



US005708584A

United States Patent [19]

[11] Patent Number: **5,708,584**

Doi et al.

[45] Date of Patent: **Jan. 13, 1998**

[54] **VEHICLE RUNNING MODE DETECTING SYSTEM**

FOREIGN PATENT DOCUMENTS

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[57] ABSTRACT

In a vehicle running mode detecting system, a relative speed of a vehicle, equipped with the vehicle running mode detecting system, to a forward object is calculated on the basis of a time elapsed from a reference time based on which the time elapsed is measured and a change in the distance between the vehicle and the forward object during the time elapsed. Whether the vehicle is running in a constant distance mode where the distance between the vehicle and the forward object is kept substantially constant or in a varying distance mode where the vehicle is accelerating or decelerating relative to the forward object and the distance between the vehicle and the forward object is varying is determined on the basis of the change in the distance between the vehicle and the forward object. The reference time is updated less frequently when the vehicle is running in the constant distance mode than when the vehicle is running in the varying distance mode.

[21] Appl. No.: **525,218**

[22] Filed: **Sep. 8, 1995**

[30] Foreign Application Priority Data

Sep. 14, 1994 [JP] Japan 6-220294

[51] Int. Cl.⁶ **B60T 8/32**

[52] U.S. Cl. **364/426.044; 364/461; 180/169; 180/170; 340/903**

[58] Field of Search **364/426.041, 426.044, 364/460, 461, 565; 180/167-170, 176-179; 123/350, 352; 342/454, 455; 340/903, 904**

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9 Claims, 5 Drawing Sheets

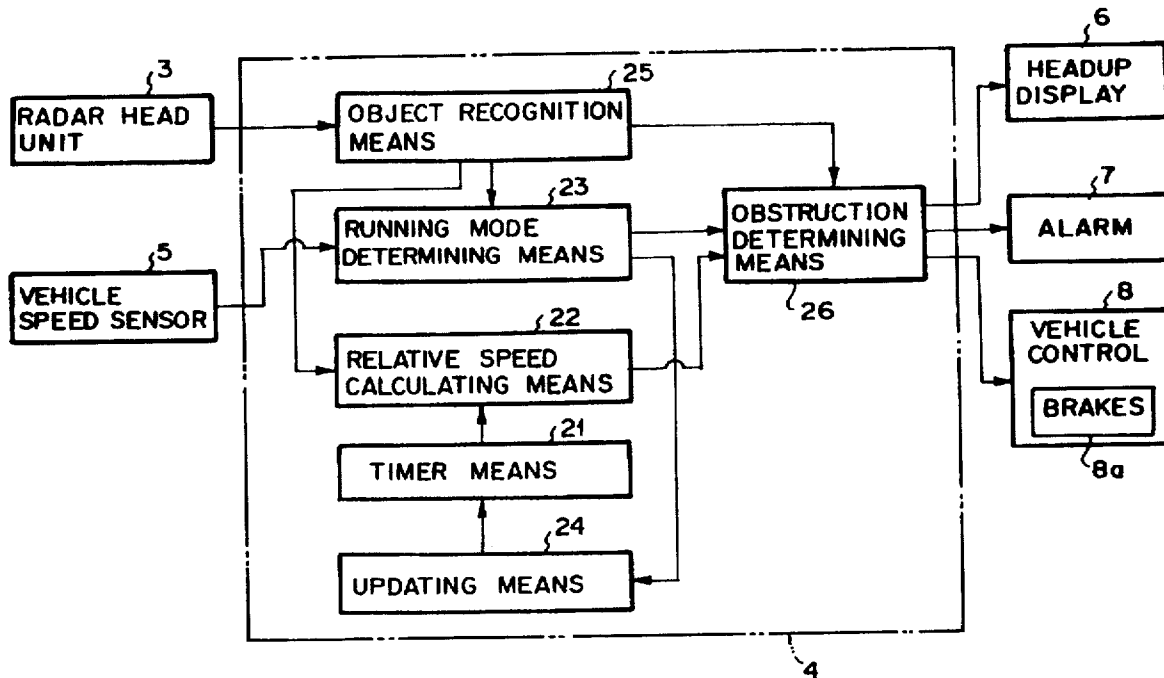


FIG. 1

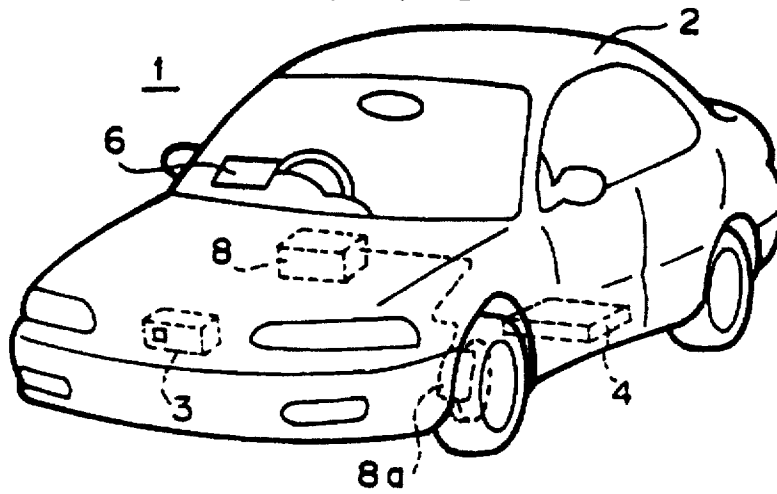
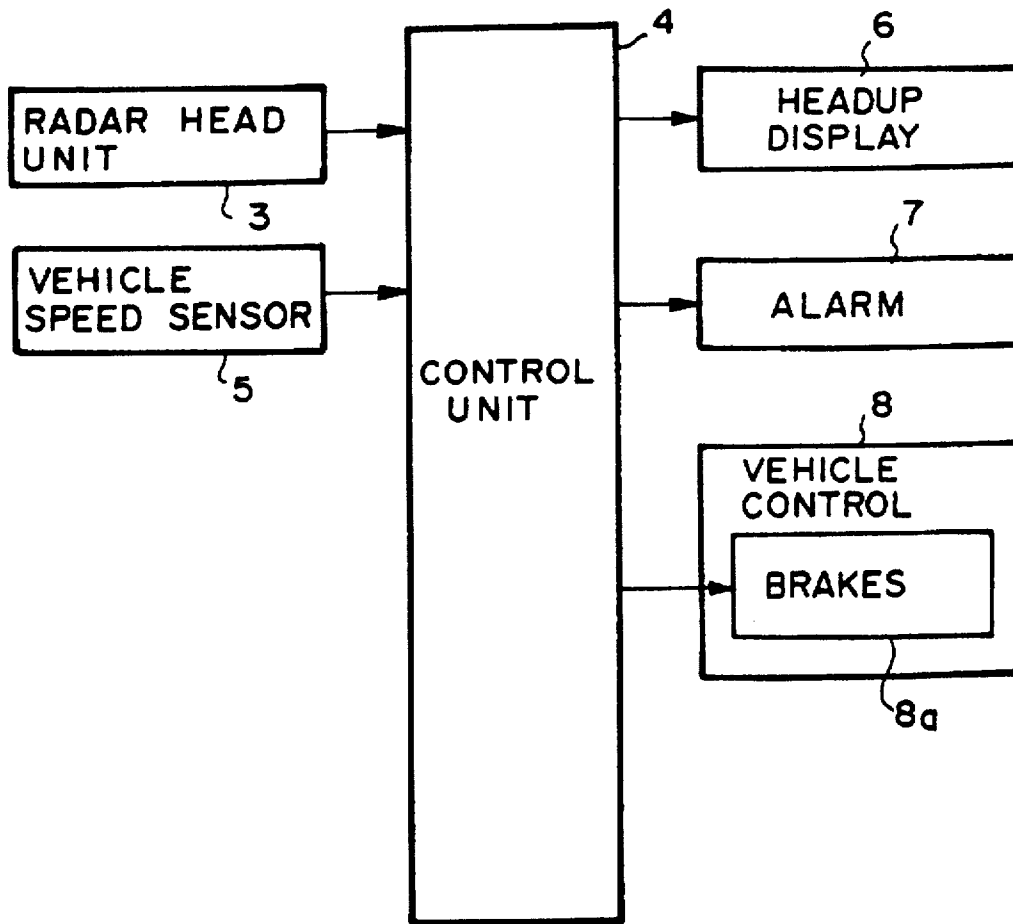


FIG. 2



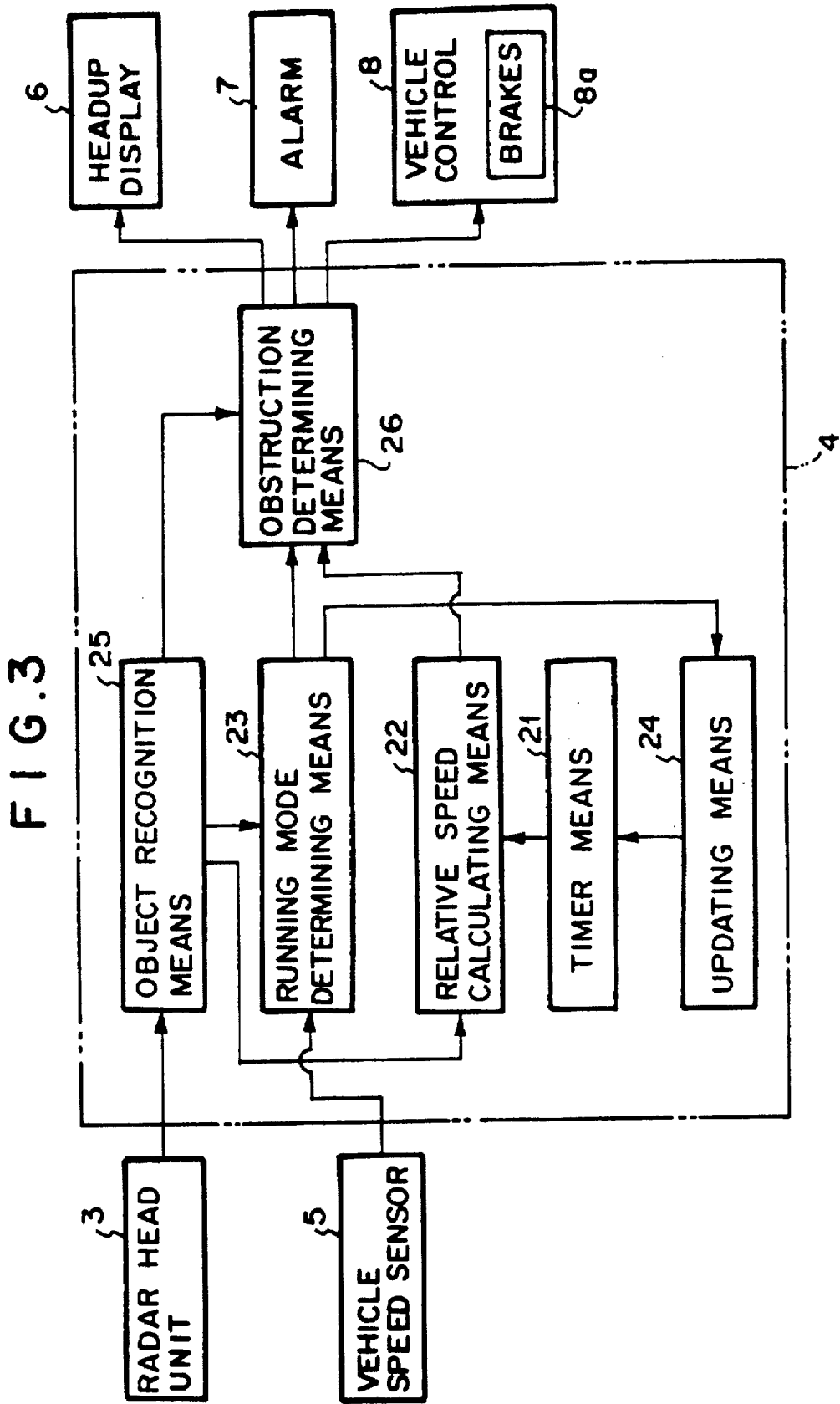


FIG. 4

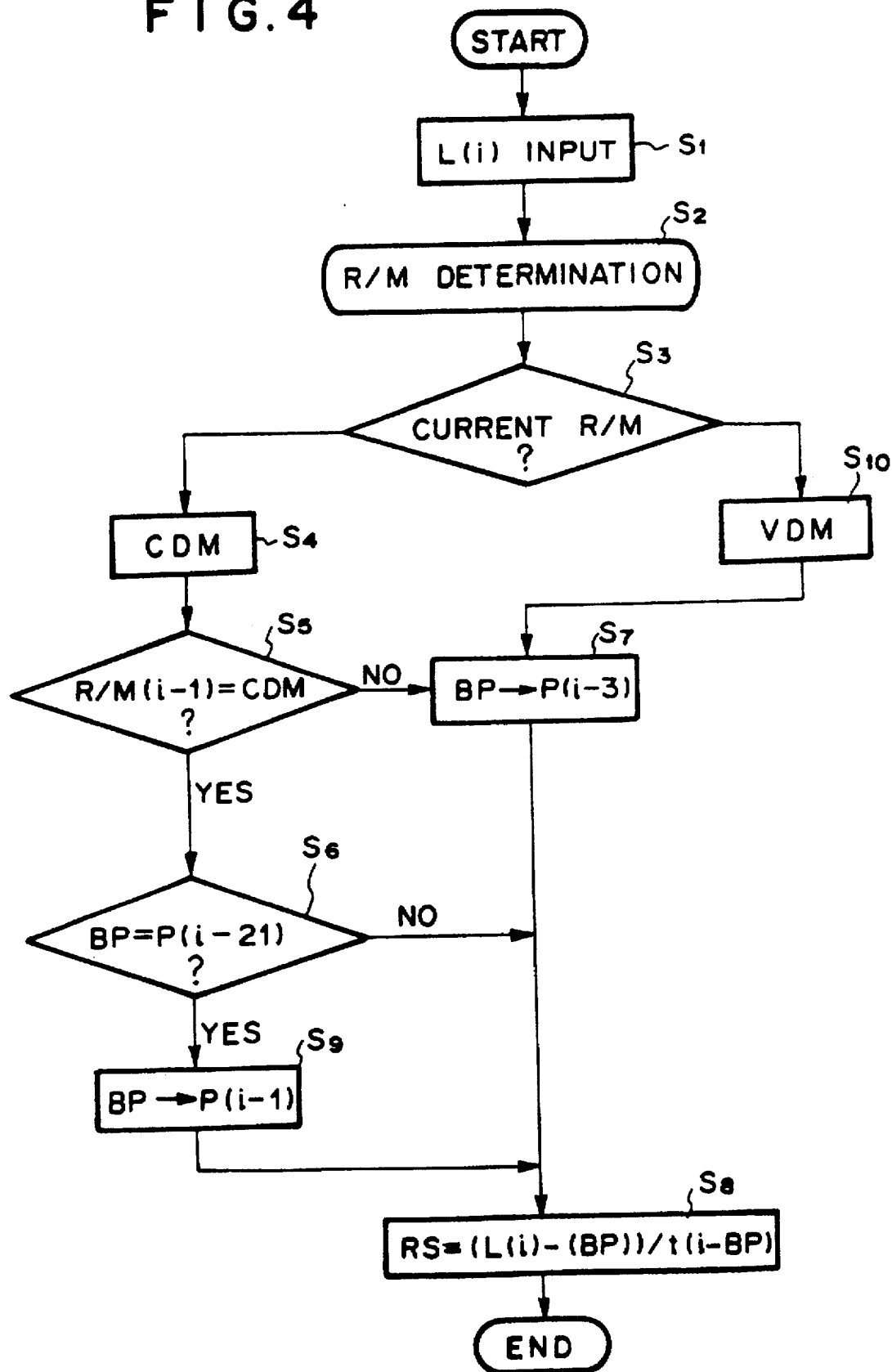
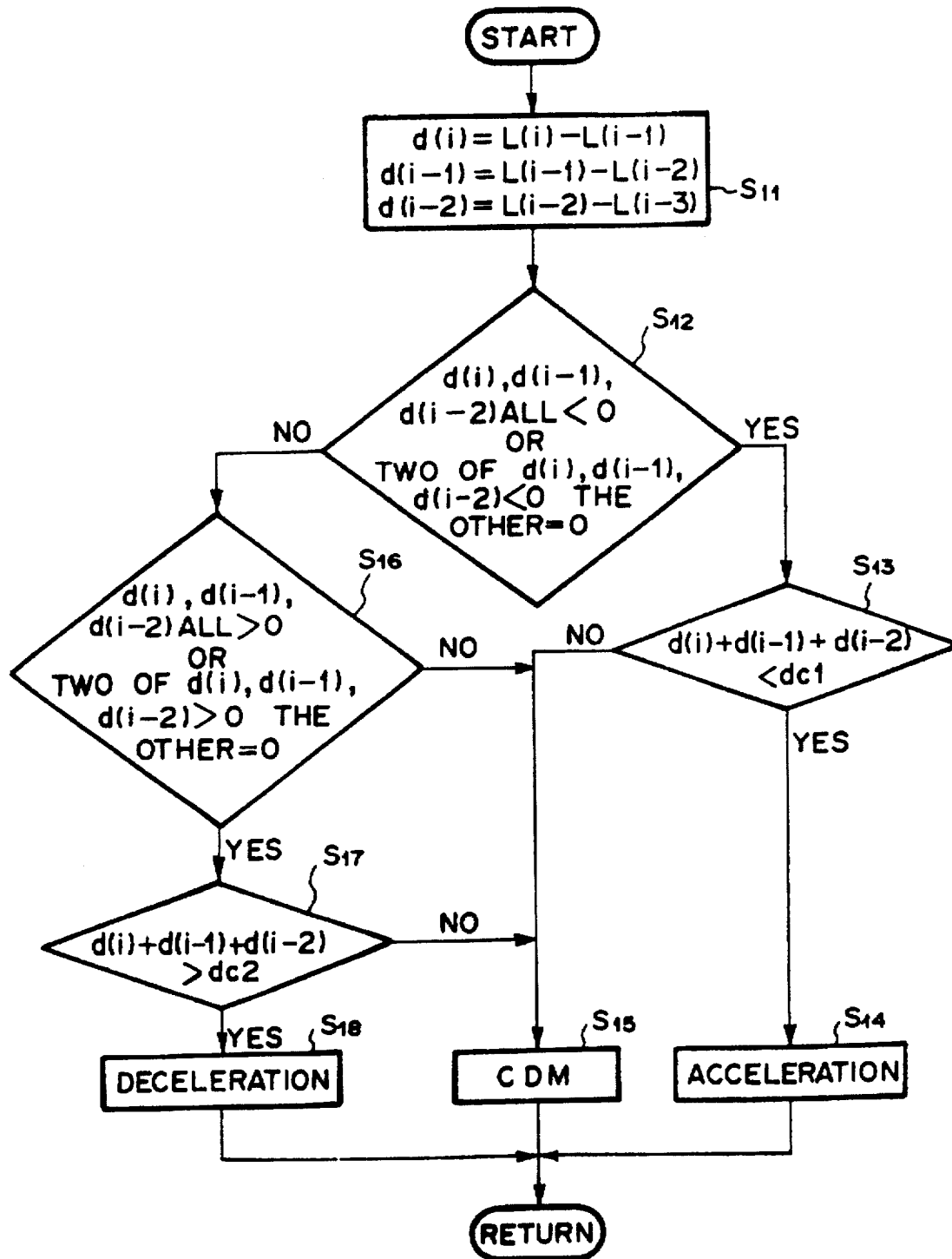


FIG. 5



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