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(12) United States Patent Kalb et al.

(10) Patent No.: US 6,710,562 B1 (45) Date of Patent: Mar. 23, 2004

(54)	SYNCHRONOUS MOTOR WITH AN
	ELECTRONIC CONTROL DEVICE FOR
	ADJUSTING DEVICES IN MOTOR
	VEHICLES AND METHOD FOR
	CONTROLLING THEM

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(73) Assignee: Brose Fahrzeugteile GmbH & Co.

KG, Coburg (DE)

(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35

U.S.C. 154(b) by 13 days.

(21) Appl. No.: 10/129,465

(22) Filed: Aug. 2, 2002

(30) Foreign Application Priority Data

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(58)	Field of Search	318/264, 265
` ′	210/266 206	122 122 121 127 166

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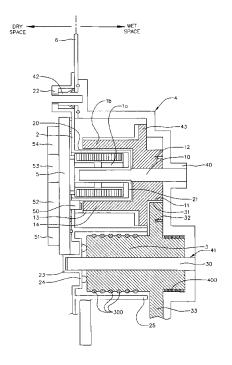
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Primary Examiner—Bentsu Ro (74) Attorney, Agent, or Firm—Christie, Parker & Hale, LLP

(57) ABSTRACT

Amethod for controlling a synchronous motor driven adjustment device is used in motor vehicles by means of an electronic control, especially for controlling adjustment devices with an anti-trap protection and/or with an excess force limitation. The method includes evaluating variables correlating to the dynamics of the adjusting device or the position of the adjustment member and generating control signals based on the variables, controlling the adjustment rate of the adjustment member to a constant value, and setting a phase displacement between an exciting field and a rotating field of the motor to provide torque to the drive unit based on the load angle at which the torque reaches a maximum.

17 Claims, 3 Drawing Sheets



468, 469

UUSI, LLC Exhibit 2027

WEBASTO ROOF SYSTEMS, INC. Petitioner v. UUSI, LLC Patent Owner

Case:

IPR2014-00650 Patent: 7,579,802





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(54) SYNCHRONOUS MOTOR WITH AN ELECTRONIC CONTROL DEVICE FOR ADJUSTING DEVICES IN MOTOR VEHICLES AND METHOD FOR CONTROLLING THEM

(75) Inventors: Roland Kalb, Rossach (DE); Craig

Kinnell, Coburg (DE)

(73) Assignee: Brose Fahrzeugteile GmbH & Co.

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318/266, 286, 432, 433, 434, 437, 466, 468, 469

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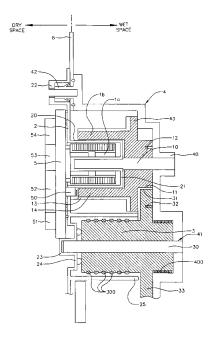
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(57) ABSTRACT

A method for controlling a synchronous motor driven adjustment device is used in motor vehicles by means of an electronic control, especially for controlling adjustment devices with an anti-trap protection and/or with an excess force limitation. The method includes evaluating variables correlating to the dynamics of the adjusting device or the position of the adjustment member and generating control signals based on the variables, controlling the adjustment rate of the adjustment member to a constant value, and setting a phase displacement between an exciting field and a rotating field of the motor to provide torque to the drive unit based on the load angle at which the torque reaches a maximum.

17 Claims, 3 Drawing Sheets



UUSI, LLC Exhibit 2031

WEBASTO ROOF SYSTEMS,

INC.

Petitioner

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UUSI, LLC

Patent Owner

Case:

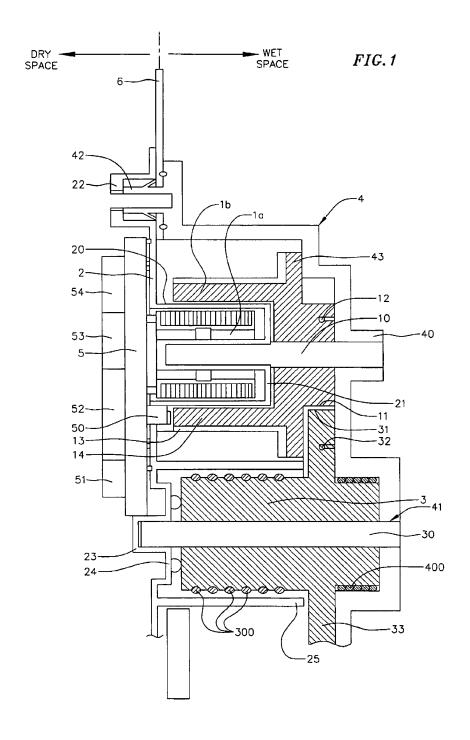
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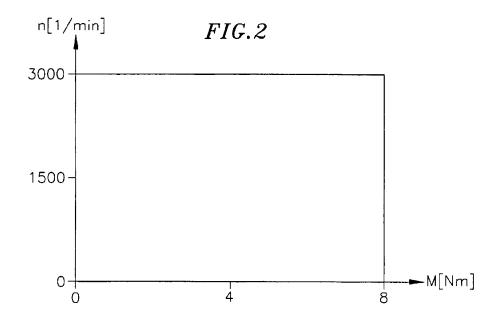
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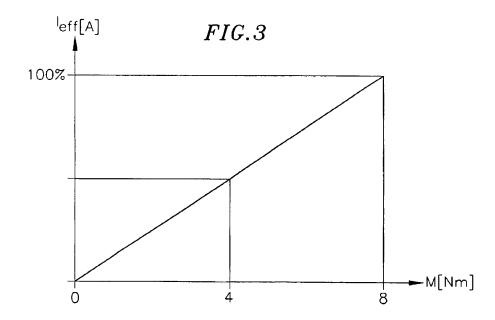


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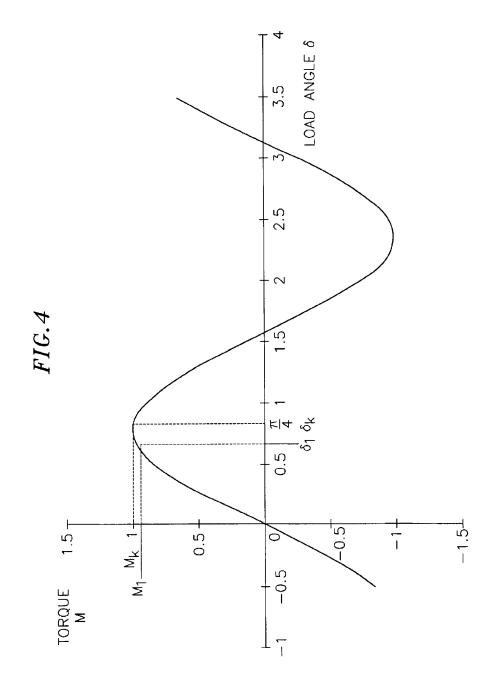


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