

UNITED STATES PATENT AND TRADEMARK OFFICE

BEFORE THE PATENT TRIAL AND APPEAL BOARD

KOITO MANUFACTURING CO., LTD,
Petitioner,

v.

ADAPTIVE HEADLAMP TECHNOLOGIES, INC.,
Patent Owner.

Case IPR2016-00079
Patent 7,241,034 C1

Before MICHAEL P. TIERNEY, RAMA G. ELLURU, and
SCOTT C. MOORE, *Administrative Patent Judges*.

MOORE, *Administrative Patent Judge*.

DECISION
Institution of *Inter Partes* Review
37 C.F.R. § 42.108

I. INTRODUCTION

Koito Manufacturing Co., Ltd. (“Petitioner”) filed a Petition to institute an *inter partes* review of claims 3–26 and 28–35 of U.S. Patent No. 7,241,034 C1 (Ex. 1001; “the ’034 Patent”). Adaptive Headlamp Technologies, Inc. (“Patent Owner”) filed a Preliminary Response (Paper 10; “Prelim. Resp.”). We have jurisdiction under 35 U.S.C. § 314(a), which provides that an *inter partes* review may not be instituted “unless . . . there is a reasonable likelihood that the petitioner would prevail with respect to at least 1 of the claims challenged in the petition.”

On this record and for the reasons discussed below, we institute an *inter partes* review of claims 3–26, 28–32, and 35 of the ’034 Patent. We have not made a final determination under 35 U.S.C. § 318(a) as to the patentability of any claim.

II. BACKGROUND

A. *Related Proceedings*

The ’034 Patent was previously the subject of an *inter partes* reexamination that resulted in the issuance of an *inter partes* reexamination certificate (Ex. 1002). The ’034 Patent also was the subject of prior litigation in the U.S. District Court for the Eastern District of Texas. Pet. 1–2. Neither Petitioner nor its subsidiaries were parties to this prior case, which was dismissed without prejudice on May 18, 2010. *See id.* The ’034 Patent is asserted by Patent Owner in several pending litigations in the U.S. District Court for the District of Delaware. Pet. 2; Paper 6, 2–3. Petitioner is not a party to any of the Delaware litigations. *See id.*

B. The '034 Patent

The '034 Patent discloses a structure and method for operating a directional control system for vehicle headlights. Ex. 1001, Abstract.

Figure 1 of the '034 Patent is reproduced below.

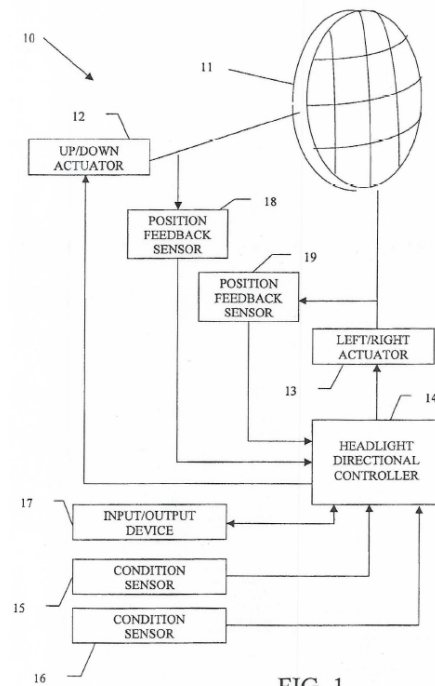


FIG. 1

Figure 1 is a block diagram of automatic directional control system 10 for a vehicle headlight. *Id.* at 2:28–30, 63–65. Headlight 11 is mounted on a vehicle in a manner that permits the direction of projected light to be adjusted by actuators 12 and 13. *Id.* at 3:10–13, 26–28. Condition sensors 15 and 16 sense operating conditions of the vehicle, and generate electrical signals that are responsive to the sensed operating conditions. *Id.* at 3:61–64. Headlight directional controller 14 receives the electrical signals generated by condition sensors 15 and 16, and responds by selectively operating actuators 12 and 13 to adjust the position of headlight 11. *Id.* at 3:49–58. The disclosed automatic directional control system also includes

feedback sensors 18 and 19, which generate signals representative of the actual up/down and left/right position of headlight 11, and supply these signals to controller 14. *Id.* at 4:8–24. These signals can be used to calibrate the disclosed system. *Id.* at 6:10–17.

C. Challenged Claims

Challenged claims 3 and 7 are independent claims, and the remaining challenged claims depend from either claim 3 or claim 7. Claim 7 is illustrative of the challenged claims, and is reproduced below.

7. An automatic directional control system for a vehicle headlight, comprising:

two or more sensors that are each adapted to generate a signal that is representative of at least one of a plurality of sensed conditions of a vehicle such that two or more sensor signals are generated, said sensed conditions including at least a steering angle and a pitch of the vehicle;

a controller that is responsive to said two or more sensor signals for generating at least one output signal only when at least one of said two or more sensor signals changes by more than a predetermined minimum threshold amount to prevent at least one of two or more actuators from being operated continuously or unduly frequently in response to relatively small variations in at least one of the sensed conditions; and

said two or more actuators each being adapted to be connected to the vehicle headlight to effect movement thereof in accordance with said at least one output signal;

wherein said two or more sensors include a first sensor and a second sensor; and

wherein said first sensor is adapted to generate a signal that is representative of a condition including the steering

angle of the vehicle and said second sensor is adapted to generate a signal that is representative of a condition including the pitch of the vehicle.

D. References and Materials Relied Upon

Petitioner relies on the following references and materials in support of the asserted grounds of unpatentability:

References and Materials	Exhibit No.
Japan Patent Application Publication H10-324191 (pub. Dec. 8, 1998) (“Kato”)	1006, 1007
UK Published Patent Application GB 2 309 774 A (pub. Aug. 6, 1997) (“Takahashi”)	1008
Japan Patent Application Publication H7-164960 (pub. June 27, 1995) (“Mori”)	1009, 1010
Japan Patent Application Publication H01-223042 (pub. Sept. 6, 1989) (“Uguchi”)	1011, 1012
Ishikawa et al, “ <i>Auto-Levelling Projector Headlamp System with Rotatable Light Shield,</i> ” SAE Technical Paper Series No. 930726, Mar.1993 (“Ishikawa”)	1013
U.S. Patent No. 5,751,832 (iss. May 12, 1998) (“Panter”)	1014
Japan Patent Application Publication H6-335228 (pub. Dec. 2, 1994) (“Suzuki”)	1015, 1016
U.S. Patent No. 6,193,398 B1 (iss. Feb. 27, 2001) (“Okuchi”)	1017
Declaration of Ralph V. Wilhelm, Ph.D. (“Wilhelm Decl.”)	1019

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