

DECLARATION OF JON MEARS

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3. The document attached as Exhibit A is a scan of a portion of a periodical that I located in the Milson S. Eisenhower Library's collection of periodicals. Specifically, Exhibit A shows the article titled "Communication Protocols for Embedded Systems" as in appears in the November 1994 issue of *Embedded Systems Programming*. This is volume 7, issue 11 of this publication.

4. The stamp on the back cover of the November 1994 issue of *Embedded Systems Programming* reads "OCT 28 1994." It is the regular practice of the Milton S. Eisenhower Library to stamp periodicals with the date the periodical is added to the library's catalog. Once a periodical is in the library's catalog, it is made available in the library for viewing by any visitor of the library.

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Dated: March 11, 2014

Samsung Ex. 1218 (Samsung v. Rembrandt)

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EXHIBIT A

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Ada Achieves Orbit

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Cruising with Ada Basics of Networking Containers in C++ Plauger on Prediction

A Satellite Case Study

BLTIMORE, MD 21218

Exhibit 1218 03/12

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WBHARGAV UPENDER AND PHILIP KOOPMAN. Some networking architectures were designed without nbedded or real-time concerns in mind. Here's an review of the tradeoffs in choosing different embedied networking protocols.

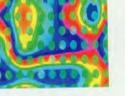
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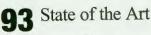
BY BRUCE ECKEL. Container classes are quite useful. mplementing them, however, often requires template apport. In keeping with our emphasis on "under the bod" details, this month's introduction to C++ containers is also an exploration in the use of templates.



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What Happens Next? by P.J. Plauger

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If your geosynchronous service calls are getting too expensive, try shifting to Ada. Cover by Rupert Adley.

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Communication Protocols for Embedded Systems

There's more to connecting multiple CPUs than just stringing wires or cable. Your choice of network protocol, in particular, will determine system performance.

he past few years have seen a growing trend to dramatically increase the embedded electronics content of automobiles, elevators, building climate control systems, jet aircraft engines, and other traditionally electro-mechanically controlled systems. In many large systems, this increasing electronics content is accompanied by a proliferation of subsystems with separate CPUs.

The increase in the number of processors in a system is often driven by computation and I/O growth. In some development environments, the increase may also be driven by a need to ease system integration burdens among multiple design groups or to provide system flexibility through "smart sensors" and "smart actuators." Whatever the reasons, once there is more than one CPU in a system, there must be some means of communication to coordinate action.

While some high-end embedded systems communicate over a VME backplane or similar arrangement, the embedded systems we're working on use physically distributed CPUs involving some sort of local area network (LAN), also called a multiplexed transmitter for access to the shared **n** work medium, typically a wire, fibe, or RF frequency.

In this article, we will discuss the special considerations for network real-time embedded systems, and look at several media access protocol, in demonstrate fundamentally different ways of accessing the shared medium The protocols are: connection-onme protocols, polling, time division multiple access (TDMA), token ring, token bus, binary countdown, carrier serve multiple access with collision deter tion (CSMA/CD), and carrier sense multiple access with collision avoid ance (CSMA/CA). For each of these we will evaluate the strength and weaknesses against special consider tions. A protocol tradeoff chart will enable you to select a protocol to fit your needs. While no protocol is refect for all purposes, a variatic CSMA/CA offers the most versati for many embedded systems.1

SPECIAL CONSIDERATIONS

I n practice, we have found to embedded real-time network require high efficiency, deterministic latency, operational robustor configuration flexibility, and low or

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