

# Patent Owners' Oral Hearing Demonstratives

IPR2014-00570 (USPN 8,214,097)  
IPR2014-00571 (USPN 7,104,347)  
IPR2014-00579 (USPN 7,104,347)  
IPR2014-00875 (USPN 7,559,388)  
IPR2014-00884 (USPN 7,104,347)  
IPR2014-00904 (USPN 7,237,634)

***Petitioner Ford Motor Company***

***v.***

***Paice LLC & The Abell Foundation, Inc.***



***Before Sally C. Medley, Kalyan K. Deshpande, and Carl M. DeFranco,  
Administrative Patent Judges***

PAICE 2009  
IPR2014-00570

Ford v. Paice & Abell

# Agenda

- **Introduction**
- **Patent/Technology Overview**
- **Claim Construction**
- **Three groups of IPRs:**
  - I. **IPR2014-00571 ('347 Patent) and IPR2014-00904 ('634 Patent)**
  - II. **IPR2014-00579 ('347 Patent) and IPR2014-00884 ('347 Patent)**
  - III. **IPR2014-00570 ('097 Patent) and IPR2014-00875 ('388 Patent)**

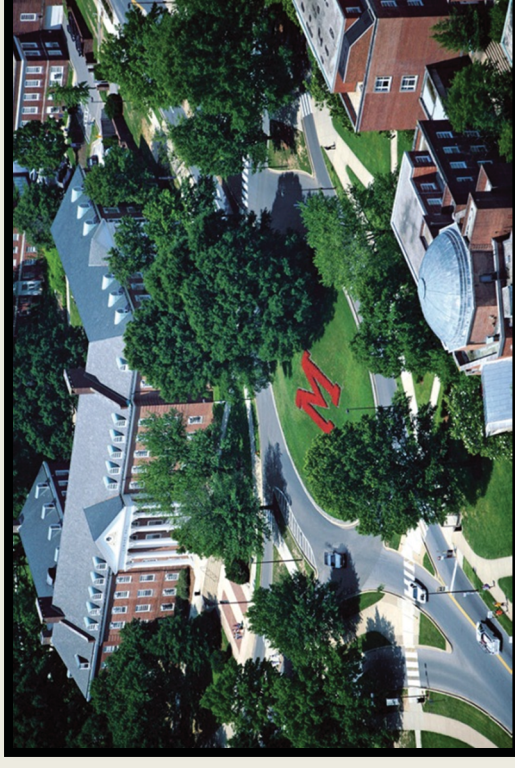
# Introduction

# Introduction to the Patent Owners



## Who is Paice?

- Paice was founded in 1992 by Dr. Alex Severinsky with support from the University of Maryland's small company incubator program.
- Paice's goal: develop the most fuel efficient and cost-effective hybrid electric vehicle system possible, while significantly lowering emissions.



## Who is The Abell Foundation?

- **The Abell Foundation is a charitable organization that contributes millions of dollars to support worthwhile causes across Maryland.**
- **Traditionally focuses on caring for the underserved through education, healthcare, and human services initiatives.**
- **But occasionally invests in promising local companies — including those focused on environmental issues — with the goal of reinvesting any earnings back into the communities it serves.**
- **The Abell Foundation invested in Paice in 1998 and has since provided more than \$30 million in support to help Paice achieve its goals.**

## History of Paice and Ford

- Paice has been involved with the world's top automotive manufacturers in developing commercially viable hybrid vehicles.
- Between 1999 and 2004, Paice spent extensive time working with Ford to teach Ford Paice's hybrid vehicle technology, including detailed modeling of Paice's patented technology in actual and proposed Ford vehicles.
- In 2010, Paice reached a significant license on Paice's entire patent portfolio with Toyota, the world's most successful hybrid auto manufacturer.
- In 2010, Ford took a license to Paice's '970 patent, and entered into an Arbitration Agreement to resolve further disputes.
- Ford ultimately declined to arbitrate, and instead filed 25 separate Petitions for *Inter Partes* Review before this Board.

# Patent/Technology Overview



# Background of the Challenged Patents

- **Challenged Patents:**
  - **U.S. Patent No. 7,104,347 (“the ‘347 Patent”)**
  - **U.S. Patent No. 7,237,634 (“the ‘634 Patent”)**
  - **U.S. Patent No. 7,559,388 (“the ‘388 Patent”)**
  - **U.S. Patent No. 8,214,097 (“the ‘097 Patent”)**



## Paice's expert – Neil Hannemann

- **Mr. Hannemann's career spans more than 25 years including specialty vehicle development positions with Ford, GM, DaimlerChrysler, Saleen, and McLaren.**
- **He has designed and worked with numerous actual hybrid vehicles including:**
  - **The Kepler Motion hybrid sports car (pictured bottom right)**
  - **The Chrysler Patriot**
  - **Hybrid configurations for the McLaren MP4/12C sports car**



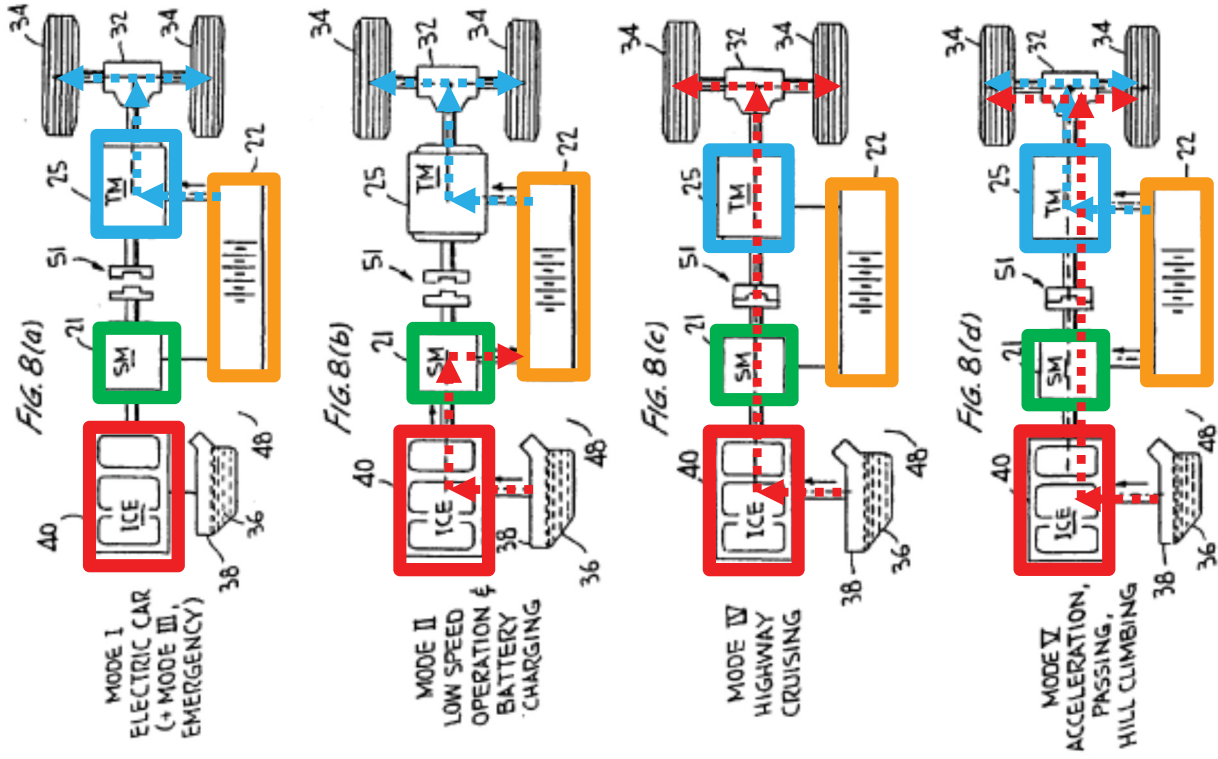




# Technology Background

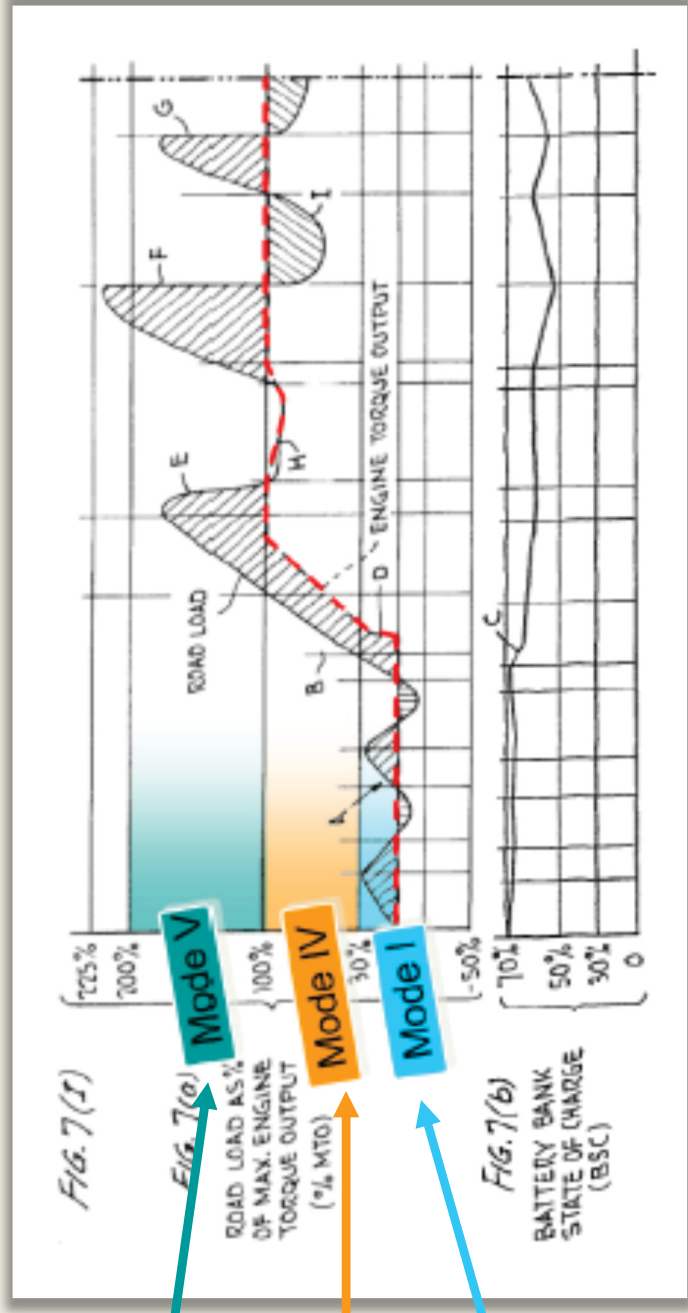
- The hybrid electric vehicle of the challenged patents can be operated in various “modes,” i.e. different combinations of the motor, engine, or both, to propel the vehicle:

- **Mode I: motor only propulsion**
- **Mode II: motor propulsion, engine charges the battery**
- **Mode IV: engine propulsion**
- **Mode V: engine and motor propulsion**



# Technology Background

- In a number of embodiments, switching between these modes depends on an innovative system that compares the “road load” (depicted as a solid line in the example from Fig. 7) to a “setpoint.”



Engine + motor propulsion

Engine propulsion

Motor only propulsion

# Technology Background

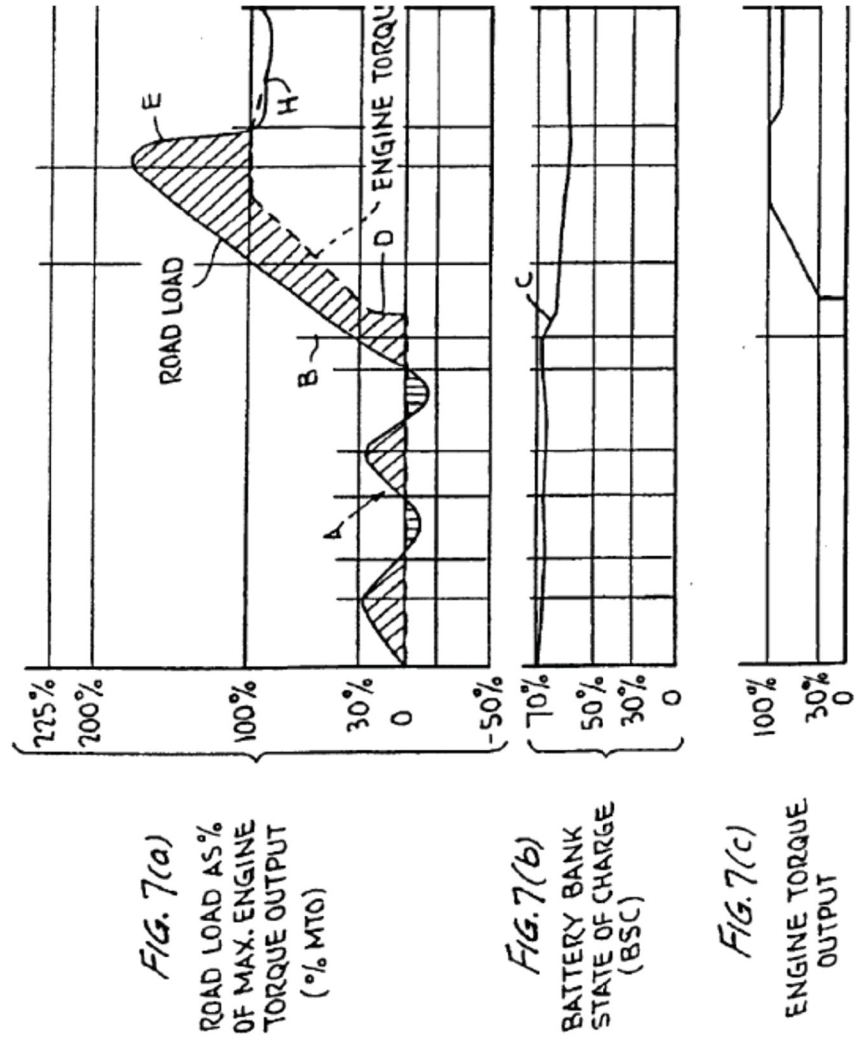
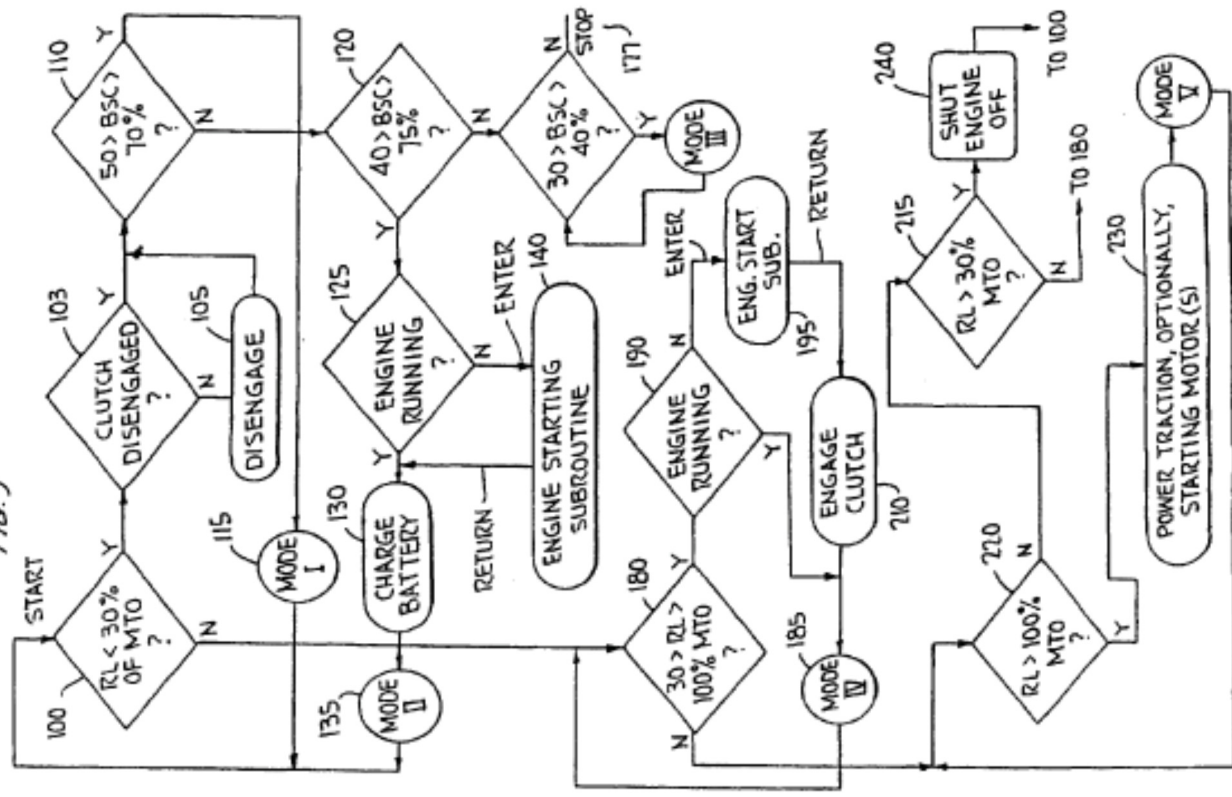


Fig. 9





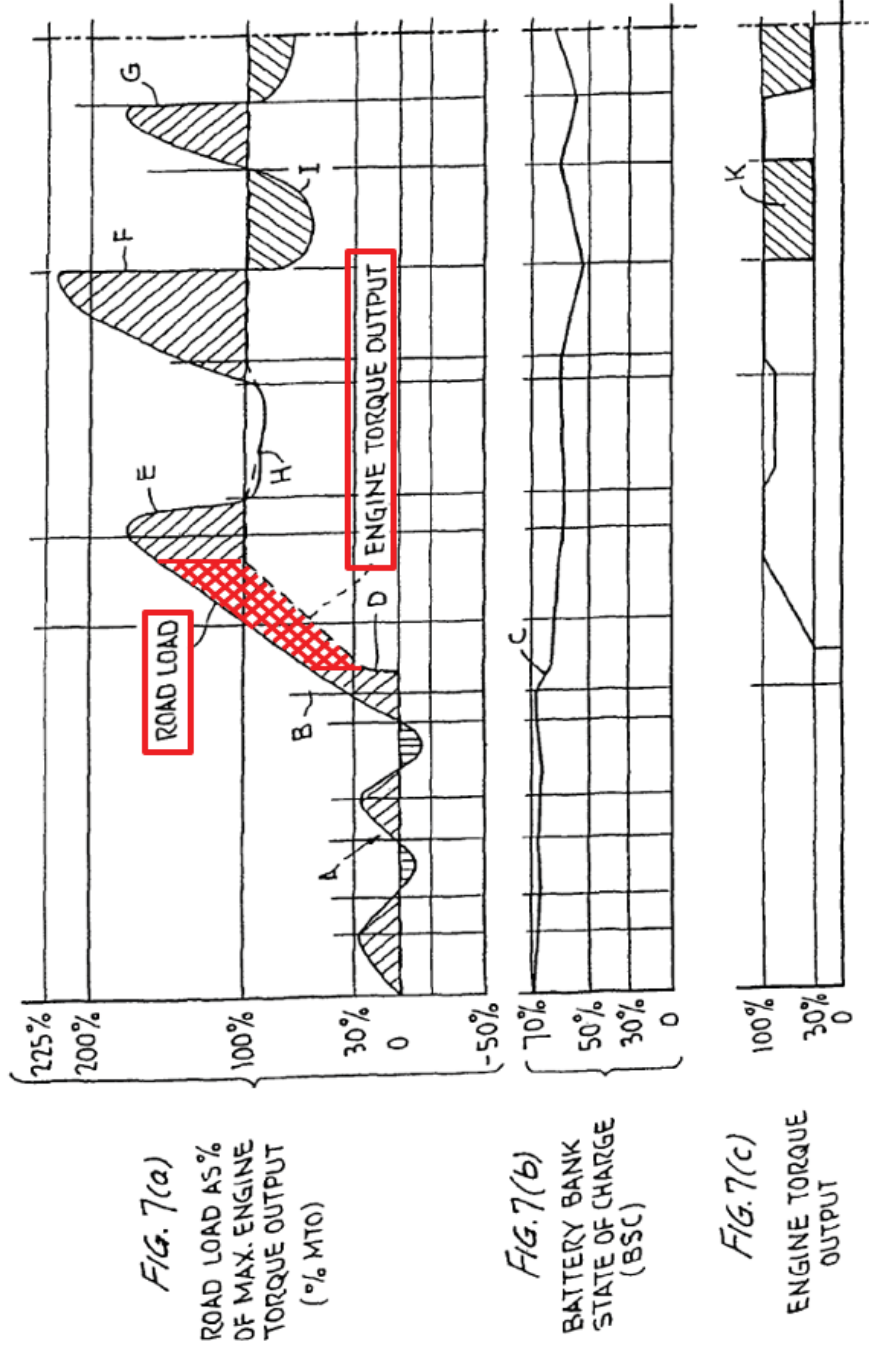


## “Road load”

- Many of the challenged claims are directed to a vehicle control system that uses “road load” in a control system that determines the vehicle operating mode based on the “road load.”
- Prior art metrics however failed to recognize that the “vehicle operational mode should preferably be controlled in response to the vehicle’s actual torque requirements, i.e., the road load.”
- “Road load” provides “superior performance, in terms of both vehicle response to operator commands and fuel efficiency, under the widely varying conditions encountered in ‘real world’ driving situations.”
- Some of the other control metrics used by Ford’s asserted prior art:
  - Vehicle speed
  - Pedal position
  - Power

# Technology Background

“The rate of change of the engine’s torque output is limited, e.g., to 2% or less per revolution, as indicated by noting that the dashed line in FIG. 7(a), indicating the instantaneous engine output torque, lags the solid line indicating the vehicle’s instantaneous torque requirement. Thus limiting the rate of change of engine output torque is preferred to limit undesirable emissions and improve fuel economy”



'097 Patent at 38:62-39:1

'097 Patent at Fig. 7.

# Claim Construction

# Board's Initial Claim Constructions

Claim Term:	Relevant Patents/IPRs:	Board's Construction:
"road load"	'347 Patent: IPR2014-00571 IPR2014-00579 IPR2014-00884 '388 Patent: IPR2014-00875 '634 Patent: IPR2014-00904	"the amount of instantaneous torque required to propel the vehicle, be it positive or negative."
"setpoint (SP)"	'347 Patent IPR2014-00571 IPR2014-00579 IPR2014-00884 '634 Patent: IPR2014-00904	"a predetermined torque value that may or may not be reset."

# Disputed Claim Constructions

- Parties do not dispute the construction of “road load” in IPRs ‘571, ‘579, ‘875, ‘884, and ‘904.
- Patent Owner opposes the Board’s construction of “setpoint (SP)” (in IPRs ‘571, ‘579, ‘884, and ‘904) and respectfully requests that the Board adopt Patent Owner’s proposed construction:

Claim term	Patent Owner’s Proposed Construction
“setpoint (SP)”	“a definite, but potentially variable value at which a transition between operating modes may occur.”

## Claim Construction Standards

- The Board’s “broadest” interpretation must be reasonable, and must be in conformity with the invention as described in the specification. *In re Vaidyanathan*, 381 Fed. Appx. 985, 995-96 (Fed. Cir. 2010)
- Board must consider the entirety of the claims and specification, and cannot limit its analysis to just a portion of the disputed claim phrase, which would be clear, reversible error.
- See e.g. *In re Abbott Diabetes Care Inc.*, 696 F.3d 1142, 1149 (Fed. Cir. 2012) (holding that Board’s construction of “electrochemical sensor” was “unreasonable and inconsistent with the language of the claims and the specification”).

# “Setpoint,” “SP”

<b>Patent Owner’s Proposed Claim Construction</b>	<b>Board’s Construction</b>
<p>“a definite, but potentially variable value at which a transition between operating modes may occur.”</p>	<p>“a predetermined torque value that may or may not be reset.”</p>

- The Board’s construction of “setpoint (SP)” is incorrect because it fails to recognize that “setpoint” represents a point at which a transition between different operating modes may occur.
- The U.S. District Court for the Eastern District of Texas and the U.S. District Court for the District of Maryland have both construed the term consistently with Patent Owner’s proposed construction.



## “Setpoint,” “SP” marks a transition between modes

- Claim language makes clear that a “setpoint” marks a point at which the vehicle may transition between two modes, for example between a mode in which only the motor propels the vehicle, to modes in which the engine also can be used to propel the vehicle or charge the battery:

16. The hybrid vehicle of claim 1, wherein the controller is operable to implement a plurality of operating modes responsive to road load (RL) and the SP, wherein both the RL and the SP are expressed as percentages of the MTO of the engine when normally-aspirated, and wherein the operating modes comprise:

a low-load mode I, wherein, when the RL < the SP, the second electric motor is operable to provide torque to propel the hybrid vehicle;

a highway cruising mode IV, wherein, when the SP < the RL < the MTO, the engine is operable to provide torque to propel the hybrid vehicle, and wherein the controller is operable to start the engine if the engine is not running to enter the highway cruising mode IV; and an acceleration mode V, wherein, when the RL > the MTO, the engine, the first electric motor, and/or the second electric motor is operable to provide torque to propel the hybrid vehicle, and wherein the controller is operable to start the engine if the engine is not running to enter the acceleration mode V.

‘634 Patent, claim 16:

## “Setpoint,” “SP” marks a transition between modes

- Claim language makes clear that a “setpoint” marks a point at which the vehicle may transition between two modes, for example between a mode in which only the motor propels the vehicle, to modes in which the engine also can be used to propel the vehicle or charge the battery:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

‘347 Patent, claim 23:

## “Setpoint,” “SP” marks a transition between modes

- Specification makes clear that a “setpoint” is synonymous with a “transition point” between modes

[I]n the example of the inventive control strategy discussed above, it is repeatedly stated that the transition from low-speed operation to highway cruising occurs when road load is equal to 30% of MTO. This setpoint, referred to in the appended claims as "SP", and sometimes hereinafter as the transition point (i.e., between operation in modes I and IV) is obviously arbitrary and can vary substantially, e.g., between 30- 50% of MTO, within the scope of the invention.

‘347 Patent at col. 40:47-55



## Board's construction is unreasonably broad

- Board's construction reads out a crucial limitation of the claims: the "setpoint" marks the amount of "road load" at which the claimed control system actively changes the vehicle from one mode to another (e.g. from motor propulsion to engine propulsion).
- Board's failure to recognize the "transition" function of "setpoints" could rob the "mode" limitations of one of the key aspects of the invention, *i.e.* the significant efficiency to be gained by transitioning between motor propulsion to engine propulsion in response to "road load."
- Under the Board's improper construction, the claims could improperly be read to broadly cover hybrid vehicle systems where *transitions between modes never occur*.
- Such an unreasonably broad construction is fundamentally contrary to the specification of the challenged patents.

**IPR2014-00571 AND IPR2014-00904**

# IPR2014-00571 – Introduction

- U.S. Patent No. 7,104,347
- Ground 1 (§ 103):
  - Challenged claims: 23 and 36
  - Asserted Art: Severinsky
- Ground 2 (§ 103):
  - Challenged claims: 1, 6, 7, 9, 15 and 21
  - Asserted Art: Severinsky and Ehsani
- Ford’s Ground 3 was included in Ground 2:

As such, we exercise our discretion under 37 C.F.R. § 42.108 to view Ford’s challenge based on “Ehsani and Severinsky” not as a different ground, but simply as additional support for the ground of “Severinsky and Ehsani” on which we institute trial.

IPR2014-00571, Paper 12, Institution Decision at 16.

## IPR2014-00904 – Introduction

- U.S. Patent No. 7,237,634
- Ground 1 (§ 103):
  - Challenged claims: 1, 14, 16, 18 and 24
  - Asserted Art: Severinsky, Field, and SAE 1996
- The Board declined to institute Ground 2

And in the absence of Ford advancing some meaningful benefit to proceeding with the additional ground of Severinsky and Ehsani, we presume that it is the weaker of the two asserted grounds, and we exercise our discretion to deny institution of this presumably weaker ground. See 37 C.F.R. § 42.108(a).

IPR '904, Paper 13, Institution Decision at 13.



# Introduction to the '347 Patent

The '347 Patent (IPR '571, Ex. 1001) is directed to hybrid vehicles and control systems thereof

The '347 patent recognized that the "vehicle operational mode should preferably be controlled in response to the vehicle's actual torque requirements, i.e., the road load."

Use of "road load" according to the patent provides "superior performance, in terms of both vehicle response to operator commands and fuel efficiency, under the widely varying conditions encountered in 'real world' driving situations."



(12) United States Patent  
Severtinsky et al.

(10) Patent No.: US 7,104,347 B2  
(45) Date of Patent: Sep. 12, 2006

(64) HYBRID VEHICLES  
(75) Inventors: Alex J. Severtinsky, Washington, DC (US); Theodore Lonetree, Holly, MI (US)  
(73) Assignee: Pate LLC, Boca Raton, FL (US)  
(\* ) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 265 days.

(21) Appl. No.: 10/982,577  
(22) Filed: Mar. 7, 2003  
(65) Prior Publication Data  
US 2003/021876 A1 Nov. 27, 2003  
Related U.S. Application Data

(60) Division of application No. 09/822,866, filed on Apr. 2, 2000, which is a continuation-in-part of application No. 09/392,743, filed on Sep. 29, 1999, which is a continuation-in-part of application No. 09/254,817, filed on Mar. 9, 1999, now Pat. No. 6,309,672.  
(60) Division of application No. 60/132,286, filed on Mar. 1, 1999, and provisional application No. 60/100,075, filed on Sep. 14, 1998.

(31) Int. Cl. (2006.01)  
B60K 6/02  
(52) U.S. Cl. 180/65.2; 180/65.4; 701/54  
(58) Field of Classification Search 180/65.2; 180/65.4; 65.8; 165; 60/706; 711; 716; 607/18; 200/17; 40 R; 40 C; 322/16; 47/72; 701/54; 701/55; 701/54  
See application file for complete search history.

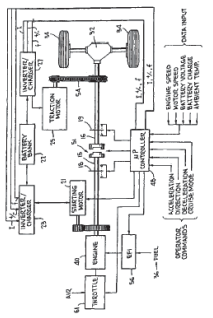
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(Continued)

Primary Examiner—David R. Dunn  
(74) Attorney, Agent, or Firm—Michael de Angelis  
ABSTRACT  
A hybrid vehicle comprises an internal combustion engine, a traction motor, a starter motor, and a battery bank, all controlled by a microprocessor in accordance with the vehicle's actual torque requirements. The microprocessor runs only under conditions of high efficiency, typically only when the load is at least equal to 30% of the engine's maximum torque output. In some embodiments, a turbo-charger may be provided, activated only when the load exceeds a predetermined threshold. In some embodiments, an extended period, a two-speed transmission may further be provided, to further broaden the vehicle's load range. A hybrid brake system provides regenerative braking, with mechanical braking available in the event the battery bank is fully charged. In some embodiments, a torque split mechanism is provided to control the brake system to provide linear brake feel under varying circumstances.

41 Claims, 17 Drawing Sheets



# Introduction to the '347 Patent

- Independent claim 1 turns the engine on “when torque require[d] to be produced by said engine to propel the vehicle and/or to drive either one or both said electric motor(s) to charge said battery is at least equal to a setpoint (SP).”
- Dependent claim 7 recites a “vehicle [that] is operated in a plurality of operating modes responsive to the value for the road load (RL) and said setpoint SP.”
- Independent claim 23 similarly recites selecting various operating modes by comparing the “road load” to a “setpoint.”



(12) United States Patent  
Severtsky et al. US 7,104,347 B2  
Sep. 12, 2006

(64) HYBRID VEHICLES  
(75) Inventors: Alex J. Severtsky, Washington, DC (US); Theodore Loncker, Holly, MI (US)  
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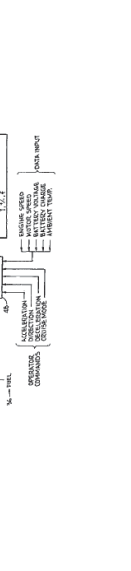
(31) Int. Cl.  
B60K 6/02 (2006.01)  
(52) U.S. Cl.  
180/65.2; 180/65.4; 701/54  
(58) Field of Classification Search  
180/65.3, 65.4, 65.8, 165; 60/706; 711, 716, 60718; 20017; 40 R; 40 C; 32216; 4772.  
See application file for complete search history.

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EP 0242 311 5/1996  
EP 0769 403 4/1997  
(Continued)

OTHER PUBLICATIONS  
Simpkins, “Electric Vehicles”, *Road & Track*, May 1992, pp. 126-129.  
Kobayashi, “AC Propulsion CRX”, *Road & Track*, Oct. 1992, pp. 126-129.  
Kubertsh, “Electric Hybrid Drive Systems . . .”, SAE Paper No. 910247, 1991.  
(Continued)


Primary Examiner—David R. Dunn  
(74) Attorney, Agent, or Firm—Michael de Angelis  
(57) ABSTRACT  
A hybrid vehicle comprises an internal combustion engine, a traction motor, a starter motor, and a battery bank, all controlled by a microprocessor in accordance with the vehicle's operating mode. The microprocessor is adapted to run only under conditions of high efficiency, typically only when the load is at least equal to 30% of the engine's maximum torque output. In some embodiments, a turbo-charger may be provided, activated only when the load is greater than a setpoint. In other embodiments, an extended period, a two-speed transmission may further be provided, to further broaden the vehicle's load range. A hybrid brake system provides regenerative braking, with mechanical braking available in the event the battery bank is fully charged. The microprocessor controls the transmission system is provided to control the brake system to provide linear brake feel under varying circumstances.



41 Claims, 17 Drawing Sheets

# Introduction to the '634 Patent

- The '634 Patent (IPR '904, Ex. 1001) is also directed to the control system of a hybrid vehicle and claims the use of road load to effect mode switching.
- Independent claim 1 operates the engine "when torque required from the engine to propel the vehicle and/or to drive one or more of the first or the second motors to charge the battery is at least equal to a setpoint (SP)."
- Dependent claim 16 recites a "wherein the controller is operable to implement a plurality of operating modes responsive to road load (RL) and the SP."


  
 US007237634B2

**(12) United States Patent**  
**Severinsky et al.**

**(10) Patent No.:** US 7,237,634 B2  
**(45) Date of Patent:** \*Jun. 3, 2007

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**(75) Inventors:** Alex J. Severinsky, Washington, DC (US); Theodore Louckes, Elroy, MI (US)

**(73) Assignee:** PAICE LLC, Boutte Springs, FL (US)

**(\*) Notice:** Subject to any disclaimer, the term of this patent is extended to its statutory term under 35 U.S.C. 154(b) by 0 days. This patent is subject to a terminal disclaimer.

**(21) Appl. No.:** 11/229,742  
**(22) Filed:** Jan. 13, 2006  
**(65) Prior Publication Data**  
 US 2006/010057 A1 May 11, 2006

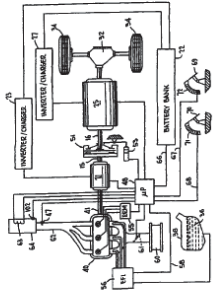
**Related U.S. Application Data**  
 Division of application No. 09/822,277, filed on Mar. 7, 2000, now Pat. No. 7,034,547, which is a continuation-in-part of application No. 09/822,866, filed on Apr. 2, 2001, now Pat. No. 6,554,088, which is a continuation-in-part of application No. 09/264,817, filed on Mar. 9, 1999, now Pat. No. 6,209,672, said application No. 09/264,817, which is a continuation-in-part of application No. 09/139,748, filed on Sep. 3, 1999, now Pat. No. 6,338,391.

**(60) Provisional application No. 60/122,206, filed on Mar. 1, 1999, provisional application No. 60/100,095, filed on Sep. 14, 1998.**

**Int. Cl.** (2006.01) B60K 6/02  
**U.S. Cl.** 180/65.2, 180/65.4, 180/701, 180/65.3, 65.4, 65.8, 165, 4772, 3, 701/54  
**(58) Field of Classification Search** 180/65.2  
 See application file for complete search history.

**(57) ABSTRACT**  
 A hybrid vehicle comprises an internal combustion engine, a traction motor, a starter motor, and a battery bank, all controlled by a microprocessor in accordance with the vehicle's instantaneous torque demands so that the engine is run only under conditions of high efficiency, typically only when the load is at least equal to 30% of the engine's maximum torque. The engine is operated only when the load charge may be provided, activated only when the load exceeds the engine's maximum torque output for an extended period; a two-speed transmission may further be provided, to further broaden the vehicle's load range. A hybrid brake system provides regenerative braking, with the engine providing the majority of the energy. The engine is fully charged in a vehicle or at a test stand; a microprocessor is provided to control the brake system to provide linear brake feel under varying circumstances.

306 Claims, 17 Drawing Sheets



# Introduction to the '347 and '634 Patents

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

'347 Patent, Claim 23

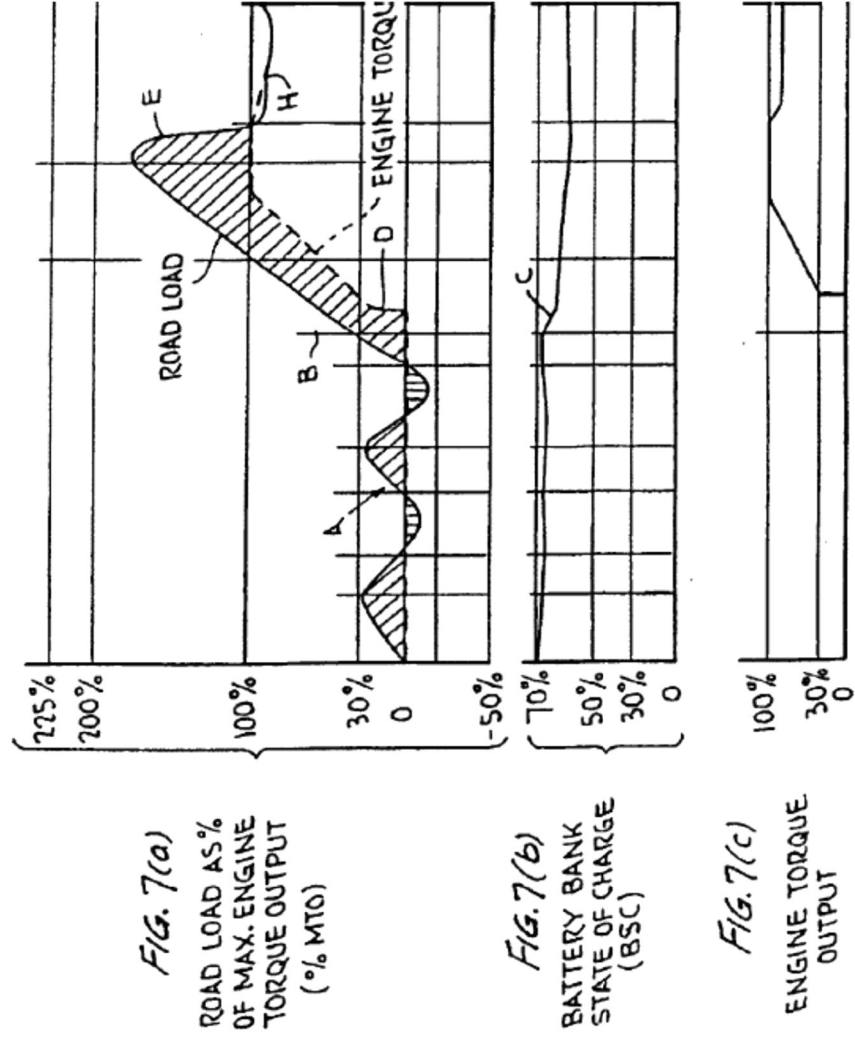
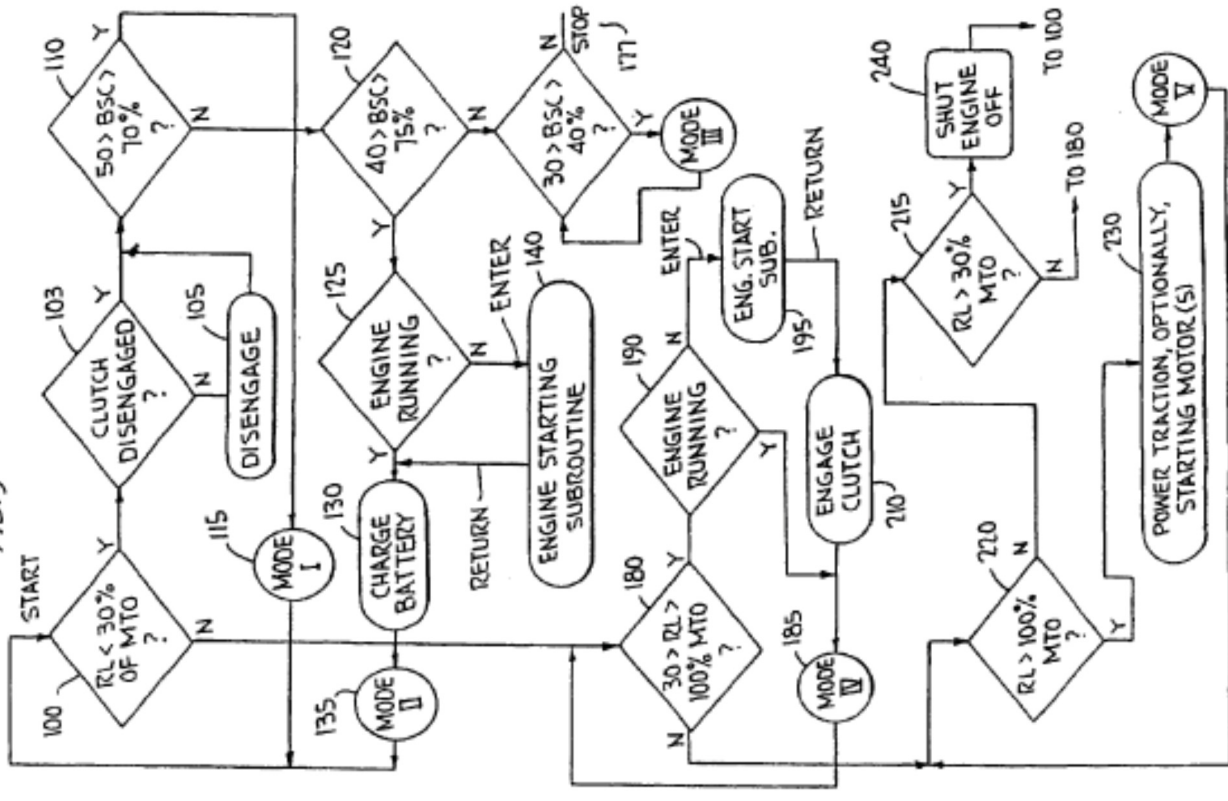


Fig. 9



'347 Patent, Fig. 7

'347 Patent, Fig. 9

# Introduction to the '347 and '634 Patents

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

'347 Patent, Claim 23

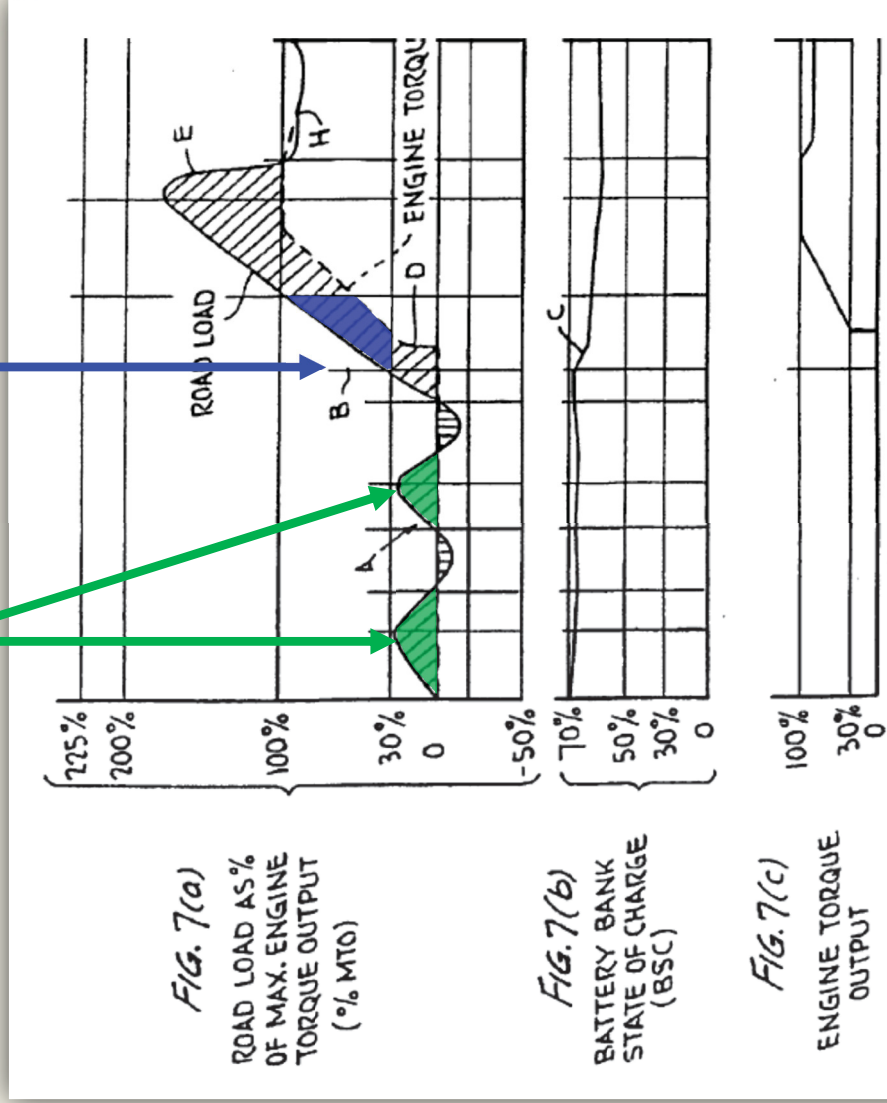
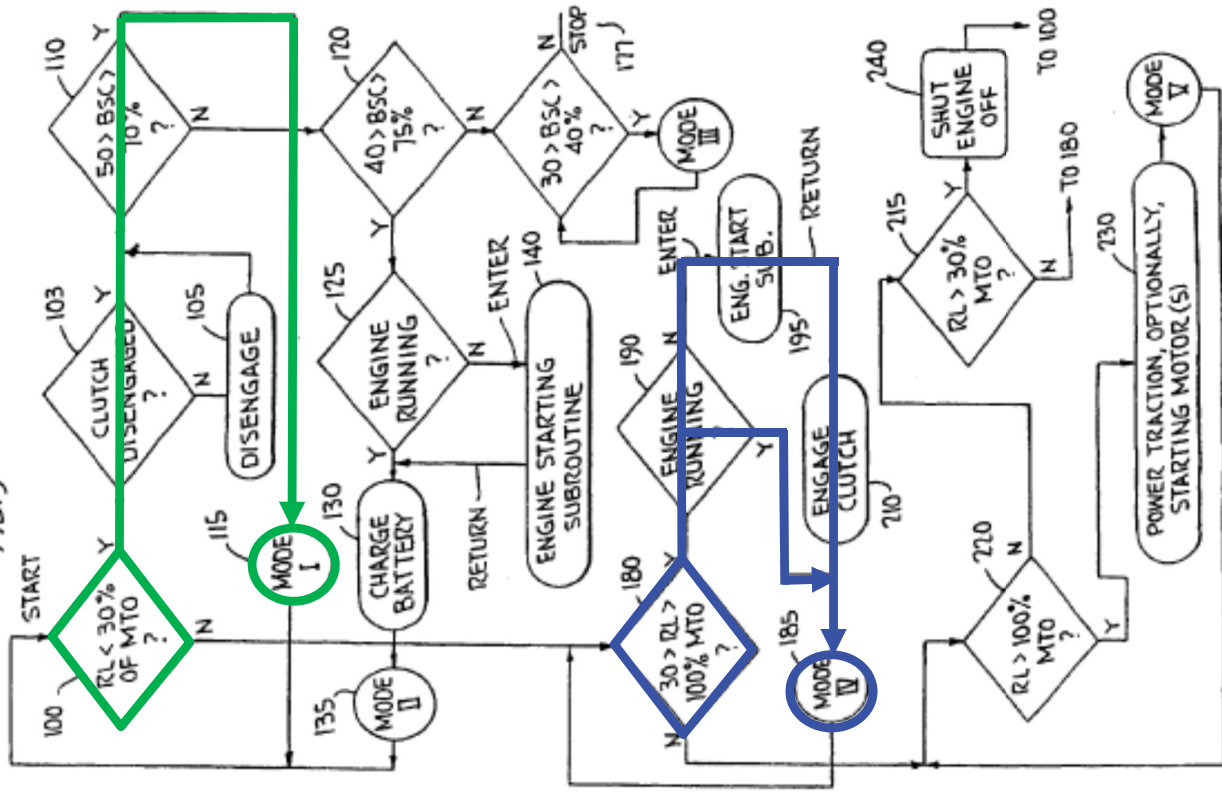


Fig. 9



# Ground 1 - Severinsky Does Not Disclose or Render Obvious Claims 23 and 36 of the '347 Patent

# '347 Patent - Claim 23 Introduction

**23.** A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery; employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP; employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO; employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**Claim 23 determines the “road load,”  
i.e. the instantaneous torque required to  
propel the vehicle**

# '347 Patent - Claim 23 Introduction

**23.** A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**Claim 23 compares the “road load” to “setpoint” to determine what operating mode to transition into**

'347 Patent, Claim 23



# '347 Patent - Claim 23 Introduction

**23.** A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**When the battery needs charging, and the "road load" is less than a "setpoint," claim 23 operates the engine at least at "setpoint" and uses the torque between "road load" and "setpoint" to charge the battery**

'347 Patent, Claim 23

# Introduction to the Prior Art

# Introduction to Severinsky

- Severinsky (Ex. 1009) shares a common inventor with the '347 and '634 patents.
- Directed to a parallel hybrid architecture.
- Discloses three primary modes:
  - Motor only (“low speed”)
  - Engine only (“highway cruising”)
  - Motor + Engine (“high-speed acceleration and/or hill climbing”)



United States Patent [9]  
Severinsky

[11] Patent Number: 5,343,970  
[45] Date of Patent: Sep. 6, 1994

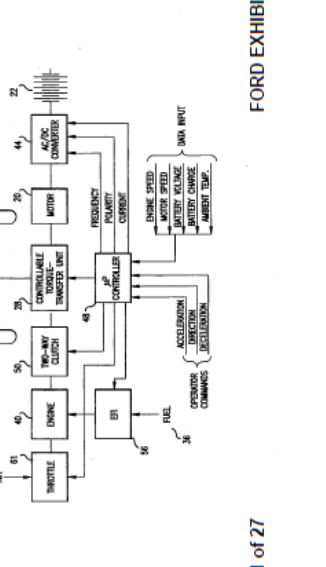
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SAE Technical Paper Series 910247, Kalberlah, pp. 69-78, Feb. 23-March 1, 1991.

Primary Examiner—Margaret A. Focaman  
Assistant Examiner—Peter C. English

[57] ABSTRACT  
An improved hybrid electric vehicle includes an internal combustion engine and an electric motor. Both the engine and the motor are mechanically coupled to a drivable shaft directly through a controllable torque transfer unit. Typically at low speeds or in traffic, the electric motor alone drives the vehicle, using power stored in batteries under regeneration and charging limitations. The electric motor and drivable shaft are also coupled to the internal combustion engine through a controllable torque transfer unit. The internal combustion engine is sized to operate at or near its maximum efficiency in steady state highway cruising. The internal combustion engine alone drives the vehicle. The internal combustion engine is also used for regenerative braking, as needed, and also for regenerative braking. No transmission is employed. The motor operates at significantly lower currents and higher voltages than conventional electric motors. The motor is sized to operate at the internal combustion engine. In this manner a cost efficient vehicle is provided, suffering no performance disadvantage compared to conventional vehicles.

40 Claims, 12 Drawing Sheets

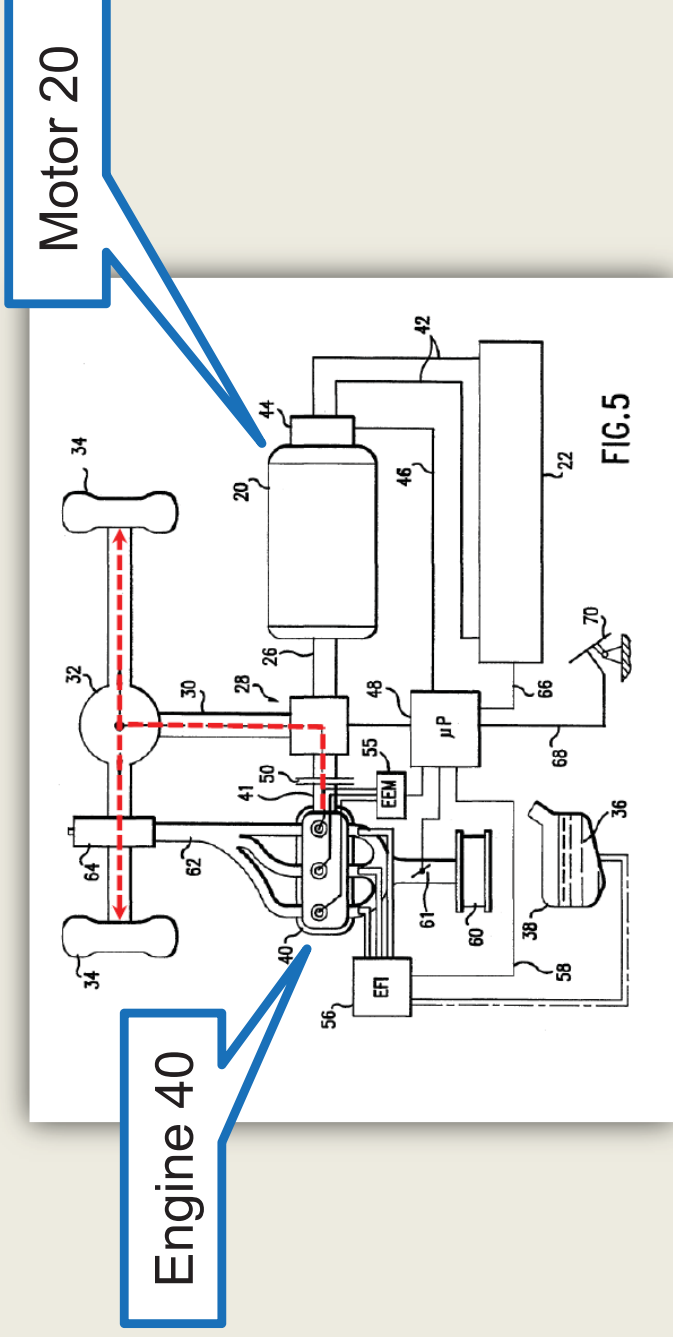


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FORD EXHIBIT 1003

# Introduction to Severinsky

- Severinsky is directed to a parallel hybrid architecture, which utilizes a single electric motor.



Severinsky, Ex. 1003 at Fig. 5.

# Introduction to Severinsky

- Severinsky's strategy to operate the engine efficiently.
- Size the engine to operate over a given speed range. IPR '571, Paper No. 20, POR at 36-37
- Utilize the engine when vehicle speed enters the given speed range. IPR '571, Paper No. 20, POR at 36-37

As the road speed increases, the internal combustion engine is started, using torque provided by the electric motor through the torque transfer unit, such that no separate starter is required. The internal combustion engine is sized to operate near maximum efficiency during steady state cruising on the highway, at between about 35 and 65 mph; at these times the electric motor is not powered. When necessary for acceleration or hill

Severinsky, Ex. 1003 at 6:36-43.

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30-45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30-35 mph. The engine will continue to run unless the engine speed is reduced to 20-25 mph for a period of time, typically 2-3 minutes. This speed-responsive hysteresis in mode switching will eliminate nuisance engine starts.

Severinsky, Ex. 1003 at 18:34-44.

## **Severinsky does not disclose all the limitations of claim 23 of the '347 Patent**

**Severinsky fails to disclose each and every claim limitation of claim 23:**

- 1) Severinsky uses speed, not “road load,” to determine when to turn the engine on and off.**
- 2) Severinsky does not determine road load at all.**
- 3) Severinsky’s battery charging mode does not use “road load” or a “setpoint” to determine when to run the engine while charging the battery**

## Severinsky does not disclose all the limitations of claim 23 of the '347 Patent

Severinsky fails to disclose each and every claim limitation of claim 23:

- 1) Severinsky uses speed, not “road load,” to determine when to turn the engine on and off.
- 2) Severinsky does not determine road load at all.
- 3) Severinsky’s battery charging mode does not use “road load” or a “setpoint” to determine when to run the engine while charging the battery

# Severinsky uses speed, not “road load,” to determine when to turn the engine on and off.

**23.** A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**‘347 Patent, claim 23 compares the “road load” to a “setpoint” to determine when to employ the engine on and when to employ the motor.**

**’347 Patent, Claim 23**



# Severinsky discloses turning the engine on and off based on speed

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30–45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30–35 mph. The engine will continue to run unless the engine speed is reduced to 20–25 mph for a period of time, typically 2–3 minutes. This speed-responsive hysteresis in mode switching will eliminate nuisance engine starts.

When to turn the engine on

When to turn the engine off.

Severinsky, Ex. 1003 at 18:34-44.

# Severinsky discloses “speed-responsive hysteresis”

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30–45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30–35 mph. The engine will continue to run unless the engine speed is reduced to 20–25 mph for a period of time, typically 2–3 minutes. This speed-responsive hysteresis in mode switching will eliminate nuisance engine starts.

Severinsky, Ex. 1003 at 18:34-44.



[H]ysteresis relates to the dependence of the state of a system on the history of past inputs in addition to the current input. Ex. 2009 at 3.... One of skill in the art would understand that a control system (such as that disclosed in Severinsky) would not use “speed responsive-hysteresis” if that same system uses road load to control engine starts and stops....

IPR '571, Ex. 2002 at ¶ 52; IPR '904, Ex. 2004 at ¶ 57.

# Severinsky consistently throughout the specification teaches turning the engine on and off based on speed

- Nowhere does Severinsky say that the engine is turned on or off based on road load or even pedal position.

Typically, the electric motor operates under battery power during low speed operation, e.g., in traffic, during reverse operation, or the like. In this mode of operation, the energy transfer

...

As the road speed increases, the internal combustion engine is started, using torque provided by the electric motor through the torque transfer unit, such that no separate starter is required. The internal combustion engine is sized to operate near maximum efficiency during steady state cruising on the highway, at between about 35 and 65 mph; at these times the electric motor is not powered.

Severinsky, Ex. 1003 at 6:26-43, 17:43-48;  
see also 10:52-53, 13:65 – 14:3.

# Severinsky's speed-based strategy cannot disclose or render obvious the claimed road load-based engine mode

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30–45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30–35 mph. The engine will continue to run unless the engine speed is reduced to 20–25 mph for a period of time, typically 2–3 minutes. This speed-responsive hysteresis in mode switching will eliminate nuisance engine starts.

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**23. A method...**

**employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;**

Severinsky, Ex. 1003 at 18:34-44.

'347 patent, claim 23.

# Severinsky's speed-based strategy cannot disclose or render obvious the claimed road load-based motor mode

Typically, the electric motor operates under battery power during low speed operation, e.g., in traffic, during reverse operation, or the like. In this mode of operation, the energy transfer

...

As the road speed increases, the internal combustion engine is started, using torque provided by the electric motor through the torque transfer unit, such that no separate starter is required. The internal combustion engine is sized to operate near maximum efficiency during steady state cruising on the highway, at between about 35 and 65 mph; at these times the electric motor is not powered.

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**23. A method...**

**employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;**

'347 patent, claim 23.

Severinsky, Ex. 1003 at 6:26-43.

# Ford's effort to recast Severinsky as a road-load based reference is a classic example of hindsight bias

- Ford's petition contains statements that are misleading and unsupported by Severinsky's disclosure.

Petition



Severinsky '970 further discloses that the "microprocessor 48" determines that "the instantaneous torque required for propulsion of the vehicle" may be positive when the vehicle "starts to climb a hill." (Ex. 1003 at 10:36-37; Ex. 1005, Davis ¶289.)

IPR '904, Paper No. 1, Petition at 38; IPR '571, Paper No. 1, Petition at 25.

Quoted portion of Severinsky

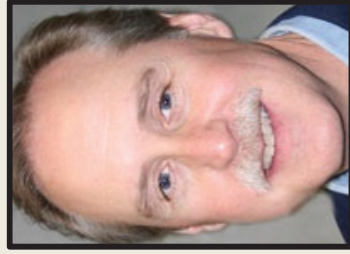


generator so as to charge the batteries. If the vehicle then starts to climb a hill, the motor 20 is used to supplement the output torque of engine 40. Similarly, the

Severinsky, Ex. 1003 at 10:36-37.

# Dr. Davis's refusal to accept Severinsky's speed-based teaching reveals his hindsight bias

- Dr. Davis agrees that Severinsky discloses “speed-responsive [sic] hysteresis in mode switching” but claims “there has to be more involved.” Ex. 2005, Davis Tr. at 169:11-16, 171:21 – 172:4.



“One of ordinary skill in the art would readily recognize that there's more involved here because this would not be a vehicle that's responsive to the driver's commands.”

...

“[O]ne of ordinary skill would readily understand that there has to be more involved, especially, you know, by now we're at Column 18 and there's been a lot of discussion about meeting the torque demands as well; for example, some of the acceleration, hill [sic] climb modes, things like that.”

Dr. Davis  
relies on  
discussion  
of “torque  
demands”

IPR '571, Ex. 2005 at 171:9-13, 171:21 – 172:4.

## The places from which Dr. Davis identifies disclosure of “torque demands” are unrelated to whether Severinsky uses road load to turn the engine on and off

- Col. 13:65 – 14:22 - relates to activating the electric motor to provide additional torque to the wheels when the engine is already in operation. IPR '571, Paper No. 20, POR at 29.
- Col. 17:7-15 – relates to providing torque from the engine to the electric motor to charge the battery when the engine is already in operation. *Id.* at 33.
- Col. 13:65-14:21 - merely states that the engine provides the torque required to drive the vehicle in engine only mode. *Id.* at 29.
- Col. 6:19-26 - simply states that the system is able to receive user inputs. *Id.*



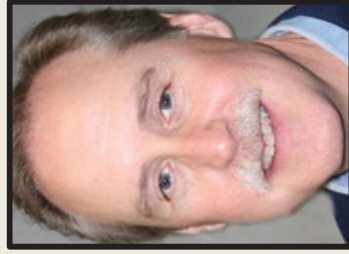
One of skill in the art would understand that vehicle systems include a large number of power, speed, and torque parameters that are used for many different purposes, for example, fuel flow, air metering, emissions control, transmission control, and stabilization. Thus, one of skill in the art would expect many references discussing a vehicle to include these concepts. However, the mention of torque as a concept does not tell one of skill in the art to use it as a control input in a hybrid system.

IPR '904, Ex. 2004 at ¶ 82.



# Dr. Davis's refusal to accept Severinsky's speed-based teaching reveals his hindsight bias

- Dr. Davis agrees that Severinsky discloses “speed-responsive [sic] hysteresis in mode switching” but claims “there has to be more involved.” Ex. 2005, Davis Tr. at 169:11-16, 171:21 – 172:4.



“One of ordinary skill in the art would readily recognize that there's more involved here because this would not be a vehicle that's responsive to the driver's commands.”

...

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Dr. Davis  
relies on the  
acceleration/  
hill climbing  
mode.

IPR '571, Ex. 2005 at 171:9-13, 171:21 – 172:4.

## Dr. Davis's reliance on "high-speed and/or acceleration hill climbing" mode is also unrelated to turning the engine on and off

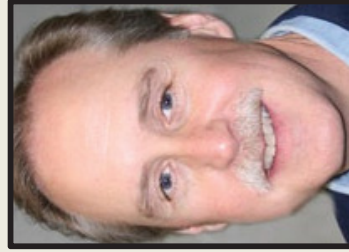
motor 20 to the wheels 34. Under these circumstances, electric motor 20 provides all of the torque needed to move the vehicle. Other combinations of torque and energy flow required under other circumstances are detailed below in connection with FIGS. 5-9. For example, if the operator continues to command acceleration, an acceleration/hill climbing mode illustrated in FIG. 6 may be entered, followed by a highway cruising mode illustrated in FIG. 5.

Severinsky, Ex. 1003 at 10:66 – 11:6.

# Dr. Davis's reliance on "high-speed and/or acceleration hill climbing" mode is also unrelated to turning the engine on and off

As Severinsky '970 discloses, this full acceleration request would result in the "acceleration mode" starting and employing both the engine and motor to propel the vehicle... The operating situation I have described illustrates a situation where the engine would be started and employed to propel the vehicle because the torque required to propel the vehicle to meet the desired acceleration has increased above the 60% lower threshold.

IPR '571, Ex. 1038, Davis Dec. at ¶¶ 24-25.



16 Q. All right. Let me stop you there. 14:24:37  
17 You said that it enters this 14:24:38  
18 acceleration/hill climbing mode because the 14:24:41  
19 torque required to propel the vehicle to meet 14:24:41  
20 the desired acceleration has increased above 14:24:43  
21 the 60 percent lower threshold. Is that right? 14:24:47  
22 A. Probably a better way to say that is 14:24:50  
23 to meet the desired accelerator pedal position, 14:24:54  
24 the indication that that's what the operator 14:24:54  
25 wants to do. He wants to achieve acceleration. 14:24:56

IPR '571, Ex. 1005, Davis Dec. at ¶¶ 286-87.

## Dr. Davis's reliance on "high-speed and/or acceleration hill climbing" mode is also unrelated to turning the engine on and off

- Dr. Davis's new testimony contradicts Severinsky and Dr. Davis's previous testimony. Indeed, Dr. Davis previously admitted that:
  - "High-speed and/or acceleration hill climbing" mode is related to when to turn on the motor.
  - In "high-speed and/or acceleration hill climbing" mode, the alleged road load is greater than the MTO.



Fig. 6 of Severinsky '970 illustrates and discloses operating the motor to provide supplemental torque when the torque required for propulsion of the vehicle exceeds the capability (i.e. maximum torque output) of the engine.... Fig. 6, reproduced below and annotated, illustrates the acceleration/hill climbing modes where both the engine and motor provide torque to the wheels to propel the vehicle.

IPR '571, Ex. 1005, Davis Dec. at ¶¶ 286-87.

# Dr. Davis's refusal to accept Severinsky's speed-based teaching reveals his hindsight bias

- Dr. Davis states that Severinsky must use road load because otherwise at low speeds the vehicle of Severinsky would not enter hill climbing mode when going up a hill.

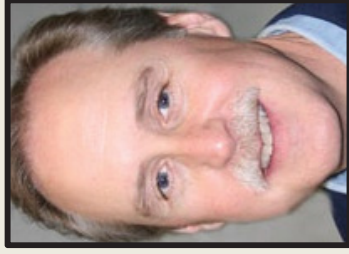


10 Q. Okay. So your opinion is, I think it's right here in 04:41:16  
11 your declaration, that Severinsky **must** consider torque 04:41:20  
12 road load to determine which mode to activate because 04:41:25  
13 otherwise the vehicle described in Severinsky '970 would 04:41:29  
14 be unable to determine when to enter into the engine 04:41:37  
15 plus motor hill climbing mode at lower speeds, is that 04:41:39  
16 fair? 04:41:42  
17 A. **Yeah, these low speeds. Yes, that's fair.** In this 04:41:42  
18 example the engine or the system would not provide the 04:41:45  
19 additional torque needed to climb the hill. 04:41:48

**IPR2014-00904, Ex. 2015 at 19:16-22.**

# Dr. Davis's refusal to accept Severinsky's speed-based teaching reveals his hindsight bias

- When asked about another reference (U.S. Patent No. 5,842,534) that discloses speed-responsive hysteresis (Ex. 2016 8:9 – 9:13) and an engine plus motor hill climbing mode (id. at 23:2-23), Dr. Davis agreed that the disclosed vehicle would be unable to determine when to enter into the engine plus motor hill climbing mode (HEV mode) at lower speeds and would instead stay in motor only mode (ZEV mode) (id. at 4:6 – 5:9).



21 tradeoff. You're making design decisions. And there  
22 are tradeoffs involved in all of your design choices.  
23 And I believe the design choices he made here would not  
24 be the -- would not always lead to the best mode of  
25 operation in really hilly terrain. You certainly  
1 wouldn't have a problem approaching the hill and you  
2 would probably climb some hills, but in extremely hilly  
3 terrain the vehicle might not respond the way most  
4 people would like.

IPR '904, Ex. 2016 at 40:21 – 41:4.

## Ford's hindsight-driven read of Severinsky's disclosure of a "sweet spot" is also improper

- Ford's reliance on Severinsky's disclosure about the engine's sweet spot for a disclosure about a control strategy is wrong. IPR '571, Paper No. 20, POR at 14.
- Paice's expert, Mr. Hannemann, testified that maintaining engine operation in the sweet spot is aspirational (i.e., the goal of hybrid vehicles), but identifying the sweet spot does not define the control strategy.



While it is possible to operate an engine at its sweet spot, such teachings of operating the engine within the sweet spot must be understood as aspirational.... In other words, while one of skill in the art understands that maintaining an engine only in its sweet spot would be advantageous, the control strategy employed to do so is not readily apparent. Indeed, much of hybrid control theory has sought to accomplish this goal with varying degrees of success.

IPR '571, Ex. 2002 at ¶ 34; see also ¶¶ 40-45, 53, 57.

# Ford's hindsight-driven read of Severinsky is improper

- The “key” passage [Passage 1] on which Ford relies (and on which institution was granted) is:
  - Unrelated to mode switching or any type of hybrid control
  - Found at the very end of the specification and related to how improving fuel economy would reduce emissions.

It will be appreciated that according to the invention the internal combustion engine is run only in the near vicinity of its most efficient operational point, that is, such that it produces 60-90% of its maximum torque whenever operated. This in itself will yield improvement in fuel economy on the order of 200-300%. More specifically, a 200-300% reduction in fuel consumption will provide an equal reduction in carbon dioxide emissions, as the amount of carbon dioxide emitted is proportional to the amount of fuel used. If ethanol is used as a fuel, that is, if the fuel is derived from renewable plant life rather than fossil fuel, an overall reduction in global carbon dioxide emissions will be achieved since the plants consume carbon dioxide during growth.

Ford's “key” passage – that the engine is “only run” ... “such that it produces 60-90%” MTO.

Proper Context

Severinsky '970 at 20:63 – 21:8.



# Both experts agree that “60-90%” MTO does not disclose when to operate the engine

- Both experts agree that:
  - “60-90%” MTO is a disclosure of the engine’s sweet spot. Ex. 2002 at ¶¶ 58-61; Ex. 1005 at ¶¶ 259-60.
  - Maintaining engine operation in the sweet spot is aspirational (*i.e.*, the goal of hybrid vehicles). Ex. 2002 at ¶¶ 42-45; Ex. 2005 at 103:20 – 105:1.
  - There is not a single control strategy that would maintain the engine within its sweet spot. Ex. 2002 at ¶¶ 46-49; Ex. 2005 at 104:3-9, 106:4-8.
  - Dr. Davis admitted that defining the engine sweet spot does not tell a POSITA when to employ the engine. Ex. 2002 ¶¶ 58-61. (IPR ‘904, POR at 16)



24 Q. So the plain reading of this passage 13:51:49  
25 is that the engine is operated near its sweet 13:51:51  
1 spot, right? 13:51:55  
2 A. The -- that's your goal, yes. 13:51:57  
3 You're optimizing to try to ensure that 13:52:00  
4 operation generally near the sweet spot, yes. 13:52:02  
5 Q. But it doesn't tell us when you 13:52:05  
6 start the engine, correct? 13:52:07  
7 A. This paragraph does not. 13:52:09

Ex. 2005 at  
164:22 – 165:7).

## Ford's hindsight-driven read of Severinsky's disclosure of a "sweet spot" is also improper

- Ford's hindsight-based reading of Passage 1 is based on confusing:
  - A teaching of how to run the engine (i.e., an aspirational sweet spot) with a teaching of when to run the engine (i.e., the actual control strategy)
  - The output torque of the engine and the road load

Severinsky '970 discloses that the engine is **only** operated under its "most efficient conditions of output power and speed" which are between "60-90% of [the engine's] maximum torque ..." (Ex. 1003 at 7:8-16; 20:63-66; Ex. 1005, Davis ¶¶278-280.) Again, the 60% of the engine's maximum torque output value would be understood by a POSA as a lower level predetermined torque value (i.e., "lower level SP"). (Ex. 1005, Davis ¶279.) Severinsky '970 thus discloses that the engine is employed to propel the vehicle **when** the "instantaneous torque required for propulsion of the vehicle" is between 60% and 90% of the maximum torque output of the engine. (Ex. 1005, Davis ¶¶278-280.)

IPR '571, Paper No. 1, Petition at 29-30; IPR '904, Paper No. 1, Petition at 42.

# Ford's hindsight-driven read of Severinsky's disclosure of a "sweet spot" is also improper

- Ford's second "key" passage supports Paice's position because highway cruising mode is defined in terms of speed.

When the engine can be used efficiently to drive the vehicle forward, e.g. in highway cruising, it is so employed. Under other circumstances, e.g. in traffic, the electric motor alone drives the vehicle forward and the internal combustion engine is used only to charge the batteries as needed. No transmission is required, thus

IPR '571, Paper No. 1, Petition at 20 (citing Severinsky '970 at 7:11-16).

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30–45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30–35 mph. The engine will continue to run unless the engine speed is reduced to 20–25 mph for a period of time, typically 2–3 minutes. This speed-responsive hysteresis in mode switching will eliminate nuisance engine starts.

Severinsky, Ex. 1003 at 18:34-44.

## Ford's reliance on the '347 and '634 patent specifications is improper

- The Federal Circuit has made clear that the proper comparison is between the claims of the patent at issue and the prior art.
- Ford's use of the '347 patent to twist the disclosure of Severinsky runs afoul of *Clearwater*.
- In subsequent IPRs Ford has stated that “Ford is relying on the quoted '634 Patent passages as patentee admissions regarding how a POSA would have understood the prior art Severinsky '970.” IPR2015-00758 Petition at 13, FN 2. IPR '904, Paper No. 22, POR at 48.



*“This comparison is erroneously premised; the correct comparison is the actual claim language in both patents, not how the later patent describes the earlier patent. In other words, the district court erroneously found the #739 patent was anticipated by its own written description. Thus, we remand for a proper claim-by-claim analysis between the allegedly anticipated claims and the prior art reference.*”

*Clearwater Sys. Corp. v. Evapco, Inc.*, 394 F. App'x 699, 705 (Fed. Cir. 2010).

# Ford's reliance on the '347 and '634 Patent specifications is improper

- **The passages from the '347 and '634 Patents on which Ford relies do not remedy Severinsky's noted deficiencies. IPR '571, Paper No. 20, POR at 38.**

engines.) According to an important aspect of the invention of the '970 patent, substantially improved efficiency is afforded by operating the internal combustion engine only at relatively high torque output levels, typically at least 35% and preferably at least 50% of peak torque. When the vehicle operating conditions require torque of this approximate magnitude, the engine is used to propel the vehicle; when less torque is required, an electric motor powered by electrical energy stored in a substantial battery bank drives the vehicle; when more power is required than provided by either the engine or the motor, both are operated simultaneously. The same advantages are provided by the system of the present invention, with further improvements and enhancements described in detail below.

According to one aspect of the invention of the '970 patent, the internal combustion engine of a hybrid vehicle is sized to supply adequate power for highway cruising, preferably with some additional power in reserve, so that the internal combustion engine operates only in its most efficient operating range. The electric motor, which is substantially equally efficient at all operating speeds, is used to supply additional power as needed for acceleration and hill climbing, and is used to supply all power at low speeds, where the internal combustion engine is particularly inefficient, e.g., in traffic.

Turning now to detailed discussion of the inventive control strategy according to which the hybrid vehicles of the invention are operated: as in the case of the hybrid vehicle system shown in the '970 patent, and as discussed in further detail below, the vehicle of the invention is operated in different modes depending on the torque required, the state of charge of the batteries, and other variables. Throughout, the object is to operate the internal combustion engine only under circumstances providing a significant load, thus ensuring efficient operation. In the following, the relationships

**'347 Patent at 35:5-14.**

**'347 Patent at 25:4-27.**

# The File History of the Related '097 Patent Confirms Severinsky's Use of Speed

As to claims 40 and 46, the Examiner states that the '970 patent teaches determination of road load (RL), comparing RL to SP, and determining whether to supply the torque required from the ICE, traction motor, or both. This is not in fact the case, as the '970 patent teaches making such "mode switching" determinations based on the vehicle speed, not the road load RL.

See col. 18, lines 34 – 40:

At moderate speeds, as experienced in suburban driving, the speed of the vehicle on average is between 30-45 mph. The vehicle will operate in a highway mode with the engine running constantly after the vehicle reaches a speed of 30-35 mph. The engine will continue to run unless the engine speed is reduced to 20-25 mph for a period of time, typically 2-3 minutes.

Likewise, at col. 17, lines 34 – 45:

In further explanation of the operation of the vehicle of the invention, there are typically two modes of operation at slow speed, that is, at up to about 25-35 mph, depending on the state of charge of the battery 22. Because the engine 40 is cycled on and off in this speed range when the average power demand is small, in one mode the system is operated as a pure electric drive system (as in FIG. 4) and in the other mode it is operated as a differential drive system.

When the battery 22 is fully charged, and the vehicle speed is below about 25-35 mph, the microprocessor 48 disconnects the engine 40 from the drive and shuts it off. Under these circumstances only the motor 20 provides power to drive the vehicle.

Thus it is clear that the '970 patent does not in fact teach mode switching based on RL, but on vehicle speed. Mode switching based on RL is fundamentally different from mode switching based on vehicle speed. RL may be a function of numerous factors, including desired

'097 File History, Ex. 2004 at 16-17.

## Severinsky does not disclose all the limitations of claim 23 of the '347 Patent

**Severinsky fails to disclose each and every claim limitation of claim 23:**

- 1) Severinsky uses speed, not “road load,” to determine when to turn the engine on and off.
- 2) Severinsky does not determine road load at all.
- 3) Severinsky’s battery charging mode does not use “road load” or a “setpoint” to determine when to run the engine while charging the battery

# Severinsky does not determine the road load.

23. A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**'347 Patent, claim 23 determines the "road load," i.e. the instantaneous torque required to propel the vehicle**

**'347 Patent, Claim 23**



## “Road load” is not pedal position



- While a pedal position can be an input into a system that calculates “road load,” the accelerator position alone is not determinative of “road load.” IPR ’571, Ex. 2002 at ¶ 85.
- Pedal position can cause the engine to produce more torque, a phenomenon familiar to anyone who drives conventional vehicles – when you want to accelerate, press down on the accelerator pedal. *Id.* at ¶¶ 81-84.

## “Road load” is not pedal position

- Severinsky’s disclosure of measuring pedal position is unrelated to turning the engine on and off (*i.e.*, transitioning between “low speed” mode and “highway cruising” mode).



The relationship between the accelerator pedal and engine output described above is true for all engines including conventional engines in non-hybrid vehicles. This relationship (that the engine varies in response to the accelerator pedal position), however, is not premised on the calculation of the road load. In nonhybrid vehicles, for example, the accelerator pedal is simply connected mechanically or electronically to the throttle, which controls the flow of air to the engine.... Moreover, there is not disclosure in Severinsky that the accelerator pedal position is used to turn the engine on or off. As I discuss above, the accelerator pedal position is simply used to determine how to operate the throttle as is true for conventional vehicles.

IPR '571, Ex. 2002 at ¶¶ 82-85; see also IPR '904, Ex. 2004 at ¶¶ 87-90.

## “Road load” is not pedal position

- Conventional non-hybrid vehicles going back to the Model T used the pedal to set engine output torque. Those vehicles did not determine or use “road load.”
- Unlike pedal position, “road load” can be different according to the operating conditions:



- The “road load” could be vastly different according to the operating conditions at, for example, 30%. For example, if the vehicle is currently going five miles per hour, the road load will be much different than if the vehicle is traveling at 50 miles per hour at the same (in this case 30%) pedal position.
- Factors such as rolling resistance, grade resistance, and wind resistance affect the “road load,” but are not necessarily indicated by pedal position alone.

## “Road load” is not pedal position

- Pedal position is related to the internal power sources while “road load” is related to the external torque requirements.



In terms of vehicle design, accelerator pedal position is scaled to the capability of the internal power source(s) (e.g., the engine and/or the motor). Road load, on the other hand, is not concerned with the capabilities of the internal power sources. Road load—the instantaneous torque required to propel the vehicle—is based on external torque requirements such as driving conditions.

IPR '904, Ex. 2004 at ¶ 92.

## “Road load” is not pedal position

- Dr. Davis admitted
  - i) one could not determine whether or not the instantaneous torque required to propel the vehicle would be positive or negative from looking at only the pedal position when the driver presses on the accelerator pedal from 0% to 10% because pedal position does not provide enough information.
  - ii) he would need to know “what speed is the vehicle going” and if the vehicle is “going down a hill.”

8 Q. So if the driver -- if the 13:01:07  
9 accelerator pedal position is at zero percent 13:01:10  
10 and the driver pushes it to 10 percent, that's 13:01:12  
11 always going to indicate that the instantaneous 13:01:15  
12 torque required to propel the vehicle is 13:01:22  
13 positive. 13:01:23  
14 MR. RONDINI: Objection, vague. 13:01:24  
15 A. No. That's going to indicate an 13:01:25  
16 increase. A desired increase from zero to 10 13:01:28  
17 percent on the pedal position is an indication 13:01:32  
18 there's an increase in desired instantaneous 13:01:34  
19 torque required to propel the vehicle. 13:01:40  
20 Q. But it could be a -- it could be 13:01:40  
21 negative? The instantaneous torque could still 13:01:43  
22 be negative? 13:01:46  
23 A. I can't answer that without knowing 13:01:48  
24 more. I mean you haven't given me enough. 13:01:50  
25 Q. What more do you need? 13:01:52  
1 A. Well, I mean what are the 13:01:53  
2 conditions? What speed is the vehicle going? 13:01:55  
3 Is it going down a hill, for example. 13:01:59

## **Severinsky does not disclose all the limitations of claim 23 of the '347 Patent**

**Severinsky fails to disclose each and every claim limitation of claim 23:**

- 1) Severinsky uses speed, not “road load,” to determine when to turn the engine on and off.**
- 2) Severinsky does not determine road load at all.**
- 3) Severinsky’s battery charging mode does not use “road load” or a “setpoint” to determine when to run the engine while charging the battery**

# Severinsky fails to disclose the battery charging limitation

**23.** A method of control of a hybrid vehicle, said vehicle comprising an internal combustion engine capable of efficiently producing torque at loads between a lower level SP and a maximum torque output MTO, a battery, and one or more electric motors being capable of providing output torque responsive to supplied current, and of generating electrical current responsive to applied torque, said engine being controllably connected to wheels of said vehicle for applying propulsive torque thereto and to said at least one motor for applying torque thereto, said method comprising the steps of:

determining the instantaneous torque RL required to propel said vehicle responsive to an operator command; monitoring the state of charge of said battery;

employing said at least one electric motor to propel said vehicle when the torque RL required to do so is less than said lower level SP;

employing said engine to propel said vehicle when the torque RL required to do so is between said lower level SP and MTO;

employing both said at least one electric motor and said engine to propel said vehicle when the torque RL required to do so is more than MTO; and

employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so; and

wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**'347 Patent, claim 23 - When the battery needs charging, and the "road load" is less than a "setpoint," claim 23 operates the engine at least at "setpoint" and uses the torque between "road load" and "setpoint" to charge the battery**

**'347 Patent, Claim 23**

# Severinsky fails to disclose the battery charging limitation

- The battery charging limitation explicitly requires evaluating RL:

and employing said engine to propel said vehicle when the torque RL required to do so is less than said lower level SP and using the torque between RL and SP to drive said at least one electric motor to charge said battery when the state of charge of said battery indicates the desirability of doing so

'347 Patent, Claim 23

- Severinsky clearly evaluates speed

By comparison, if the battery is discharged by 10-20% and the vehicle speed is below 25-35 mph, the microprocessor 48 actuates the two-way clutch 50 (see FIG. 10) to connect the engine 40 to the torque transfer unit. Then the motor 20 will start the engine 40 while driving the vehicle, with the microprocessor 48 providing optimal starting conditions as above. Locking devices 106 are released, such that the torque transfer unit 28 operates in differential mode. The microprocessor 48 then controls the speeds of both the engine 40 and the motor 20 such that the difference in speed of their output shafts is equal to the speed required by the driver for vehicle propulsion. As noted, engine speed is controlled

Severinsky, Ex. 1003 at 7:56-68.



**IPR2014-00571 Grounds 2 and 3 - Severinsky and Ehsani Do  
Not Disclose or Render Obvious Claims 1, 6, 7, 9, 15 and 21  
of the '347 Patent**

## United States Patent

Ehsani

[11] Patent Number: **5,586,613**  
 [45] Date of Patent: **Dec. 24, 1996**



US905586613A

[54] **ELECTRICALLY PEAKING HYBRID SYSTEM AND METHOD**  
 [73] Inventor: Mehdiad Ehsani, Bryan, Tex.  
 [73] Assignee: The Texas A&M University System, College Station, Tex.

[21] Appl. No.: 312,438  
 [22] Filed: Sep. 26, 1994

### Related U.S. Application Data

[63] Continuation of Ser. No. 31,135, Apr. 22, 1993, abandoned.  
 [51] Int. Cl.<sup>6</sup>: B60K 6/04  
 [52] U.S. Cl.: 180/65.2, 318/139  
 [58] Field of Search: 290/95; 180/65.1, 65.2, 65.3, 65.4, 65.8; 318/139

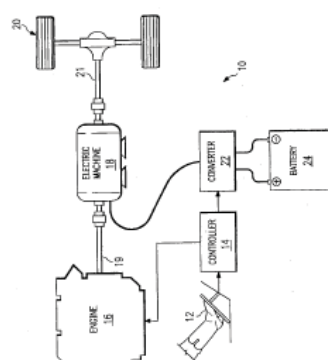
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[57] **ABSTRACT**  
 A hybrid electric propulsion system is provided which includes an electric machine (18) which converts electrical energy and transmits it to a drive shaft (21). A battery (24) is included that is operable to store electrical energy and to deliver electrical energy. Also provided is an electric machine (18) which is mechanically coupled to engine (16) and electrically coupled to battery (24). The electric machine (18) converts mechanical energy from battery (24) into additional mechanical energy at drive shaft (21). In the second mode of operation, electric machine (18) delivers electrical energy to battery (24) for storage. The electric machine (18) also converts mechanical energy from battery (24) and also for converting electrical energy from battery (24) for use by electric machine (18). The system also includes a controller (12) for inputting system parameters and a converter (22) for converting electrical energy from battery (24) and engine (16) to the mode of operation of the system.

Primary Examiner—Brian L. Johnson  
 Assistant Examiner—Michael Mar  
 Attorney, Agent, or Firm—Baker & Botts, L.L.P.

### 8 Claims, 3 Drawing Sheets



Page 1 of 9

FORD EXHIBIT 1004

# Ehsani (Ex. 1004) discloses a series-parallel hybrid architecture utilizing two motors instead of one.

## Grounds 2 and 3 – Severinsky and Ehsani

- In Grounds 2 and 3, Ford combines the control strategy of Severinsky with Ehsani's teaching of a two-motor system—interchanging Severinsky and Ehsani as the primary reference.
- Because the basis for these grounds are premised upon the same misapplication of Severinsky, the deficiencies in Severinsky and the defects in Ford's reasoning also apply to Grounds 2 and 3.
- Ehsani does not remedy these noted deficiencies of Severinsky, and Ford does not contend otherwise. Dr. Davis confirmed this at his deposition. Ex. 2003 at 186:13-23.

13 Q. You didn't rely on the Ehsani for 14:27:03  
14 disclosure for set points, correct? 14:27:07  
15 A. No. I think what I looked at Ehsani 14:27:13  
16 for is that Severinsky discloses a one-motor 14:27:15  
17 parallel hybrid system, and then I looked at 14:27:21  
18 the idea that, you know, there's -- obviously 14:27:24  
19 starter motors are, you know, widely known. 14:27:29  
20 People have known about starter motors forever, 14:27:31  
21 but Ehsani also goes further with a parallel 14:27:34  
22 drive system where it's not just a starter 14:27:37  
23 motor, but a motor generator that's added. 14:27:39

Ex. 2003 at 186:13-23.

# Because Severinsky considers speed (not torque), Severinsky does not disclose '347 Patent, claim 1

What is claimed is:

1. A hybrid vehicle, comprising:  
an internal combustion engine controllably coupled to road wheels of said vehicle;  
a first electric motor connected to said engine and operable to start the engine responsive to a control signal;  
a second electric motor connected to road wheels of said vehicle, and operable as a motor, to apply torque to said wheels to propel said vehicle, and as a generator, for accepting torque from at least said wheels for generating current;  
a battery, for providing current to said motors and accepting charging current from at least said second motor; and  
a controller for controlling the flow of electrical and mechanical power between said engine, first and second motors, and wheels,  
wherein said controller starts and operates said engine when torque require to be produced by said engine to propel the vehicle and/or to drive either one or both said electric motor(s) to charge said battery is at least equal to a setpoint (SP) above which said engine torque is efficiently produced, and wherein the torque produced by said engine when operated at said setpoint (SP) is substantially less than the maximum torque output (MTO) of said engine.

**Claim 1 compares the “torque require[d] to be produced by said engine to propel the vehicle and/or drive either one or both said electric motor(s) to charge said battery” to a “setpoint” to determine whether to “start and operate” the engine.**

'347 Patent, Claim 1

# Because Severinsky considers speed (not torque), Severinsky does not disclose '347 Patent, claim 7

- **Claim 7 (like claim 23) requires comparing the “road load” to a “setpoint” to determine when to turn the engine on and when to turn the engine off and use the motor.**

7. The vehicle of claim 1, wherein said vehicle is operated in a plurality of operating modes responsive to the value for the road load (RL) and said setpoint SP, both expressed as percentages of the maximum torque output of the engine when normally-aspirated (MTO), and said operating modes include:

a low-load mode I, wherein said vehicle is propelled by torque provided by said second electric motor in response to energy supplied from said battery, while  $RL < SP$ ,

a highway cruising mode IV, wherein said vehicle is propelled by torque provided by said internal combustion engine, while  $SP < RL < MTO$ , and an acceleration mode V, wherein said vehicle is propelled by torque provided by said internal combustion engine and by torque provided by either or both electric motor(s) in response to energy supplied from said battery, while  $RL > MTO$ .

**Dependent claim 7 requires a plurality of operating modes responsive to the value of RL and the setpoint**

**Dependent claim 7 operates the motor while  $RL < SP$**

**Dependent claim 7 operates engine while  $SP < RL < MTO$**

**'347 Patent, Claim 7**

# Severinsky and Ehsani do not disclose or render obvious '347 Patent, claim 9

9. The vehicle of claim 7, wherein said operating modes further include a low-speed battery charging mode II, entered while  $RL < SP$  and the state of charge of the battery is below a predetermined level, and during which said vehicle is propelled by torque provided by said second electric motor in response to energy supplied from said battery, and wherein said battery is simultaneously charged by supply of electrical energy from said first electric motor, being driven by torque in excess of SP by said internal combustion engine, the combination of said engine and said first motor being disengaged from said wheels during operation in mode II.

**Dependent claim 9 recites a battery charging mode entered while  $RL < SP$**

**Dependent claim 9 recites that the battery is charged by energy from the motor, being driven by torque in excess of SP by the engine**

'347 Patent, Claim 9

# The combination of Severinsky and Ehsani fails to disclose a first motor that can receive torque $\geq$ SP

- Ehsani teaches the use of a small motor that receives torque during idling.
- The engine would produce torque  $<$  SP when idling.

and electric motor 51. Generator 50 is also electrically coupled to first converter 52. First converter 52 is an AC to DC converter. First converter 52 is also electrically coupled to controller 14 and battery 24. Second converter 54 is electrically coupled to controller 14, electric motor 51 and battery 24.

In operation of this embodiment, generator 50 can be much smaller than electric motor 51 because it only provides steady state charging at a much lower level than the peaking power of electric motor 51. This allows charging of battery 24 even during idling of engine 16. Furthermore, engine 16

Ehsani, Ex. 1004 at 8:28-34.

**IPR2014-00904 Ground 1 - Severinsky and Field and SAE  
1996 Do Not Disclose or Render Obvious Claims 1, 14, 16,  
18, and 24 of the '634 Patent**



- **U.S. Patent No. 7,237,634**
- **Ground 1 (§ 103):**
  - **Challenged claims: 1, 14, 16, 18 and 24**
  - **Asserted Art: Severinsky, Field, and SAE 1996**
- **The Board declined to institute Ground 2**

And in the absence of Ford advancing some meaningful benefit to proceeding with the additional ground of Severinsky and Ehsani, we presume that it is the weaker of the two asserted grounds, and we exercise our discretion to deny institution of this presumably weaker ground. See 37 C.F.R. § 42.108(a).

**IPR '904, Paper 13, Institution Decision at 13.**

# Introduction to Field and SAE 1996

Ford relies on Field (Ex. 1039) and SAE 1996 (Ex. 1025) in place of Ehsani for their disclosure of two motor hybrid vehicle topologies.

## Field

PCT WORLD INTELLECTUAL PROPERTY ORGANIZATION  
International Bureau

INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification: B60K 6/02	(11) International Publication Number: WO 93/23863
(12) International Filing Date: 07/30/92 07/30/92 07/30/92	(13) International Publication Date: 21 November 1993 (23.11.93)
(14) Priority Date: 07/30/92 07/30/92 07/30/92	(15) Designated States: CA, JP, European patent (AT, BE, CH, DE, DK, ES, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE).
(17) Applicant and Inventor: FIELD, Bruce, F. (US/US); Inventor: William Wirth Parkway, Golden Valley, MN 55422 (US).	(18) Published: With international search report.
(19) Agents: FRIEDBERG, Norman, P. et al.; Klemm & Lange, 625 40 Avenue South, Suite 1500, Minneapolis, MN 55415-1639 (US).	

(64) Title: ELECTRIC HYBRID VEHICLE

(67) Abstract  
A vehicle having an electric hybrid power system (10) is provided. The vehicle (10) includes an electric motor (10) drivably connected to the drive shaft (40) of the engine (24) and a generator (24) drivably connected to the engine (24) for recharging an accessory battery. The engine is located near the end of the vehicle (10) opposite the end where the electric motor (10) is located and the two motors (10) are joined with a lightweight small-diameter drive shaft (40). The alternator (28) has at least a voltage output range that is adjustable to provide a constant voltage output through the battery pack (18) and the accessory battery (20). In accordance with the present invention, a mechanism for electrically connecting the alternator (28) to the battery pack (18) is provided such that the alternator (28) alternatively recharges both the battery pack (18) and the accessory battery (20).

FORD EXHIBIT 1039

## SAE 1996

### Development of a New Hybrid System - Dual System

Kozo Yamaguchi, Shuzo Moroto, Koji Kobayashi, Mutsumi Kawamoto, and Yoshinori Miyajima  
Espar Research Co., Ltd.

its combination with the motor (4). The hybrid system can improve fuel economy in light of the following:

1. Operation of the engine in optimum efficiency range
2. Transmission efficiency between the engine and the driving wheels is improved
3. Regeneration of deceleration energy

Figure 1 shows the four different hybrid systems.

(A) SERIES SYSTEM - This system supplements electricity generated by the engine. It is most commonly used as a range extender for electric vehicles. Since the engine is not mechanically connected to the drive wheels, this system has an advantage of controlling the engine independently of the driving conditions. Accordingly, the engine is used in its optimum efficiency range and the generator is mechanically connected to the drive wheels which are hard to mechanically connect to the drive wheels such as gas turbine engines.

Disadvantages, however, include large energy conversion losses because of the necessity of full electricity conversion of the engine output. Further, a generator large enough to convert the maximum engine output is required.

(B) PARALLEL SYSTEM - With the parallel system, an electric motor which supplements the engine torque, is added to the conventional driveline system of the engine and transmission. Accordingly, operations of the engine are quite similar to those of an engine in a normal vehicle. This system requires no generator, and there is a direct mechanical connection between the engine and the drive wheels, providing an advantage of less energy being lost through conversion to electricity.

On the other hand, this system requires a transmission because no speed adjustment mechanism is installed, though the motor supplements the torque. When an automatic transmission is used, a torque converter, oil pump, and other ancillary components can reduce the transmission efficiency. Accordingly, the transmission efficiency is lowered, and the engine speed is determined by gear ratios like a

ABSTRACT  
A new hybrid vehicle system has been developed, the Dual System, which combines the series and parallel hybrid systems. Combination with a motor has reduced the engine size, only using the most efficient range of the engine. A transmission with a torque converter is used to reduce the engine speed, and compact package is applicable to currently produced vehicles with little modification. Use of the generator as a motor realizes multiple control functions. A prototype vehicle with this new Dual System was built and tested. Its driving performance and the fuel economy were measured, and the fuel economy results were analyzed.

INTRODUCTION  
Toward the 21st century, energy conservation has been global interest due to an expected sharp increase in energy demands according to ever increasing population and global warming caused by an increasing volume of generated CO<sub>2</sub>. To decrease the energy used for vehicles, there are a number of alternative methods. One of them is the "Energy Efficient Concept" in the U.S. It is required to adapt a completely new system, not just make a simple modification to the current system, to realize a dramatic improvement in fuel economy. It is recognized that one promising field is hybrid systems.

Both series and parallel hybrid systems are well known. The series system which splits energy from the engine using a planetary gear (11)(12)(3), the new system being called the Dual System.

COMPARISON OF VARIOUS HYBRID SYSTEMS  
Not only used as a range extender of electric vehicles, the hybrid system can improve fuel economy using the engine through making the engine operate in its most efficient range. The engine, can improve fuel economy using the engine through

# Because Severinsky considers speed (not torque), Severinsky does not disclose '634 Patent, claim 1

1. A hybrid vehicle, comprising:  
an internal combustion engine operable to propel the hybrid vehicle by providing torque to the one or more wheels;  
a first electric motor coupled to the engine;  
a second electric motor operable to propel the hybrid vehicle by providing torque to the one or more wheels;  
a battery coupled to the first and second electric motors, operable to:  
provide current to the first and/or the second electric motors; and  
accept current from the first and second electric motors;  
and  
a controller, operable to control the flow of electrical and mechanical power between the engine, the first and the second electric motors, and the one or more wheels;  
wherein the controller is operable to operate the engine when torque required from the engine to propel the hybrid vehicle and/or to drive one or more of the first or the second motors to charge the battery is at least equal to a setpoint (SP) above which the torque produced by the engine is efficiently produced, and wherein the torque produced by the engine when operated at the SP is substantially less than the maximum torque output (MTO) of the engine.

**Claim 1 compares the “torque required from the engine to propel the hybrid vehicle and/or to drive one or more of the first or the second motors to charge the battery” to a “setpoint” to determine whether to “operate” the engine.**

'634 Patent, Claim 1

# Because Severinsky considers speed (not torque), Severinsky does not disclose '634 Patent, claim 16

- **Claim 16 (like claim 23 of the '347 patent) requires comparing the “road load” to a “setpoint” to determine when to turn the engine on and when to turn the engine off and use the motor.**

16. The hybrid vehicle of claim 1, wherein the controller is operable to implement a plurality of operating modes responsive to road load (RL) and the SP, wherein both the RL and the SP are expressed as percentages of the MTO of the engine when normally-aspirated, and wherein the operating modes comprise:

a low-load mode I, wherein, when the  $RL < the SP$ , the second electric motor is operable to provide torque to propel the hybrid vehicle;

a highway cruising mode IV, wherein, when the  $SP < the RL < the MTO$ , the engine is operable to provide torque to propel the hybrid vehicle, and wherein the controller is operable to start the engine if the engine is not running to enter the highway cruising mode IV; and an acceleration mode V, wherein, when the  $RL > the MTO$ , the engine, the first electric motor, and/or the second electric motor is operable to provide torque to propel the hybrid vehicle, and wherein the controller is operable to start the engine if the engine is not running to enter the acceleration mode V.

**Dependent claim 16 is operable to implement a plurality of operating modes responsive to the value of RL and the setpoint**

**Dependent claim 16 operates the motor when  $RL < SP$**

**Dependent claim 16 operates engine while  $SP < the RL < the MTO$**

'634 Patent, Claim 16

# Severinsky and Ehsani do not disclose or render obvious '634 Patent, claim 18

18. The hybrid vehicle of claim 16, wherein the plurality of operating modes further comprise a low-speed battery charging mode II, wherein, when the  $RL < \text{the SP}$  and a state of charge of the battery is below a predetermined level: the controller is operable to decouple the engine and the first electric motor from the one or more wheels and start the engine if the engine is not running to enter the battery charging mode II; the second electric motor is operable to provide torque to propel the hybrid vehicle; and the engine is operable to provide torque at least equal to the SP to the first motor for charging the battery.

Dependent claim 18 recites a battery charging mode entered while  $RL < SP$

Dependent claim 18 recites that the battery is charged by energy from the motor, being driven by torque in excess of SP by the engine,

'634 Patent, Claim 18

## The combination of Severinsky, Field, and SAE 1996 fails to disclose a first motor that can receive torque $\geq$ SP

- The motor of SAE 1996 on which Ford relies is only 6 kW (8 hp) and is too small to accept torque equal to the alleged 60% setpoint of Severinsky
  - The engine of Severinsky has an MTO of “about 45 horsepower.” Ex. 1003 at 6:63-66; 8:52-36. Thus, the engine could operate at best at roughly 18% MTO to charge the battery. Ex. 2004 at ¶¶ 148-49.
  - The relative fuel consumption of the engine of Severinsky at 8 hp is 210% of the most efficient value—far below a setpoint “above which the torque produced by the engine is efficiently produced.” Ex. 2004 at ¶¶ 148-49.

Generator Motor - The generator motor is a DC brushless motor with a maximum output of 6 kW. Using a motor with 8 poles, which is more than usual, the generator brake and the planetary gear are arranged inside the coil ends, causing the total length to be shortened.

SAE 1996, Ex. 1025 at 11.

**END**