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FIRST NAMED INVENTOR ATTORNEY DOCKET NO. CONFIRMATION NO. APPLICATION NO. FILING DATE 01/27/2004 9537 10/765,487 Mario Boisvert 14-733C2D1 EXAMINER WATTS HOFFMANN CO. L.P.A. FLETCHER, MARLON T 1100 SUPERIOR AVE., SUITE 1750 ART UNIT PAPER NUMBER CLEVELAND, OH 44114 2837

DATE MAILED: 10/16/2006

Please find below and/or attached an Office communication concerning this application or proceeding.

PTO-90C (Rev. 10/03)



	Application No.	Applicant(s)
	10/765,487	BOISVERT ET AL.
Office Action Summary	Examiner	Art Unit
	Marlon T. Fletcher	2837
The MAILING DATE of this communication	appears on the cover sheet w	rith the correspondence address
Period for Reply		
A SHORTENED STATUTORY PERIOD FOR REWHICHEVER IS LONGER, FROM THE MAILING. Extensions of time may be available under the provisions of 37 CF after SIX (6) MONTHS from the mailing date of this communication. If NO period for reply is specified above, the maximum statutory properties to reply within the set or extended period for reply will, by so Any reply received by the Office later than three months after the rearned patent term adjustment. See 37 CFR 1.704(b).	G DATE OF THIS COMMUNI R 1.136(a). In no event, however, may a n. eriod will apply and will expire SIX (6) MO tatute, cause the application to become A	CATION. reply be timely filed NTHS from the mailing date of this communication. BANDONED (35 U.S.C. § 133).
Status		
1) Responsive to communication(s) filed on	05 June 2006.	
	This action is non-final.	
3) Since this application is in condition for all		ters, prosecution as to the merits is
closed in accordance with the practice und		
,		
Disposition of Claims		
4) ☐ Claim(s) <u>1-35</u> is/are pending in the applica		
4a) Of the above claim(s) is/are with	ndrawn from consideration.	
5) Claim(s) is/are allowed.		
6) Claim(s) <u>1-35</u> is/are rejected.		
7) Claim(s) is/are objected to.		
8) Claim(s) are subject to restriction a	nd/or election requirement.	
Application Papers	*	
9) The specification is objected to by the Exar	miner	
10) The drawing(s) filed on is/are: a)		by the Examiner
Applicant may not request that any objection to	그 그 그렇게 되는 그 맛있었다. 그 맛이 되었다.	But the state of t
Replacement drawing sheet(s) including the co		
11) The oath or declaration is objected to by the		
	e Examinor. Note the attache	a chiec riction of form 170 102.
Priority under 35 U.S.C. § 119		
12) Acknowledgment is made of a claim for for	eign priority under 35 U.S.C.	§ 119(a)-(d) or (f).
a) ☐ All b) ☐ Some * c) ☐ None of:		
 Certified copies of the priority documents. 		
Certified copies of the priority documents		\$1. THE COURT POST OF THE PROPERTY OF THE POST OF THE
Copies of the certified copies of the		received in this National Stage
application from the International Bu		
* See the attached detailed Office action for a	a list of the certified copies no	t received.
Attachment(s)		
1) Notice of References Cited (PTO-892)		Summary (PTO-413)
2) Notice of Draftsperson's Patent Drawing Review (PTO-948		(s)/Mail Date Informal Patent Application
Information Disclosure Statement(s) (PTO/SB/08) Paper No(s)/Mail Date	6) Other:	3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
S. Patent and Trademark Office	ce Action Summary	Part of Paper No./Mail Date 20061010



Application/Control Number: 10/765,487

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DETAILED ACTION

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Claim Rejections - 35 USC § 102

1. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

(b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.

2. Claims 1-20, 23, 25, 28-33, and 35, are rejected under 35 U.S.C. 102(b) as being anticipated by Jones et al. (4,831,509).

As recited in claims 1 and 2, Jones et al. disclose an apparatus for controlling motion of a motor driven element in a vehicle over a range of motion and for altering said motion when undesirable resistance to the motion is encountered, said apparatus comprising: a sensor for measuring a parameter of a motor coupled to the motor driven element that varies in response to a resistance to motion during all or part of a range of motion of the motor driven element (column 3, lines 7-16); a memory for storing a number of measurement values from the sensor based on measurements of said parameter over at least a portion of the range of motion (abstract; column 3, line 56 through column 4, line 14; and column 5, lines 26-57); a controller (microprocessor', figure 8) coupled to the memory for determining to de-activate the motor based on the measurement values stored in the memory as the motor driven element moves over its range of motion (column 4, lines 49-55); and a controller interface coupled to the motor for altering motion of said motor driven element in response to a determination made by



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the controller (column 4, lines 53-57), wherein altering is also in response to a determination that the parameter is outside the parameter range.

As recited in claims 3 and 31, Jones et al. disclose the method, wherein the motor driven element is a window or panel and additionally comprising reverse actuating the window or panel prior to moving said window or panel in a direction to close the window or panel (column 4, lines 55-57).

As recited in claim 4, Jones et al. disclose the method, additionally comprising maintaining a position of the window or panel based on the sensed parameter and the reverse actuation is initiated if a leading edge of the window or panel is near a closed position (column 3, lines 17-28).

As recited in claims 5, 10, and 11, Jones et al. disclose the method, movement is first initiated toward a closed position when a leading edge of the window or panel is near the closed position and wherein the reverse actuation is performed upon a sensing of an obstacle that is based on determining the parameter is outside the parameter range (column 3, lines 17-28; and column 4, lines 49-57).

As recited in claims 6 and 33, Jones et al. disclose an apparatus for controlling activation of a motor coupled to a motor vehicle window or panel for moving said window or panel along a travel path and deactivating the motor if an obstacle is encountered by the window or panel, said apparatus comprising: a sensor for sensing movement of the window or panel and providing a sensor output signal related to a speed of movement of the window or panel (discussed above; a switch for controllably actuating the motor by providing an energization signal (figure 7), and a controller



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having an interface coupled to the sensor and the switch for controllably energizing the motor (figures 7 and 8); said controller sensing a collision with an obstruction when power is applied to the controller by: monitoring movement of the window or panel by monitoring a signal from the sensor related to the movement of the window or panel (column 3, Lines 9-28), identifying a collision of the window or panel with an obstacle due to a change in the signal from the sensor that is related to a change in movement of the window or panel (column 3, line 56 through column 4, line 55); and outputting a control signal to said switch to deactivate said motor in response to a sensing of a collision between an obstacle and said window or panel (column 4, Lines 55-57).

As recited in claims 7, 29, and 35, Jones et al. disclose the apparatus, wherein the controller comprises a programmable controller including a processing unit for executing a control program and including a memory for storing multiple window or panel speed values corresponding to a signal received from the sensor (column 3, line 36 through column 4, line 39).

As recited in claims 8 and 30, Jones et al. disclose the apparatus, additionally comprising one or more limit switches for use by the controller to determine window or panel position for use in identifying a collision (column 5, Lines 26-57).

As recited in claim 9, Jones et al. disclose the apparatus, wherein the control program adjusts an obstacle detection threshold in real time based on immediate past measures of the signal sensed by the sensor to adapt to varying conditions encountered during operation of the window or panel (column 4, Lines 49-68).



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