts may be used for the calculations from $t=t_a$ to $t=t_a+t_w$. Using Figure 5.14 with

$$Bi^{-1} = \frac{k}{h_w r_o} = \frac{20 \text{ W/m} \cdot \text{K}}{6000 \text{ W/m}^2 \cdot \text{K} \times 0.005 \text{ m}} = 0.67$$

$$\frac{\theta_o}{\theta_i} = \frac{T_o - T_\infty}{T_i - T_\infty} = \frac{50 - 20}{335 - 20} = 0.095$$

it follows that $Fo \approx 0.80$, and

$$t_w = Fo \frac{r_o^2}{\alpha} \approx 0.80 \frac{(0.005 \text{ m})^2}{6.66 \times 10^{-6} \text{ m}^2/\text{s}} \approx 3.0 \text{ s}$$

Comments:

- 1. If the temperature distribution in the sphere at the conclusion of step 1 were not uniform, the Heisler chart could not be used for the calculations of step 2.
- The surface temperature of the sphere at the conclusion of step 2 may be obtained from Figure 5.15. With

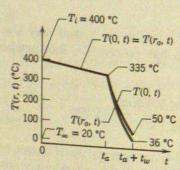
$$Bi^{-1} = 0.67$$
 and $\frac{r}{r_0} = 1$

$$\frac{\theta(r_o)}{\theta_o} = \frac{T(r_o) - T_\infty}{T_o - T_\infty} \approx 0.52$$

Hence

$$T(r_o) \approx 20^{\circ}\text{C} + 0.52(50 - 20)^{\circ}\text{C} \approx 36^{\circ}\text{C}$$

The variation of the center and surface temperature with time is then as follows.



3. For the step 2 transient process in water, the one-term approximation is appropriate for determining the time t_w at which the center temperature reaches 50°C, that is, $T(0, t_w) = 50$ °C. Rearranging Equation

$$F_0 = -\frac{1}{\zeta_1^2} \ln \left[\frac{\theta_o^*}{C_1} \right] = -\frac{1}{\zeta_1^2} \ln \left[\frac{1}{C_1} \times \frac{T(0, t_w) - T_\infty}{T_i - T_\infty} \right]$$

Using Table 5.1 to obtain the coefficients for Bi = 1/0.67 = 1.50 ($C_1 = 1.376$ and $\zeta_1 = 1.800$ rad) and substituting appropriate tempera-

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tures, it follows that

$$F_0 = -\frac{1}{(1.800 \text{ rad})^2} \ln \left[\frac{1}{1.376} \times \frac{(50 - 20)^{\circ} \text{C}}{(335 - 20)^{\circ} \text{C}} \right] = 0.82$$

Substituting for r_o and α , it follows that $t_w = 3.1$ s, which is within 3% of the value of 3.0 s obtained from the Heisler chart.

nclusion of step 1 d for the calcula-

ion of step 2 may

th time is then as

approximation is center temperaanging Equation

 $-\frac{T_{\infty}}{s}$

= 1/0.67 = 1.50 opriate tempera-

5.7 THE SEMI-INFINITE SOLID

Another simple geometry for which analytical solutions may be obtained is the semi-infinite solid. Since such a solid extends to infinity in all but one direction, it is characterized by a single identifiable surface (Figure 5.17). If a sudden change of conditions is imposed at this surface, transient, one-dimensional conduction will occur within the solid. The semi-infinite solid provides a useful idealization for many practical problems. It may be used to determine transient heat transfer near the surface of the earth or to approximate the transient response of a finite solid, such as a thick slab. For this second situation the approximation would be reasonable for the early portion of the transient, during which temperatures in the slab interior (well removed from the surface) are uninfluenced by the change in surface conditions.

The heat equation for transient conduction in a semi-infinite solid is given by Equation 5.26. The initial condition is prescribed by Equation 5.27, and the interior boundary condition is of the form

$$T(\infty, t) = T_i \tag{5.53}$$

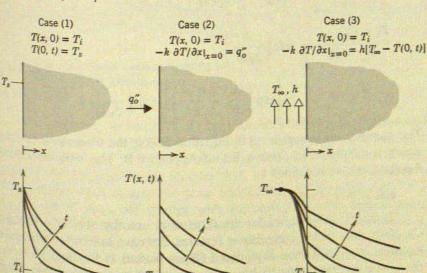


Figure 5.17 Transient temperature distributions in a semi-infinite solid for three surface conditions: constant surface temperature, constant surface heat flux, and surface convection.

Closed-form solutions have been obtained for three important surface conditions, instantaneously applied at t=0 [1,2]. These conditions are shown in Figure 5.17. They include application of a constant surface temperature $T_s \neq T_i$, application of a constant surface heat flux q_o'' , and exposure of the surface to a fluid characterized by $T_\infty \neq T_i$ and the convection coefficient h. The solutions are summarized as follows.

Case 1 Constant Surface Temperature

$$T(0,t) = T_s \tag{5.54}$$

$$\frac{T(x,t) - T_s}{T_i - T_s} = \operatorname{erf}\left(\frac{x}{2\sqrt{\alpha t}}\right) \tag{5.55}$$

$$q_s''(t) = -k \frac{\partial T}{\partial x} \bigg|_{x=0} = \frac{k(T_s - T_i)}{\sqrt{\pi \alpha t}}$$
 (5.56)

Case 2 Constant Surface Heat Flux

$$q_s^{\prime\prime} = q_o^{\prime\prime} \tag{5.57}$$

$$T(x,t) - T_i = \frac{2q_o''(\alpha t/\pi)^{1/2}}{k} \exp\left(\frac{-x^2}{4\alpha t}\right) - \frac{q_o''x}{k} \operatorname{erfc}\left(\frac{x}{2\sqrt{\alpha t}}\right)$$
 (5.58)

Case 3 Surface Convection

$$-k\frac{\partial T}{\partial x}\Big|_{x=0} = h[T_{\infty} - T(0,t)] \tag{5.59}$$

$$\frac{T(x,t) - T_i}{T_{\infty} - T_i} = \operatorname{erfc}\left(\frac{x}{2\sqrt{\alpha t}}\right)$$

$$-\left[\exp\left(\frac{hx}{k} + \frac{h^2\alpha t}{k^2}\right)\right] \left[\operatorname{erfc}\left(\frac{x}{2\sqrt{\alpha t}} + \frac{h\sqrt{\alpha t}}{k}\right)\right]$$
(5.60)

The quantity erf w appearing in Equation 5.55 is the Gaussian error function, which is tabulated in Section B.1 of Appendix B. The complementary error function, erfc w, is defined as

$$\operatorname{erfc} w \equiv 1 - \operatorname{erf} w$$

Temperature histories for the three cases are also shown in Figure 5.17. Carefully note their distinguishing features. For case 3 the specific temperature histories computed from Equation 5.60 are plotted in Figure 5.18. Note that the curve corresponding to $h=\infty$ is equivalent to the result that would be obtained for a sudden change in the surface temperature to $T_s=T_\infty$. That is, for $h=\infty$ the second term on the right-hand side of Equation 5.60 goes to zero, and the result is equivalent to Equation 5.55.

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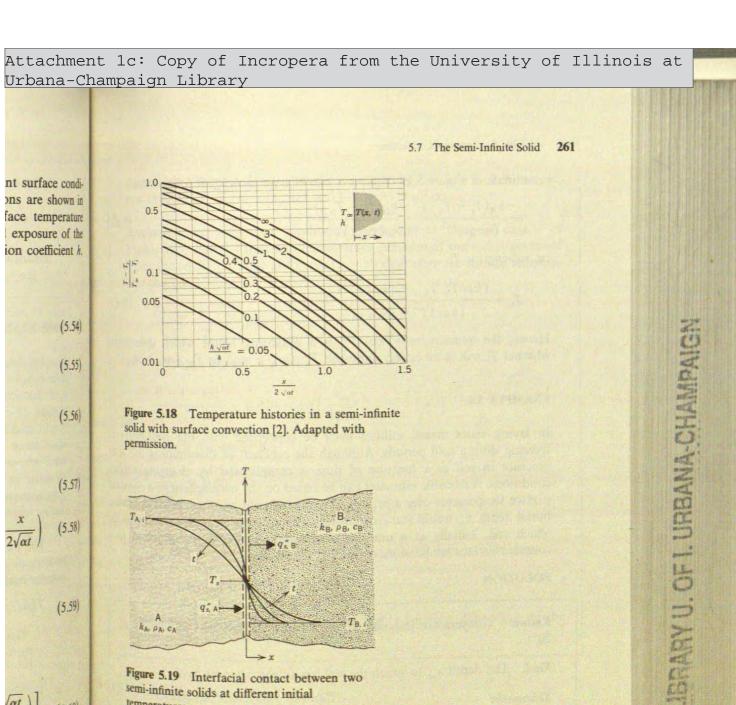
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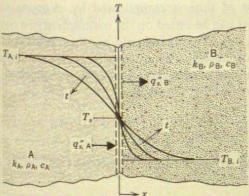


Figure 5.19 Interfacial contact between two semi-infinite solids at different initial temperatures.

An interesting permutation of case 1 results when two semi-infinite solids, initially at uniform temperatures $T_{A,i}$ and $T_{B,i}$, are placed in contact at their free surfaces (Figure 5.19). If the contact resistance is negligible, the requirement of thermal equilibrium dictates that, at the instant of contact (t = 0), both surfaces must assume the same temperature T_s , for which $T_{B,i} < T_s < T_s$ $T_{A,i}$. Since T_s does not change with increasing time, it follows that the transient thermal response and the surface heat flux of each of the solids is determined by Equations 5.55 and 5.56, respectively.

The equilibrium surface temperature of Figure 5.19 may be determined from a surface energy balance, which requires that

$$q_{s,A}^{"} = q_{s,B}^{"} \tag{5.61}$$

Substituting from Equation 5.56 for $q_{s,A}^{"}$ and $q_{s,B}^{"}$ and recognizing that the x



(5.58)

(5.59)

n error function, plementary error

in Figure 5.17. ific temperature 5.18. Note that that would be $=T_{\infty}$. That is, on 5.60 goes to

coordinate of Figure 5.19 requires a sign change for $q_{s,A}^{"}$, it follows that

$$\frac{-k_{\rm A}(T_s - T_{\rm A,i})}{(\pi \alpha_{\rm A} t)^{1/2}} = \frac{k_{\rm B}(T_s - T_{\rm B,i})}{(\pi \alpha_{\rm B} t)^{1/2}}$$
(5.62)

or, solving for $T_{\rm e}$,

$$T_{s} = \frac{(k\rho c)_{A}^{1/2} T_{A,i} + (k\rho c)_{B}^{1/2} T_{B,i}}{(k\rho c)_{A}^{1/2} + (k\rho c)_{B}^{1/2}}$$
(5.63)

Hence, the quantity $m \equiv (k\rho c)^{1/2}$ is a weighting factor which determines whether T_s will more closely approach $T_{A,i}(m_A > m_B)$ or $T_{B,i}(m_B > m_A)$.

EXAMPLE 5.4

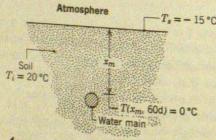
In laying water mains, utilities must be concerned with the possibility of freezing during cold periods. Although the problem of determining the temperature in soil as a function of time is complicated by changing surface conditions, reasonable estimates can be based on the assumption of a constant surface temperature over a prolonged period of cold weather. What minimum burial depth x_m would you recommend to avoid freezing under conditions for which soil, initially at a uniform temperature of 20°C, is subjected to a constant surface temperature of −15°C for 60 days?

SOLUTION

Temperature imposed at the surface of soil that is initially at

Find: The depth x_m to which the soil has frozen after 60 days.

Schematic:



Assumptions:

- 1. One-dimensional conduction in x.
- 2. Soil is a semi-infinite medium.
- 3. Constant properties.

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Properties: Table A.3, soil (300 K): $\rho = 2050 \text{ kg/m}^3$, $k = 0.52 \text{ W/m} \cdot \text{K}$, $c = 1840 \text{ J/kg} \cdot \text{K}$, $\alpha = (k/\rho c) = 0.138 \times 10^{-6} \text{ m}^2/\text{s}$.

Analysis: The prescribed conditions correspond to those of case 1 of Figure 5.17, and the transient temperature response of the soil is governed by Equation 5.55. Hence at the time t = 60 days after the surface temperature change,

$$\frac{T(x_m, t) - T_s}{T_i - T_s} = \operatorname{erf}\left(\frac{x_m}{2\sqrt{\alpha t}}\right)$$

or

$$\frac{0 - (-15)}{20 - (-15)} = 0.429 = \operatorname{erf}\left(\frac{x_m}{2\sqrt{\alpha t}}\right)$$

Hence from Appendix B.1

$$\frac{x_m}{2\sqrt{\alpha t}} = 0.40$$

and

$$x_m = 0.80\sqrt{\alpha t} = 0.80(0.138 \times 10^{-6} \text{ m}^2/\text{s} \times 60 \text{ days} \times 24 \text{ h/day}$$

 $\times 3600 \text{ s/h})^{1/2} = 0.68 \text{ m}$

Comments: The properties of soil are highly variable, depending on the nature of the soil and its moisture content.

5.8 MULTIDIMENSIONAL EFFECTS

Transient problems are frequently encountered for which two- and even three-dimensional effects are significant. Solution to a class of such problems can be obtained from the one-dimensional results of Sections 5.6 and 5.7.

Consider immersing the *short* cylinder of Figure 5.20, which is initially at a uniform temperature T_i , in a fluid of temperature $T_{\infty} \neq T_i$. Because the length and diameter are comparable, the subsequent transfer of energy by conduction will be significant for both the r and x coordinate directions. The temperature within the cylinder will therefore depend on r, x, and t.

Assuming constant properties and no generation, the appropriate form of the heat equation is, from Equation 2.20,

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial T}{\partial r}\right) + \frac{\partial^2 T}{\partial x^2} = \frac{1}{\alpha}\frac{\partial T}{\partial t}$$

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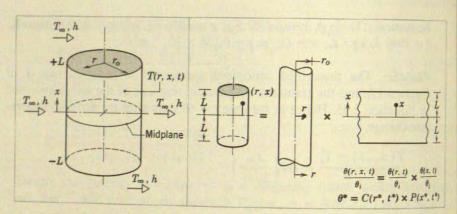


Figure 5.20 Two-dimensional, transient conduction in a short cylinder. (a) Geometry. (b) Form of the product solution.

where x has been used in place of z to designate the axial coordinate. A closed-form solution to this equation may be obtained by the separation of variables method. Although we will not consider the details of this solution, it is important to note that the end result may be expressed in the following form.

$$\frac{T(r, x, t) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(x, t) - T_{\infty}}{T_i - T_{\infty}} \left| \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}} \cdot \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \left| \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}} \cdot \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \left| \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}} \cdot \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}} \cdot \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \left| \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}} \cdot \frac{T(r, t) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(r, t) - T_{\infty}}{T_i$$

That is, the two-dimensional solution may be expressed as a product of one-dimensional solutions that correspond to those for a plane wall of thickness 2L and an infinite cylinder of radius r_o . These solutions are available from Figures 5.8 and 5.9 for the plane wall and Figures 5.11 and 5.12 for the infinite cylinder. They are also available from the one-term approximations given by Equations 5.40 and 5.49.

Results for other multidimensional geometries are summarized in Figure 5.21. In each case the multidimensional solution is prescribed in terms of a product involving one or more of the following one-dimensional solutions.

$$S(x,t) = \frac{T(x,t) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Semi-infinite} \\ \text{solid}}}$$
(5.64)

$$P(x,t) \equiv \frac{T(x,t) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Plane} \\ \text{well}}}$$
(5.65)

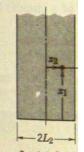
$$C(r,t) \equiv \frac{T(r,t) - T_{\infty}}{T_i - T_{\infty}} \left| \begin{array}{c} \text{Infinite} \\ \text{cylinder} \end{array} \right|$$
 (5.66)

The x coordinate for the semi-infinite solid is measured from the surface,

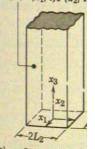


SI

Semi-infinite solid $S(x_1, t) P($



(d) Semi-infinite plate $S(x_3, t)P(x_1, t)P(x_2, t)$

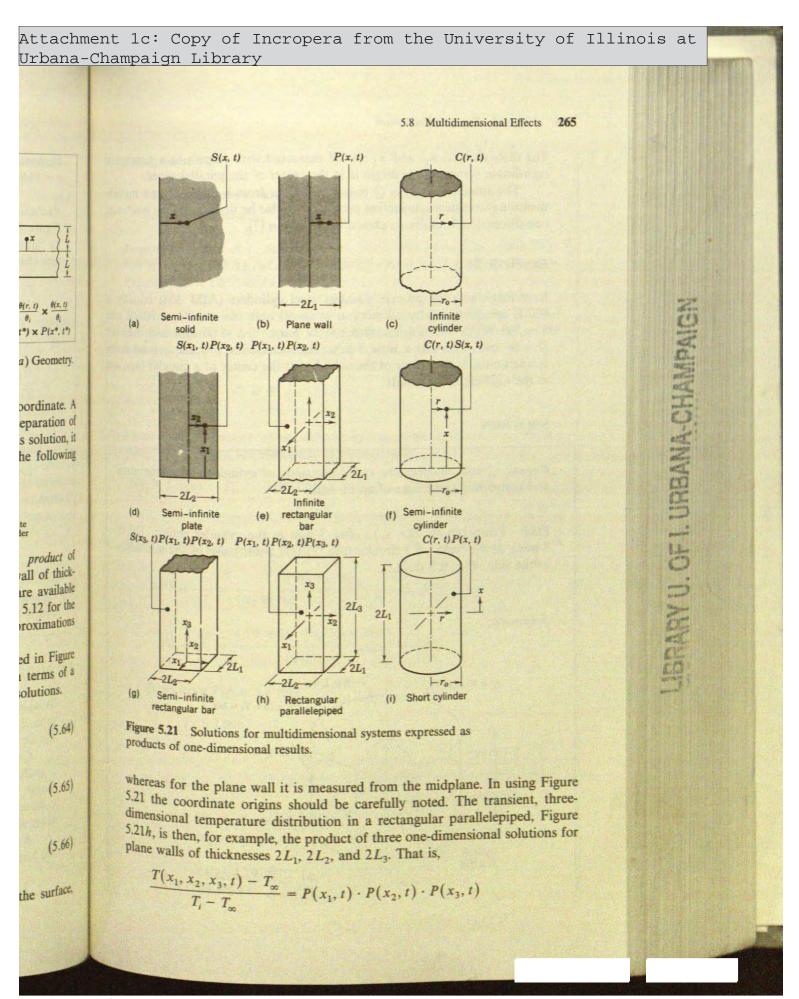


(g) Semi-infinite rectangular bar

Figure 5.21 Soluti products of one-dir

whereas for the p 5.21 the coordina dimensional temp 5.21h, is then, for plane walls of thi

$$\frac{T(x_1, x_2, x_3)}{T_i -}$$



The distances x_1 , x_2 , and x_3 are all measured with respect to a rectangular coordinate system whose origin is at the center of the parallelepiped.

The amount of energy Q transferred to or from a solid during a multidimensional transient conduction process may also be determined by combining one-dimensional results, as shown by Langston [7].

EXAMPLE 5.5

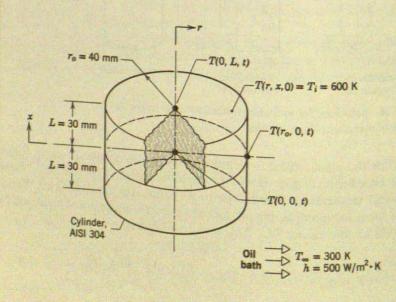
In a manufacturing process stainless steel cylinders (AISI 304) initially at 600 K are quenched by submersion in an oil bath maintained at 300 K with $h = 500 \text{ W/m}^2 \cdot \text{K}$. Each cylinder is of length 2L = 60 mm and diameter D = 80 mm. Consider a time 3 min into the cooling process and determine temperatures at the center of the cylinder, at the center of a circular face, and at the midheight of the side.

SOLUTION

Known: Initial temperature and dimensions of cylinder and temperature and convection conditions of an oil bath.

Find: Temperatures T(r, x, t) after 3 min at the cylinder center, T(0,0, 3 min), at the center of a circular face, T(0, L, 3 min), and at the midheight of the side, $T(r_o, 0, 3 \text{ min})$.

Schematic:



Assumptions:

- 1. Two-dim
- 2. Constant

Properties:

450 K]: $\rho = k/\rho c = 4.19$

Analysis: T the tempera following pr

 $\frac{T(r, x, T_i)}{T_i}$

where P(x, tively. Accordingly

 $\frac{T(0,0,3 \text{ mi})}{T_i - T_i}$

Hence, for t

 $Bi^{-1} =$

Fo =

it follows fr

 $\frac{\theta_o}{\theta_i} = \frac{1}{2}$

Similarly, fo

 $Bi^{-1} =$

Fo =

5.8 Multidimensional Effects 26

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04) initially at at 300 K with and diameter and determine cular face, and

temperature

nter, T(0,0, e midheight

Assumptions:

- 1. Two-dimensional conduction in r and x.
- 2. Constant properties.

Properties: Table A.1, stainless steel, AISI 304 [T = (600 + 300)/2 = 450 K]: $\rho = 7900 \text{ kg/m}^3$, $c = 526 \text{ J/kg} \cdot \text{K}$, $k = 17.4 \text{ W/m} \cdot \text{K}$, $\alpha = k/\rho c = 4.19 \times 10^{-6} \text{ m}^2/\text{s}$.

Analysis: The solid steel cylinder corresponds to case i of Figure 5.21, and the temperature at any point in the cylinder may be expressed as the following product of one-dimensional solutions.

$$\frac{T(r,x,t)-T_{\infty}}{T_{i}-T_{\infty}}=P(x,t)C(r,t)$$

where P(x, t) and C(r, t) are defined by Equations 5.65 and 5.66, respectively. Accordingly, for the center of the cylinder,

$$\frac{T(0,0,3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(0,3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \left|_{\substack{\text{Plane} \\ \text{wall}}} \cdot \frac{T(0,3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite} \\ \text{cylinder}}}$$

Hence, for the plane wall, with

$$Bi^{-1} = \frac{k}{hL} = \frac{17.4 \text{ W/m} \cdot \text{K}}{500 \text{ W/m}^2 \cdot \text{K} \times 0.03 \text{ m}} = 1.16$$

$$Fo = \frac{\alpha t}{L^2} = \frac{4.19 \times 10^{-6} \text{ m}^2/\text{s} \times 180 \text{ s}}{(0.03 \text{ m})^2} = 0.84$$

it follows from Figure 5.8 that

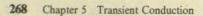
$$\frac{\theta_o}{\theta_i} = \frac{T(0, 3 \text{ min}) - T_\infty}{T_i - T_\infty} \bigg|_{\substack{\text{Plane} \\ \text{wall}}} \approx 0.64$$

Similarly, for the infinite cylinder, with

$$Bi^{-1} = \frac{k}{hr_o} = \frac{17.4 \text{ W/m} \cdot \text{K}}{500 \text{ W/m}^2 \cdot \text{K} \times 0.04 \text{ m}} = 0.87$$

$$F_0 = \frac{\alpha t}{r_o^2} = \frac{4.19 \times 10^{-6} \text{ m}^2/\text{s} \times 180 \text{ s}}{(0.04 \text{ m})^2} = 0.47$$

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it follows from Figure 5.11 that

$$\frac{\theta_o}{\theta_i} = \frac{T(0, 3 \text{ min}) - T_\infty}{T_i - T_\infty} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}} \approx 0.55$$

Hence, for the center of the cylinder,

$$\frac{T(0,0,3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \approx 0.64 \times 0.55 \approx 0.35$$

$$T(0,0,3 \text{ min}) \approx 300 \text{ K} + 0.35(600 - 300) \text{ K} \approx 405 \text{ K}$$

The temperature at the center of a circular face may be obtained from the requirement that

$$\frac{T(0, L, 3 \min) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(L, 3 \min) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Plane} \\ \text{wall}}} \cdot \frac{T(0, 3 \min) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}}$$

where, from Figure 5.9 with (x/L) = 1 and $Bi^{-1} = 1.16$,

$$\frac{\theta(L)}{\theta_o} = \frac{T(L, 3 \text{ min}) - T_{\infty}}{T(0, 3 \text{ min}) - T_{\infty}} \bigg|_{\substack{\text{Plane wall}}} \approx 0.68$$

Hence

$$\left. \frac{T(L, 3 \min) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Plane} \\ \text{wall}}} = \frac{T(L, 3 \min) - T_{\infty}}{T(0, 3 \min) - T_{\infty}} \left|_{\substack{\text{Plane} \\ \text{wall}}} \cdot \frac{T(0, 3 \min) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Plane} \\ \text{wall}}}$$

$$\frac{T(L, 3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Plane} \\ \text{wall}}} \approx 0.68 \times 0.64 \approx 0.44$$

Hence

$$\frac{T(0, L, 3 \min) - T_{\infty}}{T_{i} - T_{\infty}} \approx 0.44 \times 0.55 \approx 0.24$$

$$T(0, L, 3 \text{ min}) \approx 300 \text{ K} + 0.24(600 - 300) \text{ K} \approx 372 \text{ K}$$

The temperature at the midheight of the side may be obtained from the requirement that

$$\frac{T(r_o, 0, 3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} = \frac{T(0, 3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Plane} \\ \text{wall}}} \cdot \frac{T(r_o, 3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}}$$

where, from Fig

$$\frac{\theta(r_o)}{\theta_o} = \frac{T}{T}$$

Hence

$$\frac{T(r_o, 3 \min}{T_i - }$$

$$\frac{T(r_o, 3 \text{ min})}{T_c - 1}$$

Hence

$$\frac{T(r_o, 0, 3)}{T_i - T_i}$$

Comments:

- 1. Verify that 3 min) ≈ 3.
- 2. The one-ter less temper midplane to

$$\theta_o^* = \frac{1}{l}$$

where, with With Fo =

$$\frac{\theta_o}{\theta_i}$$
 Plan

where, from Figure 5.12 with $(r/r_o) = 1$ and $Bi^{-1} = 0.87$,

$$\frac{\theta(r_o)}{\theta_o} = \frac{T(r_o, 3 \text{ min}) - T_\infty}{T(0, 3 \text{ min}) - T_\infty} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}} \approx 0.61$$

Hence

$$\frac{T(r_o, 3 \text{ min}) - T_\infty}{T_i - T_\infty} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}} = \frac{T(r_o, 3 \text{ min}) - T_\infty}{T(0, 3 \text{ min}) - T_\infty} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}}$$

$$\left| \frac{T(0, 3 \text{ min}) - T_{\infty}}{T_i - T_{\infty}} \right|_{\substack{\text{Infinite cylinder}}}$$

$$\frac{T(r_o, 3 \text{ min}) - T_\infty}{T_i - T_\infty} \bigg|_{\substack{\text{Infinite} \\ \text{cylinder}}} \approx 0.61 \times 0.55 \approx 0.34$$

Hence

$$\frac{T(r_o, 0, 3 \text{ min}) - T_\infty}{T_i - T_\infty} \approx 0.64 \times 0.34 \approx 0.22$$

$$T(r_o, 0, 3 \text{ min}) \approx 300 \text{ K} + 0.22(600 - 300) \text{ K} \approx 366 \text{ K}$$

Comments:

- 1. Verify that the temperature at the edge of the cylinder is $T(r_o, L, 3 \text{ min}) \approx 345 \text{ K}$
- 2. The one-term approximations can be used to calculate the dimensionless temperatures read from the Heisler charts. For the plane wall, the midplane temperature can be determined from Equation 5.41

$$\theta_o^* = \frac{\theta_o}{\theta_i} = C_1 \exp\left(-\zeta_1^2 F_O\right)$$

where, with Bi = 0.862, $C_1 = 1.109$ and $\zeta_1 = 0.814$ rad from Table 5.1. With $F_0 = 0.84$,

$$\frac{\theta_o}{\theta_i}\Big|_{\substack{\text{Plane} \\ \text{wall}}} = 1.109 \exp\left[-(0.814 \text{ rad})^2 \times 0.84\right] = 0.636$$

 $\frac{1}{T_{\infty}} - \frac{1}{T_{\infty}}$ Infinite cylinder

ained from the

 $\frac{\operatorname{nin}) - T_{\infty}}{-T_{\infty}}\Big|_{\substack{\text{Plane} \\ \text{wall}}}$

ned from the

 $\frac{1}{r_{\infty}} - \frac{1}{r_{\infty}}$ Infinite cylinder

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The surface temperature can be evaluated using Equation 5.40b

$$\frac{\theta^*}{\theta_o^*} = \frac{\theta}{\theta_o} = \cos\left(\zeta_1 x^*\right)$$

with $x^* = 1$ to give

$$\frac{\theta^*(1, F_0)}{\theta_0^*} = \frac{\theta(L, t)}{\theta_0} = \cos(0.814 \text{ rad} \times 1) = 0.687$$

For the *infinite cylinder*, the centerline temperature can be determined from Equation 5.49c.

$$\theta_o^* = \frac{\theta_o}{\theta_i} = C_1 \exp\left(-\zeta_1^2 F_O\right)$$

where, with Bi = 1.15, $C_1 = 1.227$ and $\zeta_1 = 1.307$ from Table 5.1. With Fo = 0.47,

$$\left. \frac{\theta_o}{\theta_i} \right|_{\substack{\text{Infinite} \\ \text{cylinder}}} = 1.109 \exp\left[-(1.307 \text{ rad})^2 \times 0.47 \right] = 0.550$$

The surface temperature can be evaluated using Equation 5.49b

$$\frac{\theta^*}{\theta_o^*} = \frac{\theta}{\theta_o} = J_0(\zeta_1 r^*)$$

with $r^* = 1$ and the value of the Bessel function determined from Table B.4.

$$\frac{\theta^*(1, F_0)}{\theta_o^*} = \frac{\theta(L, t)}{\theta_o} = J_0(1.307 \text{ rad} \times 1) = 0.616$$

The one-term approximations are in good agreement with results from the Heisler charts

5.9 FINITE-DIFFERENCE METHODS

Analytical solutions to transient problems are restricted to simple geometries and boundary conditions, such as those considered in the preceding sections. Extensive coverage of these and other solutions is treated in the literature [1-4]. However, in many cases the geometry and/or boundary conditions preclude the use of analytical techniques, and recourse must be made to

5.9.1

.40b

finite-difference methods. Such methods, introduced in Section 4.4 for steady-state conditions, are readily extended to transient problems. In this section we consider *explicit* and *implicit* forms of finite-difference solutions to transient conduction problems. More detailed treatments, as well as related algorithms, may be found in the literature [8–10].

5.9.1 Discretization of the Heat Equation: The Explicit Method

Once again consider the two-dimensional system of Figure 4.5. Under transient conditions with constant properties and no internal generation, the appropriate form of the heat equation, Equation 2.15, is

$$\frac{1}{\alpha} \frac{\partial T}{\partial t} = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \tag{5.67}$$

To obtain the finite-difference form of this equation, we may use the *central-difference* approximations to the spatial derivatives prescribed by Equations 4.31 and 4.32. Once again the m and n subscripts may be used to designate the x and y locations of discrete nodal points. However, in addition to being discretized in space, the problem must be discretized in time. The integer p is introduced for this purpose, where

$$t = p \Delta t \tag{5.68}$$

and the finite-difference approximation to the time derivative in Equation 5.67 is expressed as

$$\left. \frac{\partial T}{\partial t} \right|_{m,n} \approx \frac{T_{m,n}^{p+1} - T_{m,n}^{p}}{\Delta t}$$
 (5.69)

The superscript p is used to denote the time dependence of T, and the time derivative is expressed in terms of the difference in temperatures associated with the new (p+1) and previous (p) times. Hence calculations must be performed at successive times separated by the interval Δt , and just as a finite-difference solution restricts temperature determination to discrete points in space, it also restricts it to discrete points in time.

If Equation 5.69 is substituted into Equation 5.67, the nature of the finite-difference solution will depend on the specific time at which temperatures are evaluated in the finite-difference approximations to the spatial derivatives. In the explicit method of solution, these temperatures are evaluated at the previous (p) time. Hence Equation 5.69 is considered to be a forward-difference approximation to the time derivative. Evaluating terms on the right-hand side of Equations 4.31 and 4.32 at p and substituting into Equation 5.67, the explicit form of the finite-difference equation for the

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interior node m, n is

$$\frac{1}{\alpha} \frac{T_{m,n}^{p+1} - T_{m,n}^{p}}{\Delta t} = \frac{T_{m+1,n}^{p} + T_{m-1,n}^{p} - 2T_{m,n}^{p}}{(\Delta x)^{2}} + \frac{T_{m,n+1}^{p} + T_{m,n-1}^{p} - 2T_{m,n}^{p}}{(\Delta y)^{2}}$$
(5.70)

Solving for the nodal temperature at the new (p + 1) time and assuming that $\Delta x = \Delta y$, it follows that

$$T_{m,n}^{p+1} = Fo(T_{m+1,n}^p + T_{m-1,n}^p + T_{m,n+1}^p + T_{m,n-1}^p) + (1 - 4Fo)T_{m,n}^p$$
(5.71)

where Fo is a finite-difference form of the Fourier number

$$Fo = \frac{\alpha \,\Delta t}{\left(\Delta x\right)^2} \tag{5.72}$$

If the system is one-dimensional in x, the explicit form of the finite-difference equation for an interior node m reduces to

$$T_m^{p+1} = Fo(T_{m+1}^p + T_{m-1}^p) + (1 - 2Fo)T_m^p$$
 (5.73)

Equations 5.71 and 5.73 are explicit because unknown nodal temperatures for the new time are determined exclusively by known nodal temperatures at the previous time. Hence calculation of the unknown temperatures is straightforward. Since the temperature of each interior node is known at t=0 (p=0) from prescribed initial conditions, the calculations begin at $t=\Delta t$ determine its temperature. With temperatures known for $t=\Delta t$, the appropriate finite-difference equation is then applied at each node to determine its temperature at $t=2\Delta t$ (p=2). In this way, the transient temperature distribution is obtained by marching out in time, using intervals of Δt .

The accuracy of the finite-difference solution may be improved by decreasing the values of Δx and Δt . Of course, the number of interior nodal points that must be considered increases with decreasing Δx , and the number of time intervals required to carry the solution to a prescribed final time increases with decreasing Δt . Hence, the computation time increases with decreasing Δx and Δt . The choice of Δx is typically based on a compromise between accuracy and computational requirements. Once this selection has been made, however, the value of Δt may not be chosen independently. It is instead, determined by stability requirements.

An undesirable feature of the explicit method is that it is not unconditionally stable. In a transient problem, the solution for the nodal temperatures should continuously approach final (steady-state) values with increasing time. However, with the explicit method, this solution may be characterized by numerically induced oscillations, which are physically impossible. The oscillations may become unstable, causing the solution to diverge from the actual steady-state conditions. To prevent such erroneous results, the prescribed value of Δt must be maintained below a certain limit, which depends on Δx and other parameters of the system. This dependence is termed a stability criterion, which may be obtained mathematically [8] or demonstrated from a thermodynamic argument (see Problem 5.69). For the problems of interest in this text, the criterion is determined by requiring that the coefficient associated with the node of interest at the previous time is greater than or equal to zero. In general, this is done by collecting all terms involving $T_{m,n}^p$ to obtain the form of the coefficient. This result is then used to obtain a limiting relation involving Fo, from which the maximum allowable value of Δt may be determined. For example, with Equations 5.71 and 5.73 already expressed in the desired form, it follows that the stability criterion for a one-dimensional interior node is $(1 - 2Fo) \ge 0$, or

$$F_0 \le \frac{1}{2} \tag{5.74}$$

and for a two-dimensional node, it is $(1 - 4Fo) \ge 0$, or

$$Fo \le \frac{1}{4} \tag{5.75}$$

For prescribed values of Δx and α , these criteria may be used to determine upper limits to the value of Δt .

Equations 5.71 and 5.73 may also be derived by applying the energy balance method of Section 4.4.3 to a control volume about the interior node. Accounting for changes in thermal energy storage, a general form of the energy balance equation may be expressed as

$$\dot{E}_{\rm in} + \dot{E}_{\rm g} = \dot{E}_{\rm st} \tag{5.76}$$

In the interest of adopting a consistent methodology, it is again assumed that all heat flow is *into* the node.

To illustrate application of Equation 5.76, consider the surface node of the one-dimensional system shown in Figure 5.22. To more accurately determine thermal conditions near the surface, this node has been assigned a thickness which is one-half that of the interior nodes. Assuming convection transfer from an adjoining fluid and no generation, it follows from Equation 5.76 that

$$hA(T_{\infty} - T_0^p) + \frac{kA}{\Delta x}(T_1^p - T_0^p) = \rho cA \frac{\Delta x}{2} \frac{T_0^{p+1} - T_0^p}{\Delta t}$$

(5.70)

assuming that

(5.71)

(5.72)

rite-difference

(5.73)

temperatures at es is straightwn at t = 0 in at $t = \Delta t$ rior node to the appropridetermine its temperature of Δt .

roved by denterior nodal I the number of final time ccreases with compromise selection has idently. It is, JERARY U. OF I. URBANA-CHAMPAICN

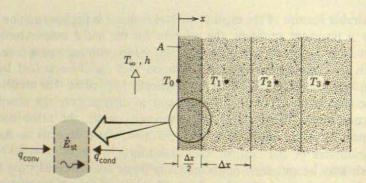


Figure 5.22 Surface node with convection and one-dimensional transient conduction.

or, solving for the surface temperature at $t + \Delta t$,

$$T_0^{p+1} = \frac{2h\,\Delta t}{\rho c\,\Delta x} \big(T_\infty - T_0^p\big) + \frac{2\alpha\,\Delta t}{\Delta x^2} \big(T_1^p - T_0^p\big) + T_0^p$$

Recognizing that $(2h \Delta t/\rho c \Delta x) = 2(h \Delta x/k)(\alpha \Delta t/\Delta x^2) = 2BiFo$ and grouping terms involving T_0^p , it follows that

$$T_0^{p+1} = 2Fo(T_1^p + BiT_{\infty}) + (1 - 2Fo - 2BiFo)T_0^p$$
 (5.77)

The finite-difference form of the Biot number is

$$Bi = \frac{h \, \Delta x}{k} \tag{5.78}$$

Recalling the procedure for determining the stability criterion, we require that the coefficient for T_0^p be greater than or equal to zero. Hence

$$1 - 2Fo - 2BiFo \ge 0$$

$$Fo(1+Bi) \le \frac{1}{2} \tag{5.79}$$

Since the complete finite-difference solution requires the use of Equation 5.73 for the interior nodes, as well as Equation 5.77 for the surface node, Equation 5.79 must be contrasted with Equation 5.74 to determine which requirement is the more stringent. Since $Bi \ge 0$, it is apparent that the limiting value of Fo for Equation 5.79 is less than that for Equation 5.74. To ensure stability for all nodes, Equation 5.79 should therefore be used to select the maximum allowable value of Fo, and hence Δt , to be used in the calculations.

Forms of the explicit finite-difference equation for several common geometries are presented in Table 5.2. Each equation may be derived by applying the energy balance method to a control volume about the corresponding node. To develop confidence in your ability to apply this method, you should attempt to verify at least one of these equations.

Table 5.2 Summary of transient, two-dimensional finite-difference equations $(\Delta x = \Delta y)$

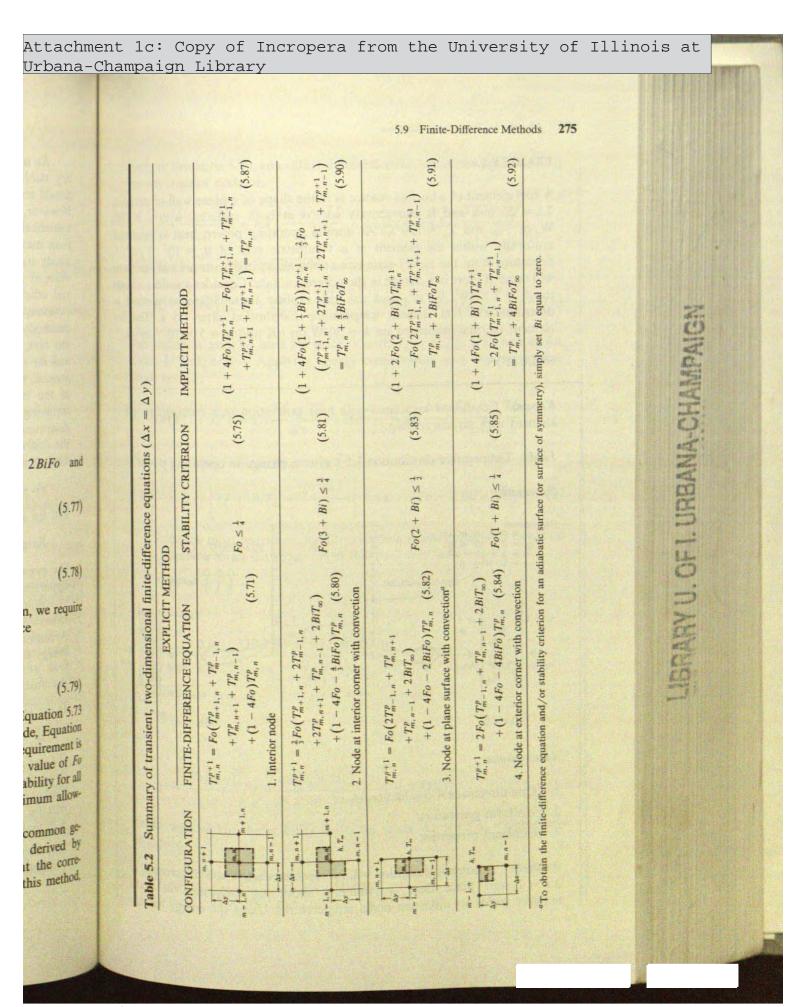
IMPLICIT METHOD

CRITERION

STABILITY

FINITE-DIFFERENCE EQUATION

CONFIGURATION



EXAMPLE 5.6

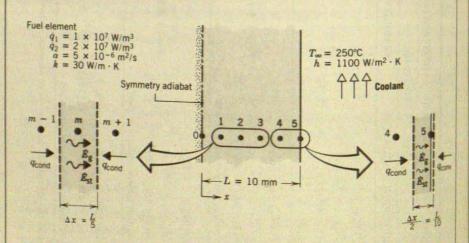
A fuel element of a nuclear reactor is in the shape of a plane wall of thickness $2L=20\,$ mm and is convectively cooled at both surfaces, with $h=1100\,$ W/m²·K and $T_{\infty}=250\,^{\circ}\text{C}$. At normal operating power, heat is generated uniformly within the element at a volumetric rate of $\dot{q}_1=10^7\,$ W/m³. A departure from the steady-state conditions associated with normal operation will occur if there is a change in the generation rate. Consider a sudden change to $\dot{q}_2=2\times10^7\,$ W/m³, and use the explicit finite-difference method to determine the fuel element temperature distribution after 1.5 s. The fuel element thermal properties are $k=30\,$ W/m·K and $\alpha=5\times10^{-6}\,$ m²/s.

SOLUTION

Known: Conditions associated with heat generation in a rectangular fuel element with surface cooling.

Find: Temperature distribution 1.5 s after a change in operating power.

Schematic:



Assumptions:

- 1. One-dimensional conduction in x.
- 2. Uniform generation.
- 3. Constant properties.

Analysis: A numerical solution will be obtained using a space increment of $\Delta x = 2$ mm. Since there is symmetry about the midplane, the nodal network yields six unknown nodal temperatures. Using the energy balance

method, Equation for any interior

$$kA\frac{T_{m-1}^p-}{\Delta x}$$

Solving for T_m^p

$$T_m^{p+1} = Fc$$

This equation nodes 1, 2, 3, about node 5,

$$hA(T_{\infty} -$$

or

$$T_5^{p+1} = 2Fo$$

Since the 12, we select Fo

$$Fo(1+B)$$

Hence, with

$$Bi = \frac{h \, \Delta x}{k}$$

it follows that

$$Fo \leq 0.46$$

Or

$$\Delta t = \frac{Fo}{}$$

To be well wisponds to

$$F_0 = \frac{5 \times 10^{-5}}{10^{-5}}$$

wall of thickness s, with h = 1100heat is generated = 10^7 W/m³. A normal operation a sudden change tence method to

1.5 s. The fuel $\times 10^{-6} \text{ m}^2/\text{s}$.

ctangular fuel

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n² - K

increment of e, the nodal tergy balance method, Equation 5.76, an explicit finite-difference equation may be derived for any interior node m.

$$kA\frac{T_{m-1}^{p}-T_{m}^{p}}{\Delta x}+kA\frac{T_{m+1}^{p}-T_{m}^{p}}{\Delta x}+\dot{q}A\Delta x=\rho A\Delta xc\frac{T_{m}^{p+1}-T_{m}^{p}}{\Delta t}$$

Solving for T_m^{p+1} and rearranging,

$$T_m^{p+1} = Fo \left[T_{m-1}^p + T_{m+1}^p + \frac{\dot{q}(\Delta x)^2}{k} \right] + (1 - 2Fo)T_m^p \tag{1}$$

This equation may be used for node 0, with $T_{m-1}^p = T_{m+1}^p$, as well as for nodes 1, 2, 3, and 4. Applying energy conservation to a control volume about node 5,

$$hA(T_{\infty} - T_5^p) + kA\frac{T_4^p - T_5^p}{\Delta x} + \dot{q}A\frac{\Delta x}{2} = \rho A\frac{\Delta x}{2}c\frac{T_5^{p+1} - T_5^p}{\Delta t}$$

01

$$T_5^{p+1} = 2Fo \left[T_4^p + BiT_\infty + \frac{\dot{q}(\Delta x)^2}{2k} \right] + (1 - 2Fo - 2BiFo)T_5^p$$
 (2)

Since the most restrictive stability criterion is associated with Equation 2, we select Fo from the requirement that

$$Fo(1+Bi) \leq \frac{1}{2}$$

Hence, with

$$Bi = \frac{h \Delta x}{k} = \frac{1100 \text{ W/m}^2 \cdot \text{K (0.002 m)}}{30 \text{ W/m} \cdot \text{K}} = 0.0733$$

it follows that

or

$$\Delta t = \frac{Fo(\Delta x)^2}{\alpha} \le \frac{0.466(2 \times 10^{-3} \text{ m})^2}{5 \times 10^{-6} \text{ m}^2/\text{s}} \le 0.373 \text{ s}$$

To be well within the stability limit, we select $\Delta t = 0.3$ s, which corresponds to

$$F_0 = \frac{5 \times 10^{-6} \text{ m}^2/\text{s}(0.3 \text{ s})}{(2 \times 10^{-3} \text{ m})^2} = 0.375$$

Substituting numerical values, including $\dot{q} = \dot{q}_2 = 2 \times 10^7 \text{ W/m}^3$, the nodal equations become

$$T_0^{p+1} = 0.375(2T_1^p + 2.67) + 0.250T_0^p$$

$$T_1^{p+1} = 0.375(T_0^p + T_2^p + 2.67) + 0.250T_1^p$$

$$T_2^{p+1} = 0.375(T_1^p + T_3^p + 2.67) + 0.250T_2^p$$

$$T_3^{p+1} = 0.375(T_2^p + T_4^p + 2.67) + 0.250T_3^p$$

$$T_4^{p+1} = 0.375(T_3^p + T_5^p + 2.67) + 0.250T_4^p$$

$$T_5^{p+1} = 0.750(T_4^p + 19.67) + 0.195T_5^p$$

To begin the marching solution, the initial temperature distribution must be known. This distribution is given by Equation 3.42, with $\dot{q} = \dot{q}_1$. Obtaining $T_s = T_5$ from Equation 3.46,

$$T_5 = T_{\infty} + \frac{\dot{q}L}{h} = 250^{\circ}\text{C} + \frac{10^7 \text{ W/m}^3 \times 0.01 \text{ m}}{1100 \text{ W/m}^2 \cdot \text{K}} = 340.91^{\circ}\text{C}$$

it follows that

$$T(x) = 16.67 \left(1 - \frac{x^2}{L^2}\right) + 340.91$$
°C

Computed temperatures for the nodal points of interest are shown in the first row of the accompanying table.

Using the finite-difference equations, the nodal temperatures may be sequentially calculated with a time increment of 0.3 s until the desired final time is reached. The results are illustrated in rows 2 through 6 of the table and may be contrasted with the new steady-state condition (row 7), which was obtained by using Equations 3.42 and 3.46 with $\dot{q} = \dot{q}_2$,

Tabulated nodal	temperatures
-----------------	--------------

p t	(s)	T_0	T_1	T ₂	<i>T</i> ₃	T	-
0 0	10 1	357.58			Sent State of the	T_4	T_5
			356.91	354.91	351.58	346.91	340.91
1 0.	3	358.08	357.41	355.41	352.08		
2 0.	6	358.58	357.91			347.41	341.41
3 0	9			The state of the s	352.58	347.91	341.88
		359.08	358.41	356.41	353.08	348.41	342.35
4 1.	2	359.58	358.91	356.91			
5 1.	5	360.08	359.41		353.58	348.89	342.82
∞ ∞					354.07	349.37	343.27
-		465.15	463.82	459.82	453.15	443.82	
		THE PERSON			The state of the s	443.82	431.82

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)7 W/m3, the nodal

Comments: It is evident that at 1.5 s, the wall is in the early stages of the transient process and that many additional calculations would have to be made to reach steady-state conditions with the finite-difference solution. The computation time could be slightly reduced by using the maximum allowable time increment ($\Delta t = 0.373$ s), but with some loss of accuracy. In the interest of maximizing accuracy, the time interval should be reduced until the computed results become independent of further reductions in Δt .

rature distribution 3.42, with $\dot{q} = \dot{q}_1$.

340.91°C

are shown in the

iperatures may be il the desired final ugh 6 of the table on (row 7), which \dot{q}_2 ,

5.9.2 Discretization of the Heat Equation: The Implicit Method

In the explicit finite-difference scheme, the temperature of any node at $t + \Delta t$ may be calculated from knowledge of temperatures at the same and neighboring nodes for the preceding time t. Hence, determination of a nodal temperature at some time is independent of temperatures at other nodes for the same time. Although the method offers computational convenience, it suffers from limitations on the selection of Δt . For a given space increment, the time interval must be compatible with stability requirements. Frequently, this dictates the use of extremely small values of Δt , and a very large number of time intervals may be necessary to obtain a solution.

A reduction in the amount of computation time may often be realized by employing an *implicit*, rather than explicit, finite-difference scheme. The implicit form of a finite-difference equation may be derived by using Equation 5.69 to approximate the time derivative, while evaluating all other temperatures at the new(p+1) time, instead of the previous (p) time. Equation 5.69 is then considered to provide a backward-difference approximation to the time derivative. In contrast to Equation 5.70, the implicit form of the finite-difference equation for the interior node of a two-dimensional system is then

$$\frac{1}{\alpha} \frac{T_{m,n}^{p+1} - T_{m,n}^{p}}{\Delta t} = \frac{T_{m+1,n}^{p+1} + T_{m-1,n}^{p+1} - 2T_{m,n}^{p+1}}{(\Delta x)^{2}} + \frac{T_{m,n+1}^{p+1} + T_{m,n-1}^{p+1} - 2T_{m,n}^{p+1}}{(\Delta y)^{2}}$$
(5.86)

Rearranging and assuming $\Delta x = \Delta y$, it follows that

$$(1+4Fo)T_{m,n}^{p+1} - Fo(T_{m+1,n}^{p+1} + T_{m-1,n}^{p+1} + T_{m,n+1}^{p+1} + T_{m,n-1}^{p+1}) = T_{m,n}^{p}$$
(5.87)

From Equation 5.87 it is evident that the *new* temperature of the *m*, *n* node depends on the *new* temperatures of its adjoining nodes, which are, in

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general, unknown. Hence, to determine the unknown nodal temperatures at $t + \Delta t$, the corresponding nodal equations must be solved simultaneously. Such a solution may be effected by using Gauss-Seidel iteration or matrix inversion, as discussed in Section 4.5. The marching solution would then involve simultaneously solving the nodal equations at each time $t = \Delta t, 2\Delta t, \ldots$, until the desired final time was reached.

Although computations involving the implicit method are more complicated than those of the explicit method, the implicit formulation has the important advantage of being unconditionally stable. That is, the solution remains stable for all space and time intervals, in which case there are no restrictions on Δx and Δt . Since larger values of Δt may therefore be used with an implicit method, computation times may often be reduced, with little loss of accuracy. Nevertheless, to maximize accuracy, Δt should be sufficiently small to ensure that the results are independent of further reductions in its value.

The implicit form of a finite-difference equation may also be derived from the energy balance method. For the surface node of Figure 5.22, it is readily shown that

$$(1 + 2Fo + 2FoBi)T_0^{p+1} - 2FoT_1^{p+1} = 2FoBiT_{\infty} + T_0^p$$
 (5.88)

For any interior node of Figure 5.22, it may also be shown that

$$(1+2Fo)T_m^{p+1} - Fo(T_{m-1}^{p+1} + T_{m+1}^{p+1}) = T_m^p$$
(5.89)

Forms of the implicit finite-difference equation for other common geometries are presented in Table 5.2. Each equation may be derived by applying the energy balance method.

EXAMPLE 5.7

A thick slab of copper initially at a uniform temperature of 20°C is suddenly exposed to radiation at one surface such that the net heat flux is maintained at a constant value of 3×10^5 W/m². Using the explicit and implicit finite-difference techniques with a space increment of $\Delta x = 75$ mm, determine the temperature at the irradiated surface and at an interior point that is 150 mm from the surface after 2 min have elapsed. Compare the results with those obtained from an appropriate analytical solution.

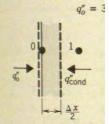
SOLUTION

Known: Thick slab of copper, initially at a uniform temperature, is subjected to a constant net heat flux at one surface.

Find:

- 1. Using the exp the surface as min.
- 2. Repeat the ca
- 3. Determine th

Schematic:



Assumptions:

- 1. One-dimension
- 2. Thick slab constant surf
- 3. Constant pro

Properties: Tab. 10⁻⁶ m²/s.

Analysis:

1. An explicit 1 may be obta about the no

 $q_o^{\prime\prime}A$ +

or

 T_0^{p+1} :

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5.9 Finite-Difference Methods 2

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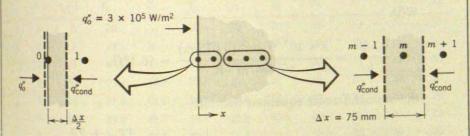
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50 mm those

- 1. Using the explicit finite-difference method, determine temperatures at the surface and 150 mm from the surface after an elapsed time of 2 min.
- 2. Repeat the calculations using the implicit finite-difference method.
- 3. Determine the same temperatures analytically.

Schematic:



Assumptions:

- 1. One-dimensional conduction in x.
- 2. Thick slab may be approximated as a semi-infinite medium with constant surface heat flux.
- 3. Constant properties.

Properties: Table A.1, copper (300 K): k = 401 W/m·K, $\alpha = 117 \times 10^{-6}$ m²/s.

Analysis:

 An explicit form of the finite-difference equation for the surface node may be obtained by applying an energy balance to a control volume about the node.

$$q_o''A + kA \frac{T_1^p - T_0^p}{\Delta x} = \rho A \frac{\Delta x}{2} c \frac{T_0^{p+1} - T_0^p}{\Delta t}$$

0

$$T_0^{p+1} = 2Fo\left(\frac{q_o''\Delta x}{k} + T_1^p\right) + (1 - 2Fo)T_0^p$$

The finite-difference equation for any interior node is given by Equation 5.73. Both the surface and interior nodes are governed by the

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stability criterion

$$Fo \leq \frac{1}{2}$$

Noting that the finite-difference equations are simplified by choosing the maximum allowable value of F_0 , we select $F_0 = \frac{1}{2}$. Hence

$$\Delta t = Fo \frac{(\Delta x)^2}{\alpha} = \frac{1}{2} \frac{(0.075 \text{ m})^2}{117 \times 10^{-6} \text{ m}^2/\text{s}} = 24 \text{ s}$$

With

$$\frac{q_o'' \Delta x}{k} = \frac{3 \times 10^5 \text{ W/m}^2 (0.075 \text{ m})}{401 \text{ W/m} \cdot \text{K}} = 56.1 \text{°C}$$

the finite-difference equations become

$$T_0^{p+1} = 56.1$$
°C + T_1^p and $T_m^{p+1} = \frac{T_{m+1}^p + T_{m-1}^p}{2}$

for the surface and interior nodes, respectively. Performing the calculations, the results are tabulated as follows.

t (s)	T_0	T_1	T ₂	<i>T</i> ₃	T ₄
0	20	20	20	20	20
24	76.1	20	20	20	20
48	76.1	48.1	20	20	20
72	104.2	48.1	34.1	20	20
96	104.2	69.1	34.1	27.1	20
120	125.3	69.1	48.1	27.1	20

After 2 min, the surface temperature and the desired interior temperature are $T_0 = 125.3$ °C and $T_2 = 48.1$ °C.

Note that calculation of identical temperatures at successive times for the same node is an idiosyncrasy of using the maximum allowable value of Fo with the explicit finite-difference technique. The actual physical condition is, of course, one in which the temperature changes continuously with time. The idiosyncrasy is eliminated and the accuracy of the calculations is improved by reducing the value of Fo.

To determine the extent to which the accuracy may be improved by reducing F_0 , let us redo the calculations for $F_0 = \frac{1}{4}(\Delta t = 12 \text{ s})$. The

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 T_m^{p+1}

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p	t (s)
0	0
1	12
2	24

2 24 3 36 4 48

5 60 6 72

7 84 8 96

9 108 10 120

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5.9 Finite-Difference Methods

finite-difference equations are then of the form

$$T_0^{p+1} = \frac{1}{2} (56.1^{\circ}\text{C} + T_1^p) + \frac{1}{2} T_0^p$$

$$T_m^{p+1} = \frac{1}{4} (T_{m+1}^p + T_{m-1}^p) + \frac{1}{2} T_m^p$$

and the results of the calculations are tabulated as follows.

p	t (s)	T_0	T_1	T_2	T_3	T_4	T_5	T_6	<i>T</i> ₇	T_8
0	0	20	20	20	20	20	20	20	20	.20
1	12	48.1	20	20	20	20	20	20	20	20
2	24	62.1	27.0	20	20	20	20	20	20	20
3	36	72.6	34.0	21.8	20	20	20	20	20	20
4	48	81.4	40.6	24.4	20.4	20	20	20	20	20
5	60	89.0	46.7	27.5	21.3	20.1	20	20	20	20
6	72	95.9	52.5	30.7	22.6	20.4	20.0	20	20	20
7	84	102.3	57.9	34.1	24.1	20.8	20.1	20.0	20	20
8	96	108.1	63.1	37.6	25.8	21.5	20.3	20.0	20.0	20
9	108	113.7	68.0	41.0	27.6	22.2	20.5	20.1	20.0	20.0
10	120	118.9	72.6	44.4	29.6	23.2	20.8	20.2	20.0	20.0

After 2 min, the desired temperatures are $T_0 = 118.9^{\circ}\text{C}$ and $T_2 = 44.4^{\circ}\text{C}$. Comparing the above results with those obtained for $F_0 = \frac{1}{2}$, it is clear that by reducing F_0 we have eliminated the problem of recurring temperatures. We have also predicted greater thermal penetration (to node 6 instead of node 3). An assessment of the improvement in accuracy must await a comparison with results based on an exact solution.

 Performing an energy balance on a control volume about the surface node, the implicit form of the finite-difference equation is

$$q_o'' + k \frac{T_1^{p+1} - T_0^{p+1}}{\Delta x} = \rho \frac{\Delta x}{2} c \frac{T_0^{p+1} - T_0^p}{\Delta t}$$

or,

$$(1+2Fo)T_0^{p+1}-2FoT_1^{p+1}=\frac{2\alpha q_o'' \Delta t}{k \Delta x}+T_0^p$$

Arbitrarily choosing $F_0 = \frac{1}{2}(\Delta t = 24 \text{ s})$, it follows that

$$2T_0^{p+1} - T_1^{p+1} = 56.1 + T_0^p$$

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From Equation 5.89, the finite-difference equation for any interior node is then of the form

$$-T_{m-1}^{p+1} + 4T_m^{p+1} - T_{m+1}^{p+1} = 2T_m^p$$

Since we are dealing with a semi-infinite solid, the number of nodes is, in principle, infinite. In practice, however, the number may be limited to the nodes that are affected by the change in the boundary condition for the time period of interest. From the results of the explicit method, it is evident that we are safe in choosing nine nodes corresponding to T_0, T_1, \ldots, T_8 . We are thereby assuming that, at t = 120 s, there has been no change in T_8 .

We now have a set of nine equations that must be solved simultaneously for each time increment. Using the matrix inversion method, we express the equations in the form [A][T] = [C], where

$$[C] = \begin{bmatrix} 56.1 + T_0^p \\ 2T_1^p \\ 2T_2^p \\ 2T_3^p \\ 2T_4^p \\ 2T_5^p \\ 2T_6^p \\ 2T_7^p \\ 2T_8^p + T_9^{p+1} \end{bmatrix}$$

Note that numerical values for the components of [C] are determined from previous values of the nodal temperatures. Note also how the finite-difference equation for node 8 appears in matrices [A] and [C].

A table of nodal temperatures may be compiled, beginning with the first row (p = 0) corresponding to the prescribed initial condition. To obtain nodal temperatures for subsequent times, the inverse of the

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\hline
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1 & 24
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are determined e also how the s [A] and [C]. beginning with nitial condition. e inverse of the

coefficient matrix $[A]^{-1}$ must first be found. At each time p+1, it is then multiplied by the column vector [C], which is evaluated at p, to obtain the temperatures $T_0^{p+1}, T_1^{p+1}, \ldots, T_8^{p+1}$. For example, multiplying $[A]^{-1}$ by the column vector corresponding to p=0,

$$\begin{bmatrix} C \end{bmatrix}_{p=0} = \begin{bmatrix} 76.1 \\ 40 \\ 40 \\ 40 \\ 40 \\ 40 \\ 40 \\ 60 \end{bmatrix}$$

the second row of the table is obtained. Updating [C], the process is repeated four more times to determine the nodal temperatures at 120 s. The desired temperatures are $T_0 = 114.7^{\circ}\text{C}$ and $T_2 = 44.2^{\circ}\text{C}$.

Implicit finite-difference solution for $Fo = \frac{1}{2}$

p	t (s)	T_0	<i>T</i> ₁	<i>T</i> ₂	<i>T</i> ₃	<i>T</i> ₄	<i>T</i> ₅	T_6	<i>T</i> ₇	T_8
0	0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
1	24	52.4	28.7	22.3	20.6	20.2	20.0	20.0	20.0	20.0
2	48	74.0	39.5	26.6	22.1	20.7	20.2	20.1	20.0	20.0
3	72	90.2	50.3	32.0	24.4	21.6	20.6	20.2	20.1	20.0
4	96	103.4	60.5	38.0	27.4	22.9	21.1	20.4	20.2	20.1
5	120	114.7	70.0	44.2	30.9	24.7	21.9	20.8	20.3	20.1

3. Approximating the slab as a semi-infinite medium, the appropriate analytical expression is given by Equation 5.58, which may be applied to any point in the slab.

$$T(x,t) - T_i = \frac{2q_o''(\alpha t/\pi)^{1/2}}{k} \exp\left(-\frac{x^2}{4\alpha t}\right) - \frac{q_o''x}{k} \operatorname{erfc}\left(\frac{x}{2\sqrt{\alpha t}}\right)$$

At the surface, this expression yields

$$T(0, 120 \text{ s}) - 20^{\circ}\text{C} = \frac{2 \times 3 \times 10^{5} \text{ W/m}^{2}}{401 \text{ W/m} \cdot \text{K}} (117 \times 10^{-6} \text{ m}^{2}/\text{s} \times 120 \text{ s/m})^{1/2}$$

or

$$T(0, 120 \text{ s}) = 120.0^{\circ}\text{C}$$

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$$T(0.15 \text{ m}, 120 \text{ s}) - 20^{\circ}\text{C} = \frac{2 \times 3 \times 10^{5} \text{ W/m}^{2}}{401 \text{ W/m} \cdot \text{K}}$$

$$\times (117 \times 10^{-6} \text{ m}^2/\text{s} \times 120 \text{ s}/\pi)^{1/2}$$

At the interior point (x = 0.15 m)

$$\times \exp \left[-\frac{\left(0.15 \text{ m}\right)^2}{4 \times 117 \times 10^{-6} \text{ m}^2/\text{s} \times 120 \text{ s}} \right] - \frac{3 \times 10^5 \text{ W/m}^2 \times 0.15 \text{ m}}{401 \text{ W/m} \cdot \text{K}}$$

$$\times \left[1 - \text{erf} \left(\frac{0.15 \text{ m}}{2\sqrt{117 \times 10^{-6} \text{ m}^2/\text{s} \times 120 \text{ s}}} \right) \right] = 45.4^{\circ}\text{C}$$

Comments:

1. Comparing the exact results with those obtained from the three approximate solutions, it is clear that the explicit method with Fo = 1/4 provides the most accurate predictions.

METHOD	$T_0 = T(0, 120 \text{ s})$	$T_2 = T(0.15 \text{ m}, 120 \text{ s})$
Explicit $(Fo = \frac{1}{2})$	125.3	48.1
Explicit $(Fo = \frac{1}{4})$	118.9	44.4
Implicit $(Fo = \frac{1}{2})$	114.7	44.2
Exact	120.0	45.4

This is not unexpected, since the corresponding value of Δt is 50% smaller than that used in the other two methods.

- Although computations are simplified by using the maximum allowable value of Fo in the explicit method, the accuracy of the results is seldom satisfactory.
- 3. Note that the coefficient matrix [A] is tridiagonal. That is, all elements are zero except those which are on, or to either side of, the main diagonal. Tridiagonal matrices are associated with one-dimensional conduction problems. In such cases the problem of solving for the unknown temperatures is greatly simplified, and stock computer programs may readily be obtained for this purpose.
- 4. A more general radiative heating condition would be one in which the surface is suddenly exposed to large surroundings at an elevated temperature T_{sur} (Problem 5.84). The net rate at which radiation is transferred to the surface may then be calculated from Equation 1.7. Allowing for convection heat transfer to the surface, application of conservation of energy to the surface node yields an explicit finite-

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difference equation of the form

$$\varepsilon\sigma \left[T_{\rm sur}^4 - \left(T_0^p \right)^4 \right] + h \left(T_\infty - T_0^p \right) + k \frac{T_1^p - T_0^p}{\Delta x} = \rho \frac{\Delta x}{2} c \frac{T_0^{p+1} - T_0^p}{\Delta t}$$

Use of this finite-difference equation in a numerical solution is complicated by the fact that it is *nonlinear*. However, the equation may be linearized by introducing the radiation heat transfer coefficient h, defined by Equation 1.9, and the finite-difference equation is

$$h_r^p (T_{\text{sur}} - T_0^p) + h(T_\infty - T_0^p) + k \frac{T_1^p - T_0^p}{\Delta x} = \rho \frac{\Delta x}{2} c \frac{T_0^{p+1} - T_0^p}{\Delta t}$$

The solution may proceed in the usual manner, although the effect of a radiative Biot number $(Bi_r \equiv h_r \Delta x/k)$ must be included in the stability criterion and the value of h_r must be updated at each step in the calculations. If the implicit method is used, h_r is calculated at p+1, in which case an iterative calculation must be made at each time step.

5.10 SUMMARY

Transient conduction occurs in numerous engineering applications, and it is important to appreciate the different methods for dealing with it. There is certainly much to be said for simplicity, in which case, when confronted with a transient problem, the first thing you should do is calculate the Biot number. If this number is much less than unity, you may use the lumped capacitance method to obtain accurate results with minimal computational requirements. However, if the Biot number is not much less than unity, spatial effects must be considered, and some other method must be used. Analytical results are available in convenient graphical and equation form for the plane wall, the infinite cylinder, the sphere, and the semi-infinite solid. You should know when and how to use these results. If geometrical complexities and/or the form of the boundary conditions preclude their use, recourse must be made to finite-difference methods. With the digital computer, such methods may be used to solve any conduction problem, regardless of complexity.

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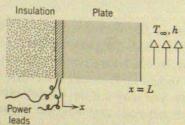
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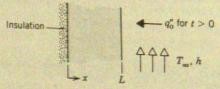
PROBLEMS

Qualitative Considerations

5.1 Consider a thin electrical heater attached to a plate and backed by insulation Initially, the heater and plate are at the temperature of the ambient air, T_{xx} Suddenly, the power to the heater is switched on giving rise to a constant heat flux q_o''' (W/m²) at the inner surface of the plate.



- (a) Sketch and label, on T-x coordinates, the temperature distributions: initial, steady-state, and at two intermediate times.
- (b) Sketch the heat flux at the outer surface $q_x''(L, t)$ as a function of time. 5.2 The inner surface of a plane wall is insulated while the outer surface is exposed to
 - an airstream at T_{∞} . The wall is at a uniform temperature corresponding to that of the airstream. Suddenly, a radiation heat source is switched on applying a uniform flux $q_o^{\prime\prime}$ to the outer surface.



- (a) Sketch and label, on T-x coordinates, the temperature distributions: initial, steady-state and at the coordinates, the temperature distributions: steady-state, and at two intermediate times.
- (b) Sketch the heat flux at the outer surface $q''_x(L, t)$ as a function of time.

5.4

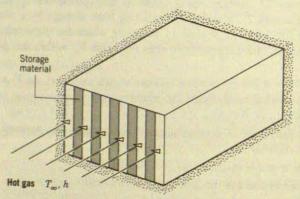
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- 5.8 A spherical lead bullet of 6 mm diameter is moving at a Mach number of approximately 3. The resulting shock wave heats the air around the bullet to 700 K, and the average convection coefficient for heat transfer between the air and the bullet is 500 W/m² · K. If the bullet leaves the barrel at 300 K and the time of flight is 0.4 s, what is its surface temperature on impact?
- 5.9 Carbon steel (AISI 1010) shafts of 0.1 m diameter are heat treated in a gas-fired furnace whose gases are at 1200 K and provide a convection coefficient of 100 W/m² · K. If the shafts enter the furnace at 300 K, how long must they remain in the furnace to achieve a centerline temperature of 800 K?
- 5.10 A thermal energy storage unit consists of a large rectangular channel, which is well insulated on its outer surface and encloses alternating layers of the storage material and the flow passage.



Each layer of the storage material is an aluminum slab of width W=0.05 m, which is at an initial temperature of 25°C. Consider conditions for which the storage unit is charged by passing a hot gas through the passages, with the gas temperature and the convection coefficient assumed to have constant values of $T_{\infty}=600$ °C and h=100 W/m²·K throughout the channel. How long will it take to achieve 75% of the maximum possible energy storage? What is the temperature of the aluminum at this time?

- 5.11 A leaf spring of dimensions 32 mm by 10 mm by 1.1 m is sprayed with a thin anticorrosion coating which is heat treated by suspending the spring vertically in the lengthwise direction and passing it through a conveyor oven maintained at an air temperature of 175°C. Satisfactory coatings have been obtained on springs, initially at 25°C, with an oven residence time of 35 min. The coating supplier has specified that the coating should be treated for 10 min above a temperature of 140°C. How long should a spring of dimensions 76 mm by 35 mm by 1.6 m remain in the oven in order to properly heat treat the coating? The thermophysical properties of the spring material are ρ = 8131 kg/m³, c_p = 473 J/kg·K, and k = 42 W/m·K.
- 5.12 A 3-mm-thick panel of aluminum alloy ($k = 177 \text{ W/m} \cdot \text{K}$ and $\alpha = 73 \times 10^{-6} \text{ m}^2/\text{s}$) is finished on both sides with an epoxy coating that must be cured at or above 150°C for at least 5 min. The production line for the curing operation involves two steps: (1) heating in an oven with air at 175°C and a convection

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Problems 291

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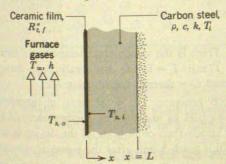
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73 × 10-0 cured at or g operation convection coefficient of 20 W/m2 · K, and (2) cooling in an enclosure with air at 25°C and a convection coefficient of 10 W/m2 · K.

- (a) Assuming the panel is initially at 25°C, what is the minimum residence time for the panel in the oven?
- (b) What is the total elapsed time for the two-step curing operation if it is completed when the panel has been cured and cooled to the safe-to-touch temperature of 37°C?
- 5.13 A plane wall of a furnace is fabricated from plain carbon steel ($k = 60 \text{ W/m} \cdot \text{K}$, $\rho = 7850 \text{ kg/m}^3$, $c = 430 \text{ J/kg} \cdot \text{K}$) and is of thickness L = 10 mm. To protect it from the corrosive effects of the furnace combustion gases, one surface of the wall is coated with a thin ceramic film which, for a unit surface area, has a thermal resistance of $R''_{t,f} = 0.01 \text{ m}^2 \cdot \text{K/W}$. The opposite surface is well insulated from the surroundings.



At furnace start-up the wall is at an initial temperature of $T_i = 300$ K, and combustion gases at $T_{\infty} = 1300$ K enter the furnace, providing a convection coefficient of $h = 25 \text{ W/m}^2 \cdot \text{K}$ at the ceramic film. Assuming the film to have negligible thermal capacitance, how long will it take for the inner surface of the steel to achieve a temperature of $T_{s,i} = 1200$ K? What is the temperature $T_{s,o}$ of the exposed surface of the ceramic film at this time?

- 5.14 In an industrial process requiring high dc currents, water-jacketed copper rods, 20 mm in diameter, are used to carry the current. The water, which flows continuously between the jacket and the rod, maintains the rod temperature at 75°C during normal operation at 1000 A. The electrical resistance of the rod is known to be $0.15 \,\Omega/m$. Problems would arise if the coolant water ceased to be available (e.g. because of a valve malfunction). In such a situation heat transfer from the rod surface would diminish greatly, and the rod would eventually melt. Estimate the time required for melting to occur.
- 5.15 A long wire of diameter D = 1 mm is submerged in an oil bath of temperature $T_{\infty} = 25$ °C. The wire has an electrical resistance per unit length of $R'_{e} = 0.01$ Ω/m . If a current of I = 100 A flows through the wire and the convection coefficient is $h = 500 \text{ W/m}^2 \cdot \text{K}$, what is the steady-state temperature of the wire? From the time the current is applied, how long does it take for the wire to reach a temperature which is within 1°C of the steady-state value? The properties of the wire are $\rho = 8000 \text{ kg/m}^3$, $c = 500 \text{ J/kg} \cdot \text{K}$, and $k = 20 \text{ W/m} \cdot \text{K}$.

5.16 Consider the system of Problem 5.1 where the temperature of the plate is spacewise isothermal during the transient process.

- (a) Obtain an expression for the temperature of the plate as a function of time T(t) in terms of q_o'' , T_∞ , h, L, and the plate properties ρ and c.
- (b) Determine the thermal time constant and the steady-state temperature for a 12-mm-thick plate of pure copper when $T_{\infty} = 27^{\circ}\text{C}$, $h = 50 \text{ W/m}^2 \cdot \text{K}$, and $q_0'' = 5000 \text{ W/m}^2$. Estimate the time required to reach steady-state conditions
- 5.17 An electronic device, such as a power transistor mounted on a finned heat sink, can be modeled as a spatially isothermal object with internal heat generation and an external convection resistance.
 - (a) Consider such a system of mass M, specific heat c, and surface area A_s , which is initially in equilibrium with the environment at T_{∞} . Suddenly, the electronic device is energized such that a constant heat generation $\dot{E}_{\rm g}$ (W) occurs. Show that the temperature response of the device is

$$\frac{\theta}{\theta_i} = \exp\left(-\frac{t}{RC}\right)$$

where $\theta \equiv T - T(\infty)$ and $T(\infty)$ is the steady-state temperature corresponding to $t \to \infty$; $\theta_i = T_i - T(\infty)$; $T_i = \text{initial temperature of device}$; $R = \text{thermal resistance } 1/hA_s$; and C = thermal capacitance Mc.

- (b) An electronic device, which generates 60 W of heat, is mounted on an aluminum heat sink weighing 0.31 kg and reaches a temperature of 100°C in ambient air at 20°C under steady-state conditions. If the device is initially at 20°C, what temperature will it reach 5 min after the power is switched on?
- 5.18 Before being injected into a furnace, pulverized coal is preheated by passing it through a cylindrical tube whose surface is maintained at $T_{\rm sur} = 1000^{\circ}$ C. The coal pellets are suspended in an airflow and are known to move with a speed of 3 m/s. If the pellets may be approximated as spheres of 1-mm diameter and it may be assumed that they are heated by radiation transfer from the tube surface, how long must the tube be to heat coal entering at 25°C to a temperature of 600°C? Is the use of the lumped capacitance method justified?

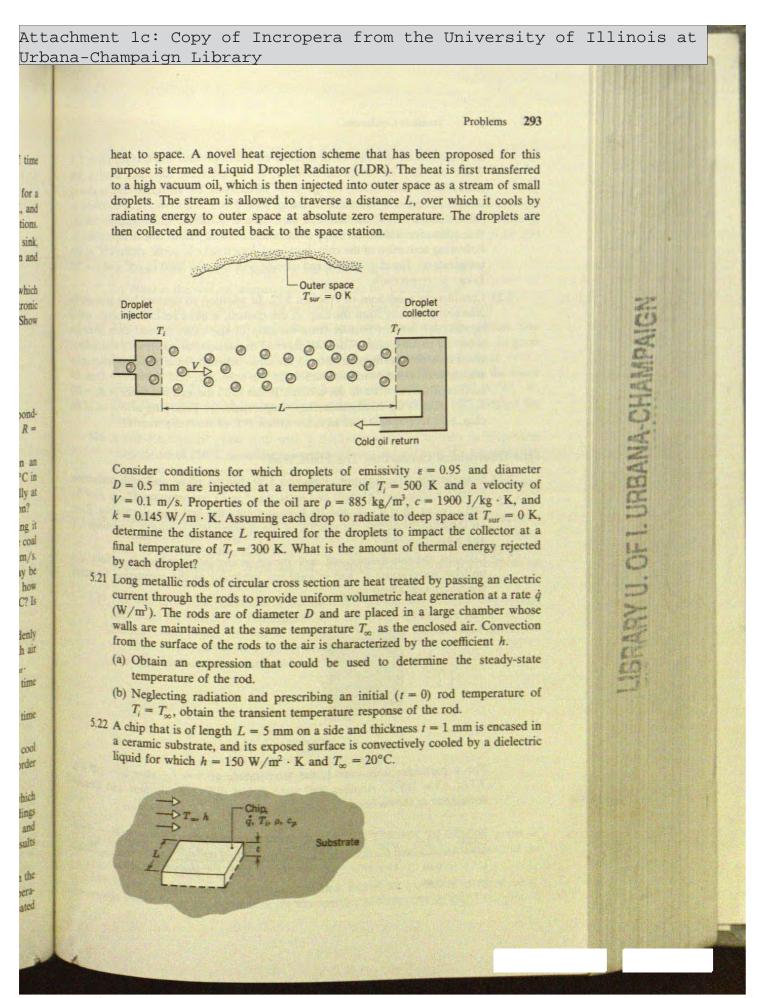
5.19 A metal sphere of diameter D, which is at a uniform temperature T_i , is suddenly removed from a furnace and suspended from a fine wire in a large room with air at a uniform temperature T_i .

- at a uniform temperature T_{∞} and the surrounding walls at a temperature T_{sur} .

 (a) Neglecting heat transfer by radiation, obtain an expression for the time required to cool the sphere to some temperature T.
- (b) Neglecting heat transfer by convection, obtain an expression for the time required to cool the sphere to the temperature T.
- (c) How would you go about determining the time required for the sphere to cool to the temperature T if both convection and radiation are of the same order of magnitude?
- (d) Consider an anodized aluminum sphere ($\varepsilon = 0.75$) 50 mm in diameter, which is at an initial temperature of $T_i = 800$ K. Both the air and the surroundings are at 300 K, and the convection coefficient is $10 \text{ W/m}^2 \cdot \text{K}$. Calculate and compare the time it will take for the sphere to cool to 400 K using the results of parts a, b, and c
- 5.20 As permanent space stations increase in size, there is an attendant increase in the amount of electrical power they dissipate. To keep station compartment temperatures from exceeding prescribed limits, it is necessary to transfer the dissipated

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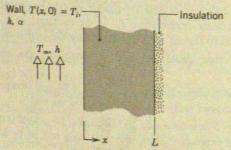


In the off-mode the chip is in thermal equilibrium with the coolant $(T_i = T_\infty)$. When the chip is energized, however, its temperature increases until a new steady-state is established. For purposes of analysis, the energized chip is characterized by uniform volumetric heating with $\dot{q} = 9 \times 10^6$ W/m³. Assuming an infinite contact resistance between the chip and substrate and negligible conduction resistance within the chip, determine the steady-state chip temperature T_f . Following activation of the chip, how long does it take to come within 1°C of this temperature? The chip density and specific heat are $\rho = 2000$ kg/m³ and c = 700 J/kg·K, respectively.

5.23 Consider the conditions of Problem 5.22. In addition to treating heat transfer by convection directly from the chip to the coolant, a more realistic analysis would account for indirect transfer from the chip to the substrate and then from the substrate to the coolant. The total thermal resistance associated with this indirect route includes contributions due to the chip-substrate interface (a contact resistance), multidimensional conduction in the substrate, and convection from the surface of the substrate to the coolant. If this total thermal resistance is $R_t = 200$ K/W, what is the steady-state chip temperature T_f ? Following activation of the chip, how long does it take to come within 1°C of this temperature?

One-Dimensional Conduction: The Plane Wall

- 5.24 Consider the series solution, Equation 5.39, for the plane wall with convection. Calculate midplane ($x^* = 0$) and surface ($x^* = 1$) temperatures θ^* for $F_0 = 0.1$ and 1, using $B_i = 0.1$, 1, and 10. Consider only the first four eigenvalues. Based on these results discuss the validity of the approximate solutions, Equations 5.40 and 5.41.
- 5.25 Consider the one-dimensional wall shown in the sketch which is initially at a uniform temperature T_i and is suddenly subjected to the convection boundary condition with a fluid at T_{∞} .



For a particular wall, case 1, the temperature at $x=L_1$ after $t_1=100~{\rm s}$ is $T_1(L_1,t_1)=315{\rm °C}$. Another wall, case 2, has different thickness and thermal conditions as shown below

CASE	- S 4 (S)		A CTUBERY CHEST			
CASE	L (m)	$\alpha (m^2/s)$	$k(W/m \cdot K)$	T (°C)	T (°C)	h (W/m² · K)
1	0.10	15 × 10 ⁻⁶	50			
2		25 × 10 ⁻⁶		300	400	200
1		100	100	30	20	100

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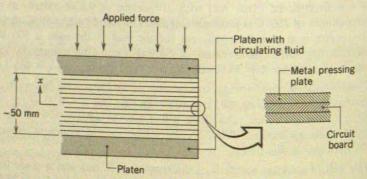
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20 mm thick, and the glass has a thermal diffusivity of 6×10^{-7} m²/s.

- (a) How long will it take for the midplane temperature to achieve 50% of its maximum possible temperature reduction?
- (b) If $(T_i T_s) = 300$ °C, what is the maximum temperature gradient in the glass at the above time?
- 5.32 Copper-coated, epoxy-filled fiberglass circuit boards are treated by heating a stack of them under high pressure as shown in the sketch. The purpose of the pressing-heating operation is to cure the epoxy which bonds the fiberglass sheets imparting stiffness to the boards. The stack, referred to as a book, is comprised of 10 boards and 11 pressing plates which prevent epoxy from flowing between the boards and impart a smooth finish to the cured boards. In order to perform simplified thermal analyses, it is reasonable to approximate the book as having an effective thermal conductivity (k) and an effective thermal capacitance (ρc_p) . Calculate the effective properties if each of the boards and plates has a thickness of 2.36 mm and the following thermophysical properties: board (b) $\rho_b = 1000$ kg/m³, $c_{p,b} = 1500$ J/kg·K, $k_b = 0.30$ W/m·K; plate (p) $\rho_p = 8000$ kg/m³, $c_{p,p} = 480$ J/kg·K, $k_p = 12$ W/m·K.



- 5.33 Circuit boards are treated by heating a stack of them under high pressure as illustrated in Problem 5.32. The platens at the top and bottom of the stack are maintained at a uniform temperature by a circulating fluid. The purpose of the pressing-heating operation is to cure the epoxy which bonds the fiberglass sheets and impart stiffness to the boards. The cure condition is achieved when the epoxy has been maintained at or above 170° C for at least 5 min. The effective thermophysical properties of the stack or book (boards and metal pressing plates) are k = 0.613 W/m·K and $\rho c_p = 2.73 \times 10^6$ J/m³·K.
 - (a) If the book is initially at 15°C and, following application of pressure, the platens are suddenly brought to a uniform temperature of 190°C, calculate the elapsed time t_e required for the midplane of the book to reach the cure temperature of 170°C.
 - (b) If, at this instant of time, $t = t_e$, the platen temperature were reduced suddenly to 15°C, how much energy would have to be removed from the book by the coolant circulating in the platen, in order to return the stack to its initial uniform temperature?

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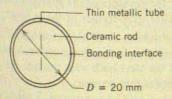
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One-Dimensional Conduction: The Long Cylinder

- 5.34 Cylindrical steel rods (AISI 1010), 50 mm in diameter, are heat treated by drawing them through an oven 5 m long in which air is maintained at 750°C. The rods enter at 50°C and achieve a centerline temperature of 600°C before leaving. For a convection coefficient of 125 W/m² · K, estimate the speed at which the rods must be drawn through the oven.
- 5.35 Estimate the time required to cook a hot dog in boiling water. Assume that the hot dog is initially at 6°C, that the convection heat transfer coefficient is 100 W/m²·K, and that the final temperature is 80°C at the centerline. Treat the hot dog as a long cylinder of 20-mm diameter having the properties: $\rho = 880 \text{ kg/m}^3$, $c = 3350 \text{ J/kg} \cdot \text{K}$, and $k = 0.52 \text{ W/m} \cdot \text{K}$.
- 5.36 A long rod of 60-mm diameter and thermophysical properties $\rho = 8000 \text{ kg/m}^3$, $c = 500 \text{ J/kg} \cdot \text{K}$ and $k = 50 \text{ W/m} \cdot \text{K}$ is initially at a uniform temperature and is heated in a forced convection furnace maintained at 750 K. The convection coefficient is estimated to be 1000 W/m² · K. At a certain time, the surface temperature of the rod is measured to be 550 K. What is the corresponding center temperature of the rod?
- 5.37 A long cylinder of 30-mm diameter, initially at a uniform temperature of 1000 K, is suddenly quenched in a large, constant-temperature oil bath at 350 K. The cylinder properties are k=1.7 W/m·K, c=1600 J/kg·K, and $\rho=400$ kg/m³, while the convection coefficient is 50 W/m²·K. Calculate the time required for the surface of the cylinder to reach 500 K.
- 5.38 A long pyroceram rod of diameter 20 mm is clad with a very thin metallic tube for mechanical protection. The bonding between the rod and the tube has a thermal contact resistance of $R'_{t,c} = 0.12 \text{ m} \cdot \text{K/W}$.



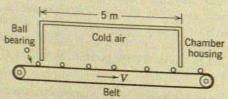
If the rod is initially at a uniform temperature of 900 K and is suddenly cooled by a fluid at $T_{\infty} = 300$ K and h = 100 W/m²·K, at what time will the rod centerline reach 600 K?

- 5.39 A long rod 40 mm in diameter, fabricated from sapphire (aluminum oxide) and initially at a uniform temperature of 800 K, is suddenly exposed to a cooling process with a fluid at 300 K having a heat transfer coefficient of 1600 W/m² · K. After 35 s of exposure to the cooling process, the rod is wrapped in insulation and experiences no heat losses. What will be the temperature of the rod after a long period of time?
- 5.40 A long bar of 70-mm diameter and initially at 90°C is cooled by immersing it in a water bath which is at 40°C and provides a convection coefficient of 20 W/m² · K. The thermophysical properties of the bar are $\rho = 2600 \text{ kg/m}^3$, $c = 1030 \text{ J/kg} \cdot \text{K}$, and $k = 3.50 \text{ W/m} \cdot \text{K}$.

- (a) How long should the bar remain in the bath in order that, when it is removed and allowed to equilibrate while isolated from any surroundings, it achieves a uniform temperature of 55°C?
- (b) What is the surface temperature of the bar when it is removed from the bath?
- 5.41 A long plastic rod of 30-mm diameter ($k = 0.3 \text{ W/m} \cdot \text{K}$ and $\rho c_p = 1040 \text{ kJ/m}^3 \cdot \text{K}$) is uniformly heated in an oven as preparation for a pressing operation. For best results, the temperature in the rod should not be less than 200°C. To what uniform temperature should the rod be heated in the oven if, for the worst case, the rod sits on a conveyor for 3 min while exposed to convection cooling with ambient air at 25°C and with a convection coefficient of 8 W/m² · K² A further condition for good results is a maximum-minimum temperature difference of less than 10°C. Is this condition satisfied and, if not, what could you do to satisfy it?

One-Dimensional Conduction: The Sphere

- 5.42 In heat treating to harden steel ball bearings ($c = 500 \text{ J/kg} \cdot \text{K}$, $\rho = 7800 \text{ kg/m}^3$, $k = 50 \text{ W/m} \cdot \text{K}$), it is desirable to increase the surface temperature for a short time without significantly warming the interior of the ball. This type of heating can be accomplished by sudden immersion of the ball in a molten salt bath with $T_{\infty} = 1300 \text{ K}$ and $h = 5000 \text{ W/m}^2 \cdot \text{K}$. Assume that any location within the ball whose temperature exceeds 1000 K will be hardened. Estimate the time required to harden the outer millimeter of a ball of diameter 20 mm, if its initial temperature is 300 K.
- 5.43 A sphere of 80-mm diameter ($k = 50 \text{ W/m} \cdot \text{K}$ and $\alpha = 1.5 \times 10^{-6} \text{ m}^2/\text{s}$) is initially at a uniform, elevated temperature and is quenched in an oil bath maintained at 50°C. The convection coefficient for the cooling process is 1000 W/m² · K. At a certain time, the surface temperature of the sphere is measured to be 150°C. What is the corresponding center temperature of the sphere?
- 5.44 A cold air chamber is proposed for quenching steel ball bearings of diameter D = 0.2 m and initial temperature T_i = 400°C. Air in the chamber is maintained at -15°C by a refrigeration system, and the steel balls pass through the chamber on a conveyor belt. Optimum bearing production requires that 70% of the initial thermal energy content of the ball above -15°C be removed. Radiation effects may be neglected, and the convection heat transfer coefficient within the chamber is 1000 W/m² · K. Estimate the residence time of the balls within the chamber, and recommend a drive velocity of the conveyor. The following properties may be used for the steel: k = 50 W/m · K, α = 2 × 10⁻⁵ m²/s, and c = 450 J/kg · K.



5.45 Stainless steel (AISI 304) ball bearings, which have been uniformly heated to 850°C, are hardened by quenching them in an oil bath that is maintained at 40°C. The ball diameter is 20 mm, and the convection coefficient associated with the oil bath is 1000 W/m²·K.

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- (a) If quenching is to occur until the surface temperature of the balls reaches 100°C, how long must the balls be kept in the oil? What is the center temperature at the conclusion of the cooling period?
- (b) If 10,000 balls are to be quenched per hour, what is the rate at which energy must be removed by the oil bath cooling system in order to maintain its temperature at 40°C?
- 5.46 A spherical hailstone that is 5 mm in diameter is formed in a high altitude cloud at -30°C. If the stone begins to fall through warmer air at 5°C, how long will it take before the outer surface begins to melt? What is the temperature of the stone's center at this point in time, and how much energy (J) has been transferred to the stone? A convection heat transfer coefficient of 250 W/m²·K may be assumed, and the properties of the hailstone may be taken to be those of ice.
- 5.47 A sphere 30 mm in diameter initially at 800 K is quenched in a large bath having a constant temperature of 320 K with a convection heat transfer coefficient of 75 W/m² · K. The thermophysical properties of the sphere material are: $\rho = 400$ kg/m³, c = 1600 J/kg · K, and k = 1.7 W/m · K.
 - (a) Show, in a qualitative manner on T-t coordinates, the temperatures at the center and at the surface of the sphere as a function of time.
 - (b) Calculate the time required for the surface of the sphere to reach 415 K.
 - (c) Determine the heat flux (W/m²) at the outer surface of the sphere at the time determined in part b.
 - (d) Determine the energy (J) that has been lost by the sphere during the process of cooling to the surface temperature of 415 K.
 - (e) At the time determined by part b, the sphere is quickly removed from the bath and covered with perfect insulation, such that there is no heat loss from the surface of the sphere. What will be the temperature of the sphere after a long period of time has elapsed?
- 5.48 Spheres A and B are initially at 800 K, and they are simultaneously quenched in large constant temperature baths, each having a temperature of 320 K. The following parameters are associated with each of the spheres and their cooling processes.

	SPHERE A	SPHERE B	
Diameter (mm)	300	30	
Density (kg/m³)	1600	400	
Specific heat (kJ/kg · K)	0.400	1.60	
Thermal conductivity (W/m · K)	170	1.70	
Convection coefficient (W/m² · K)	5	50	

- (a) Show in a qualitative manner, on T versus t coordinates, the temperatures at the center and at the surface for each sphere as a function of time. Briefly explain the reasoning by which you determine the relative positions of the curves.
- (b) Calculate the time required for the surface of each sphere to reach 415 K.

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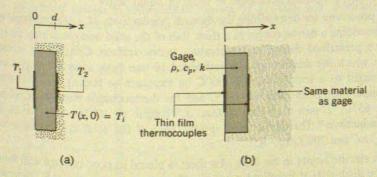
cal properties the wall of a ection process the surface of istory (followient heat flux ure of 167°C. Calculate the corresponding surface convective heat flux assuming the block behaves as a semi-infinite solid. Compare this result with that obtained from the Heisler method of solution.

5.54 A tile-iron consists of a massive plate maintained at 150°C by an imbedded electrical heater. The iron is placed in contact with a tile to soften the adhesive, allowing the tile to be easily lifted from the subflooring. The adhesive will soften sufficiently if heated above 50°C for at least 2 min, but its temperature should not exceed 120°C to avoid deterioration of the adhesive. Assume the tile and subfloor to have an initial temperature of 25°C and to have equivalent thermophysical properties of $k = 0.15 \text{ W/m} \cdot \text{K}$ and $\rho c_p = 1.5 \times 10^6 \text{ J/m}^3 \cdot \text{K}$.

Tile, 4-mm thickness

Subflooring

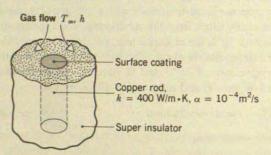
- (a) How long will it take a worker using the tile-iron to lift a tile? Will the adhesive temperature exceed 120°C?
- (b) If the tile-iron has a square surface area 254 mm to the side, how much energy has been removed from it during the time it has taken to lift the tile?
- 5.55 The manufacturer of the heat flux gage of the type illustrated in Problem 1.8 claims the time constant for a 63.2% response to be $\tau = (4d^2\rho c_p)/\pi^2 k$, where ρ , c_p , and k are the thermophysical properties of the gage material and d is its thickness. Not knowing the origin of this relation, your task is to model the gage considering the two extreme cases illustrated below. In both cases, the gage, initially at a uniform temperature T_i , is exposed to a sudden change in surface temperature, $T(0, t) = T_s$. For case a the backside of the gage is insulated, and for case b the gage is imbedded in a semi-infinite solid having the same thermophysical properties as those of the gage.



Develop relationships for predicting the time constant of the gage for the two cases and compare them to the manufacturer's relation. What conclusion can you draw from this analysis regarding the transient response of gages for different applications?

5.56 A simple procedure for measuring surface convection heat transfer coefficients involves coating the surface with a thin layer of material having a precise melting point temperature. The surface is then heated and, by determining the time required for melting to occur, the convection coefficient is determined. The

following experimental arrangement uses the procedure to determine the convection coefficient for gas flow normal to a surface. Specifically, a long copper rod is encased in a super insulator of very low thermal conductivity, and a very thin coating is applied to its exposed surface.



If the rod is initially at 25°C and gas flow for which $h = 200 \text{ W/m}^2 \cdot \text{K}$ and $T_{\infty} = 300$ °C is initiated, what is the melting point temperature of the coating if melting is observed to occur at t = 400 s?

- 5.57 An insurance company has hired you as a consultant to improve their understanding of burn injuries. They are especially interested in injuries induced when a portion of a worker's body comes into contact with machinery that is at elevated temperatures in the range of 50 to 100° C. Their medical consultant informs them that irreversible thermal injury (cell death) will occur in any living tissue that is maintained at $T \ge 48^{\circ}$ C for a duration $\Delta t \ge 10$ s. They want information concerning the extent of irreversible tissue damage (as measured by distance from the skin surface) as a function of the machinery temperature and the time during which contact is made between the skin and the machinery. Can you help them? Assume that living tissue has a normal temperature of 37° C, is isotropic, and has constant properties equivalent to those of liquid water.
- 5.58 A procedure for determining the thermal conductivity of a solid material involves embedding a thermocouple in a thick slab of the solid and measuring the response to a prescribed change in temperature at one surface. Consider an arrangement for which the thermocouple is embedded 10 mm from a surface that is suddenly brought to a temperature of 100°C by exposure to boiling water. If the initial temperature of the slab was 30°C and the thermocouple measures a temperature of 65°C, 2 min after the surface is brought to 100°C, what is its thermal conductivity? The density and specific heat of the solid are known to be 2200 kg/m³ and 700 J/kg·K
- 5.59 An electric heater in the form of a sheet is placed in good contact with the surface of a thick slab of Bakelite having a uniform temperature of 300 K. Determine the temperature of the slab at the surface and at a depth of 25 mm, 10 min after the heater has been energized and is providing a constant heat flux to the surface of 2500 W/m².
- 5.60 A very thick slab with thermal diffusivity 5.6 × 10⁻⁶ m²/s and thermal conductivity 20 W/m·K is initially at a uniform temperature of 325°C. Suddenly, the surface is exposed to a coolant at 15°C for which the convection heat transfer coefficient is 100 W/m²·K. Determine the temperatures at the surface and at a depth of 45 mm after 3 min has elapsed.

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- 5.61 A thick oak wall initially at 25°C, is suddenly exposed to combustion products at 800°C. Determine the time of exposure required for the surface to reach the ignition temperature of 400°C, assuming the convection heat transfer coefficient between the wall and products to be 20 W/m²·K.
- 5.62 It is well known that, although two materials are at the same temperature, one may feel cooler to the touch than the other. Consider thick plates of copper and glass, each at an initial temperature of 300 K. Assuming your finger to be at an initial temperature of 310 K and to have thermophysical properties of $\rho = 1000$ kg/m³, c = 4180 J/kg·K and k = 0.625 W/m·K, determine whether the copper or the glass will feel cooler to the touch.
- 5.63 Two stainless steel plates ($\rho = 8000 \text{ kg/m}^3$, $c = 500 \text{ J/kg} \cdot \text{K}$, $k = 15 \text{ W/m} \cdot \text{K}$), each 20 mm thick and insulated on one surface, are initially at 400 and 300 K when they are pressed together at their uninsulated surfaces. What is the temperature of the insulated surface of the hot plate after 1 min has elapsed?

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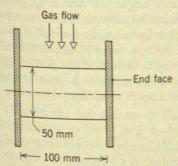
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t with the surface K. Determine the 10 min after the to the surface of

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Multidimensional Conduction

- 5.64 A long steel (plain carbon) billet of square cross section 0.3 m by 0.3 m, initially at a uniform temperature of 30°C, is placed in a soaking oven having a temperature of 750°C. If the convection heat transfer coefficient for the heating process is 100 W/m²·K, how long must the billet remain in the oven before its center temperature reaches 600°C?
- 5.65 Fireclay brick of dimensions 0.06 m \times 0.09 m \times 0.20 m is removed from a kiln at 1600 K and cooled in air at 40°C with $h = 50 \text{ W/m}^2 \cdot \text{K}$. What is the temperature at the center and at the corners of the brick after 50 min of cooling?
- 5.66 A cylindrical copper pin 100 mm long and 50 mm in diameter is initially at a uniform temperature of 20°C. The end faces are suddenly subjected to an intense heating rate that raises them to a temperature of 500°C. At the same time, the cylindrical surface is subjected to heating by gas flow with a temperature 500°C and a heat transfer coefficient 100 W/m²·K.



- (a) Determine the temperature at the center point of the cylinder 8 s after sudden application of the heat.
- (b) Considering the parameters governing the temperature distribution in transient heat diffusion problems, can any simplifying assumptions be justified in analyzing this particular problem? Explain briefly.
- 5.67 Recalling that your mother once said that meat should be cooked until every portion has attained a temperature of 80°C, how long will it take to cook a

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of 15 W/m²·K tving a diameter

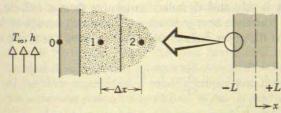
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oported by two quilibrium with K. Suddenly, an the emissivity of se Table A.1 to olution. Use a

- (a) Estimate the time required for the midlength of the rod to reach 1000 K.
- (b) Determine the steady-state temperature distribution and estimate approximately how long it will take to reach this condition.
- 5.72 A one-dimensional slab of thickness 2L is initially at a uniform temperature T_i . Suddenly, electric current is passed through the slab causing a uniform volumetric heating \dot{q} (W/m³). At the same time, both outer surfaces ($x = \pm L$) are subjected to a convection process at T_{∞} with a heat transfer coefficient h.

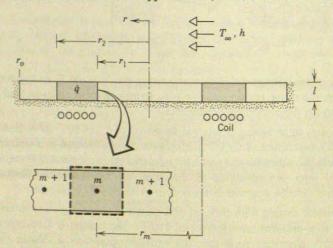


Write the finite-difference equation expressing conservation of energy for node 0 located on the outer surface at x = -L. Rearrange your equation and identify any important dimensionless coefficients.

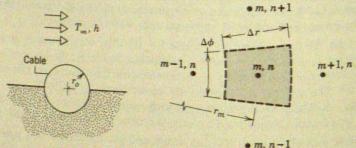
- 5.73 A wall 0.12 m thick having a thermal diffusivity of 1.5 × 10⁻⁶ m²/s is initially at a uniform temperature of 85°C. Suddenly one face is lowered to a temperature of 20°C, while the other face is perfectly insulated. Using a numerical method with space and time increments of 30 mm and 300 s, respectively, determine the temperature distribution within the wall after 45 min have elapsed.
- 5.74 A large plastic casting with thermal diffusivity 6.0×10^{-7} m²/s is removed from its mold at a uniform temperature of 150°C. The casting is then exposed to a high-velocity airstream such that the surface experiences a sudden change in temperature to 20°C. Assuming the casting approximates a semi-infinite medium and using a finite-difference method with a space increment of 6 mm, estimate the temperature at a distance 18 mm from the surface after 3 min have elapsed. Verify your result by comparison with the appropriate analytical solution.
- 5.75 A very thick plate with thermal diffusivity 5.6×10^{-6} m²/s and thermal conductivity $20 \text{ W/m} \cdot \text{K}$ is initially at a uniform temperature of 325°C . Suddenly, the surface is exposed to a coolant at 15°C for which the convection heat transfer coefficient is $100 \text{ W/m}^2 \cdot \text{K}$. Using the finite-difference method with a space increment of $\Delta x = 15 \text{ mm}$ and a time increment of 18 s, determine temperatures at the surface and at a depth of 45 mm after 3 min have elapsed.
- 5.76 Consider the fuel element of Example 5.6. Initially, the element is at a uniform temperature of 250°C with no heat generation. Suddenly, the element is inserted into the reactor core causing a uniform volumetric heat generation rate of $\dot{q} = 10^8$ W/m³. The surfaces are convectively cooled with $T_{\infty} = 250$ °C and h = 1100 W/m²·K. Using the explicit method with a space increment of 2 mm, determine the temperature distribution 1.5 s after the element is inserted into the core.
- 5.77 A plane wall of thickness 100 mm with a uniform volumetric heat generation of $\dot{q}=1.5\times 10^6~\rm W/m^3$ is exposed to convection conditions of $T_\infty=30^{\rm o}\rm C$ and $h=1000~\rm W/m^2\cdot K$ on both surfaces. The wall is maintained under steady-state conditions when, suddenly, the heat generation level (\dot{q}) is reduced to zero. The thermal diffusivity and thermal conductivity of the wall material are $1.6\times 10^{-6}~\rm m^2/s$ and 75 W/m·K. A space increment of 10 mm is suggested.

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- (a) Estimate the midplane temperature 3 min after the generation has been switched off.
- (b) Plot on T-x coordinates the temperature distribution obtained in part (a). Show also the initial and steady-state temperature distributions for the wall.
- 5.78 For the conditions described in Example 5.6, use the finite-difference method to estimate the temperature at the midplane (x = 0) 20 s after the power level has been changed from \dot{q}_1 to \dot{q}_2 .
- 5.79 A thin circular disk is subjected to induction heating from a coil, the effect of which is to provide a uniform heat generation within a ring section as shown. Convection occurs at the upper surface, while the lower surface is well insulated.



- (a) Derive the transient, finite-difference equation for node m, which is within the region subjected to induction heating.
- (b) On T-r coordinates sketch, in a qualitative manner, the steady-state temperature distribution, identifying important features.
- 5.80 An electrical cable, experiencing a uniform volumetric generation \hat{q} , is half buried in an insulating material while the upper surface is exposed to a convection process (T_{∞}, h) .



- (a) Derive the explicit, finite-difference equations for an interior node (m, n), the center node (m = 0), and the outer surface nodes (M, n) for the convection and insulated boundaries
- (b) Obtain the stability criterion for each of the finite-difference equations Identify the most restrictive criterion.

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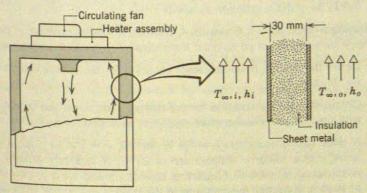
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- 5.81 One end of a stainless steel (AISI 316) rod of diameter 10 mm and length 0.16 m is inserted into a fixture maintained at 200°C. The rod, covered with an insulating sleeve, reaches a uniform temperature throughout its length. When the sleeve is removed, the rod is subjected to ambient air at 25°C such that the convection heat transfer coefficient is 30 W/m²·K. Using a numerical technique, estimate the time required for the midlength of the rod to reach 100°C.
- 5.82 The cross section of an oven wall is composed of 30-mm-thick insulation sandwiched between two thin (1.5-mm-thick) stainless steel sheets. Under steady-state conditions, the oven is operating with an inside air temperature of $T_{\infty,i} = 150^{\circ}\text{C}$ and an ambient air temperature of $T_{\infty,o} = 20^{\circ}\text{C}$ with $h_i = 100 \text{ W/m}^2 \cdot \text{K}$ and $h_o = 10 \text{ W/m}^2 \cdot \text{K}$. When the oven heater level is changed and the fan speed changed to substantially increase air circulation within the oven, the inside surface of the oven experiences a sudden temperature change to 100°C . The insulation has a thermal conductivity of $0.03 \text{ W/m} \cdot \text{K}$ and a thermal diffusivity of $7.5 \times 10^{-7} \text{ m}^2/\text{s}$. In your finite-difference solution, use a space increment of 6 mm. Assume that the effect of the stainless steel sheets is negligible and that the outside convection heat transfer coefficient h_o remains unchanged. Estimate the time required for the oven wall to approximate steady-state conditions after the inner wall temperature is changed to 100°C .



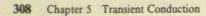
5.83 Two very long (in the direction normal to the page) bars having the prescribed initial temperature distributions are to be soldered together (see next page). At time t = 0, the m = 3 face of the copper (pure) bar contacts the m = 4 face of the steel (AISI 1010) bar. The solder and flux act as an interfacial layer of negligible thickness and effective contact resistance $R_{t,c}^{\prime\prime} = 2 \times 10^{-5} \text{ m}^2 \cdot \text{K/W}$.

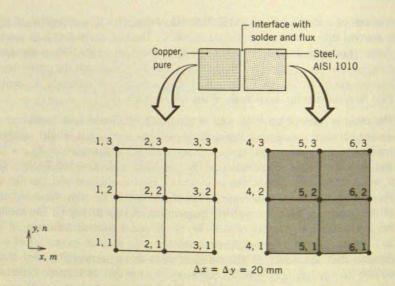
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(a) Derive the explicit, finite-difference equation in terms of Fo and $Bi_c = \frac{\Delta x/kR_{t,c}^{"}}{}$ for $T_{4,2}$ and determine the corresponding stability criterion.

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- (b) Using $F_0 = 0.01$, determine $T_{4,2}$ one time step after contact is made. What is Δt ? Is the stability criterion satisfied?
- 5.84 Referring to Example 5.7, Comment 4, consider a sudden exposure of the surface to large surroundings at an elevated temperature (T_{sur}) and to convection (T_{∞}, h)
 - (a) Derive the explicit, finite-difference equation for the surface node in terms of Fo, Bi, and Bi...
 - (b) Obtain the stability criterion for the surface node. Does this criterion change with time? Is the criterion more restrictive than that for an interior node?
 - (c) A thick slab of material (k = 1.5 W/m·K, α = 7 × 10⁻⁷ m²/s, ε = 0.9), initially at a uniform temperature of 27°C, is suddenly exposed to large surroundings at 1000 K. Neglecting convection and using a space increment of 10 mm, determine temperatures at the surface and 30 mm from the surface after an elapsed time of 1 min.
- 5.85 Consider the system of Problem 4.58. Initially with no flue gases flowing, the walls $(\alpha = 5.5 \times 10^{-6} \text{ m}^2/\text{s})$ are at a uniform temperature of 25°C. Using the implicit finite-difference method with a time increment of 1 h, find the temperature distribution in the wall 1, 2, 5, and 20 h after introduction of the flue gases.
- 5.86 Consider the system of Problem 4.66. Initially, the ceramic plate (α = 1.5 × 10⁻⁶ m²/s) is at a uniform temperature of 30°C, and suddenly the electrical heating elements are energized. Using the implicit, finite-difference method, estimate the time required for the difference between the surface and initial temperatures to reach 95% of the difference for steady-state conditions. If you write a computer program, use a time increment of 2 s; otherwise use 50 s.
- 5.87 Consider the bonding operation described in Problem 3.79, which was analyzed under steady-state conditions. In this case, however, the laser will be used to heat the film for a prescribed period of time, creating the transient heating situation shown in the sketch

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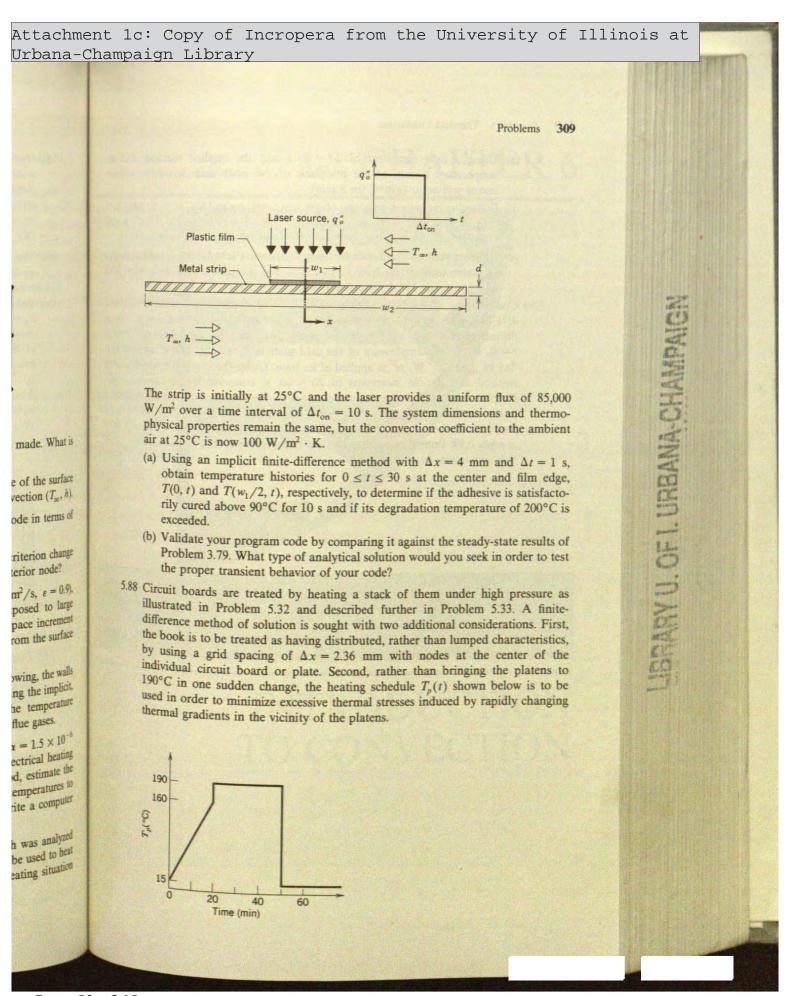
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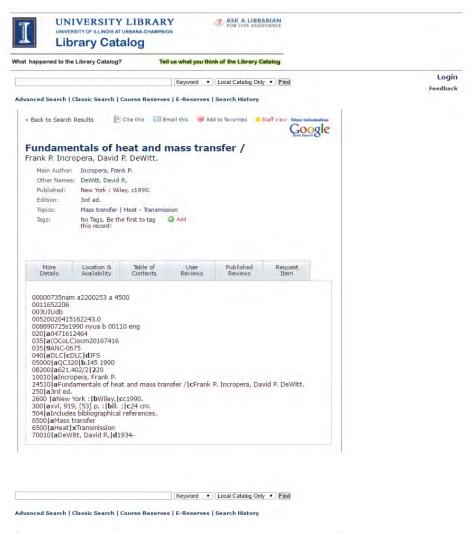
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Attachment 1d: United States Copyright Office catalog record for Incropera



Attachment le: University of Illinois at Urbana-Champaign Library catalog record, in MARC format, for Incropera



Attachment 1f: École Polytechnique Fédérale de Lausanne (EPFL) Library catalog record, in MARC format, for Incropera



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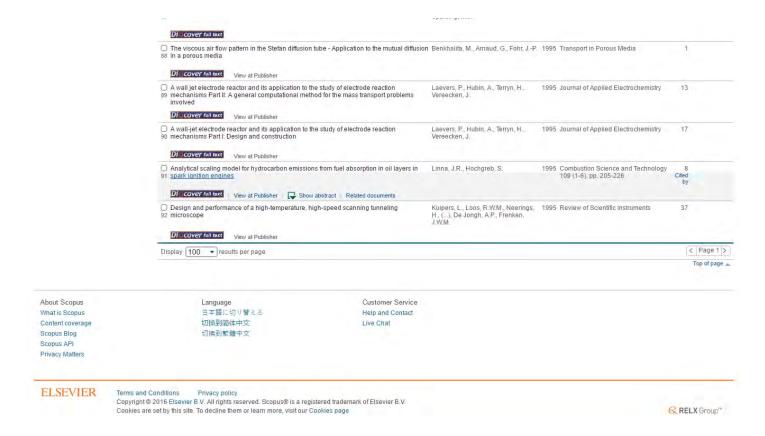
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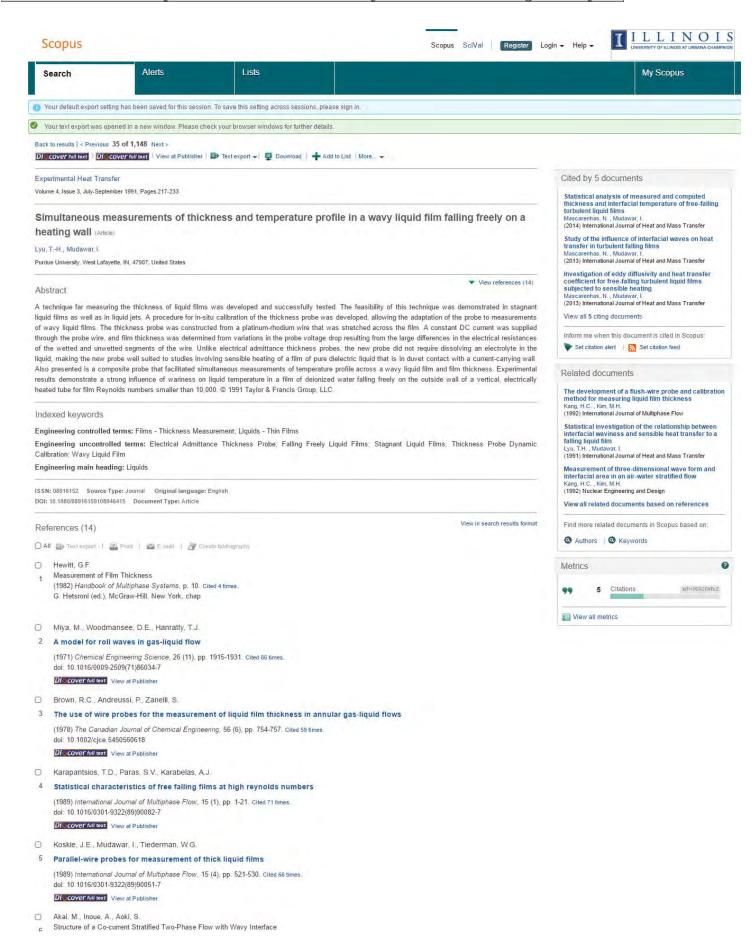
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