

PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Application of: Mario Boisvert *et al.*

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Title: *COLLISION MONITORING SYSTEM*

Examiner: Marlon T. Fletcher

Art Unit: 2837

Docket No.: 14-733C2D1

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MAIL STOP AMENDMENT
Commissioner for Patents
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RESPONSE

In response to the office action having a mailing date of July 23, 2008, please consider the following:

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August 19, 2008

Claim Status

1. (previously presented) Apparatus for controlling motion of a motor driven element in a vehicle over a range of motion and for altering said motion when undesirable resistance to said motion is encountered, said apparatus comprising:

a) a sensor for measuring a parameter of a motor coupled to the motor driven element that varies in response to a resistance to motion during all or part of a range of motion of the motor driven element;

b) a memory for storing a number of measurement values from the sensor based on immediate past measurements of said parameter over at least a portion of a present traversal of said motor driven element through said range of motion;

c) a controller coupled to the memory for determining to de-activate the motor based on a most recent sensor measurement of the parameter and the immediate past measurement values stored in the memory obtained during a present run through the motor driven element range of motion; and

d) a controller interface coupled to the motor for altering motion of said motor driven element during the present run in response to a determination made by the controller.

2. (previously presented) A method for controlling motion of a motor driven element in a vehicle over a range of motion and for altering said motion when undesirable resistance to said motion is encountered, said method comprising:

a) measuring a parameter of a motor coupled to the motor driven element that varies in response to a resistance to motion during all or part of a range of motion of the motor driven element by taking a multiplicity of measurements as the motor moves the motor driven element over its range of motion;

b) storing a number of measurement values based on measurements of said parameter over an immediate past portion of a present run through said range of motion;

c) determining that the parameter is outside a parameter range based on stored measurement values obtained during the immediate past portion as the motor driven element moves over its range of motion; and

d) altering motion of said motor driven element during the present run in response to a determination that the parameter is outside the parameter range.

3. (Original) The method of claim 2 wherein the motor driven element is a window or panel and additionally comprising reverse actuating the window or panel prior to moving said window or panel in a direction to close the window or panel.

4. (Original) The method of claim 3 additionally comprising maintaining a position of the window or panel based on the sensed parameter and the reverse actuation is initiated if a leading edge of the window or panel is near a closed position.

5. (Original) The method of claim 4 movement is first initiated toward a closed position when a leading edge of the window or panel is near the closed position and wherein the reverse actuation is performed upon a sensing of an obstacle that is based on determining the parameter is outside the parameter range.

6. (Previously Presented) Apparatus for controlling activation of a motor coupled to a motor vehicle window or panel for moving said window or panel along a travel path and de-activating the motor if an obstacle is encountered by the window or panel, said apparatus comprising:

a) a sensor for sensing movement of the window or panel and providing a sensor output signal related to a speed of movement of the window or panel;

b) a switch for controllably actuating the motor by providing an energization signal; and

c) a controller having an interface coupled to the sensor and the switch for controllably energizing the motor; said controller sensing a collision with an obstruction

when power is applied to the controller by:

- i) monitoring movement of the window or panel by monitoring a signal from the sensor related to the movement of the window or panel;
- ii) adjusting an obstacle detection threshold in real time based on immediate past measurements of the signal sensed by the sensor to adapt to varying conditions encountered during operation of the window or panel;
- iii) identifying a collision of the window or panel with an obstacle due to a change in the signal from the sensor that is related to a change in movement of the window or panel by comparing a value based on a most recent signal from the sensor with the obstacle detection threshold; and
- iv) outputting a control signal to said switch to deactivate said motor in response to a sensing of a collision between an obstacle and said window or panel.

7. (Original) The apparatus of claim 6 wherein the controller comprises a programmable controller including a processing unit for executing a control program and including a memory for storing multiple window or panel speed values corresponding to a signal received from the sensor.

8. (Original) The apparatus of claim 6 additionally comprising one or more limit switches for use by the controller to determine window or panel position for use in identifying a collision.

9. (Cancelled)

10. (Original) The apparatus of claim 6 wherein the controller maintains a position of a leading edge of the window or panel and further wherein the controller reverse energizes the motor to move the window or panel away from a closure position prior to activating the motor to close the window or panel.

11. (Original) The apparatus of claim 10 wherein the controller reverse energizes the motor in response to a sensing of an obstacle and the reverse energizing and attempt to move the window or panel to a closed position is performed to confirm sensing of the obstacle.

12. (Previously Presented) Apparatus for controlling activation of a motor for moving an object along a travel path and de-activating the motor if an obstacle is encountered by the object comprising:

a) a movement sensor for monitoring movement of the object as the motor moves said object along a travel path;

b) a switch for controlling energization of the motor with an energization signal;

and

c) a controller including an interface coupled to the switch for controllably energizing the motor and said interface additionally coupling the controller to the movement sensor for monitoring signals from said movement sensor; said controller comprising a stored program that:

i) determines motor speed of movement from an output signal from the movement sensor ;

ii) calculates an obstacle detect threshold based on motor speed of movement detected during a present run of said motor driven element;

iii) compares a value based on currently sensed motor speed of movement with the obstacle detect threshold; and

iv) outputs a signal from the interface to said switch for stopping the motor if the comparison based on currently sensed motor movement indicates the object has contacted an obstacle.

13. (Original) The apparatus of claim 12 wherein the controller includes a buffer memory for storing successive values of motor movement for use in determining the obstacle detect threshold.

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