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(54) METHOD AND SYSTEM OF SPARSE CODE BASED OBJECT CLASSIFICATION WITH SENSOR FUSION

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(51) **Int. Cl.** *H04N 7/18* (2006.01) *G06F 15/16* (2006.01)

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(10) **Patent No.:**

(45) Date of Patent:

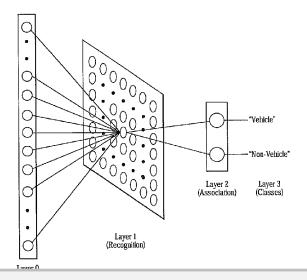
Primary Examiner — Zarni Maung

(74) Attorney, Agent, or Firm — Gifford, Krass, Spinkle, Anderson & Citkowski, P.C.

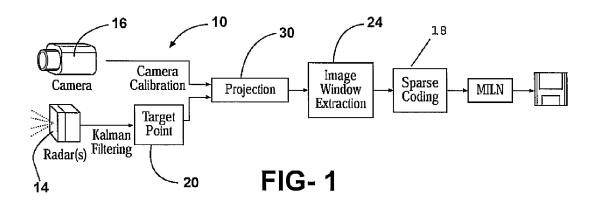
(57) ABSTRACT

A system and method for object classification based upon the fusion of a radar system and a natural imaging device using sparse code representation. The radar system provides a means of detecting the presence of an object within a predetermined path of a vehicle. Detected objects are then fused with the image gathered by the camera and then isolated in an attention window. The attention window is then transformed into a sparse code representation of the object. The sparse code representation is then compared with known sparse code representation of various objects. Each known sparse code representation is given a predetermined variance and subsequent sparse code represented objects falling within said variance will be classified as such. The system and method also includes an associative learning algorithm wherein classified sparse code representations are stored and used to help classifying subsequent sparse code representation.

4 Claims, 5 Drawing Sheets







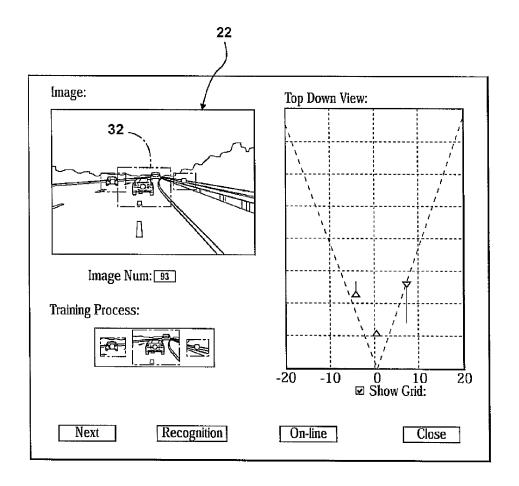
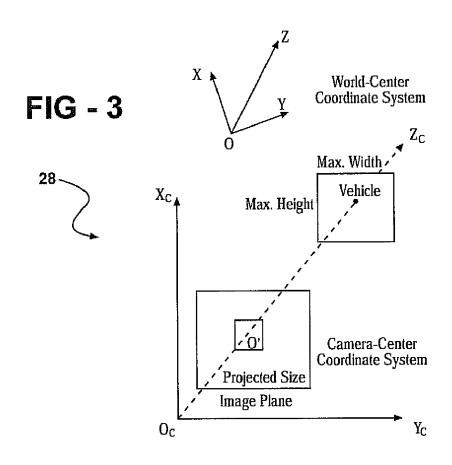


FIG - 2





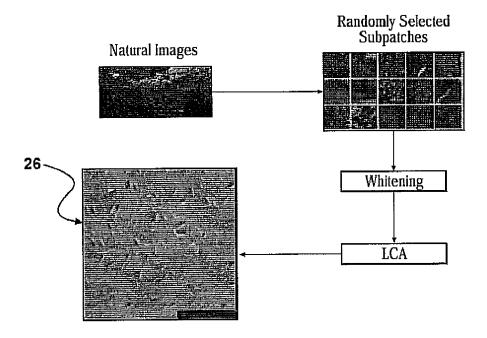


FIG - 4



FIG - 5

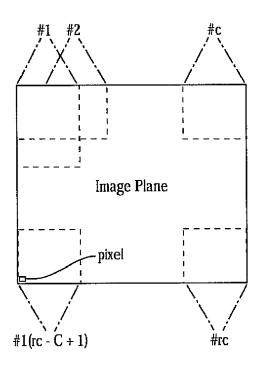
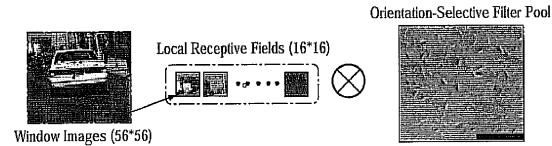
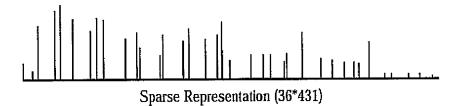


FIG - 6







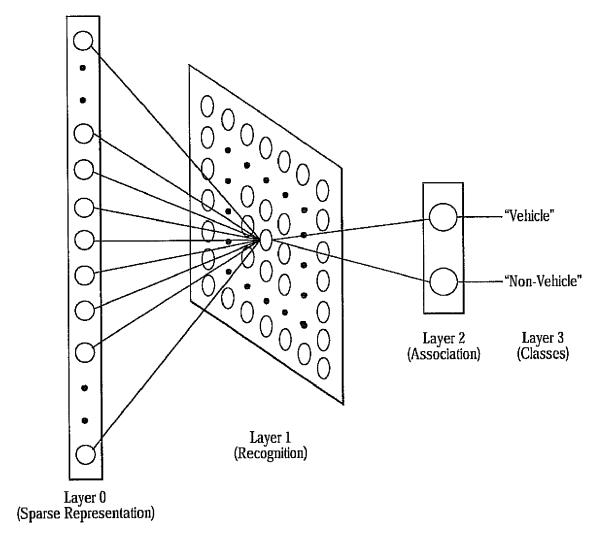


FIG - 7



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