

V.

BLUE BELT TECHNOLOGIES, INC. and CARNEGIE MELLON UNIVERSITY, Exclusive Licensee and Patent Owner.

IPR2015-00630

U.S. Patent No. 6,205,411 B1

REPLY TO PETIONTER'S OPPOSITION TO MOTION TO AMEND

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GLOSSARY OF ABBREVIATIONS

Shorthand	Description
'411 Patent	U.S. Patent No. 6,205,411, provided as Ex. 1001
Chao	E.Y.S. Chao et al., "Simulation and Animation of Musculoskeletal Joint System," Transactions of the ASME, Vol. 115, pp. 562-568, Nov. 1993, provided as Ex. 1007.
Cleary Decl.	Declaration of Dr. Kevin Cleary, provided as Ex. 2003.
DiGioia	A.M. DiGioia et al., "HipNav: Pre-operative Planning and Intraoperative Navigational Guidance for Acetabular Implant Placement in Total Hip Replacement Surgery," 2nd CAOS Symposium, 1996, provided as Ex. 1005.
DiGioia II	Anthony M. DiGioia III et al., "An Integrated Approach to Medical Robotics and Computer Assisted Surgery in Orthopaedics," Proc. 1st Int'l Symposium on Medical Robotics and Computer Assisted Surgery, pp. 106-111, 1995, provided as Ex. 1006.
Howe Decl.	Declaration of Robert D. Howe, provided as Ex. 1004.
Howe Dep.	Deposition Transcript of Dr. Robert Howe, provided as Ex. 2006.
Jaramaz Decl.	Declaration of Dr. Branislav Jaramaz, provided as Ex. 2002.
Jaramaz Dep.	Deposition Transcript of Dr. Branislav Jaramaz – Filed Under Seal, provided as Ex. 1011.
Kischell Decl.	Declaration of Eric R. Kischell, provided as Ex. 1013
MTA	Motion to Amend, Paper No. 12 (Nov. 10, 2015).
Орр.	Petitioner's Opposition, Paper No. 25 (Feb. 19, 2016).
O'Toole	R.V. O'Toole III et al., "Towards More Capable and Less Invasive Robotic Surgery in Orthopaedics," Computer



	Vision, Virtual Reality and Robotics in Medicine Lecture Notes in Computer Science, Vol. 905, pp. 123-130, 1995, provided as Ex. 1008.
Pet'r	Petitioner Mako Surgical Corp.
РО	Patent Owner Carnegie Mellon University and Exclusive Licensee Blue Belt Technologies, Inc.
Taylor	Russell H. Taylor et al., An Image-Directed Robotic System for Precise Orthopaedic Surgery, IEEE Transactions on Robotics and Automation, Vol. 10, No. 3, June 1994, provided as Ex. 1009.



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